





Gaussian Processes for Regression: Models, Algorithms, and Applications, Day 2

Tamara Broderick

Associate Professor MIT

- Bayesian modeling and inference
- Gaussian process model
 - Popular version using a squared exponential kernel
- Gaussian process inference
 - Prediction & uncertainty quantification
- Observation noise
- What uncertainty are we quantifying?
- What can go wrong?
- Bayesian optimization
- Goals:
 - Learn the mechanism behind standard GPs to identify benefits and pitfalls (also in BayesOpt)
 - Learn the skills to be responsible users of standard GPs (transferable to other ML/Al methods)

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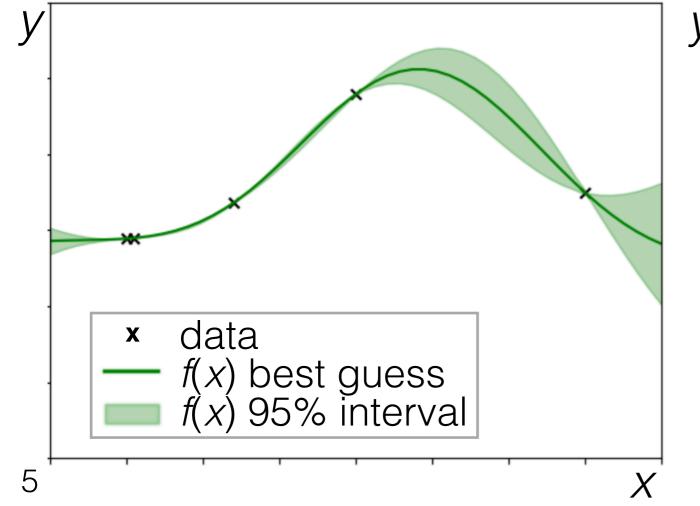
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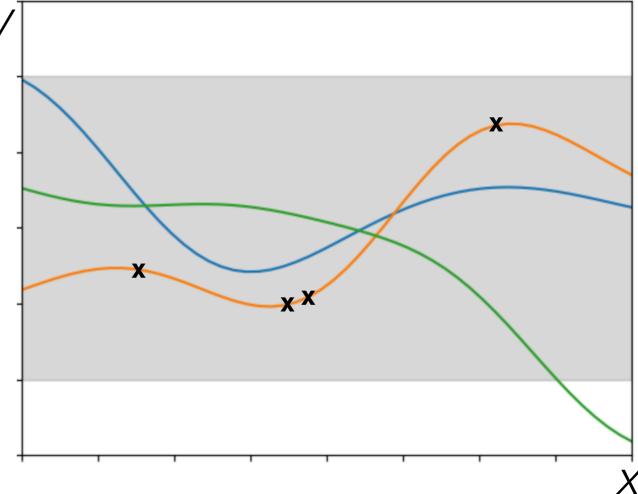
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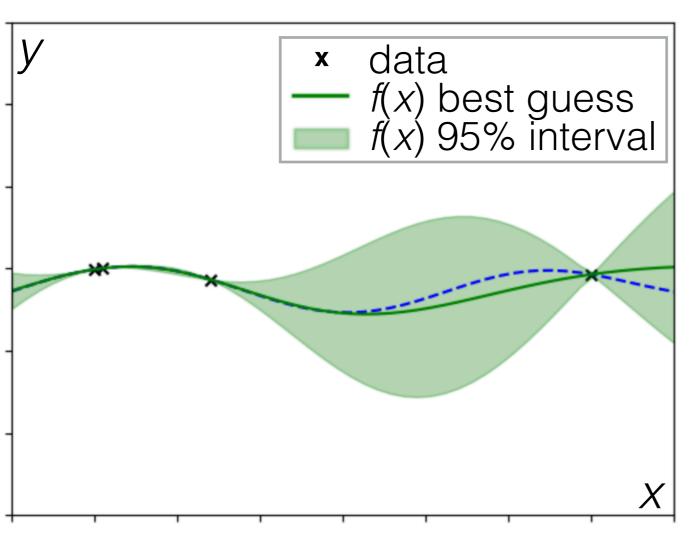
A Bayesian approach

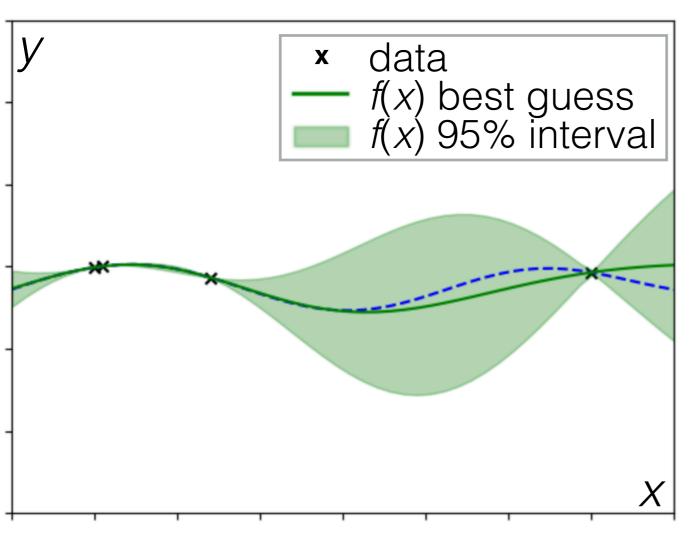
Given the data we've seen, what do we know about the underlying function?

A (statistical) model that can generate functions and data of interest

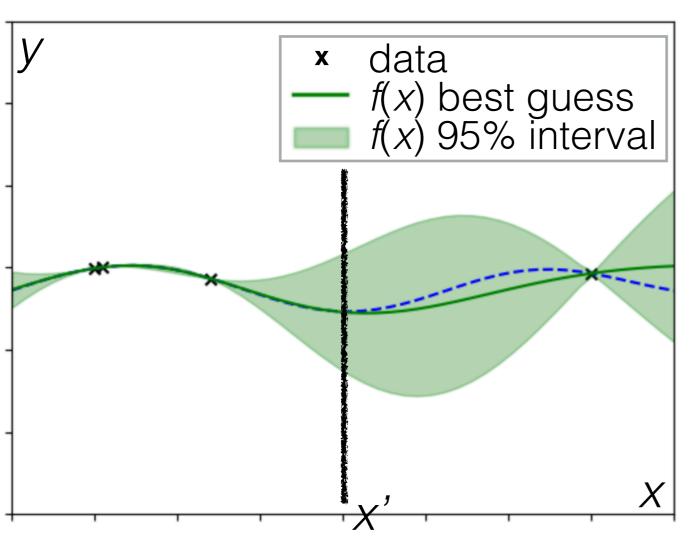




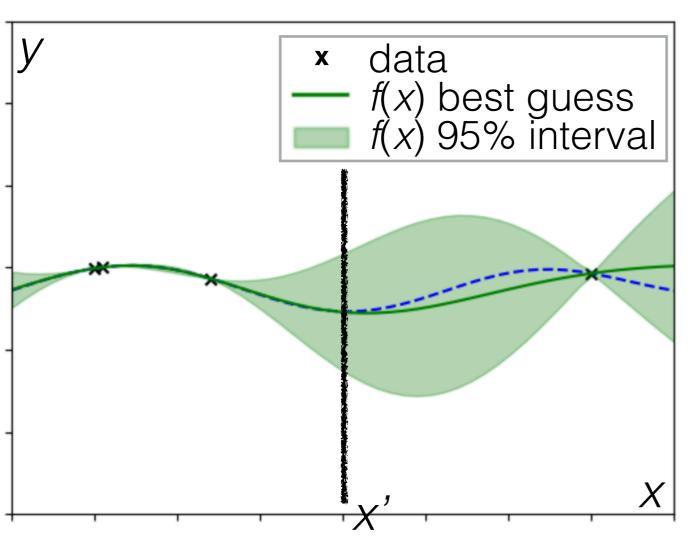




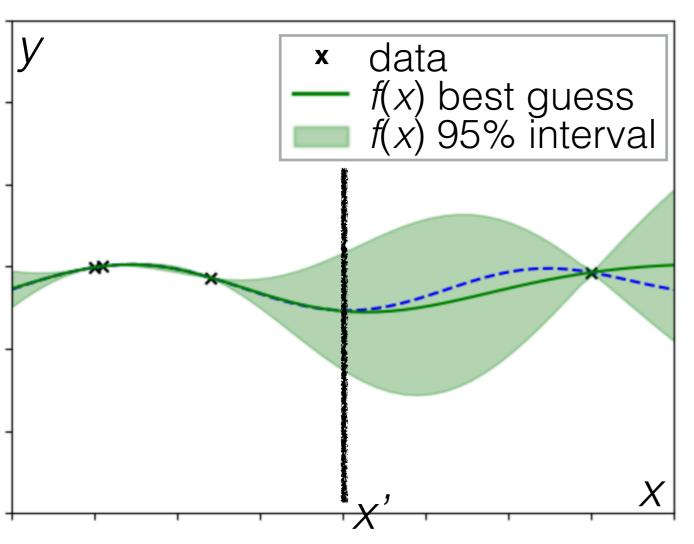
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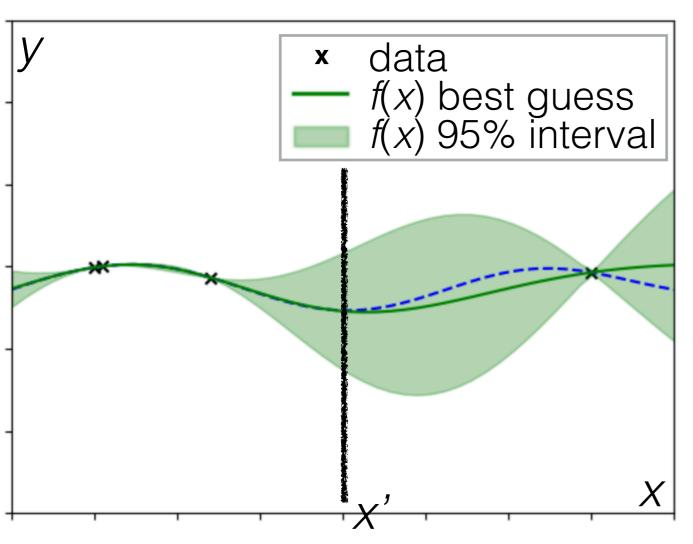
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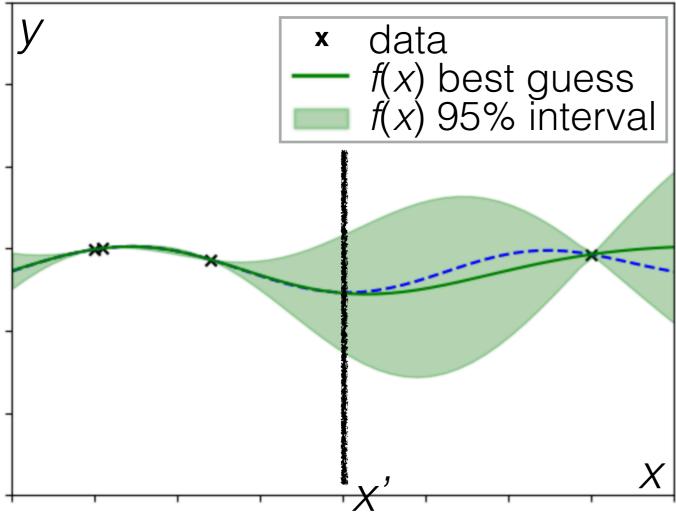


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- The green interval at that point: mean +/- 2 std devs



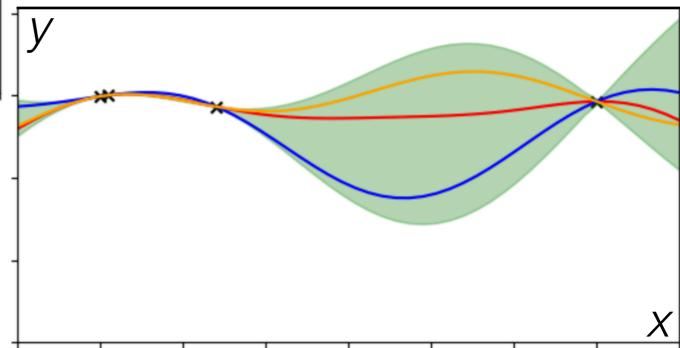
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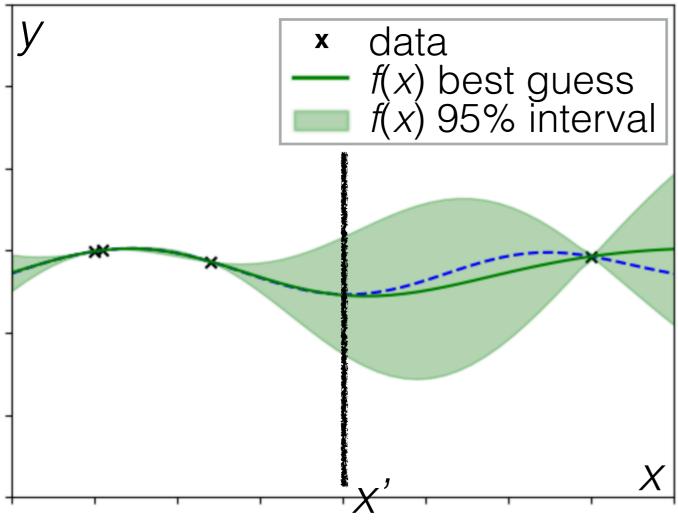
 Draw random f conditional on the training data



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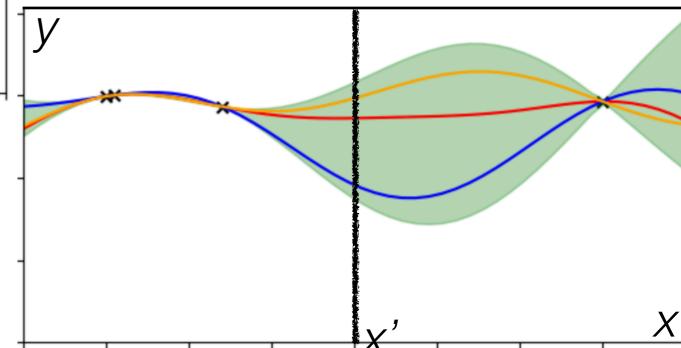
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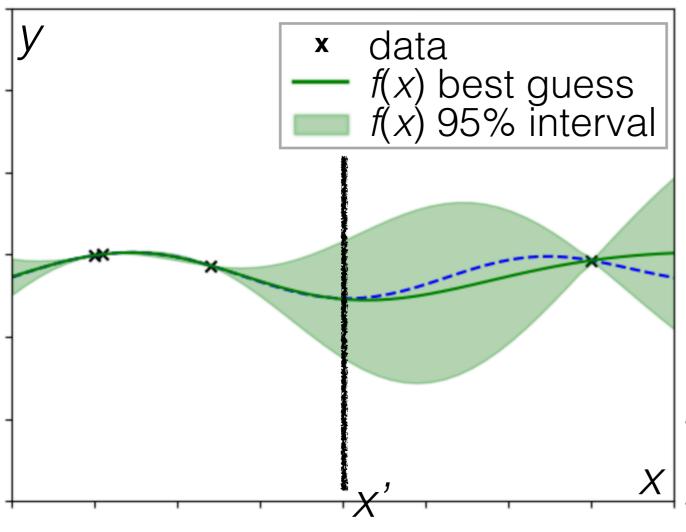




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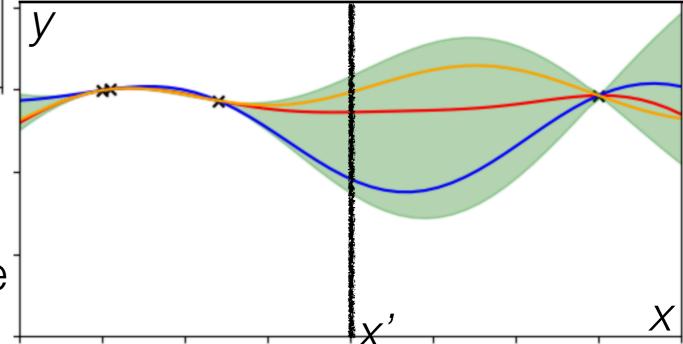
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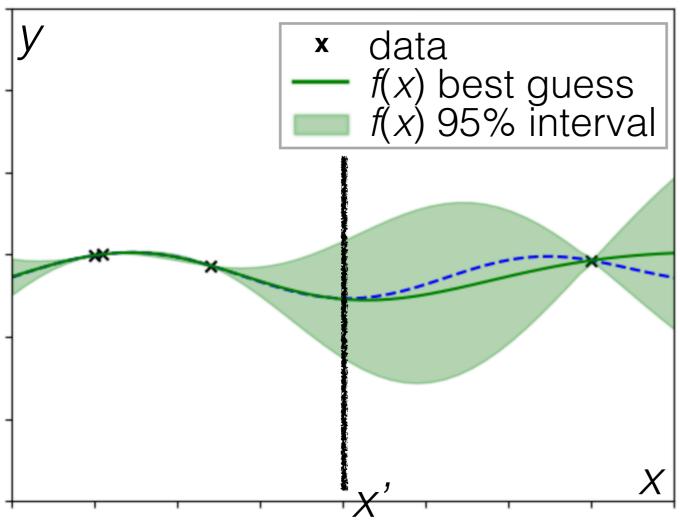




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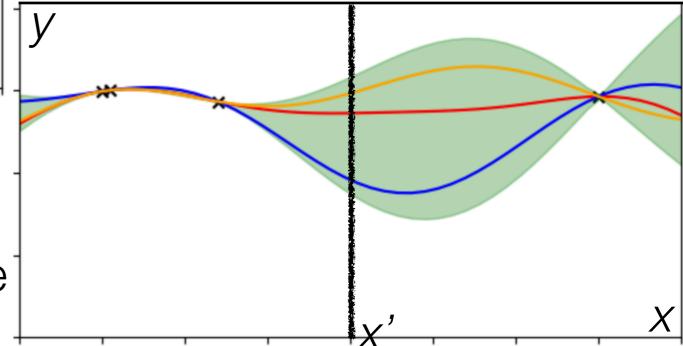
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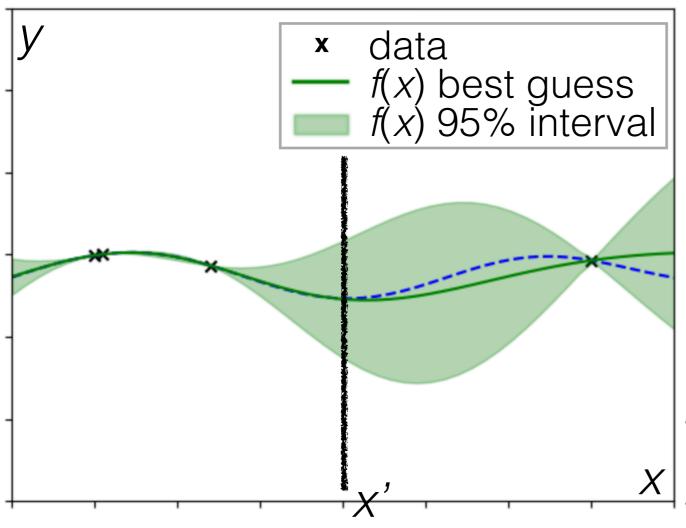




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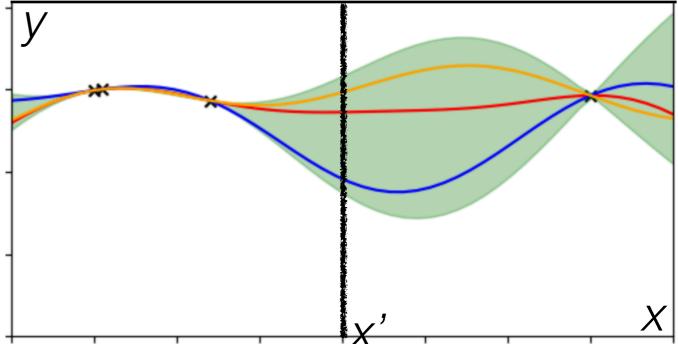
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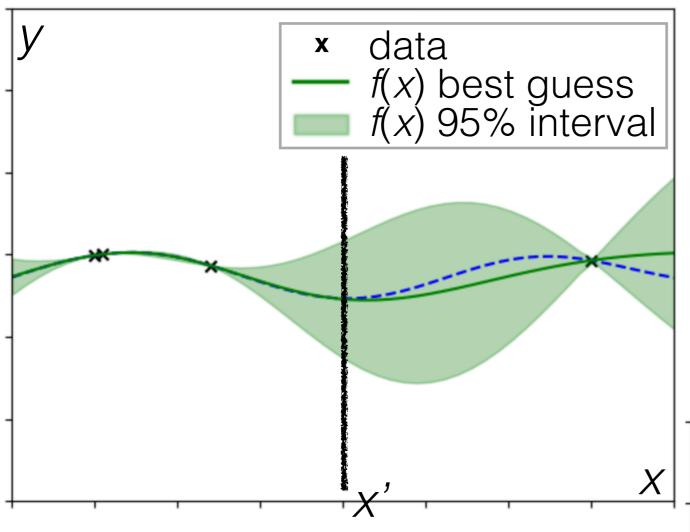




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- Probability that all points on f fall within the green interval across the whole plot
 2

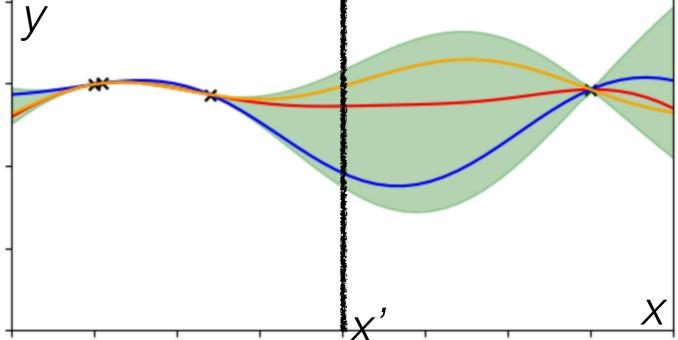
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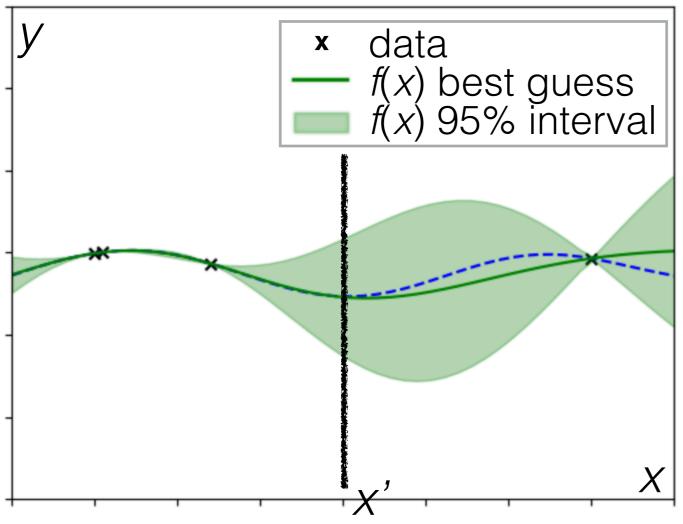




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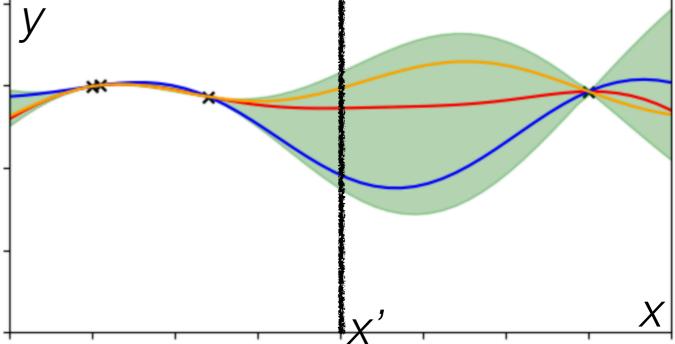
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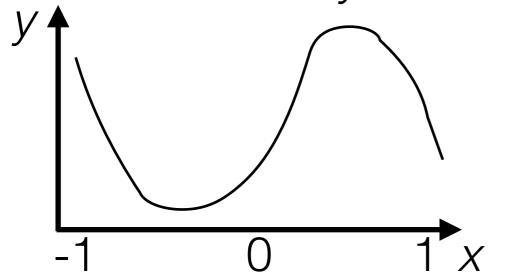
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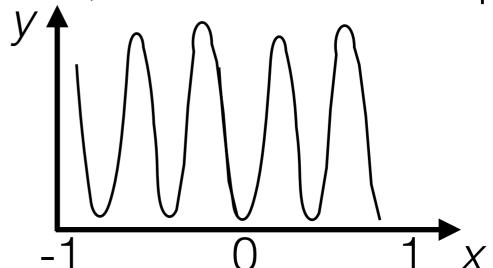
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 - So the mean of $y^{(n)}$ is $m(\mathbf{x}^{(n)})$ and

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$$\begin{bmatrix} f(X) \\ f(X') \end{bmatrix} \sim \mathcal{N} \left(\mathbf{0}, \begin{bmatrix} K(X,X) & K(X,X') \\ K(X',X) & K(X',X') \end{bmatrix} \right)$$

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What if we put y here instead?

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[demo2, demo3]

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Can you state a non-trivial lower bound [demo2, demo3] on the marginal variance of a test \sqrt{m} ?

Even when observations are Observation noise "perfect," use a (very small)

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Can you state a non-trivial lower bound [demo2, demo3] on the marginal variance of a test $y^{(m)}$?