

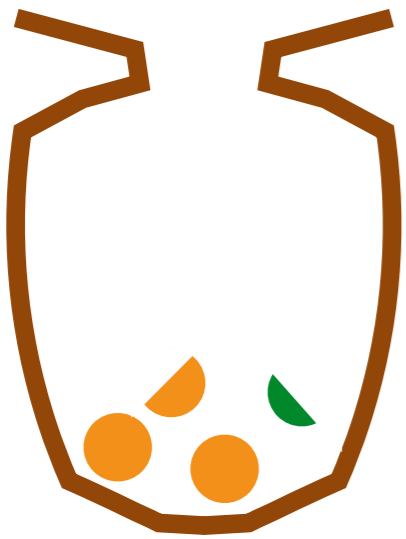


# Nonparametric Bayesian Methods: Models, Algorithms, and Applications (Part III)

Tamara Broderick

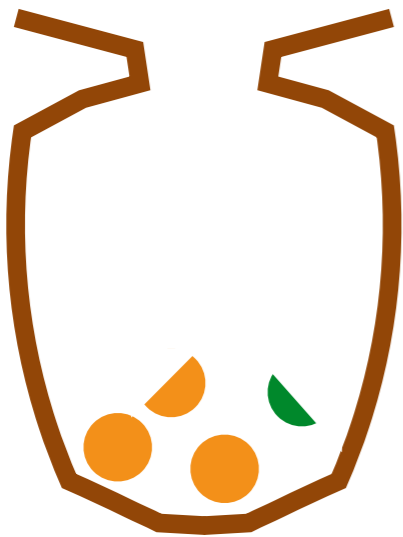
ITT Career Development Assistant Professor  
Electrical Engineering & Computer Science  
MIT

# Marginal cluster assignments



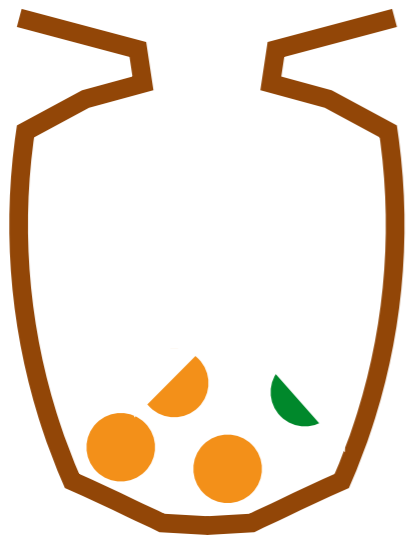
# Marginal cluster assignments

- Pólya urn



# Marginal cluster assignments

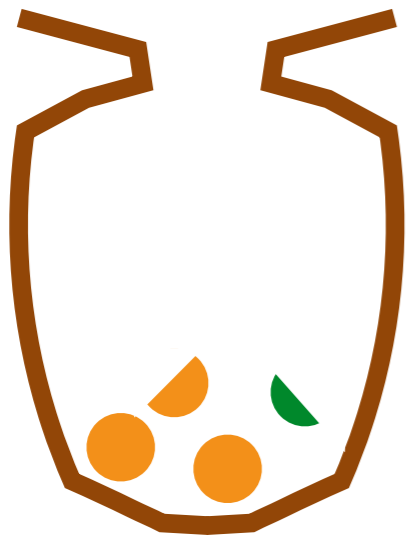
- Pólya urn
  - Choose any ball with prob proportional to its mass
  - Replace and add ball of same color



# Marginal cluster assignments

- Pólya urn
  - Choose any ball with prob proportional to its mass
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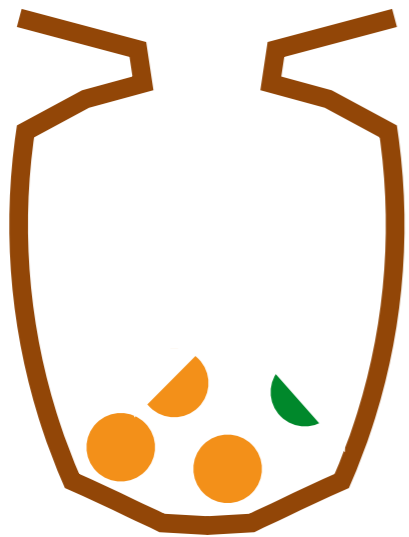
PolyaUrn( $a_{\text{orange}}$ ,  $a_{\text{green}}$ )



# Marginal cluster assignments

- Pólya urn
  - Choose any ball with prob proportional to its mass
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PolyaUrn( $a_{\text{orange}}$ ,  $a_{\text{green}}$ )



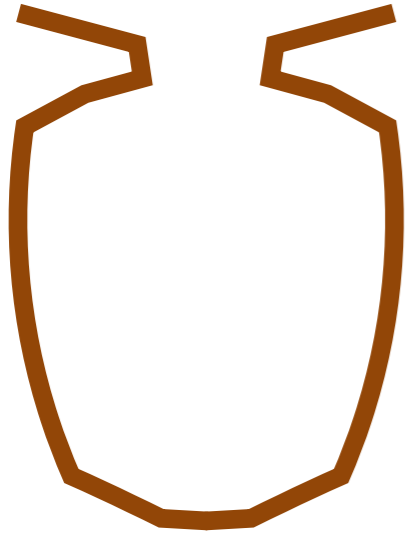
$$\lim_{n \rightarrow \infty} \frac{\# \text{ orange}}{\# \text{ total}} = \rho_{\text{orange}} \stackrel{d}{=} \text{Beta}(a_{\text{orange}}, a_{\text{green}})$$

# Marginal cluster assignments

- Hoppe urn / Blackwell-MacQueen urn

# Marginal cluster assignments

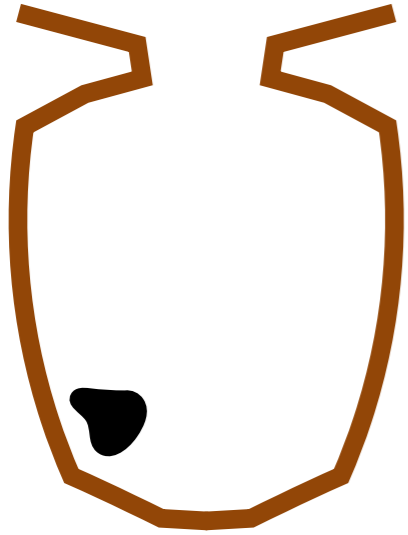
- Hoppe urn / Blackwell-MacQueen urn





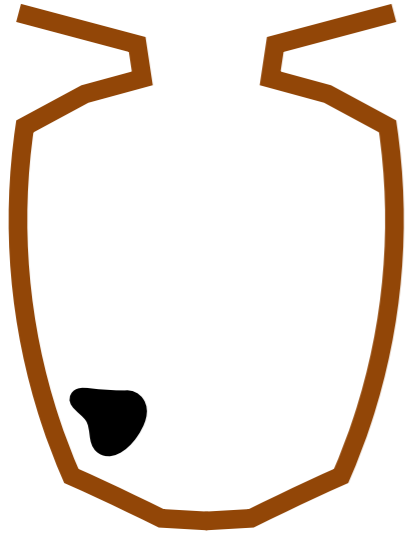
# Marginal cluster assignments

- Hoppe urn / Blackwell-MacQueen urn



# Marginal cluster assignments

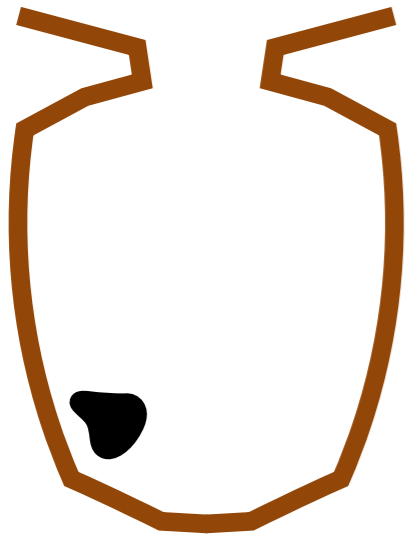
- Hoppe urn / Blackwell-MacQueen urn



- Choose ball with prob proportional to its mass

# Marginal cluster assignments

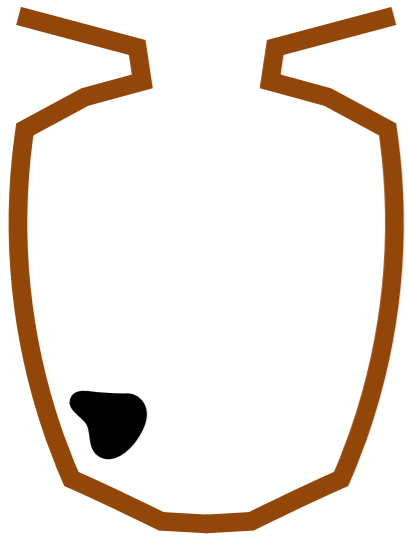
- Hoppe urn / Blackwell-MacQueen urn



- Choose ball with prob proportional to its mass
  - If black, replace and add ball of new color

# Marginal cluster assignments

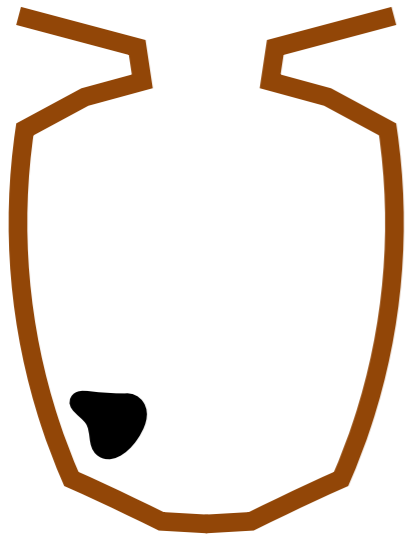
- Hoppe urn / Blackwell-MacQueen urn



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# Marginal cluster assignments

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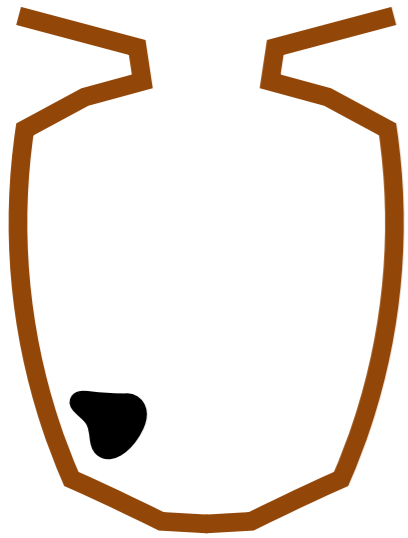
- Choose ball with prob proportional to its mass
  - If black, replace and add ball of new color
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Step 0

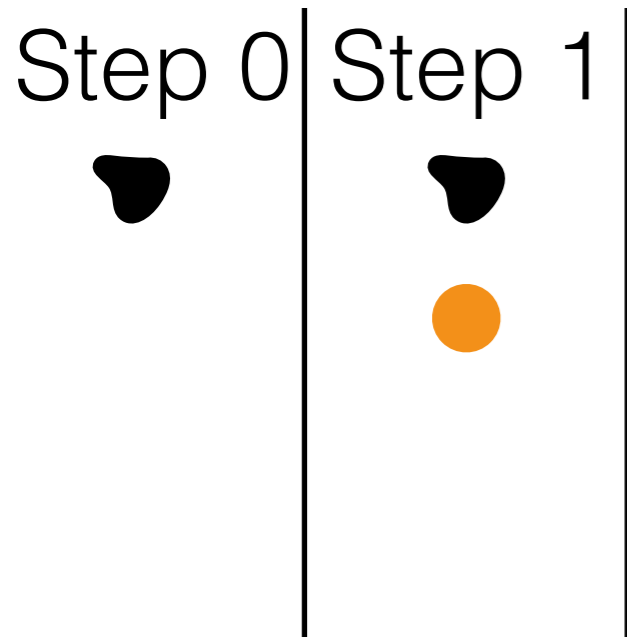


# Marginal cluster assignments

- Hoppe urn / Blackwell-MacQueen urn

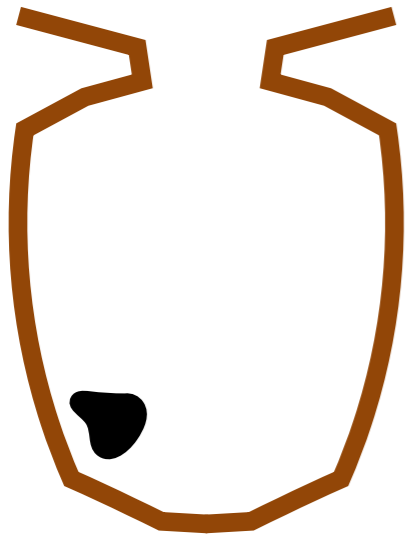


- Choose ball with prob proportional to its mass
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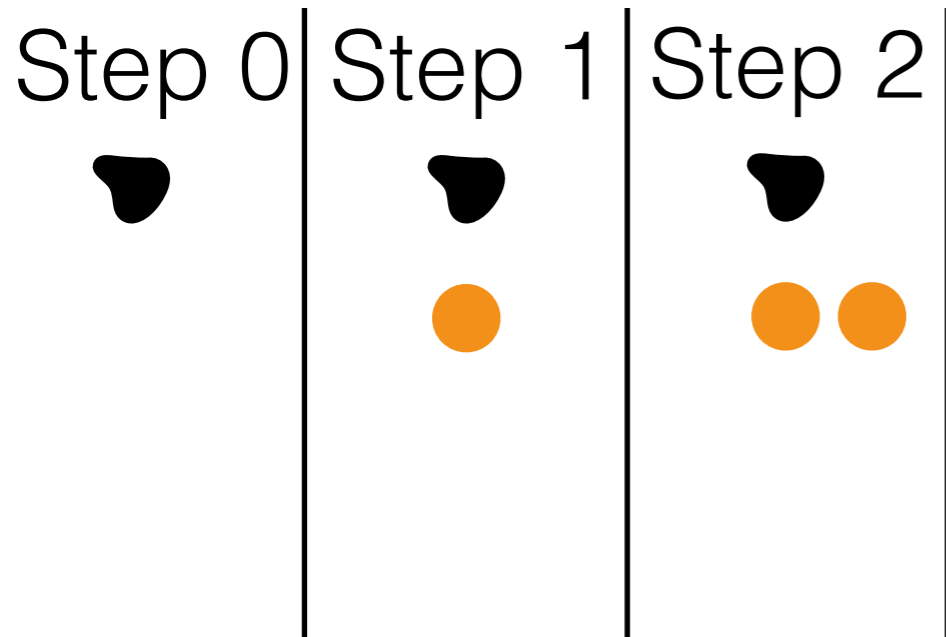


# Marginal cluster assignments

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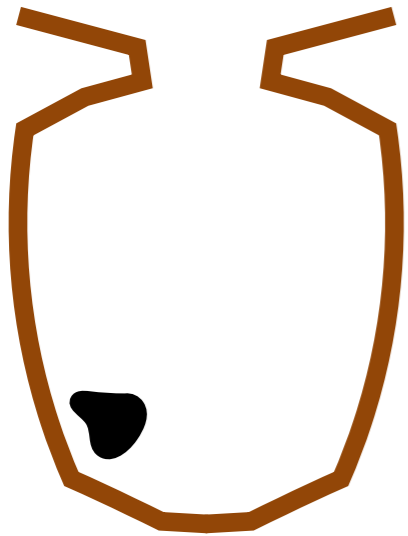


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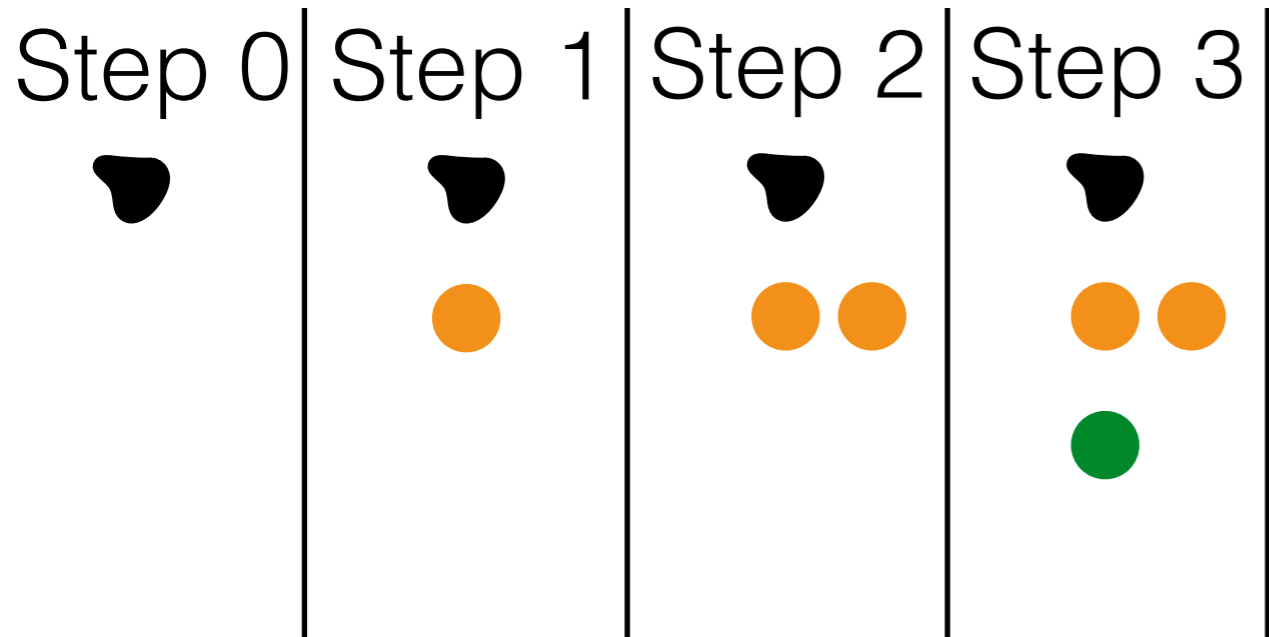


# Marginal cluster assignments

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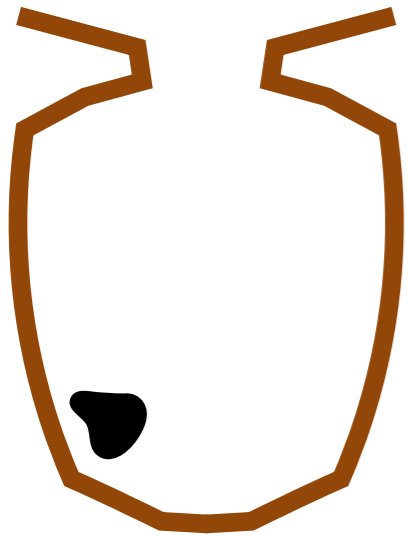
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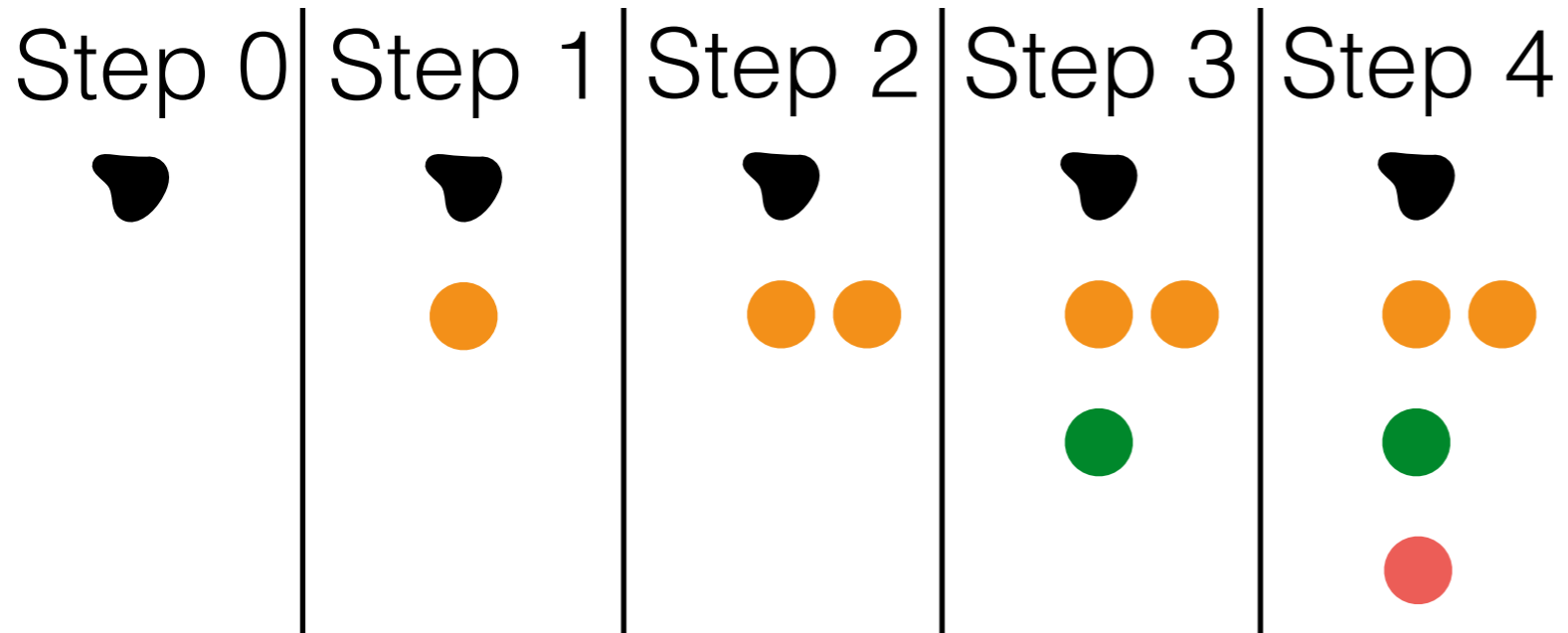


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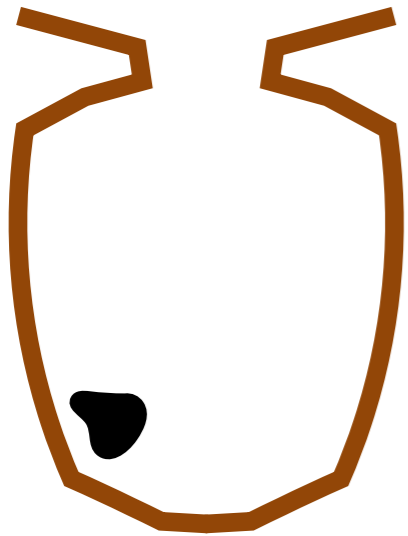


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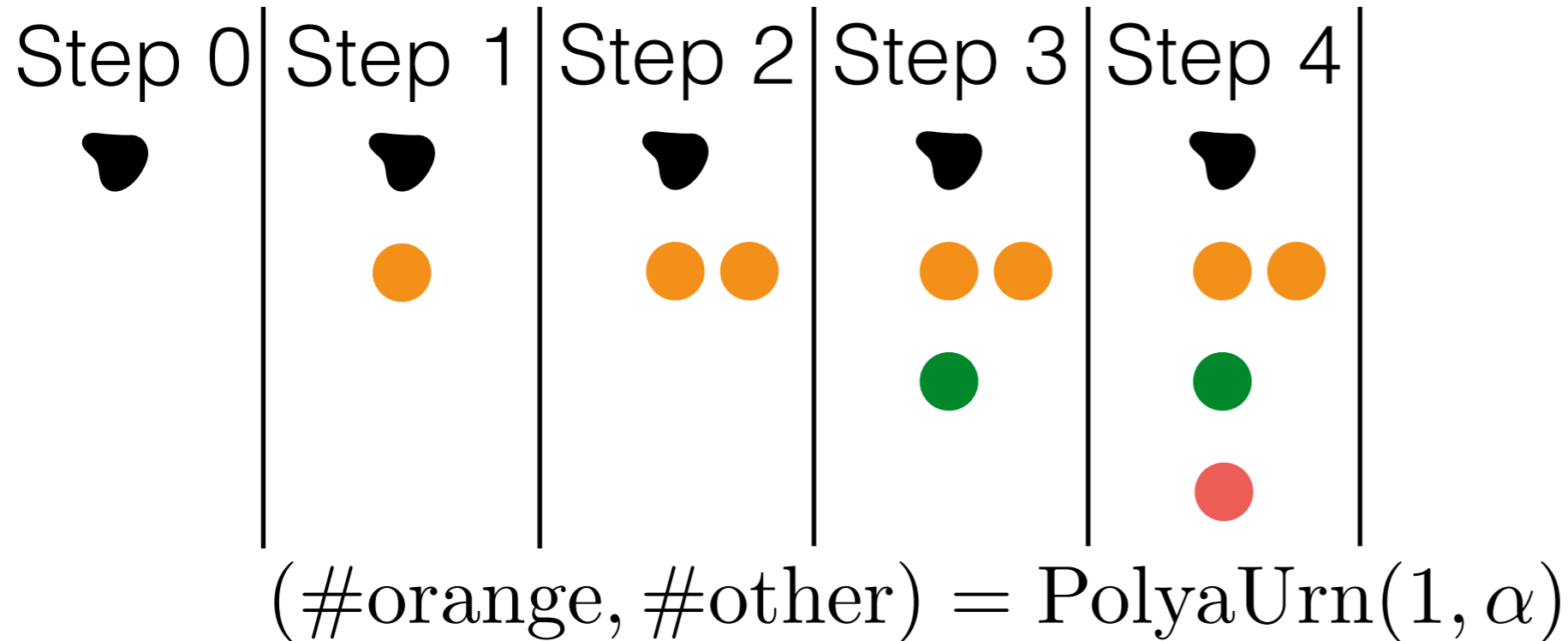


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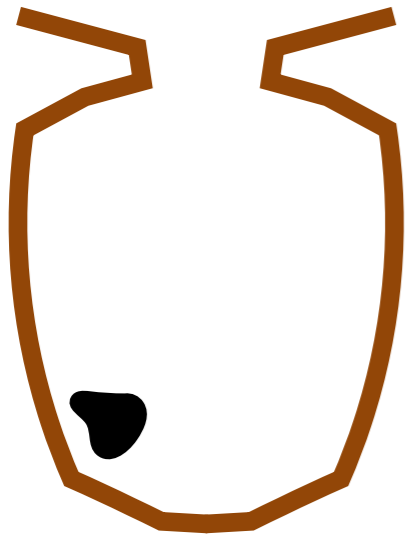


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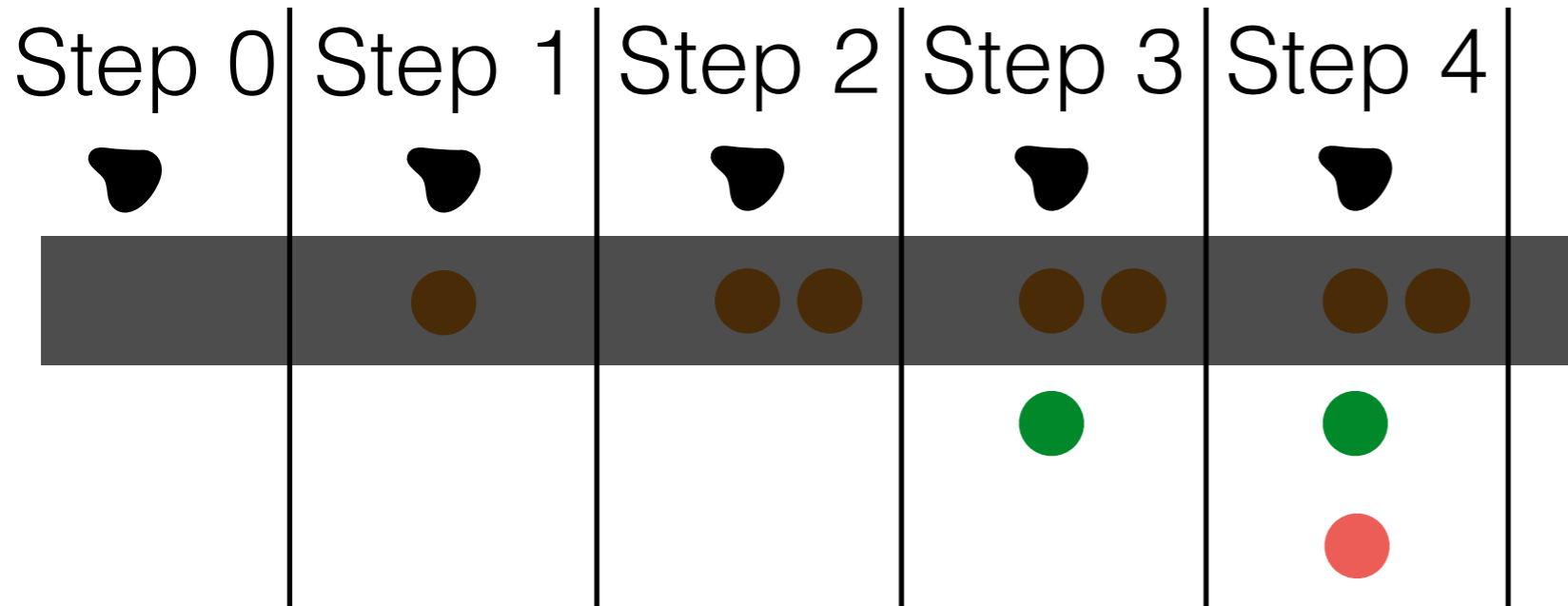


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- Hoppe urn / Blackwell-MacQueen urn



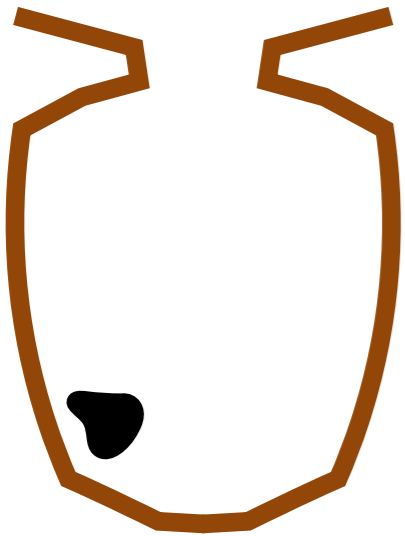
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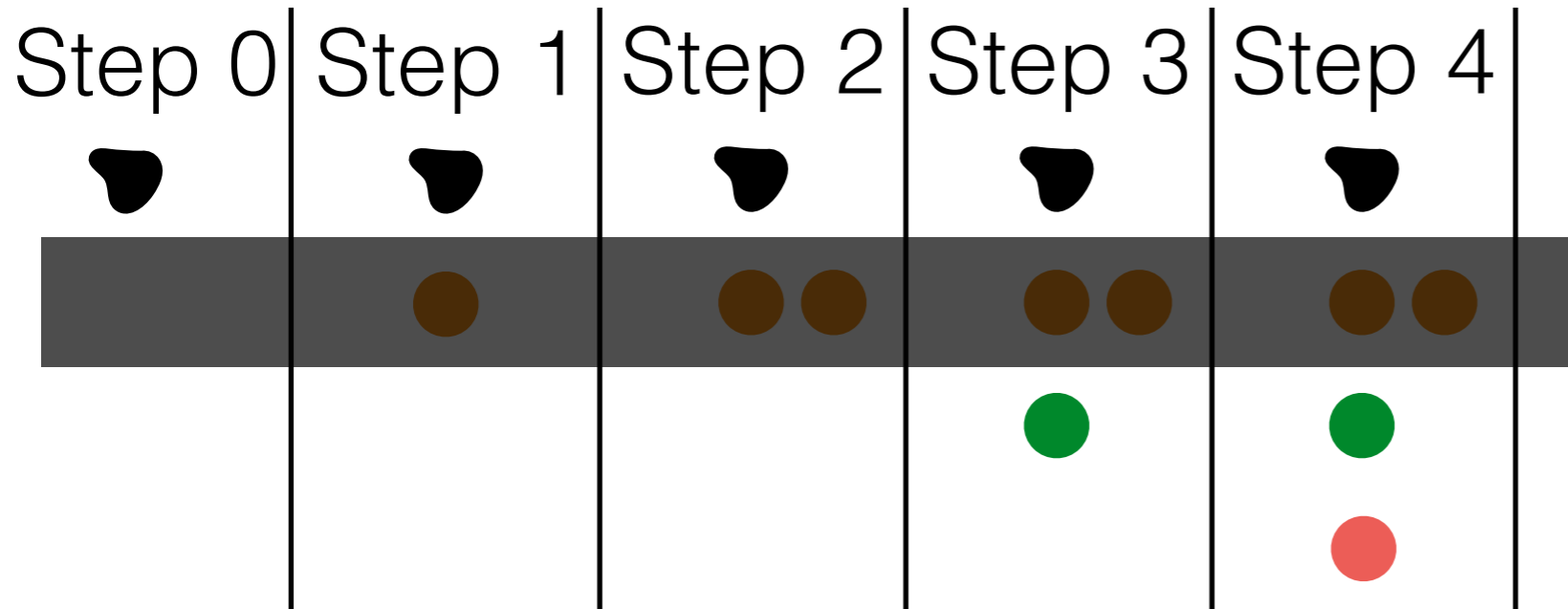
$$(\#orange, \#other) = \text{PolyaUrn}(1, \alpha)$$

# Marginal cluster assignments

- Hoppe urn / Blackwell-MacQueen urn



- Choose ball with prob proportional to its mass
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  - Else, replace and add ball of same color

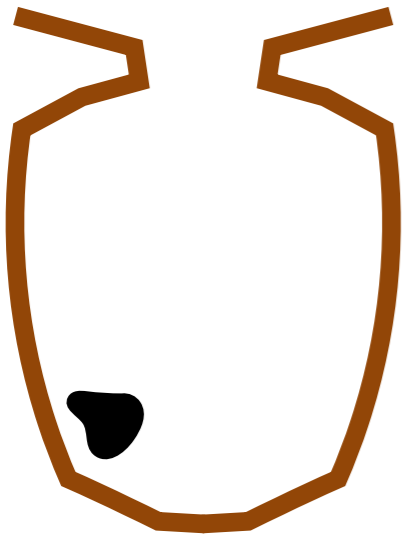


$$(\#orange, \#other) = \text{PolyaUrn}(1, \alpha)$$

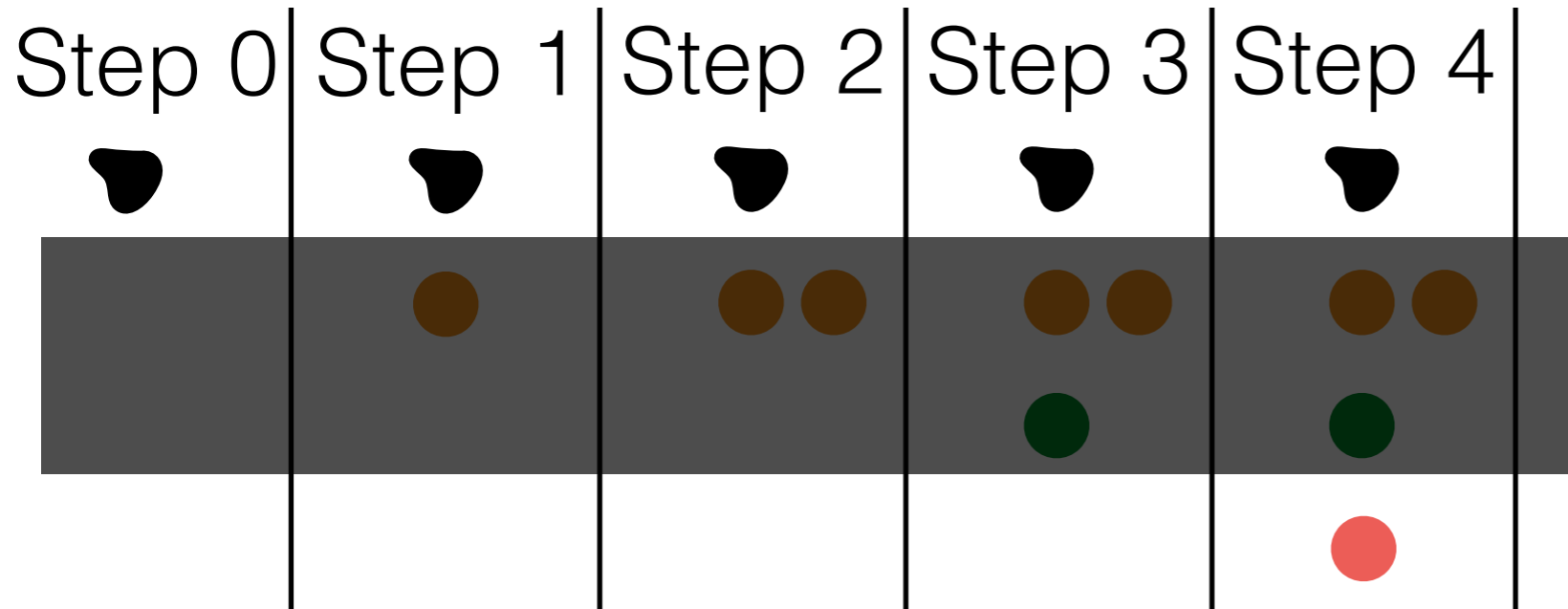
- not orange:  $(\#green, \#other) = \text{PolyaUrn}(1, \alpha)$

# Marginal cluster assignments

- Hoppe urn / Blackwell-MacQueen urn



- Choose ball with prob proportional to its mass
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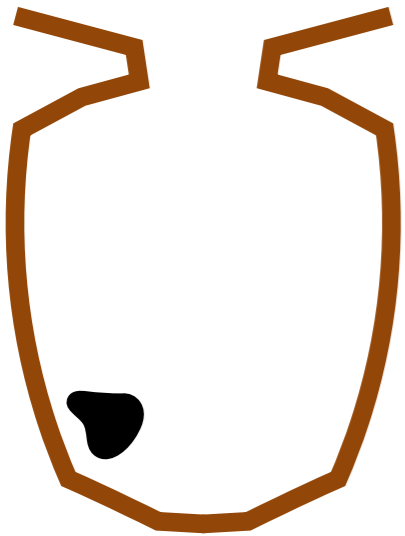


$$(\#orange, \#other) = \text{PolyaUrn}(1, \alpha)$$

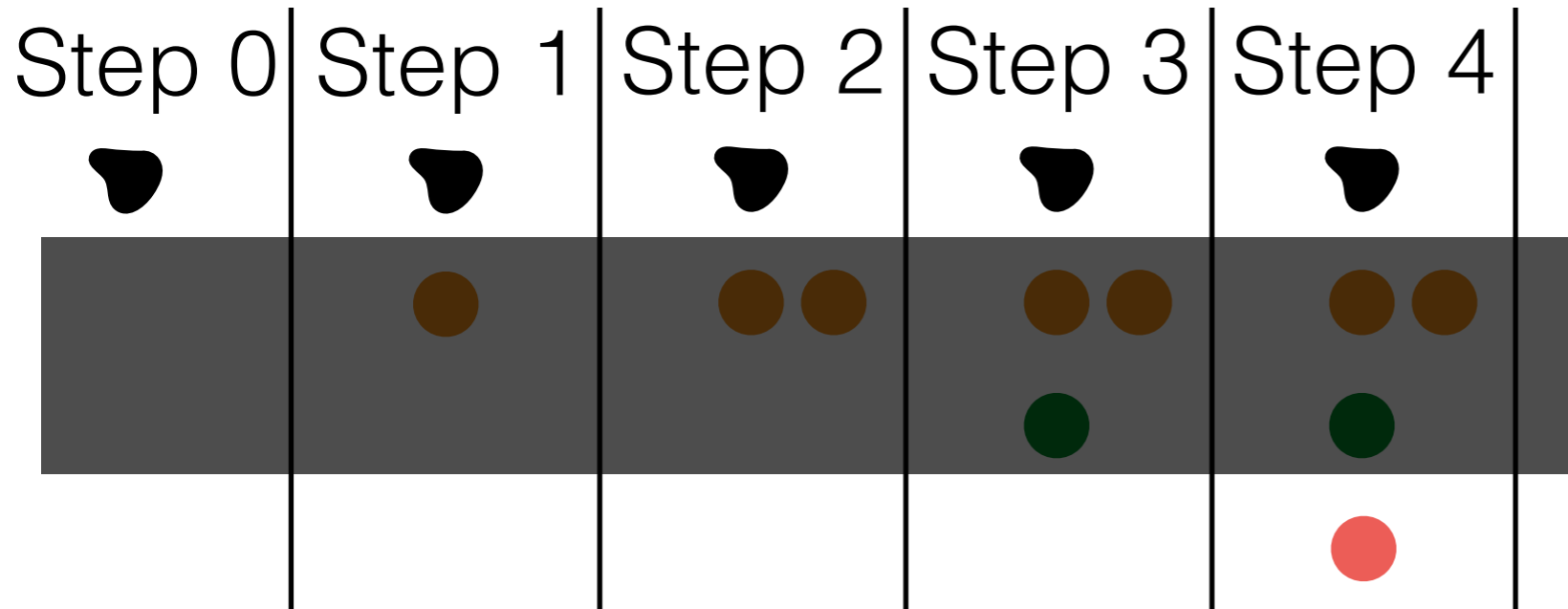
- not orange:  $(\#green, \#other) = \text{PolyaUrn}(1, \alpha)$

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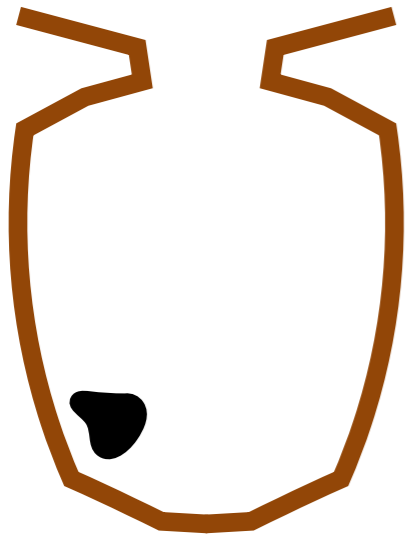


$$(\#orange, \#other) = \text{PolyaUrn}(1, \alpha)$$

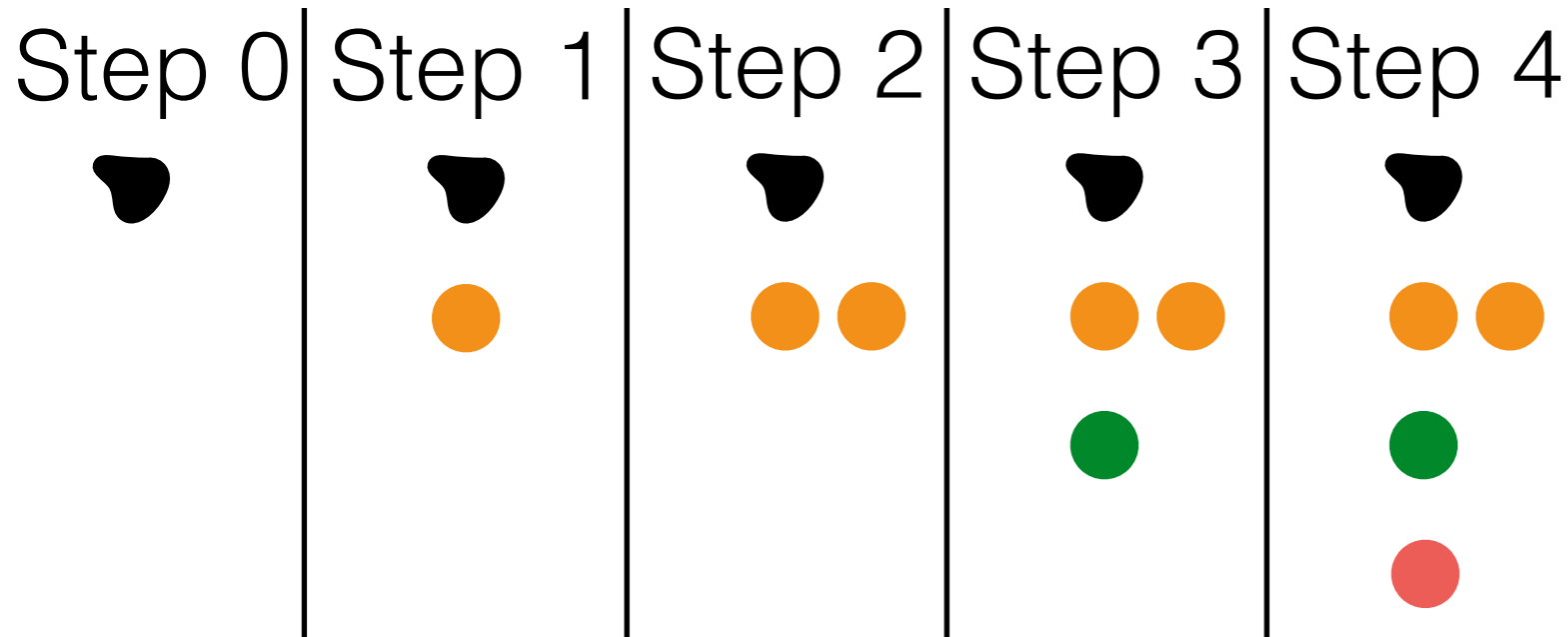
- not orange:  $(\#green, \#other) = \text{PolyaUrn}(1, \alpha)$
- not orange, green:  $(\#red, \#other) = \text{PolyaUrn}(1, \alpha)$

# Marginal cluster assignments

- Hoppe urn / Blackwell-MacQueen urn



- Choose ball with prob proportional to its mass
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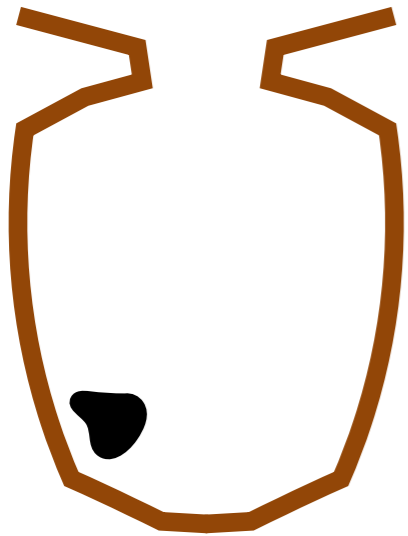


$$(\#orange, \#other) = \text{PolyaUrn}(1, \alpha)$$

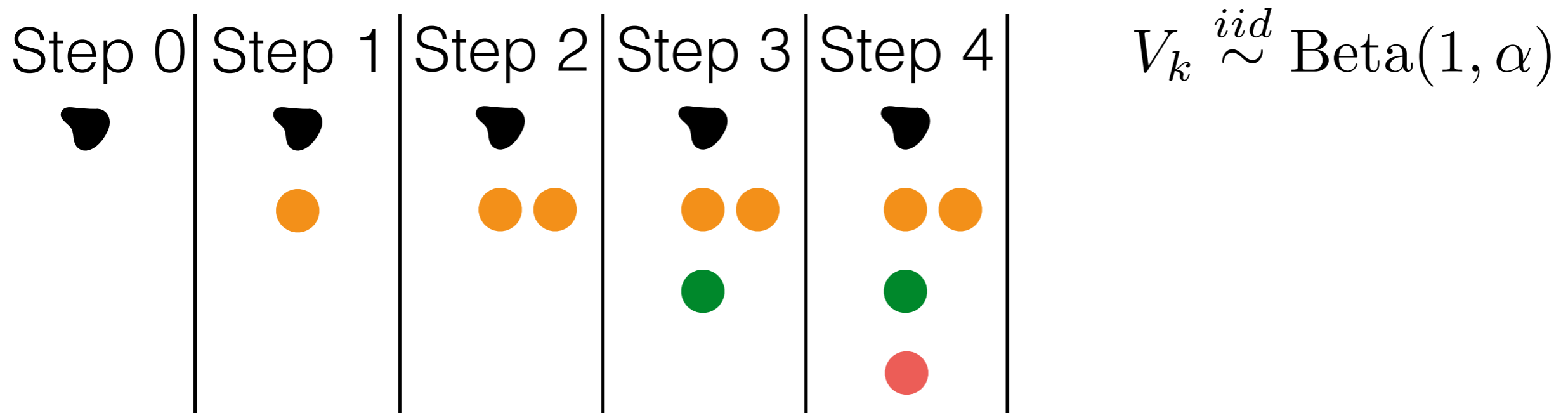
- not orange:  $(\#green, \#other) = \text{PolyaUrn}(1, \alpha)$
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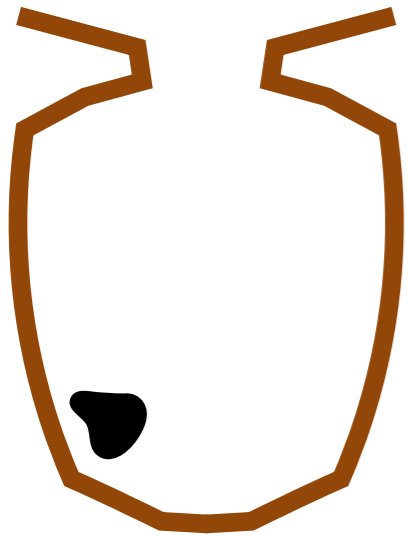
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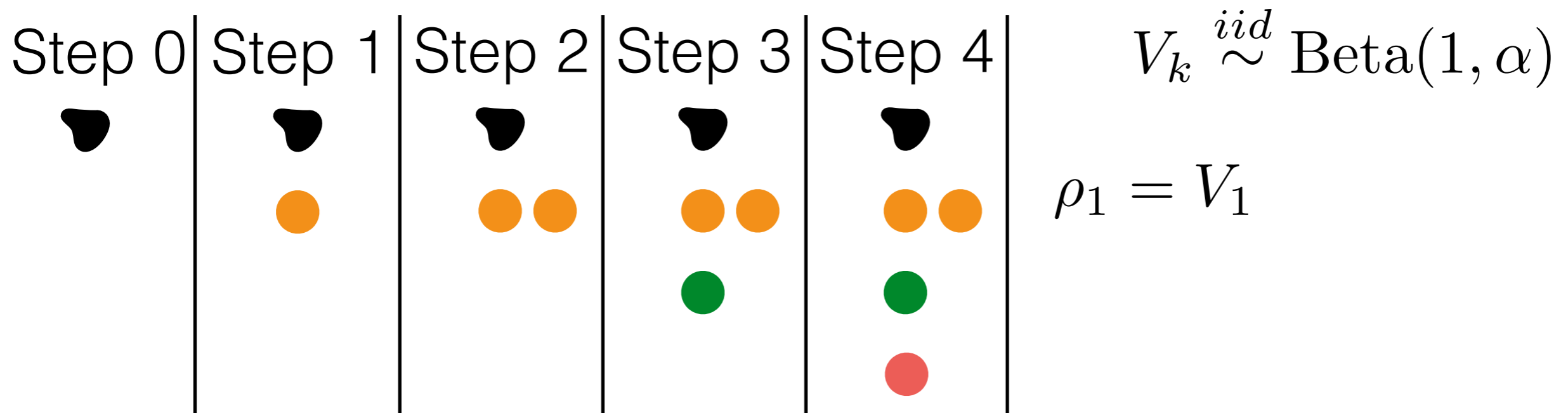


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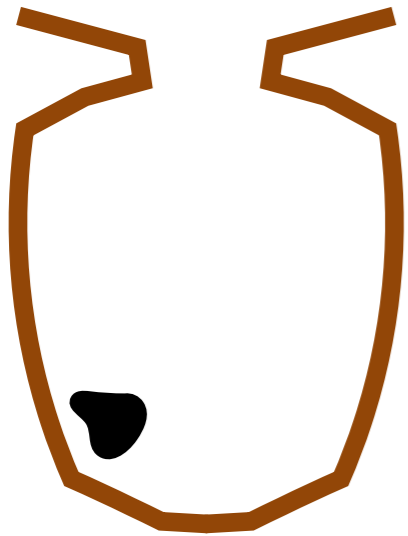


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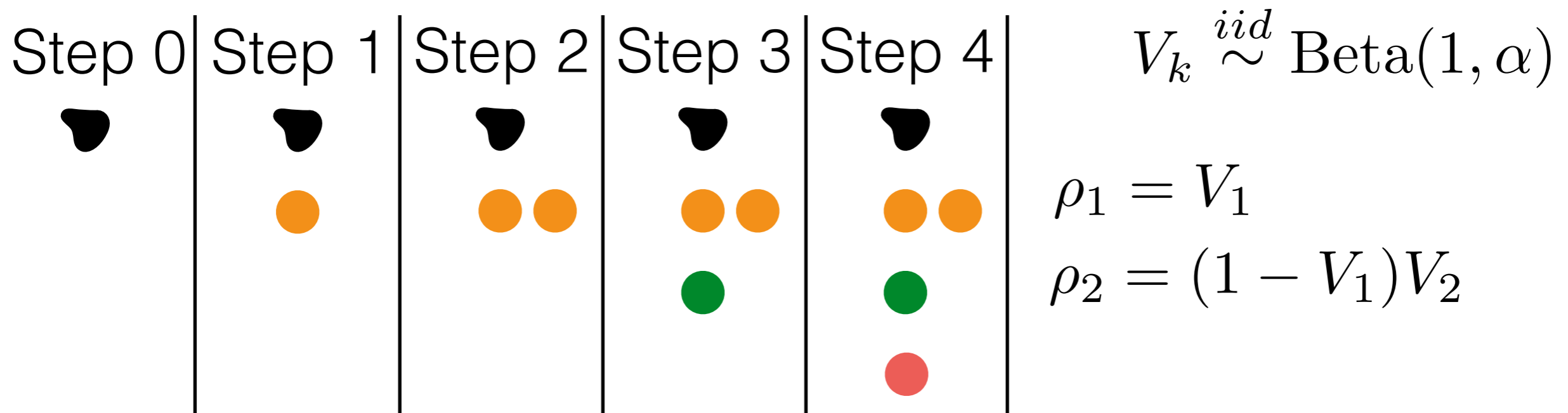
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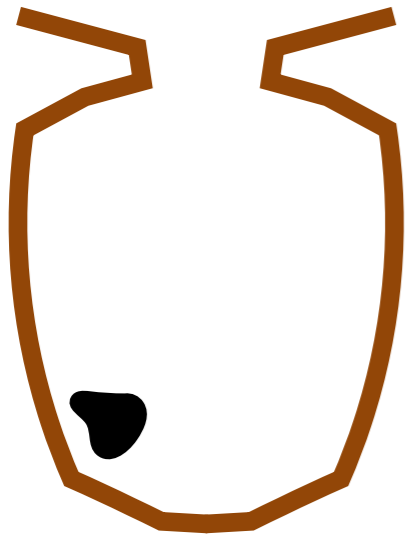


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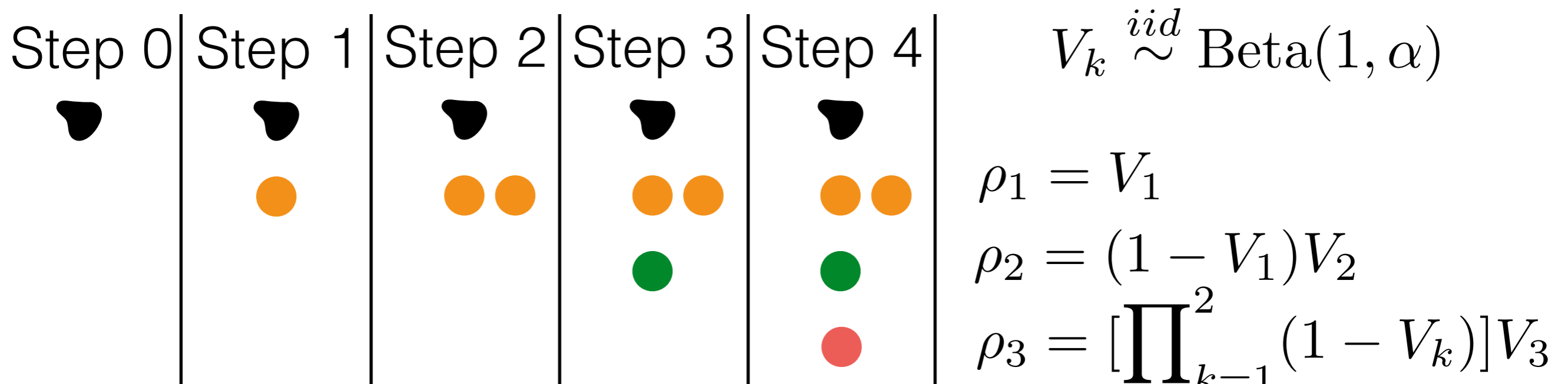
- not orange:  $(\#green, \#other) = \text{PolyaUrn}(1, \alpha)$
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# Marginal cluster assignments

- Hoppe urn / Blackwell-MacQueen urn



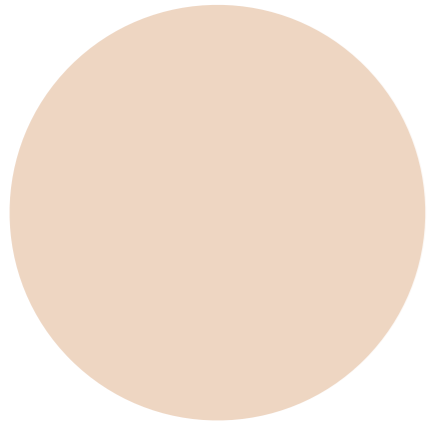
- Choose ball with prob proportional to its mass
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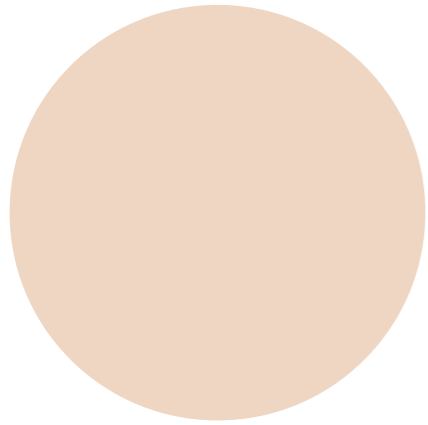
(#orange, #other) = PolyaUrn(1,  $\alpha$ )

- not orange: (#green, #other) = PolyaUrn(1,  $\alpha$ )
- not orange, green: (#red, #other) = PolyaUrn(1,  $\alpha$ )

# Chinese restaurant process

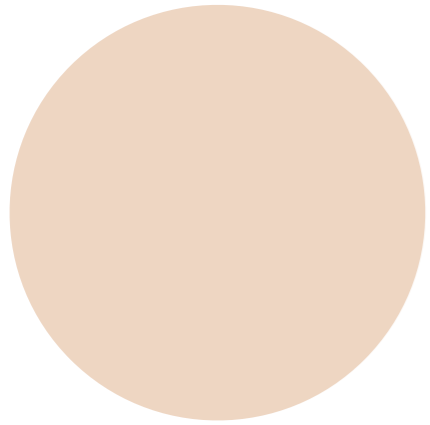


# Chinese restaurant process



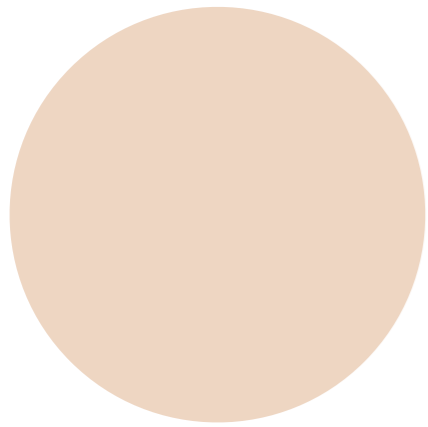
- Same thing we just did

# Chinese restaurant process



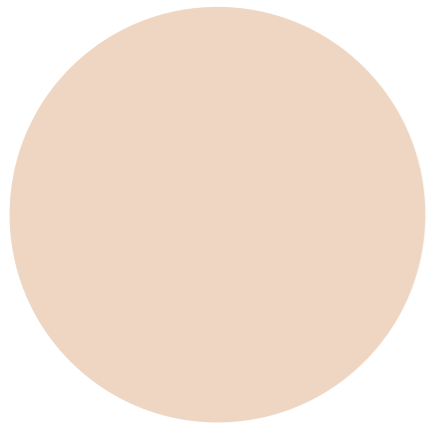
- Same thing we just did
- Each customer walks into the restaurant

# Chinese restaurant process



- Same thing we just did
- Each customer walks into the restaurant
  - Sits at existing table with prob proportional to # people there

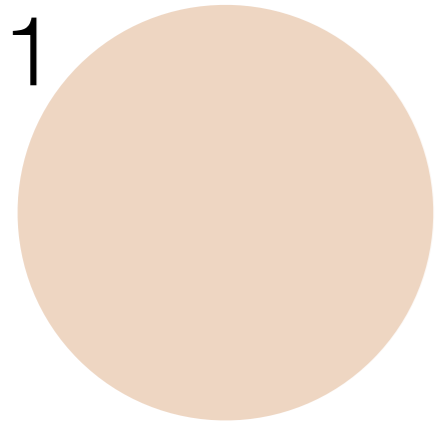
# Chinese restaurant process



- Same thing we just did
- Each customer walks into the restaurant
  - Sits at existing table with prob proportional to # people there
  - Forms new table with prob proportional to  $\alpha$

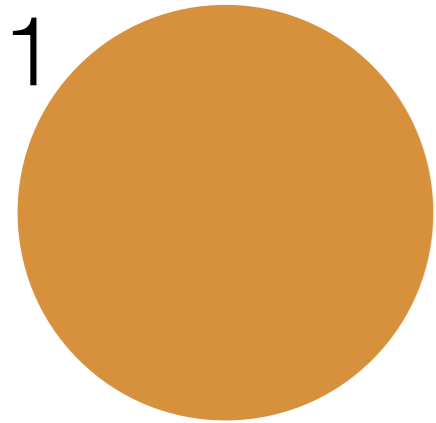


# Chinese restaurant process



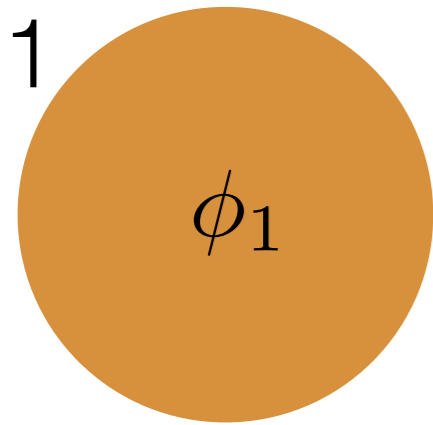
- Same thing we just did
- Each customer walks into the restaurant
  - Sits at existing table with prob proportional to # people there
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# Chinese restaurant process



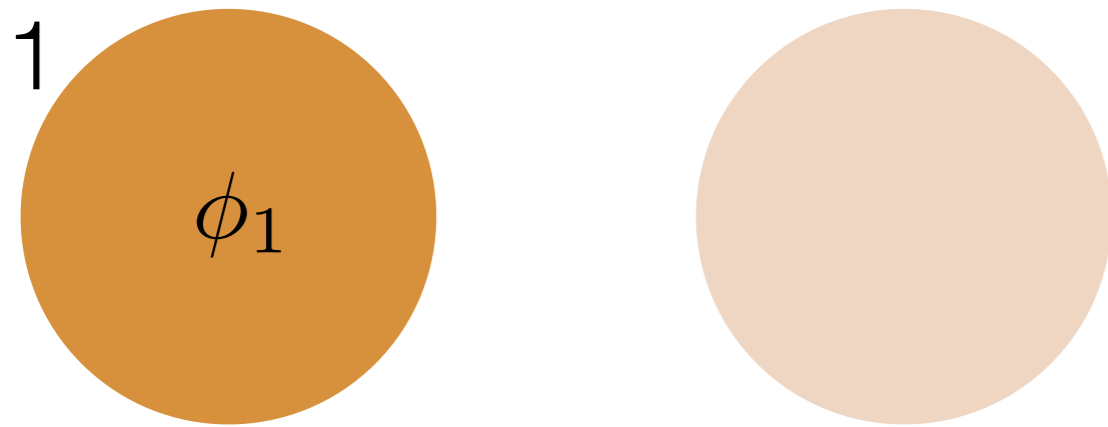
- Same thing we just did
- Each customer walks into the restaurant
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# Chinese restaurant process



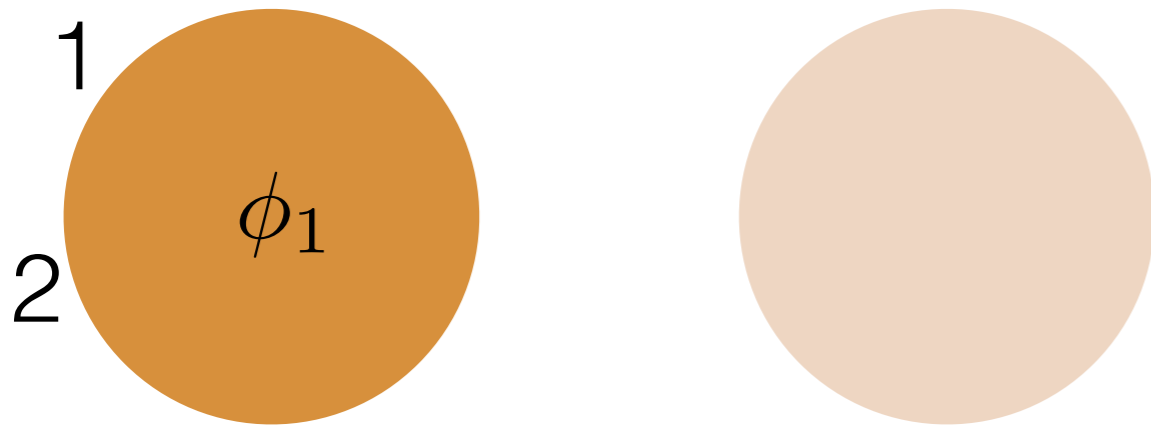
- Same thing we just did
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# Chinese restaurant process



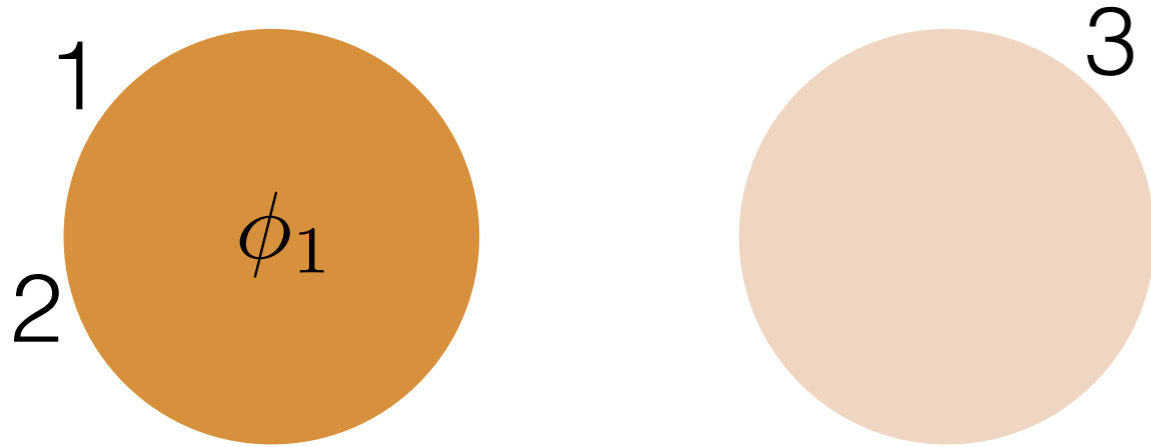
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# Chinese restaurant process



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# Chinese restaurant process



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# Chinese restaurant process



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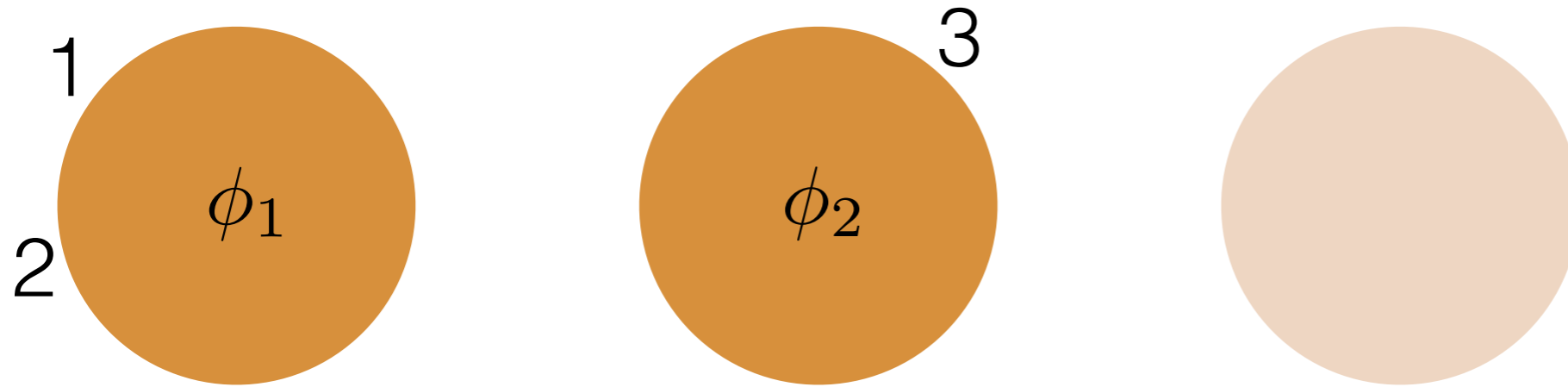
# Chinese restaurant process



- Same thing we just did
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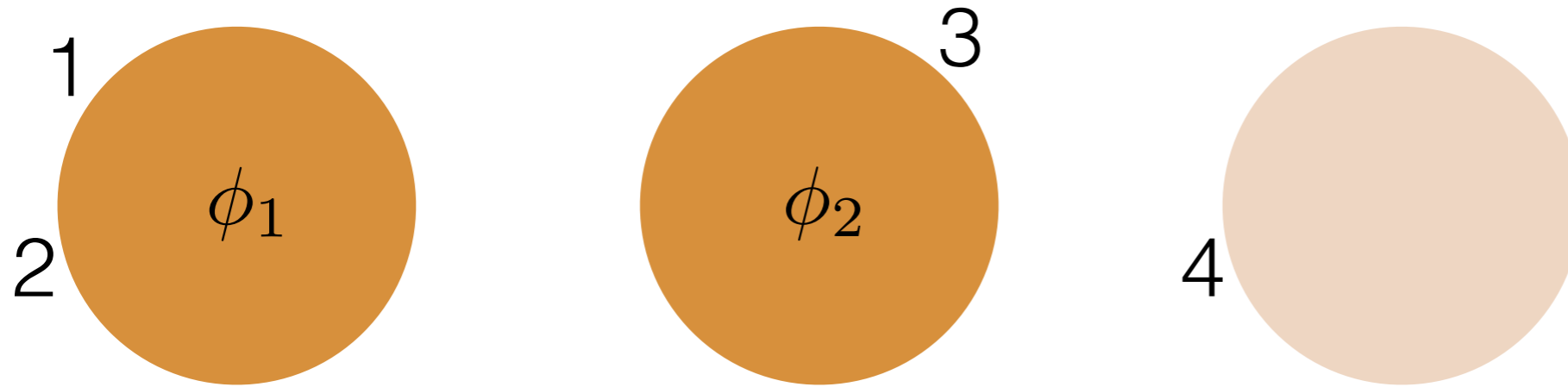


# Chinese restaurant process



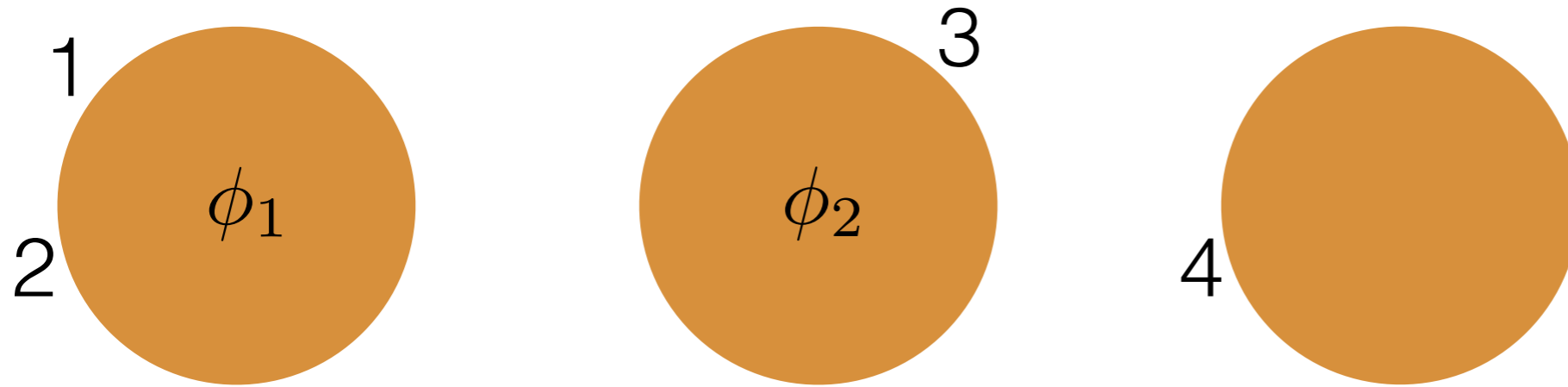
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# Chinese restaurant process



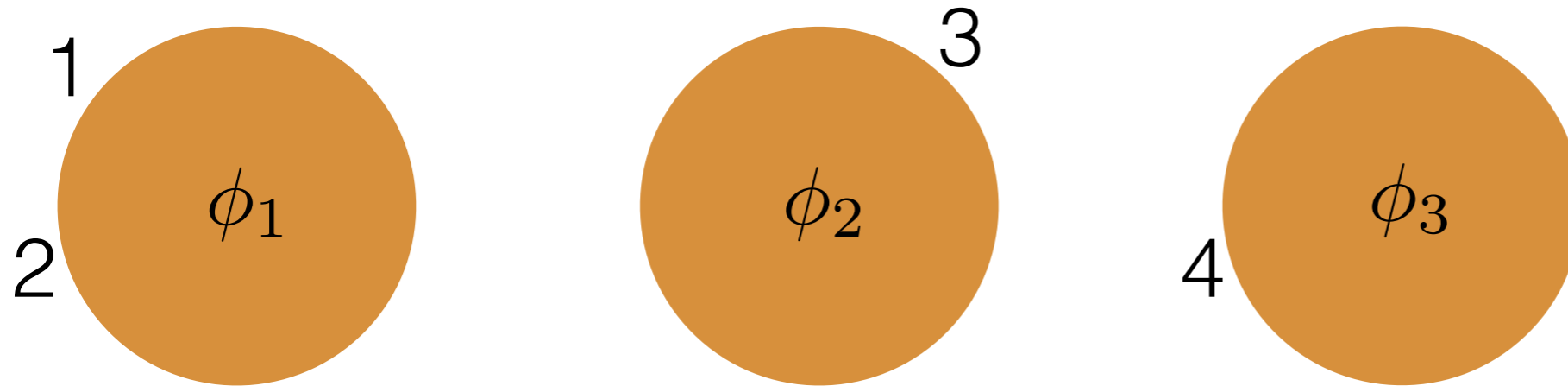
- Same thing we just did
- Each customer walks into the restaurant
  - Sits at existing table with prob proportional to # people there
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# Chinese restaurant process



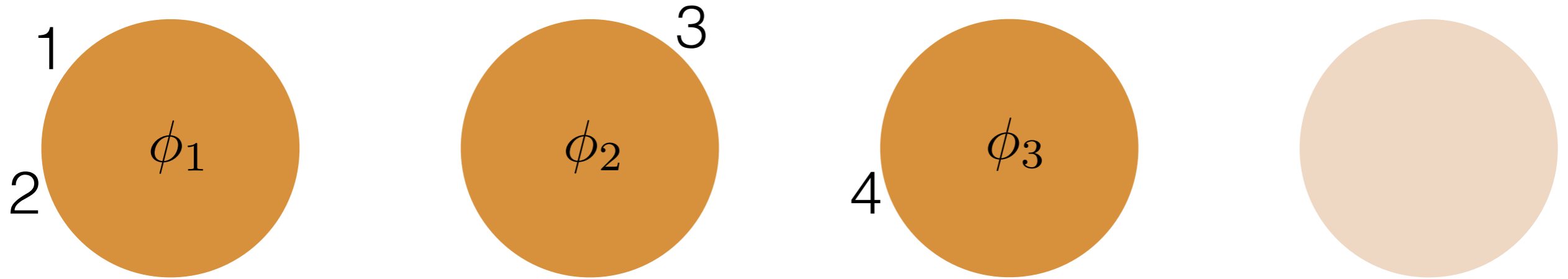
- Same thing we just did
- Each customer walks into the restaurant
  - Sits at existing table with prob proportional to # people there
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# Chinese restaurant process



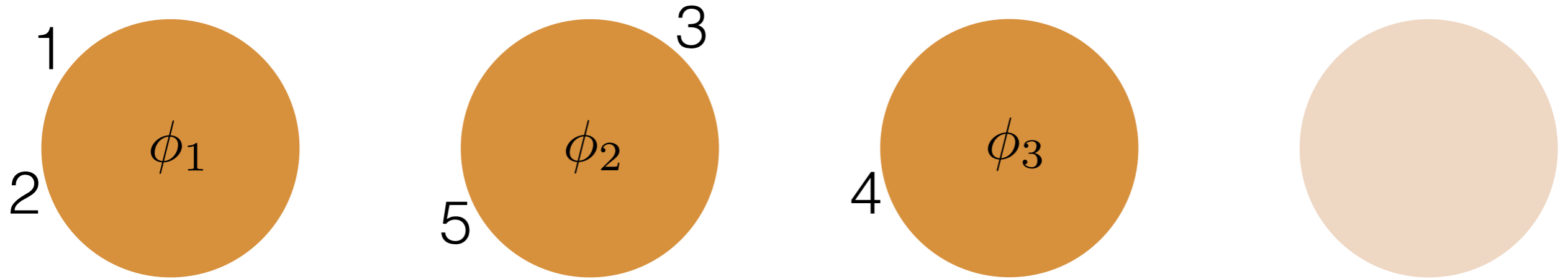
- Same thing we just did
- Each customer walks into the restaurant
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# Chinese restaurant process



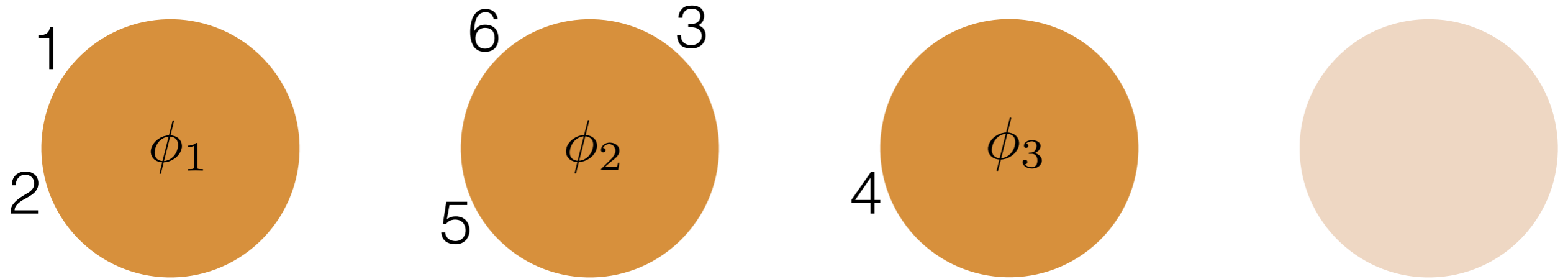
- Same thing we just did
- Each customer walks into the restaurant
  - Sits at existing table with prob proportional to # people there
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# Chinese restaurant process



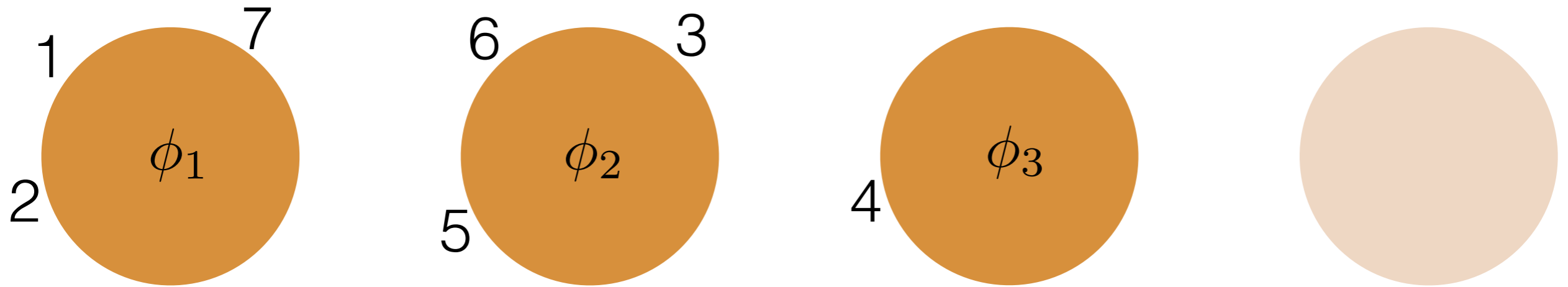
- Same thing we just did
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- Same thing we just did
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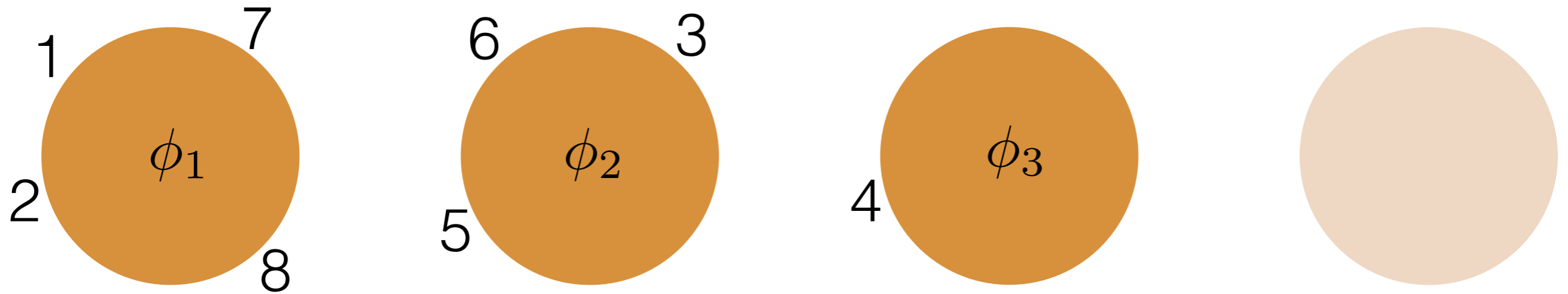
# Chinese restaurant process



- Same thing we just did
- Each customer walks into the restaurant
  - Sits at existing table with prob proportional to # people there
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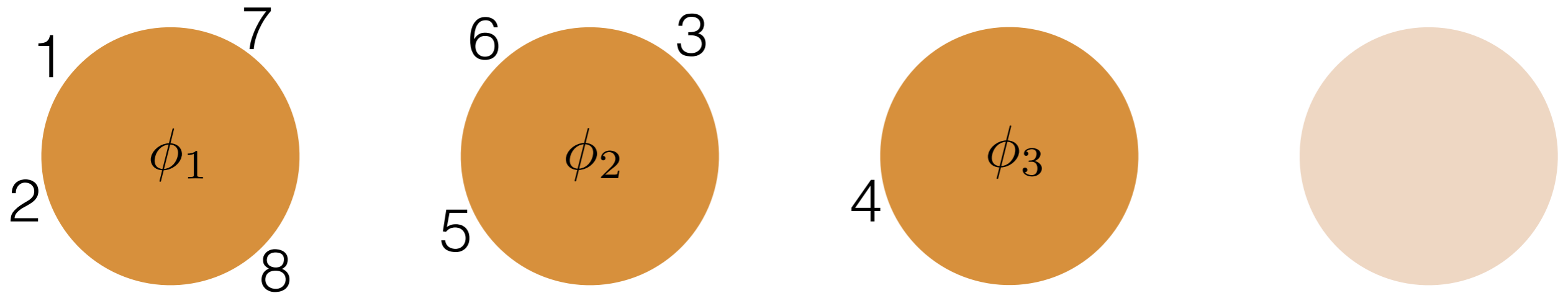


# Chinese restaurant process



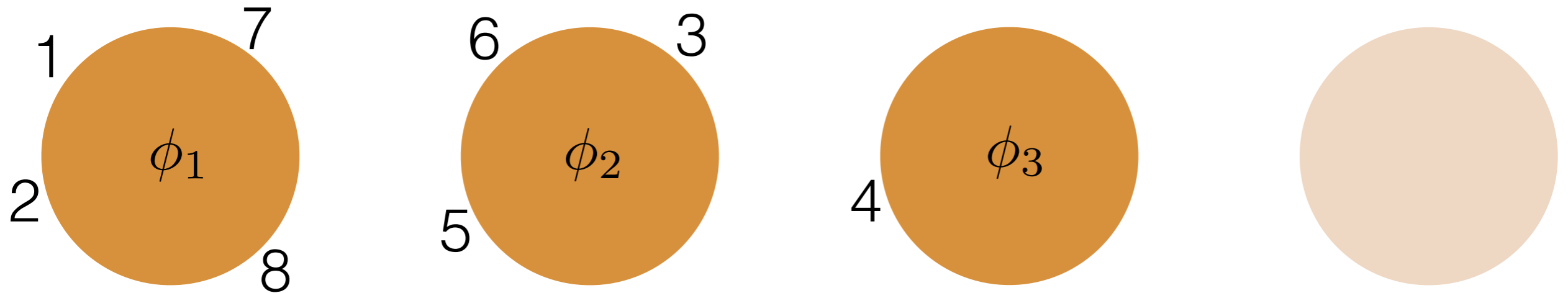
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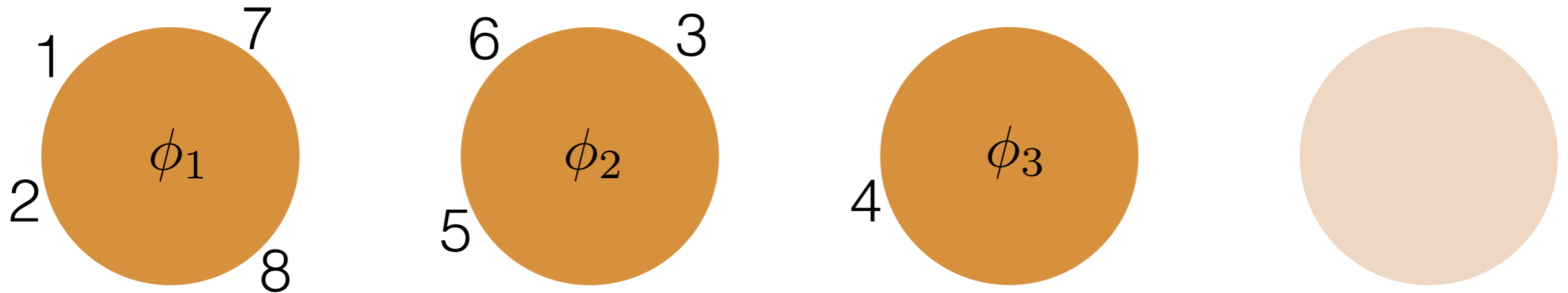
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So far: Dirichlet process, Chinese restaurant process

- Infinity of parameters, growing number of parameters

# Roadmap

- Example problem: clustering
- Example NPBayes model: Dirichlet process
- Chinese restaurant process
- Inference
- Venture further into the wild world of Nonparametric Bayes
- Big questions
  - Why NPBayes?
  - What does an infinite/growing number of parameters really mean (in NPBayes)?
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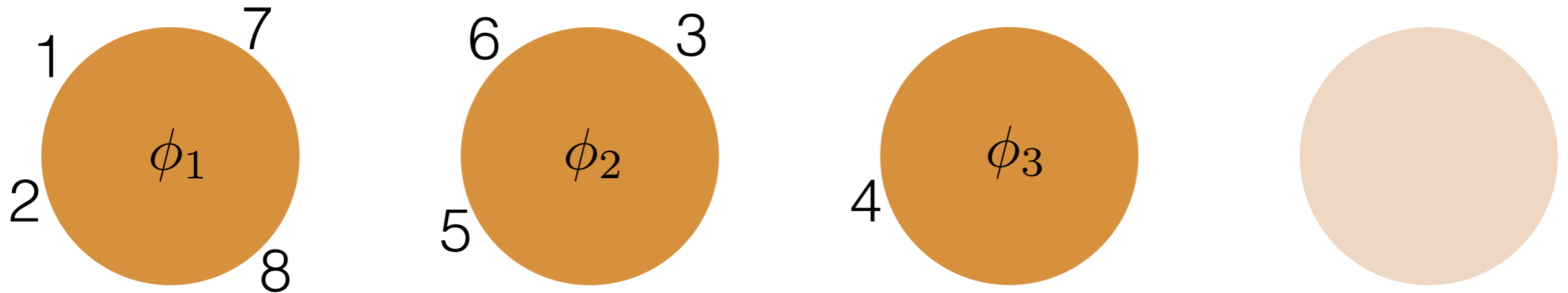
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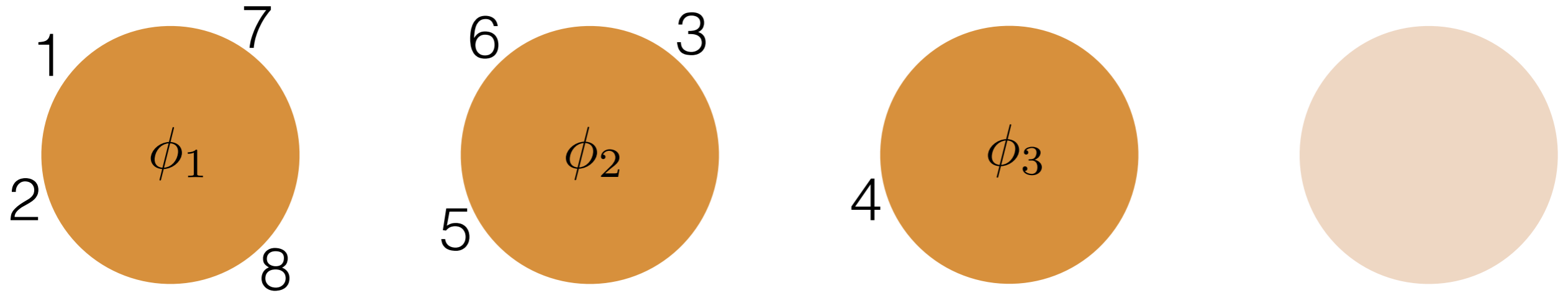
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# Chinese restaurant process



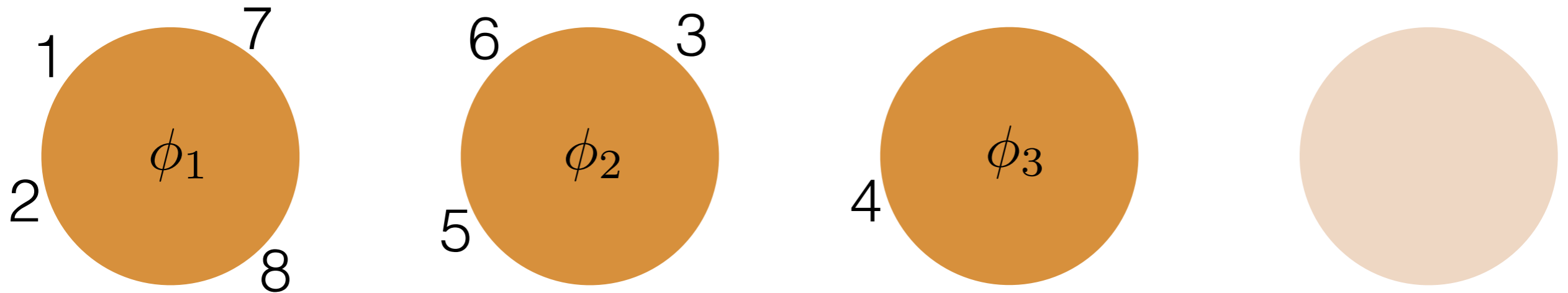
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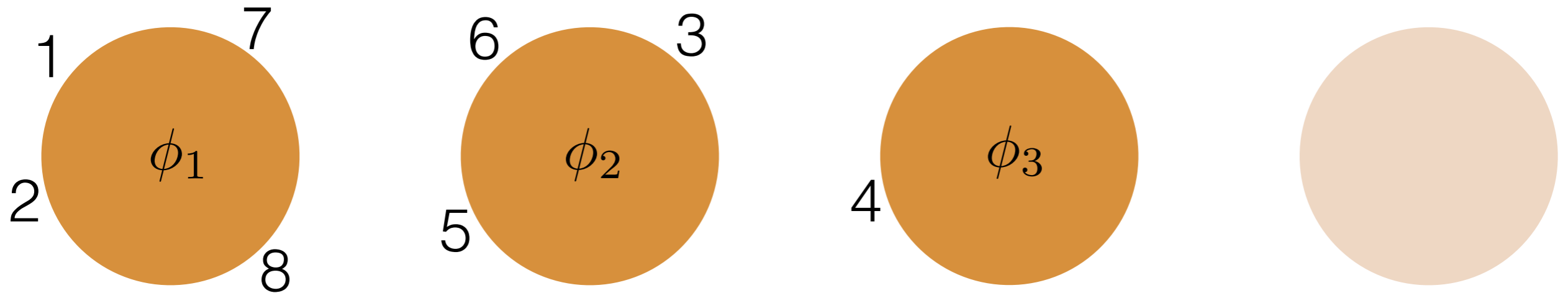
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# Chinese restaurant process



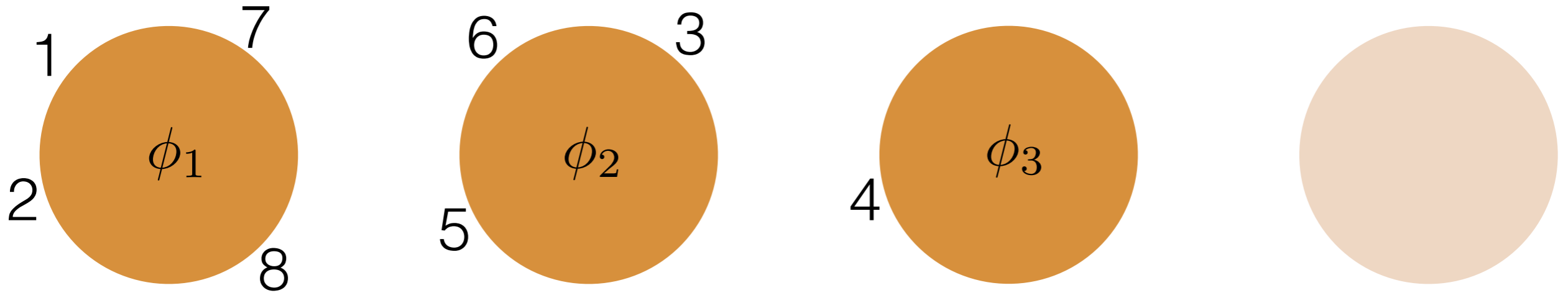
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$$z_1 = z_2 = z_7 = z_8 = 1, z_3 = z_5 = z_6 = 2, z_4 = 3$$
$$\Rightarrow \Pi_8 = \{\{1, 2, 7, 8\}, \{3, 5, 6\}, \{4\}\}$$
- *Partition of [8]*: set of mutually exclusive & exhaustive sets of  $[8] := \{1, \dots, 8\}$

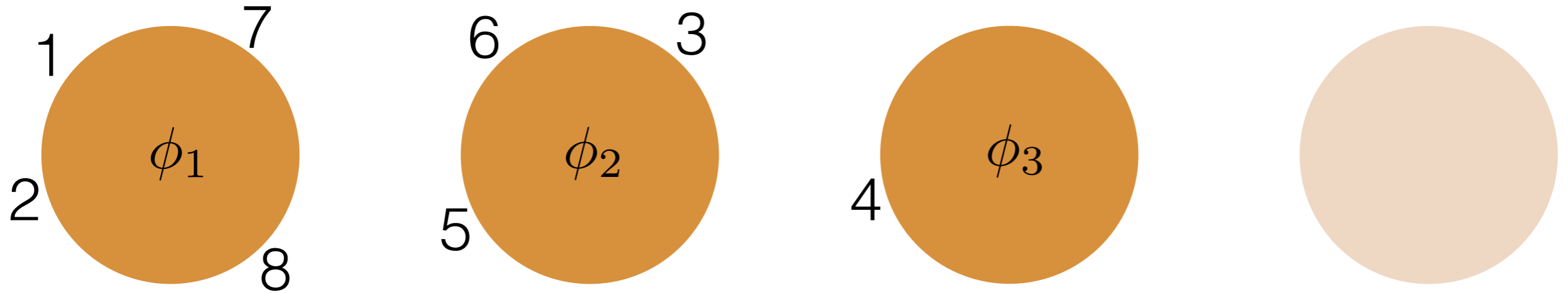
# Chinese restaurant process



- Probability of this seating:



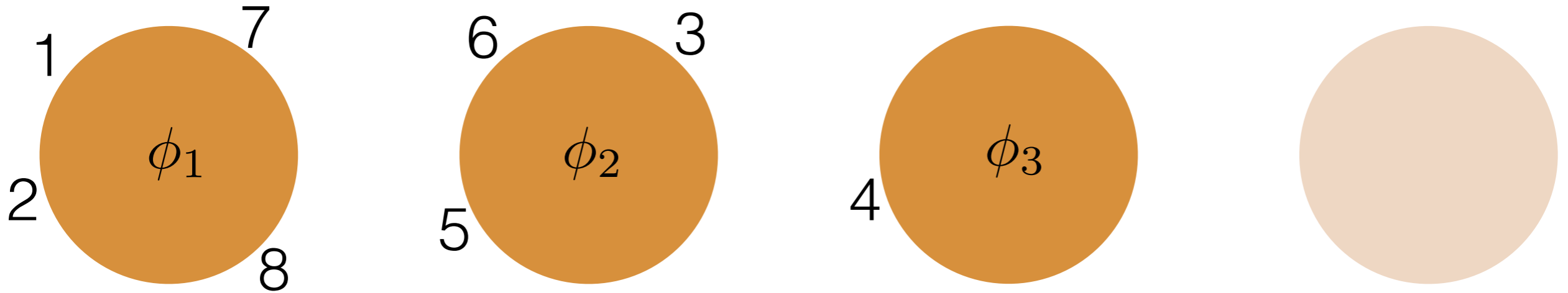
# Chinese restaurant process



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$$\frac{\alpha}{\alpha}$$

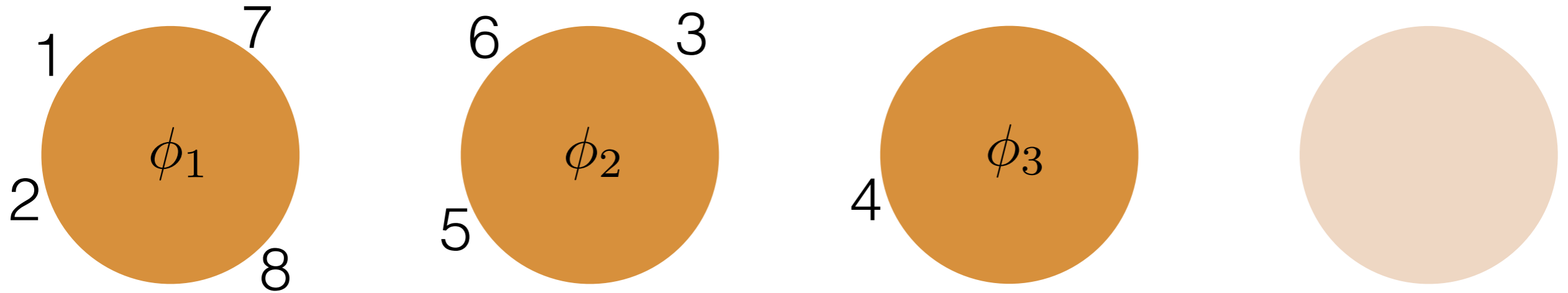
# Chinese restaurant process



- Probability of this seating:

$$\frac{\alpha}{\alpha} \cdot \frac{1}{\alpha + 1}$$

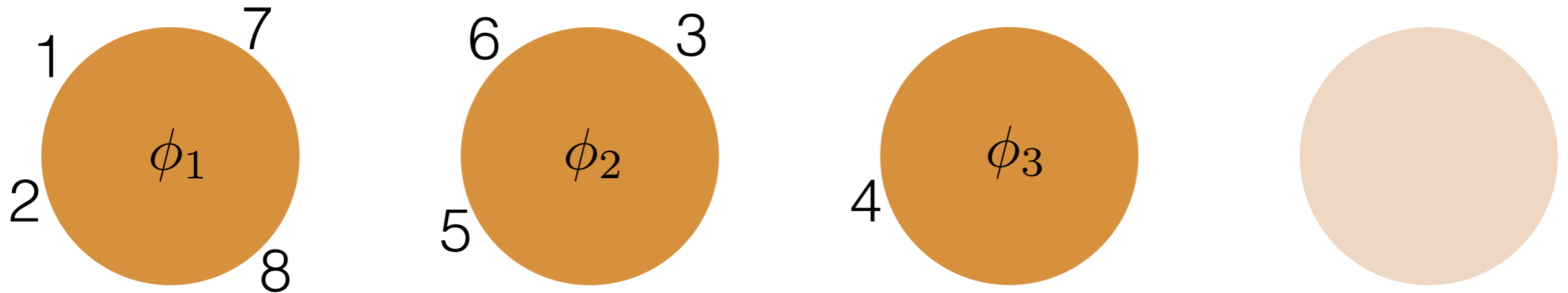
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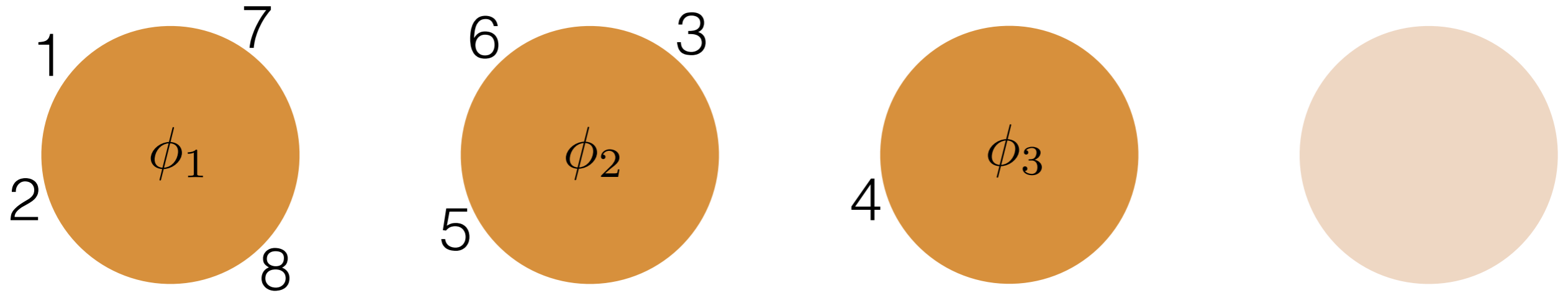
$$\frac{\alpha}{\alpha} \cdot \frac{1}{\alpha + 1} \cdot \frac{\alpha}{\alpha + 2}$$

# Chinese restaurant process



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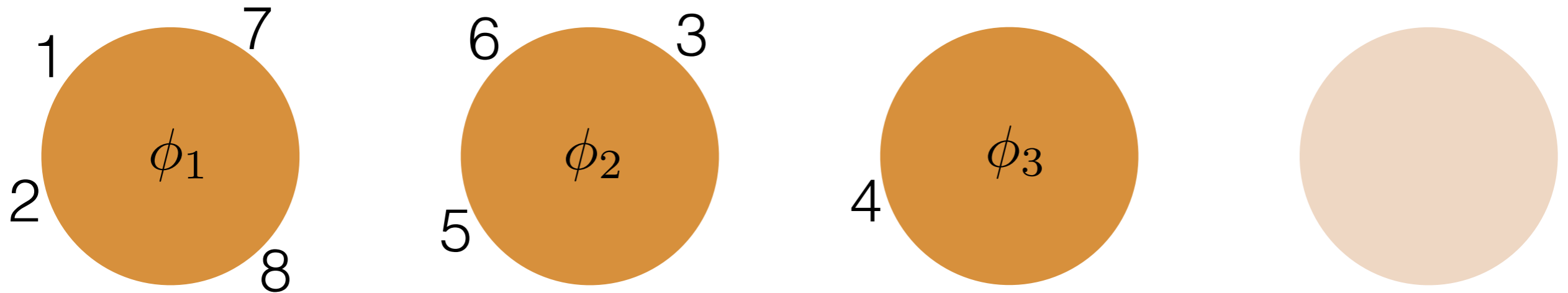
# Chinese restaurant process



- Probability of this seating:

$$\frac{\alpha}{\alpha} \cdot \frac{1}{\alpha + 1} \cdot \frac{\alpha}{\alpha + 2} \cdot \frac{\alpha}{\alpha + 3} \cdot \frac{1}{\alpha + 4}$$

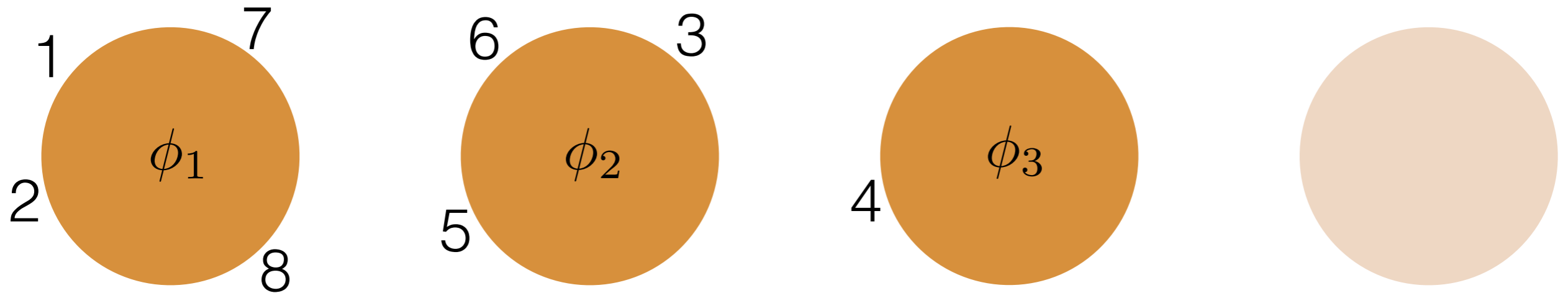
# Chinese restaurant process



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$$\frac{\alpha}{\alpha} \cdot \frac{1}{\alpha + 1} \cdot \frac{\alpha}{\alpha + 2} \cdot \frac{\alpha}{\alpha + 3} \cdot \frac{1}{\alpha + 4} \cdot \frac{2}{\alpha + 5}$$

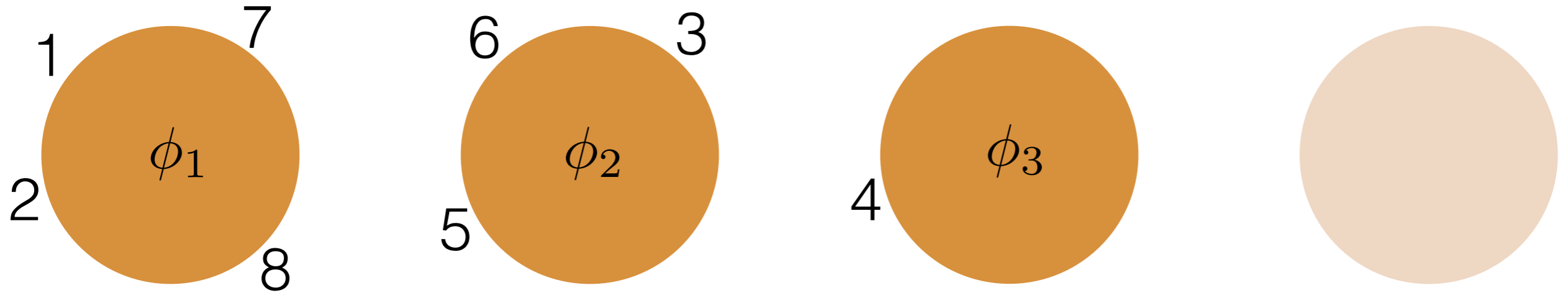
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# Chinese restaurant process

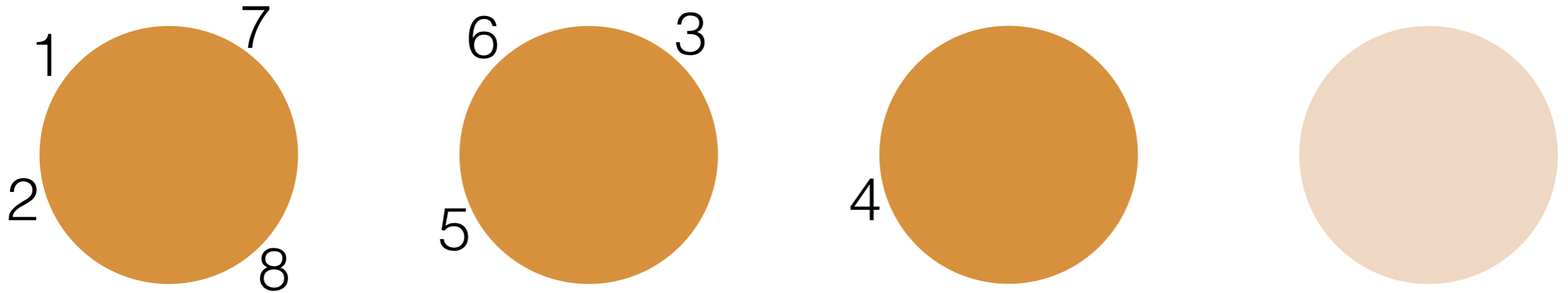


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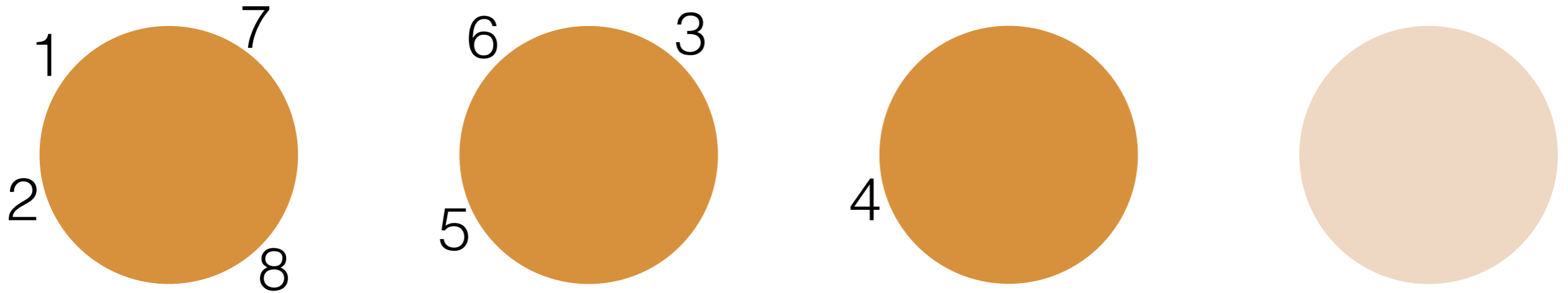


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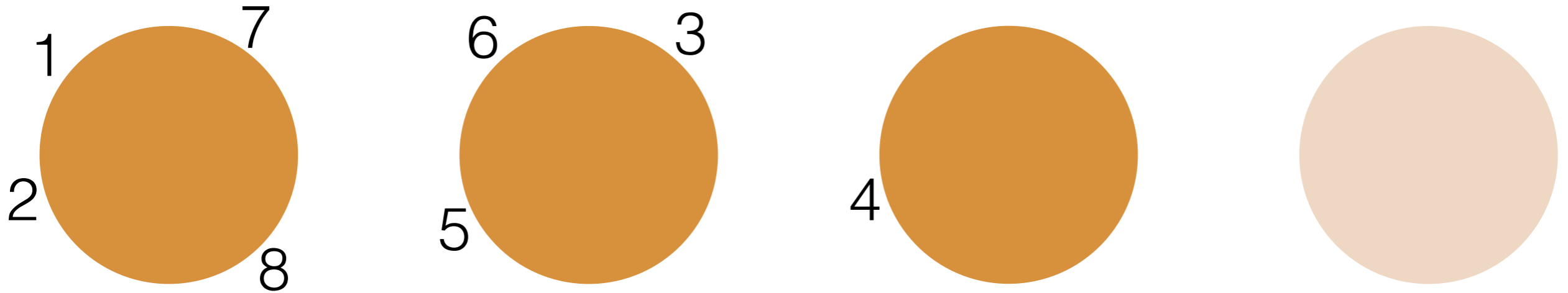


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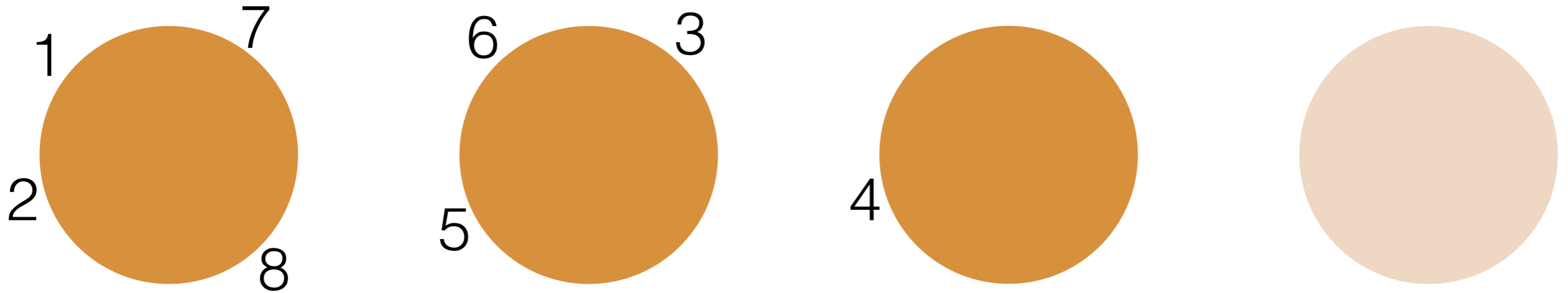
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---

$$\alpha \cdots (\alpha + N - 1)$$

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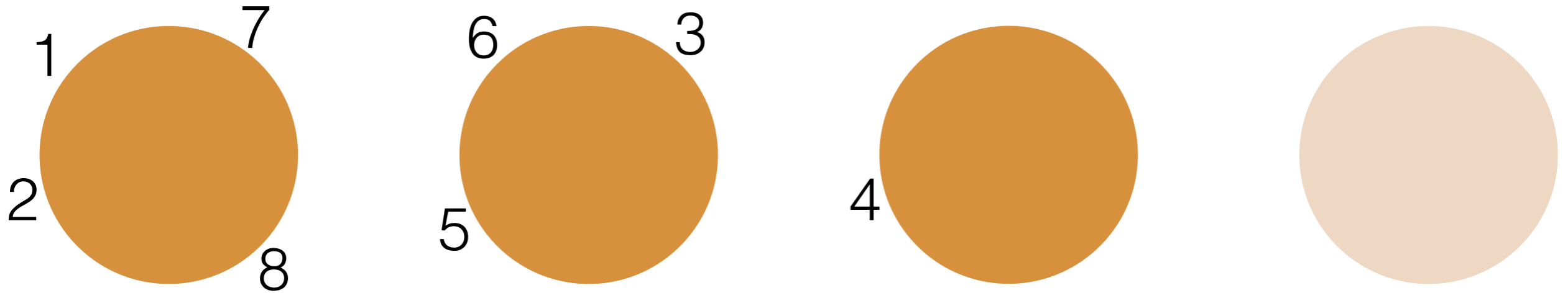
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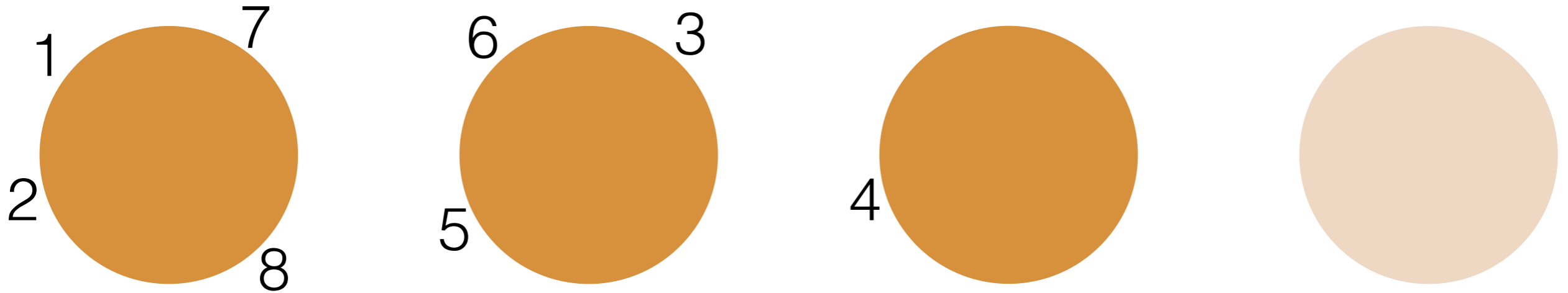
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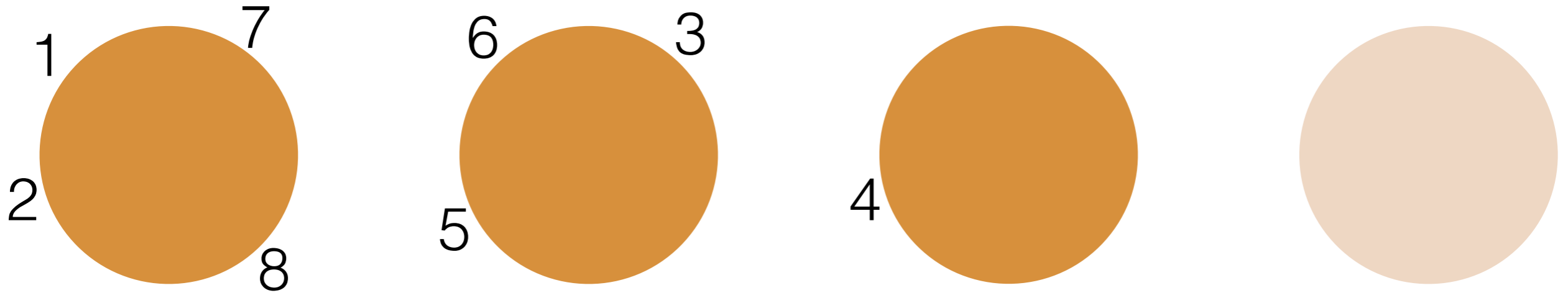
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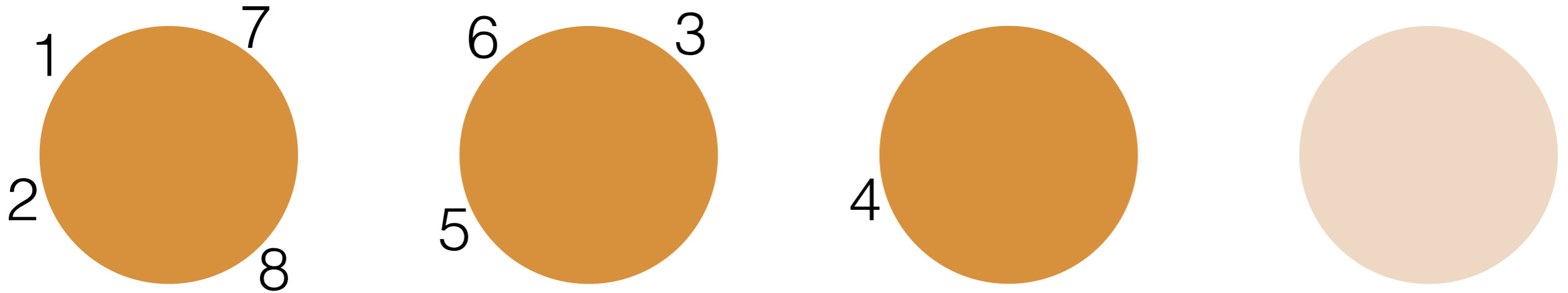
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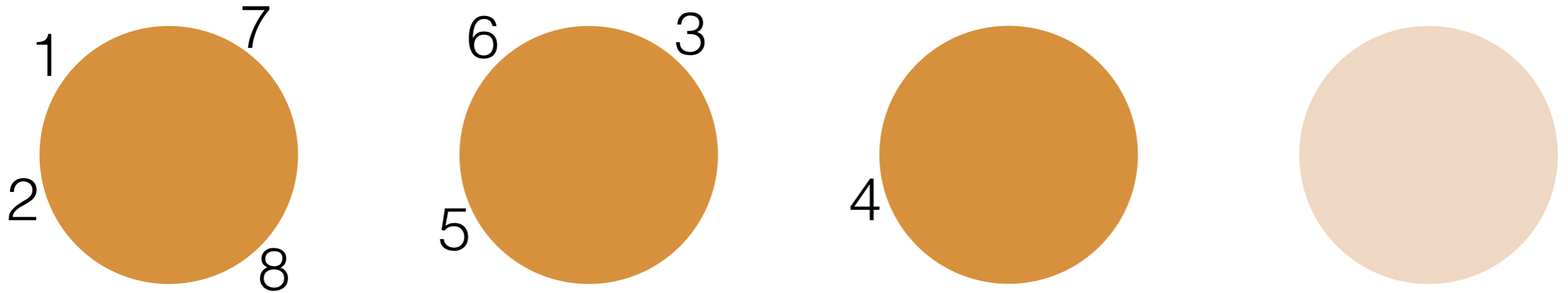
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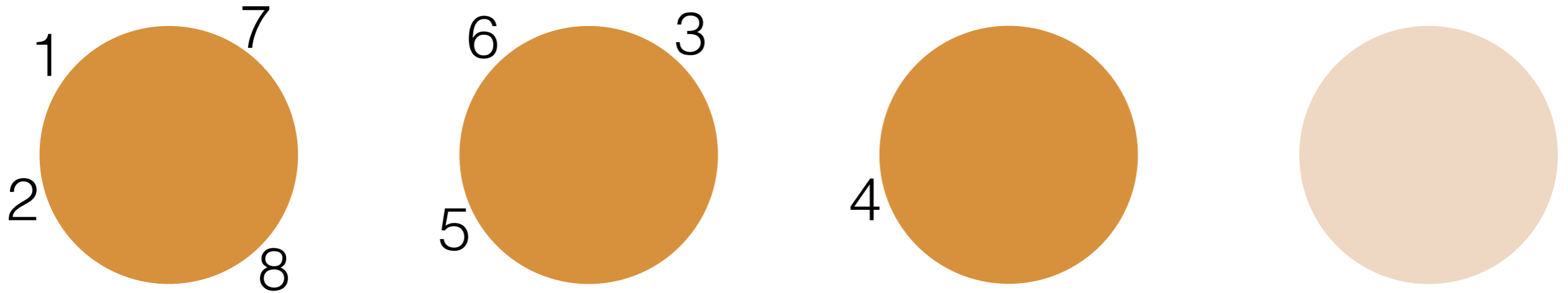
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- Probability of  $N$  customers ( $K_N$  tables,  $n_k$  at table  $k$ ):

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# Chinese restaurant process



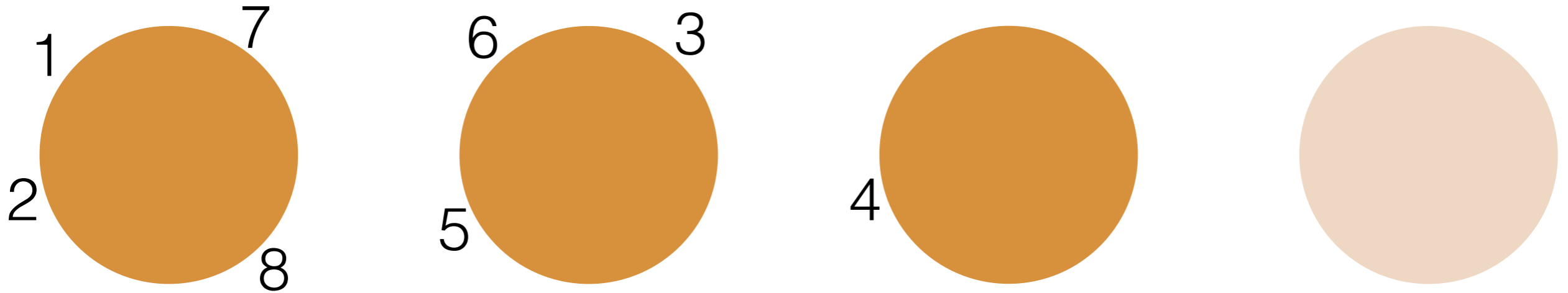
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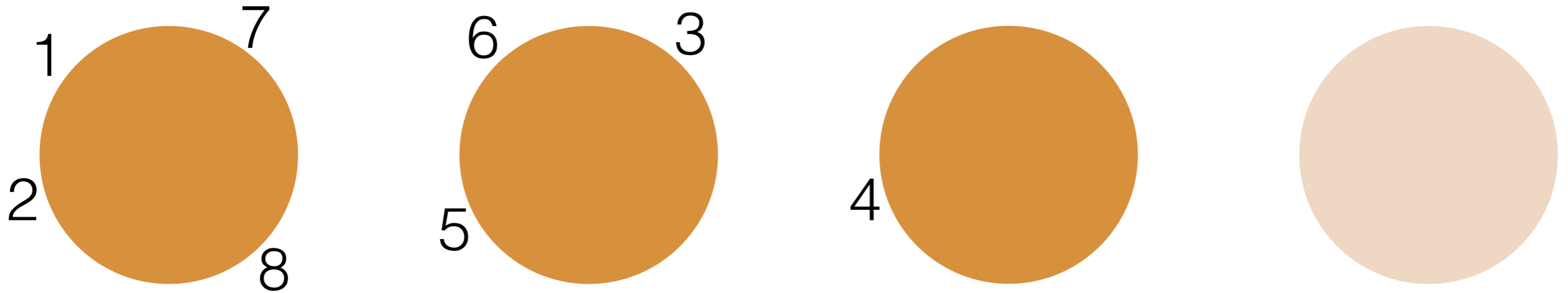
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# Chinese restaurant process



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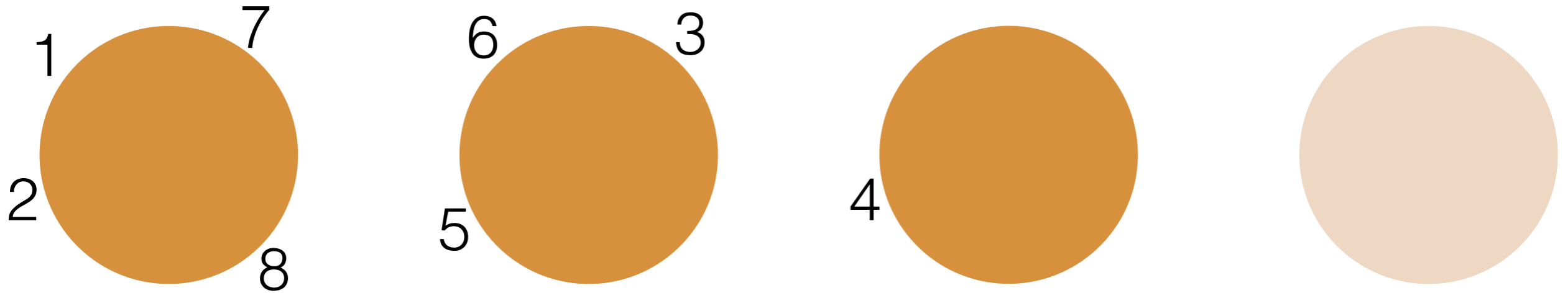
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- Prob doesn't depend on customer order: *exchangeable*

# Chinese restaurant process



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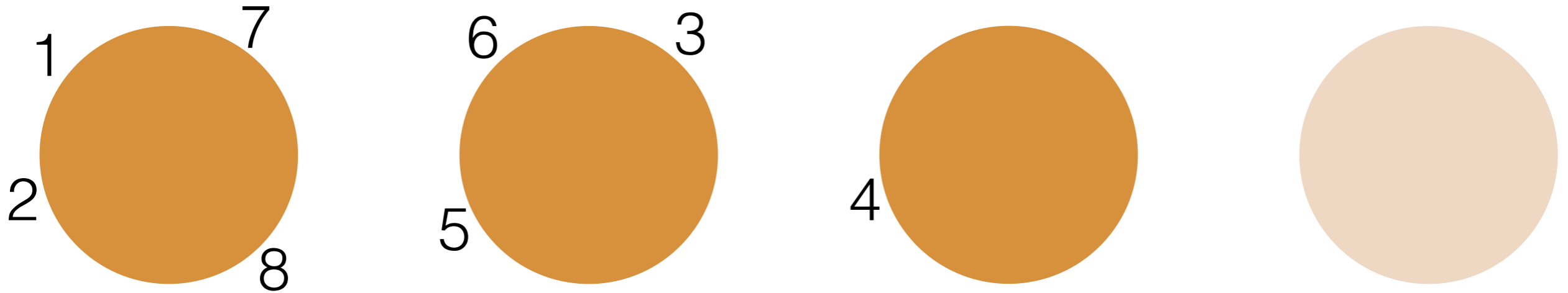
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$$\mathbb{P}(\Pi_8 = \{\{1, 2, 7, 8\}, \{3, 5, 6\}, \{4\}\}) = \mathbb{P}(\Pi_8 = \{\{2, 3, 8, 1\}, \{4, 6, 7\}, \{5\}\})$$

# Chinese restaurant process



- Probability of this seating:

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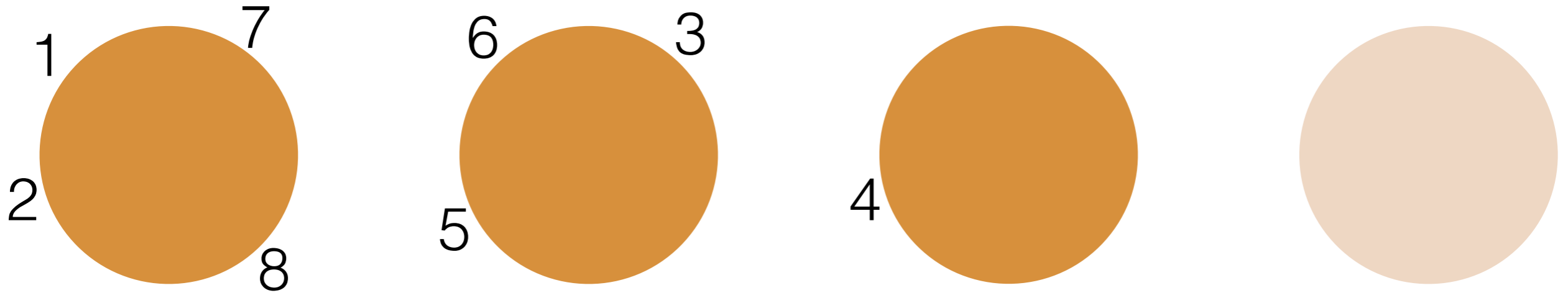
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- Can always pretend  $n$  is the last customer and calculate  $p(\Pi_N | \Pi_{N, -n})$

# Chinese restaurant process



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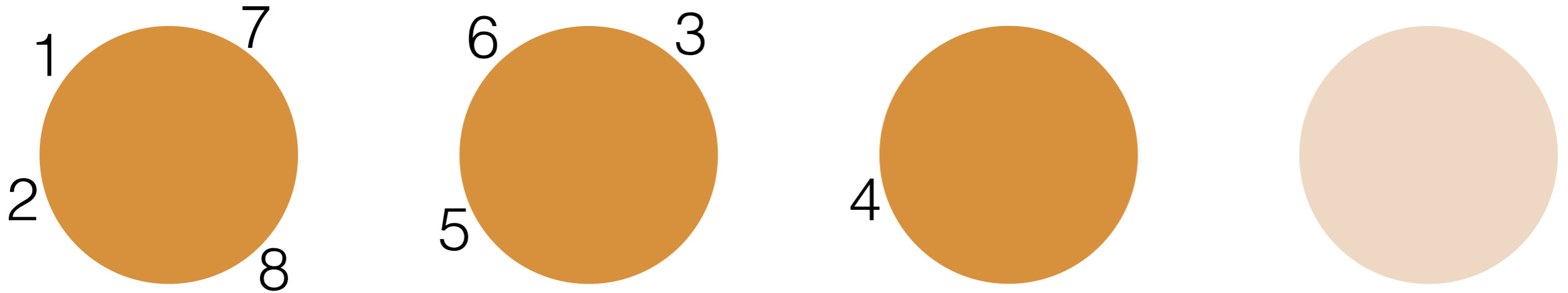
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- e.g.  $\Pi_{8, -5} = \{\{1, 2, 7, 8\}, \{3, 6\}, \{4\}\}$

# Chinese restaurant process



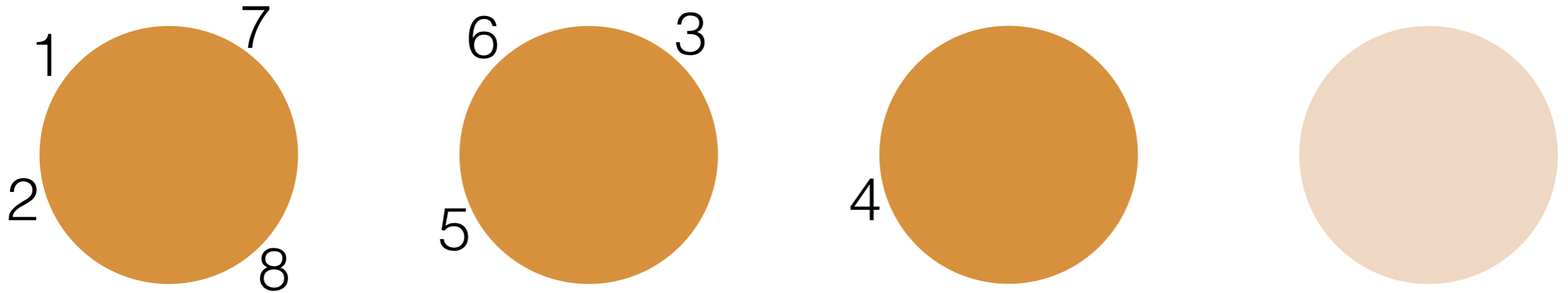
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# Chinese restaurant process

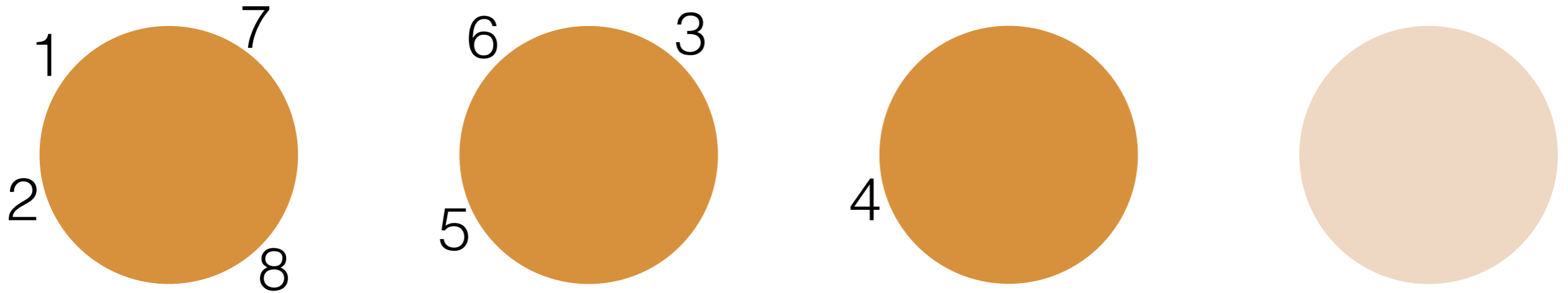


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# Chinese restaurant process

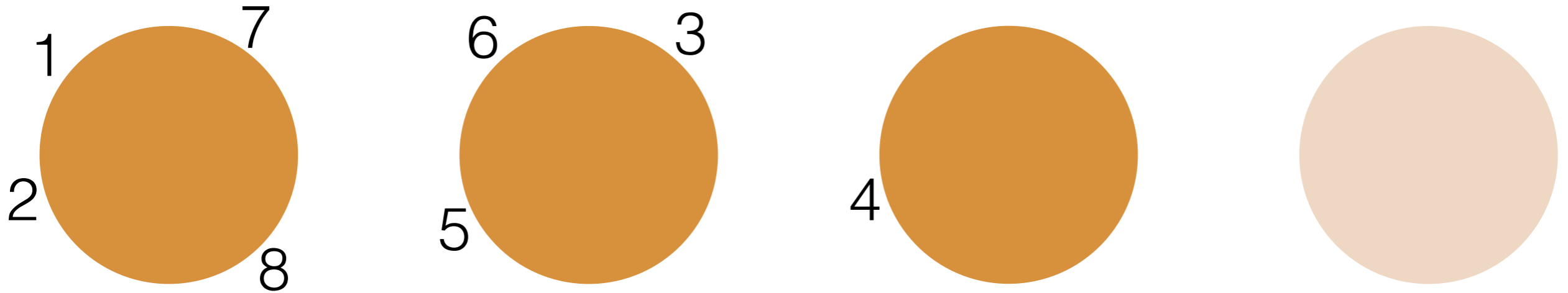


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- So:  $p(\Pi_N | \Pi_{N,-n}) = \begin{cases} \frac{\alpha}{\alpha + n} & \text{if } n \text{ joins cluster } C \\ \frac{n}{\alpha + n} & \text{if } n \text{ starts a new cluster} \end{cases}$

# Chinese restaurant process

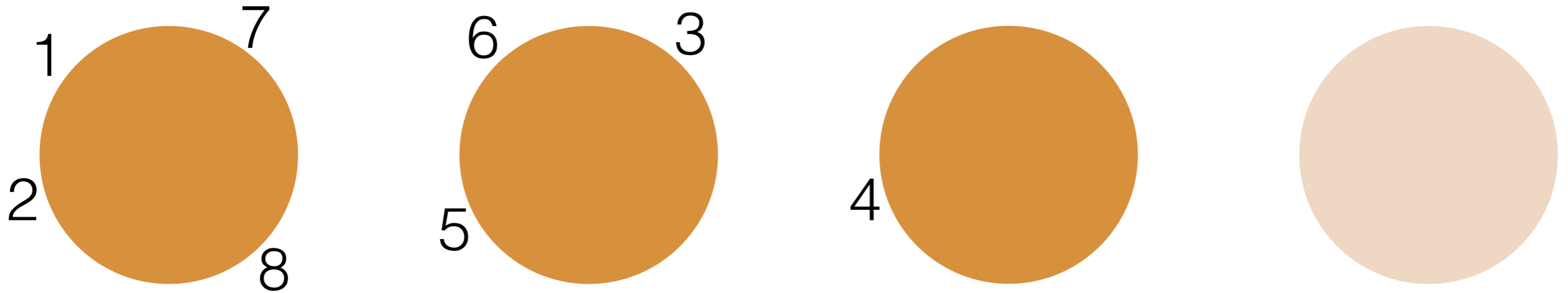


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- So: 
$$p(\Pi_N | \Pi_{N, -n}) = \begin{cases} \frac{\#C}{\alpha + N - 1} & \text{if } n \text{ joins cluster } C \\ & \text{if } n \text{ starts a new cluster} \end{cases}$$

# Chinese restaurant process

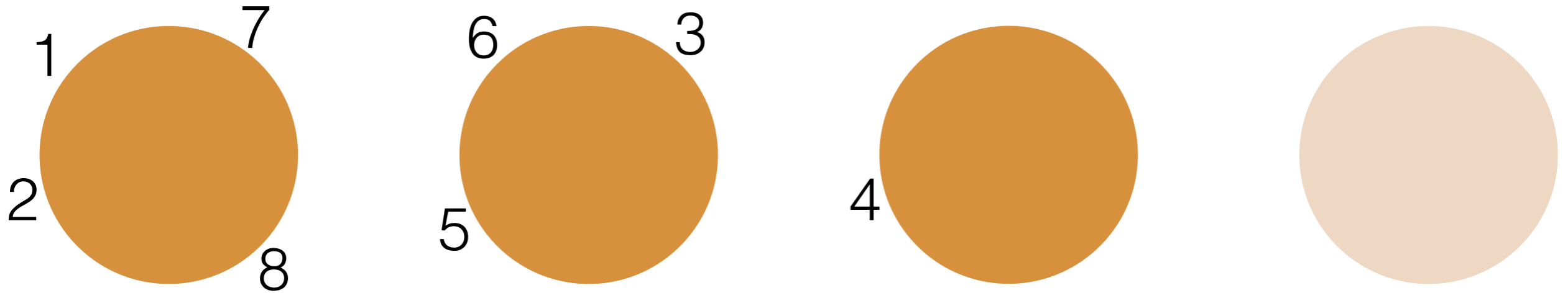


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# Chinese restaurant process



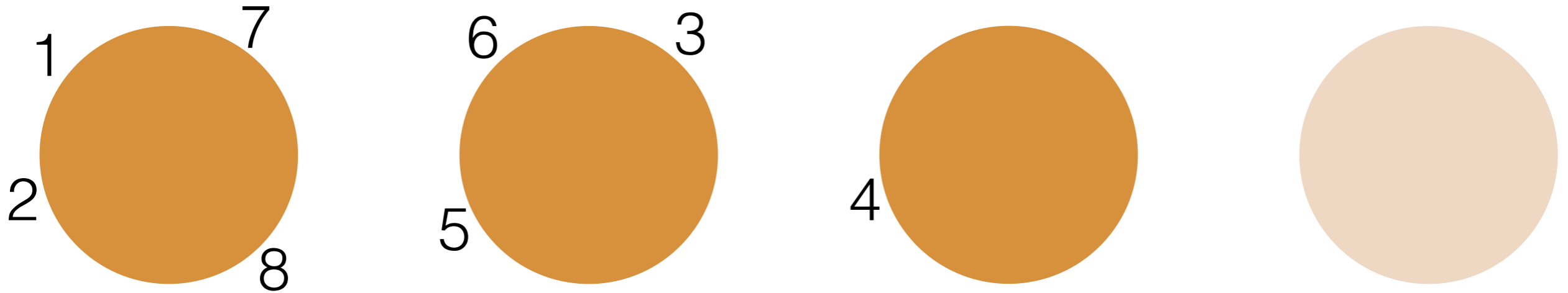
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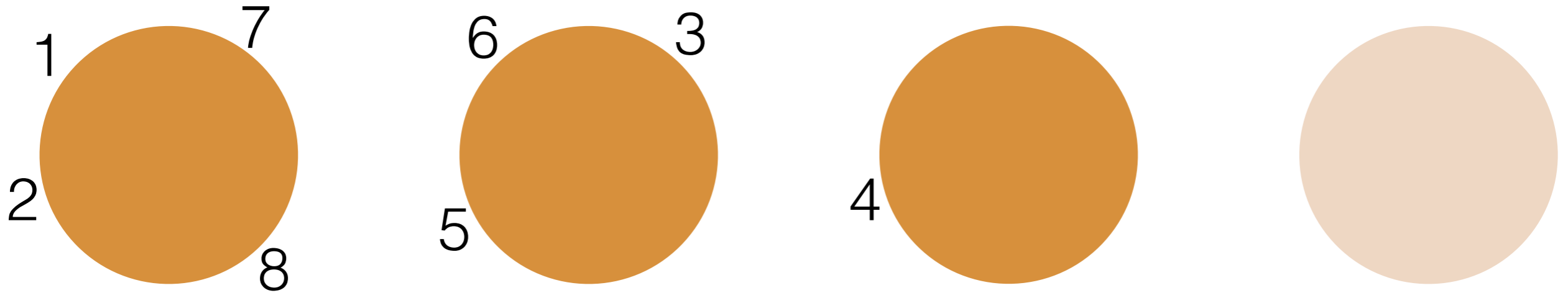
- Gibbs sampling review:

# Chinese restaurant process



- Probability of  $N$  customers ( $K_N$  tables,  $\#C$  at table  $C$ ):
 
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- Gibbs sampling review: target distribution  $p(v_1, v_2, v_3)$

# Chinese restaurant process



- Probability of  $N$  customers ( $K_N$  tables,  $\#C$  at table  $C$ ):

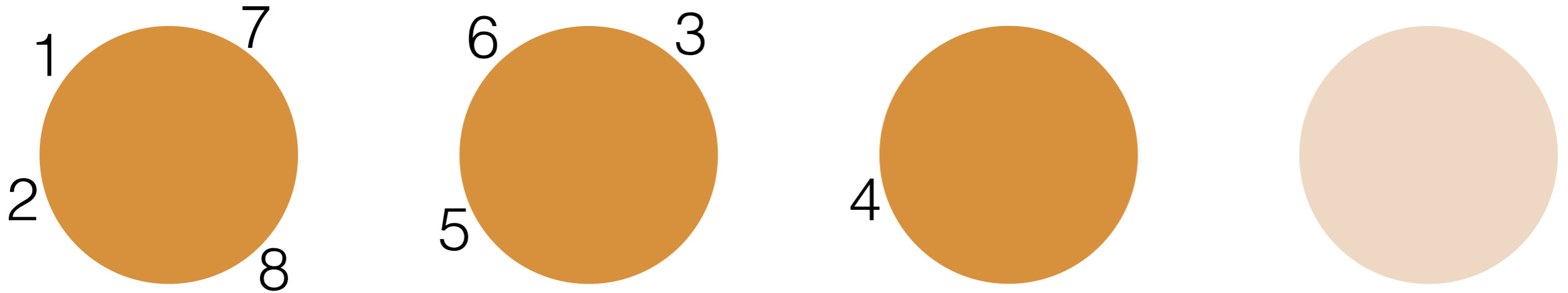
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- Gibbs sampling review: target distribution  $p(v_1, v_2, v_3)$

- Start:  $v_1^{(0)}, v_2^{(0)}, v_3^{(0)}$

# Chinese restaurant process



- Probability of  $N$  customers ( $K_N$  tables,  $\#C$  at table  $C$ ):

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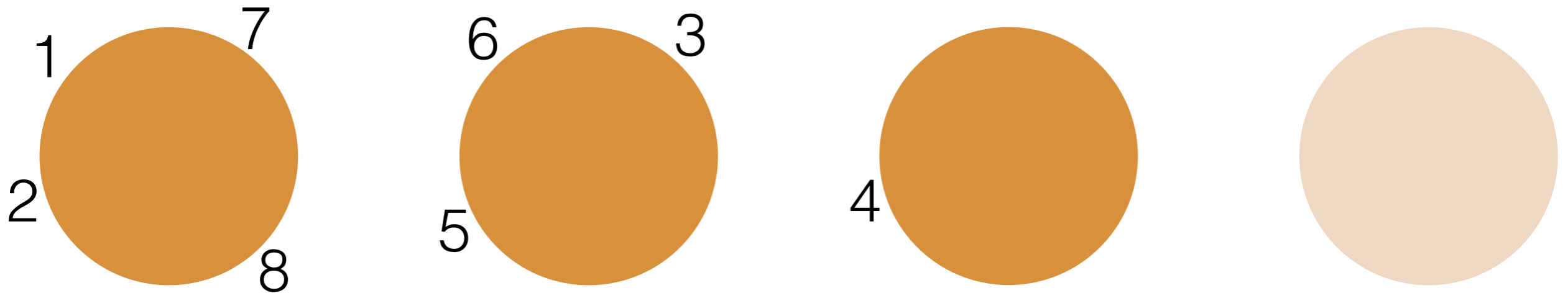
- Gibbs sampling review: target distribution  $p(v_1, v_2, v_3)$

- Start:  $v_1^{(0)}, v_2^{(0)}, v_3^{(0)}$

- $t^{\text{th}}$  step:  $v_1^{(t)} \sim p(v_1 | v_2^{(t-1)}, v_3^{(t-1)})$



# Chinese restaurant process



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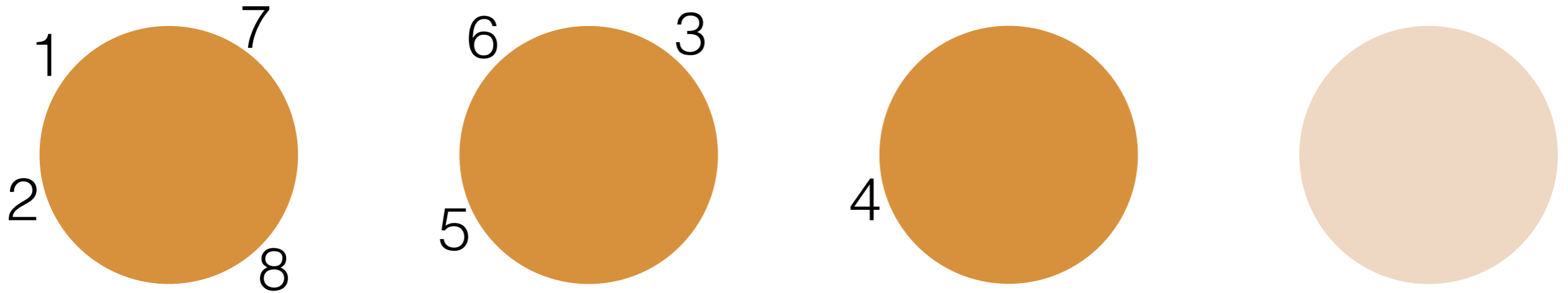
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- Gibbs sampling review: target distribution  $p(v_1, v_2, v_3)$

- Start:  $v_1^{(0)}, v_2^{(0)}, v_3^{(0)}$   $v_2^{(t)} \sim p(v_2 | v_1^{(t)}, v_3^{(t-1)})$

- $t^{\text{th}}$  step:  $v_1^{(t)} \sim p(v_1 | v_2^{(t-1)}, v_3^{(t-1)})$

# Chinese restaurant process



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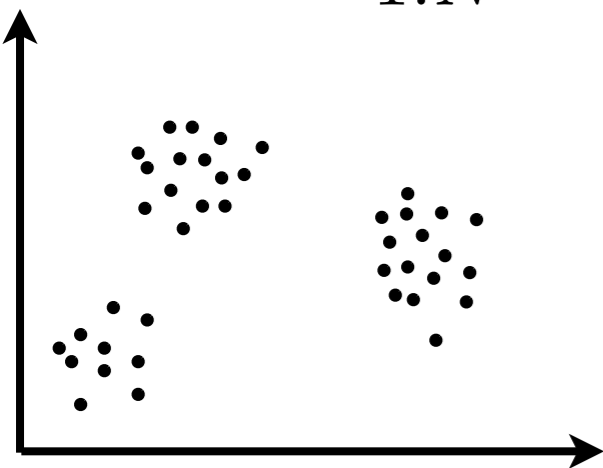
- Gibbs sampling review: target distribution  $p(v_1, v_2, v_3)$

- Start:  $v_1^{(0)}, v_2^{(0)}, v_3^{(0)}$   $v_2^{(t)} \sim p(v_2 | v_1^{(t)}, v_3^{(t-1)})$
- $t^{\text{th}}$  step:  $v_1^{(t)} \sim p(v_1 | v_2^{(t-1)}, v_3^{(t-1)})$   $v_3^{(t)} \sim p(v_3 | v_1^{(t)}, v_2^{(t)})$

# CRP mixture model: inference

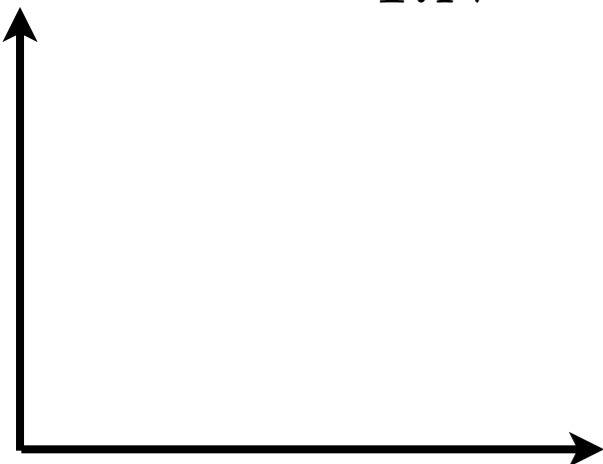
# CRP mixture model: inference

- Data  $x_{1:N}$



# CRP mixture model: inference

- Data  $x_{1:N}$



# CRP mixture model: inference

- Data  $x_{1:N}$
- Generative model



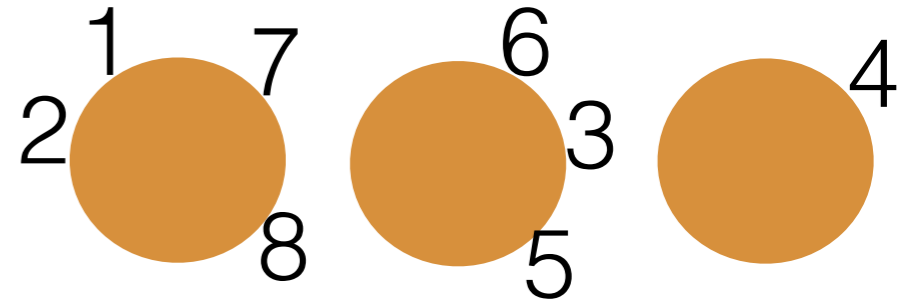
# CRP mixture model: inference

- Data  $x_{1:N}$
- Generative model  
 $\Pi_N \sim \text{CRP}(N, \alpha)$



# CRP mixture model: inference

- Data  $x_{1:N}$
- Generative model  $\Pi_N \sim \text{CRP}(N, \alpha)$





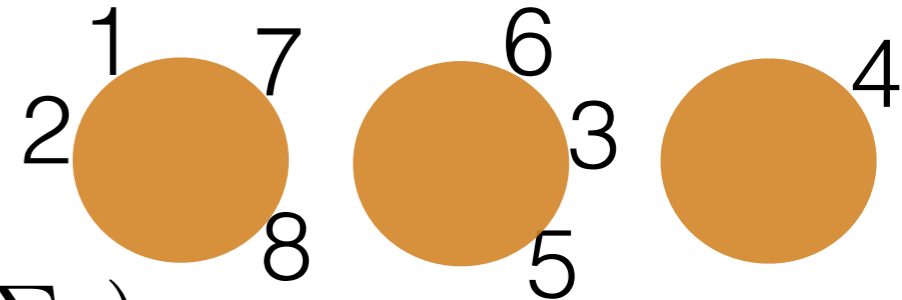
# CRP mixture model: inference

- Data  $x_{1:N}$

- Generative model

$$\Pi_N \sim \text{CRP}(N, \alpha)$$

$$\forall C \in \Pi_N, \mu_C \stackrel{iid}{\sim} \mathcal{N}(\mu_0, \Sigma_0)$$



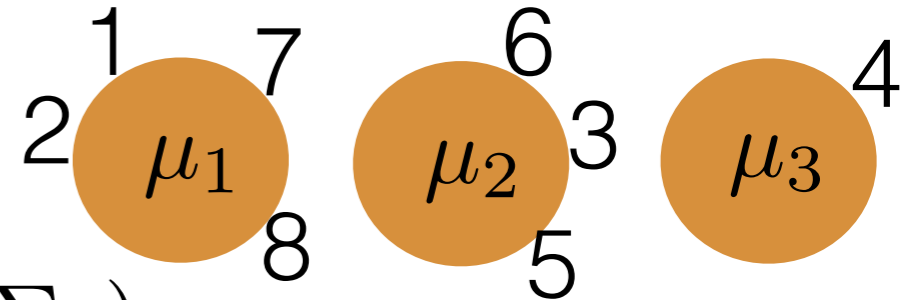
# CRP mixture model: inference

- Data  $x_{1:N}$

- Generative model

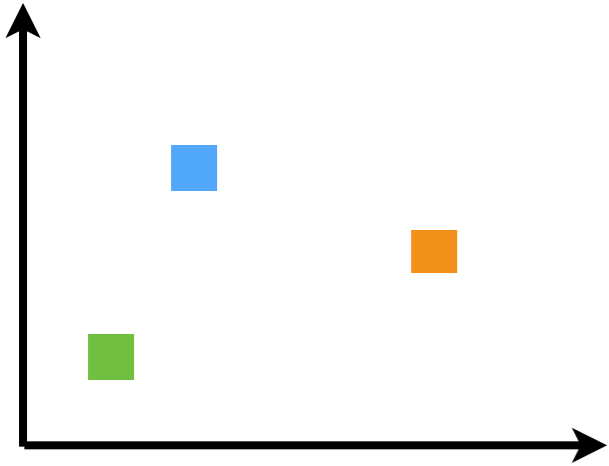
$$\Pi_N \sim \text{CRP}(N, \alpha)$$

$$\forall C \in \Pi_N, \mu_C \stackrel{iid}{\sim} \mathcal{N}(\mu_0, \Sigma_0)$$



# CRP mixture model: inference

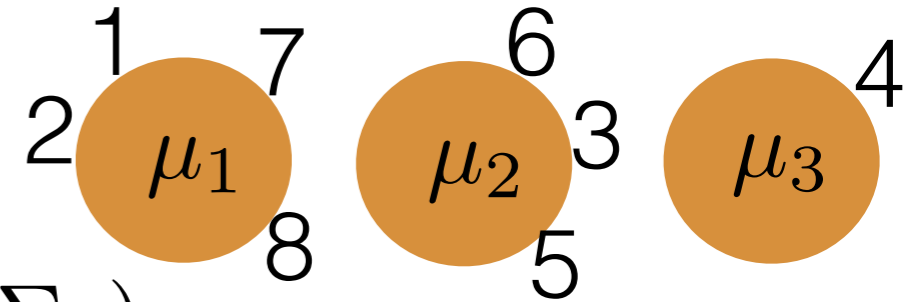
- Data  $x_{1:N}$



- Generative model

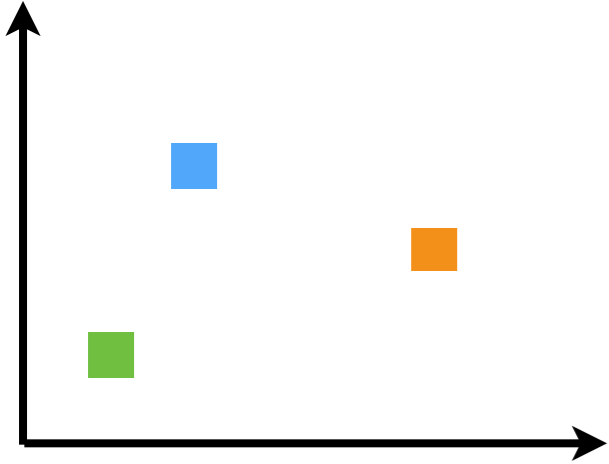
$$\Pi_N \sim \text{CRP}(N, \alpha)$$

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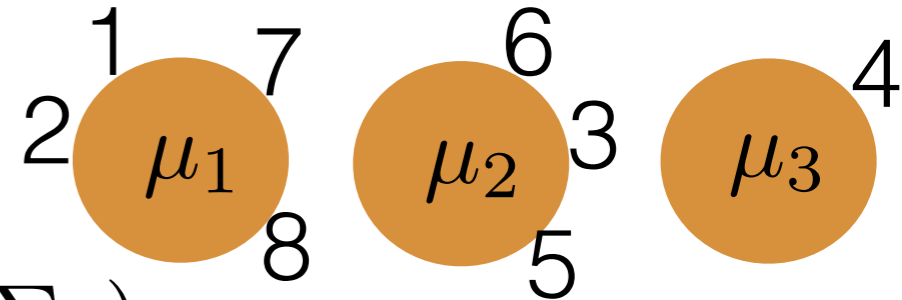


- Generative model

$$\Pi_N \sim \text{CRP}(N, \alpha)$$

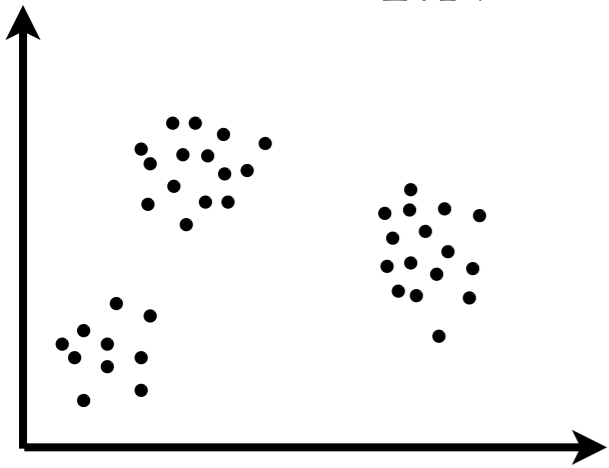
$$\forall C \in \Pi_N, \mu_C \stackrel{iid}{\sim} \mathcal{N}(\mu_0, \Sigma_0)$$

$$\forall C \in \Pi_N, \forall n \in C, x_n \stackrel{indep}{\sim} \mathcal{N}(\mu_C, \Sigma)$$



# CRP mixture model: inference

- Data  $x_{1:N}$

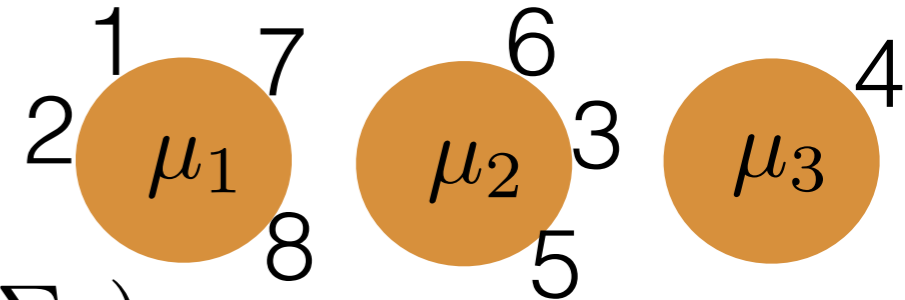


- Generative model

$$\Pi_N \sim \text{CRP}(N, \alpha)$$

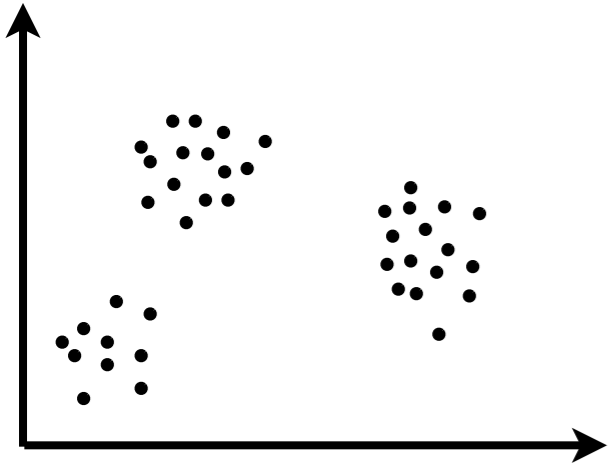
$$\forall C \in \Pi_N, \mu_C \stackrel{iid}{\sim} \mathcal{N}(\mu_0, \Sigma_0)$$

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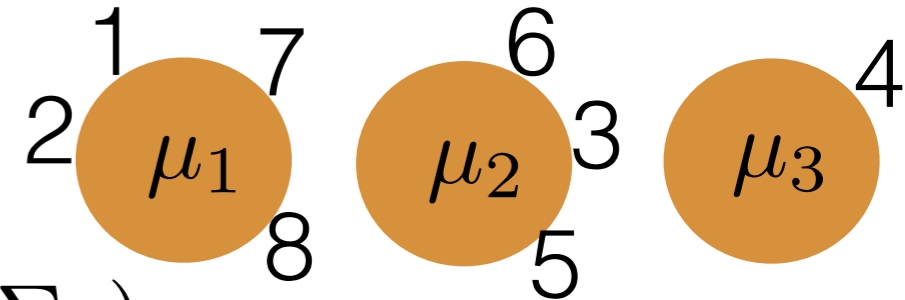


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- Want: posterior

# CRP mixture model: inference

- Data  $x_{1:N}$

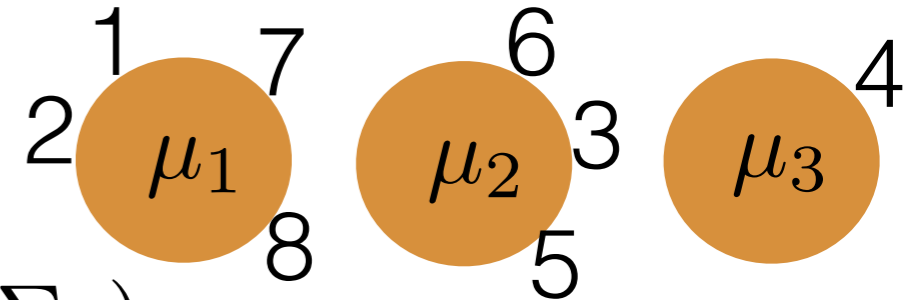


- Generative model

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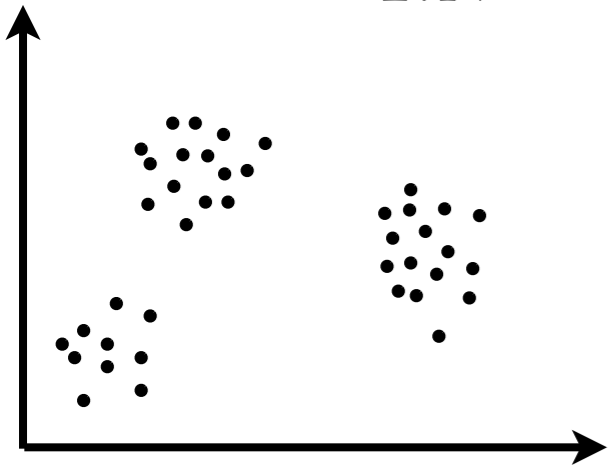
$$\forall C \in \Pi_N, \forall n \in C, x_n \stackrel{indep}{\sim} \mathcal{N}(\mu_C, \Sigma)$$



- Want: posterior  $p(\Pi_N | x_{1:N})$

# CRP mixture model: inference

- Data  $x_{1:N}$

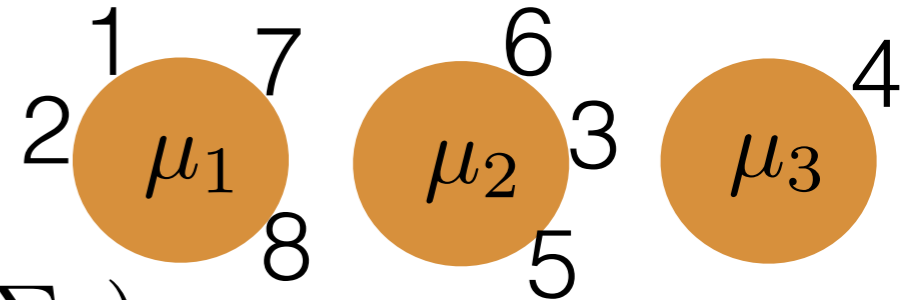


- Generative model

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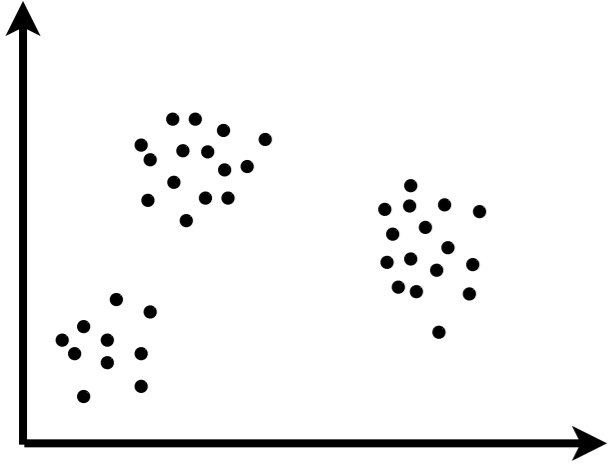


- Want: posterior  $p(\Pi_N | x_{1:N})$
- Gibbs sampler:



# CRP mixture model: inference

- Data  $x_{1:N}$

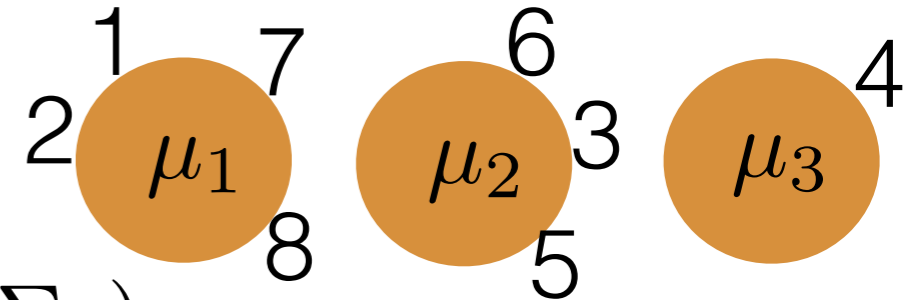


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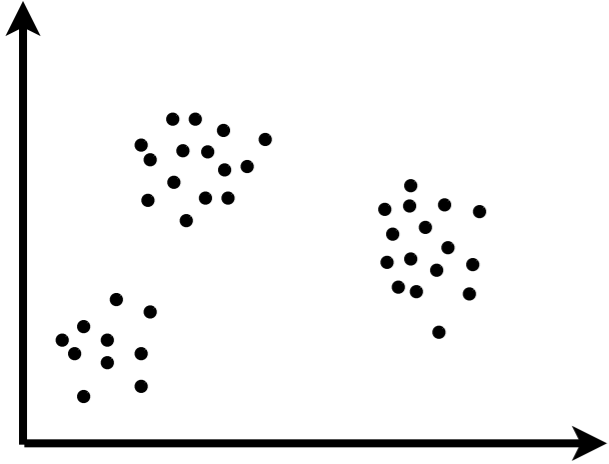
- Want: posterior  $p(\Pi_N | x_{1:N})$

- Gibbs sampler:

$$p(\Pi_N | \Pi_{N,-n}, x)$$

# CRP mixture model: inference

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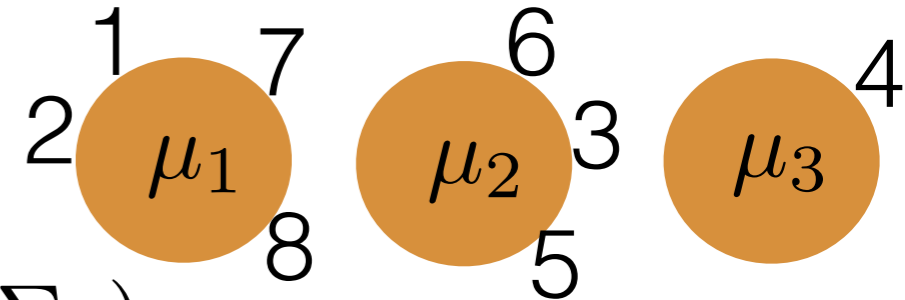


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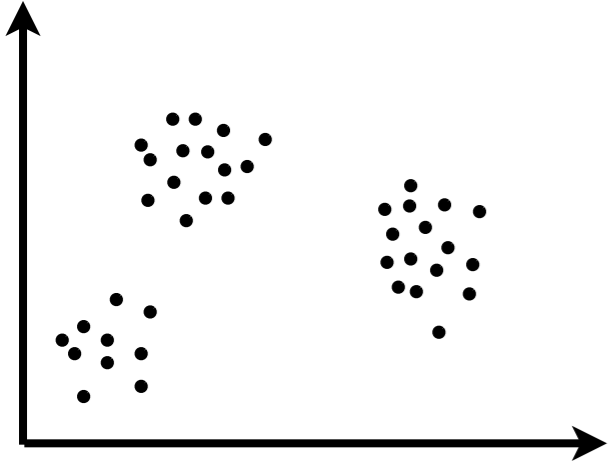
- Want: posterior  $p(\Pi_N | x_{1:N})$

- Gibbs sampler:

$$p(\Pi_N | \Pi_{N,-n}, x) \propto \left\{ \right.$$

# CRP mixture model: inference

- Data  $x_{1:N}$

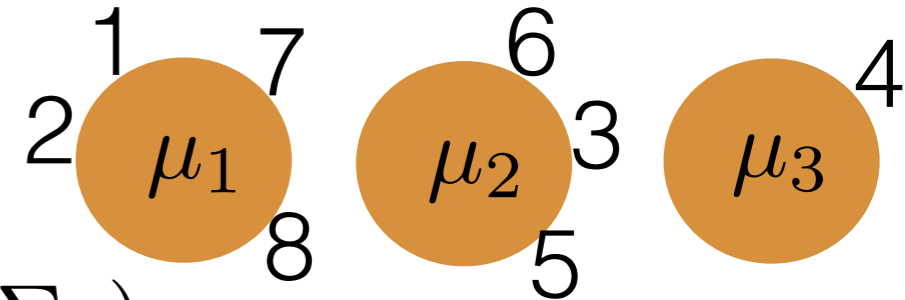


- Generative model

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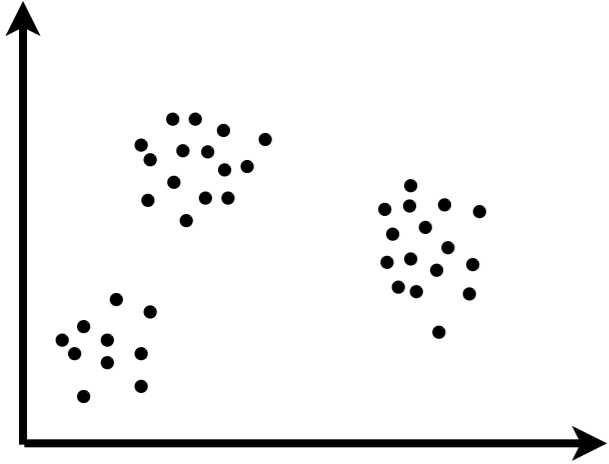
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- Gibbs sampler:

$$p(\Pi_N | \Pi_{N,-n}, x) \propto \begin{cases} \dots & \text{if } n \text{ joins cluster } C \end{cases}$$

# CRP mixture model: inference

- Data  $x_{1:N}$

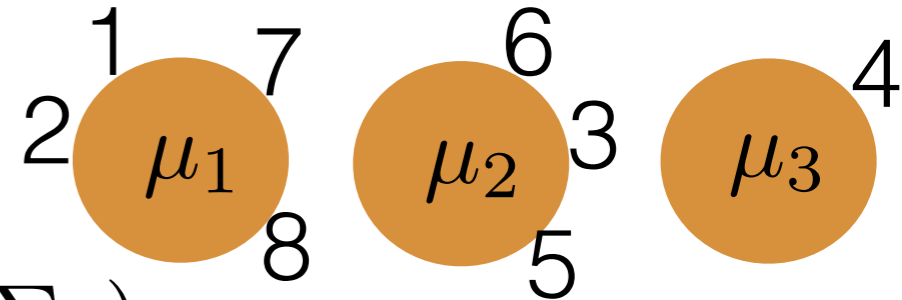


- Generative model

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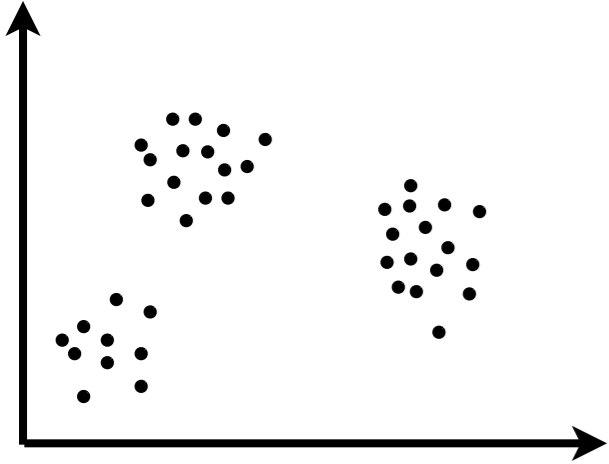
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- Gibbs sampler:

$$p(\Pi_N | \Pi_{N,-n}, x) \propto \begin{cases} & \text{if } n \text{ joins cluster } C \\ & \text{if } n \text{ starts a new cluster} \end{cases}$$

# CRP mixture model: inference

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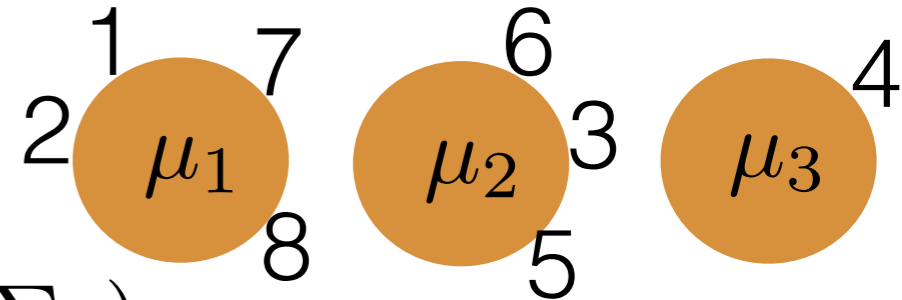


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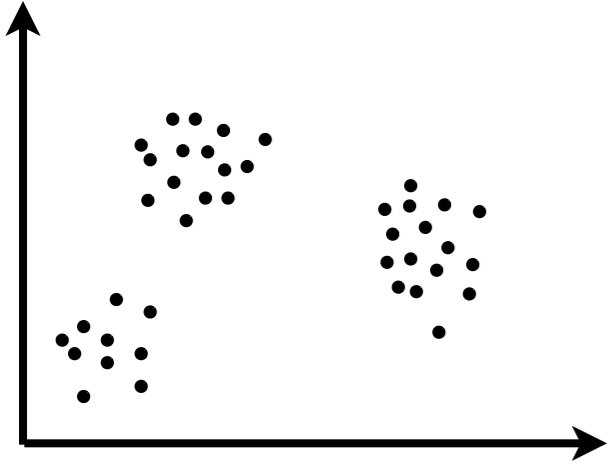
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- Gibbs sampler:

$$p(\Pi_N | \Pi_{N,-n}, x) \propto \begin{cases} \frac{\#C}{\alpha + N - 1} p(x_{C \cup \{n\}} | x_C) & \text{if } n \text{ joins cluster } C \\ & \text{if } n \text{ starts a new cluster} \end{cases}$$

# CRP mixture model: inference

- Data  $x_{1:N}$

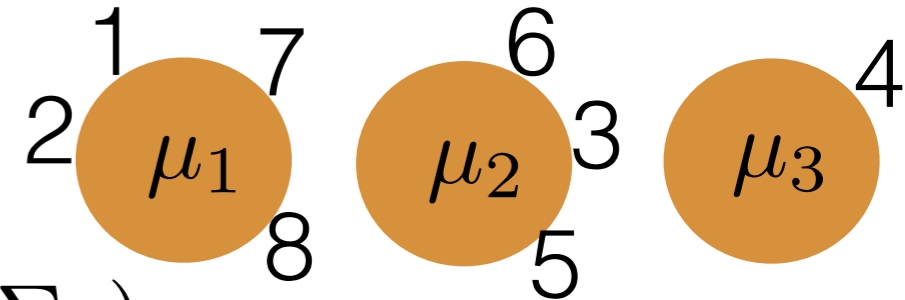


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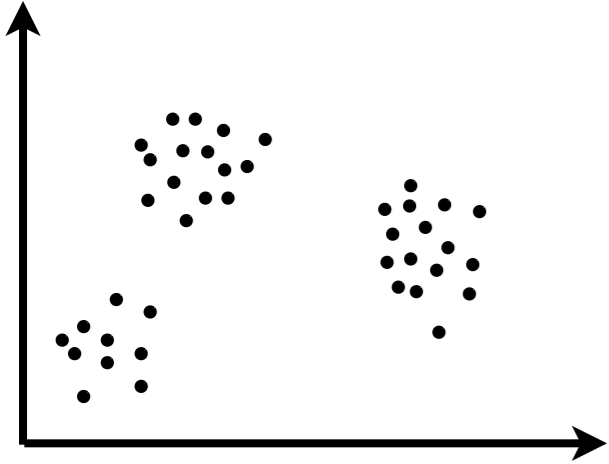
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# CRP mixture model: inference

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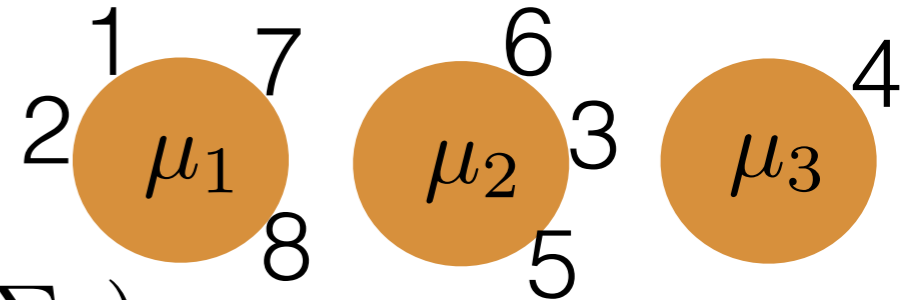


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- Want: posterior  $p(\Pi_N | x_{1:N})$

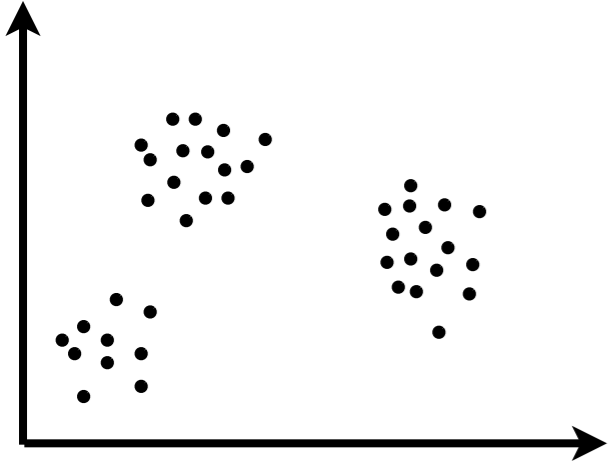
- Gibbs sampler:

$$p(\Pi_N | \Pi_{N,-n}, x) \propto \begin{cases} \frac{\#C}{\alpha + N - 1} p(x_{C \cup \{n\}} | x_C) & \text{if } n \text{ joins cluster } C \\ \frac{\alpha}{\alpha + N - 1} p(x_{\{n\}}) & \text{if } n \text{ starts a new cluster} \end{cases}$$

- For completeness:  $p(x_{C \cup \{n\}} | x_C) =$

# CRP mixture model: inference

- Data  $x_{1:N}$

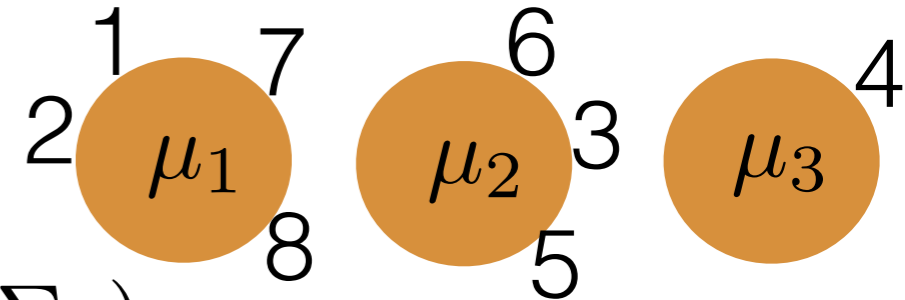


- Generative model

$$\Pi_N \sim \text{CRP}(N, \alpha)$$

$$\forall C \in \Pi_N, \mu_C \stackrel{iid}{\sim} \mathcal{N}(\mu_0, \Sigma_0)$$

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- Want: posterior  $p(\Pi_N | x_{1:N})$

- Gibbs sampler:

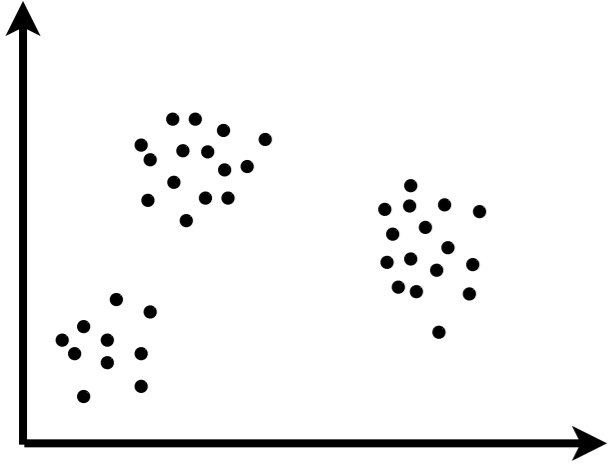
$$p(\Pi_N | \Pi_{N,-n}, x) \propto \begin{cases} \frac{\#C}{\alpha + N - 1} p(x_{C \cup \{n\}} | x_C) & \text{if } n \text{ joins cluster } C \\ \frac{\alpha}{\alpha + N - 1} p(x_{\{n\}}) & \text{if } n \text{ starts a new cluster} \end{cases}$$

- For completeness:  $p(x_{C \cup \{n\}} | x_C) = \mathcal{N}(\tilde{m}, \tilde{\Sigma} + \Sigma)$



# CRP mixture model: inference

- Data  $x_{1:N}$

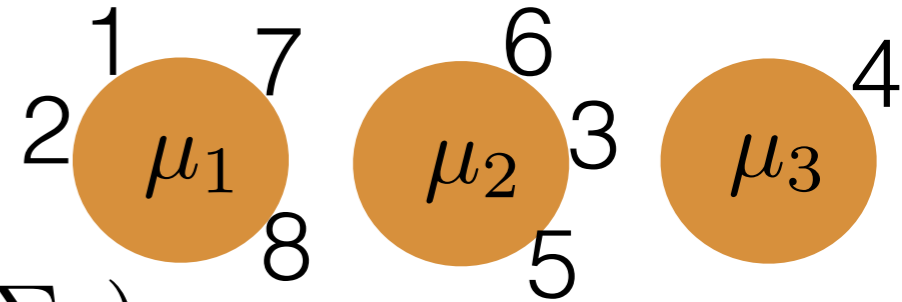


- Generative model

$$\Pi_N \sim \text{CRP}(N, \alpha)$$

$$\forall C \in \Pi_N, \mu_C \stackrel{iid}{\sim} \mathcal{N}(\mu_0, \Sigma_0)$$

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- Want: posterior  $p(\Pi_N | x_{1:N})$

- Gibbs sampler:

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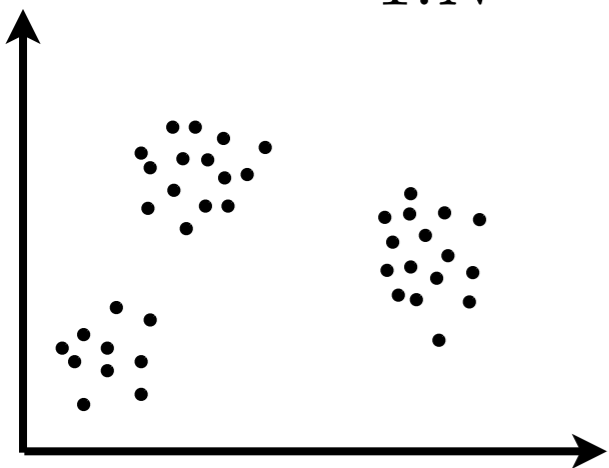
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# CRP mixture model: inference

- Data  $x_{1:N}$

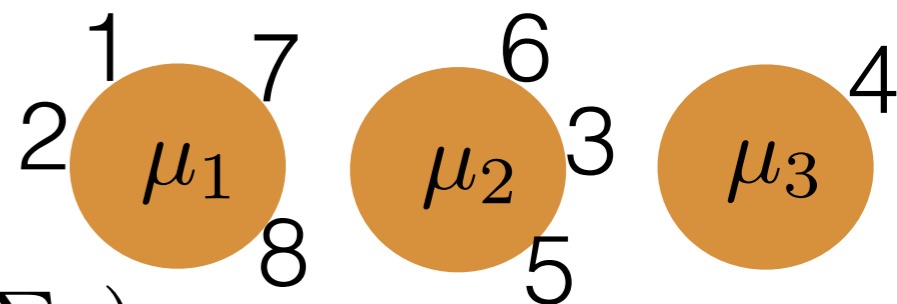


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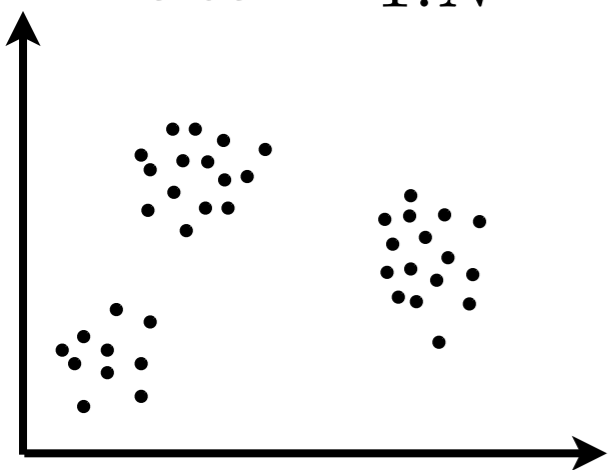
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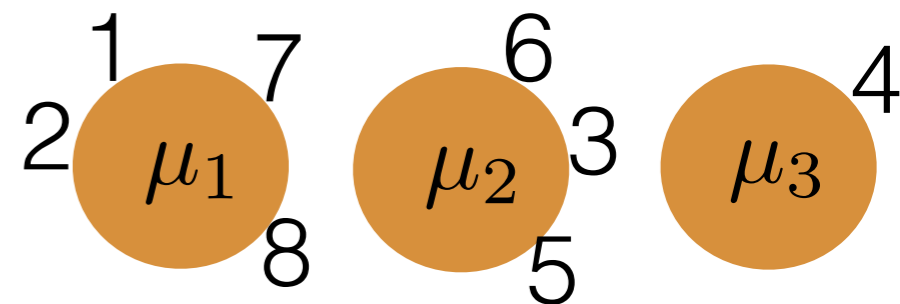


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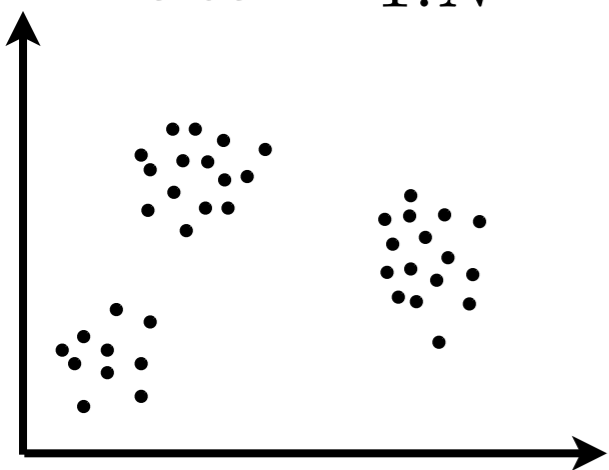
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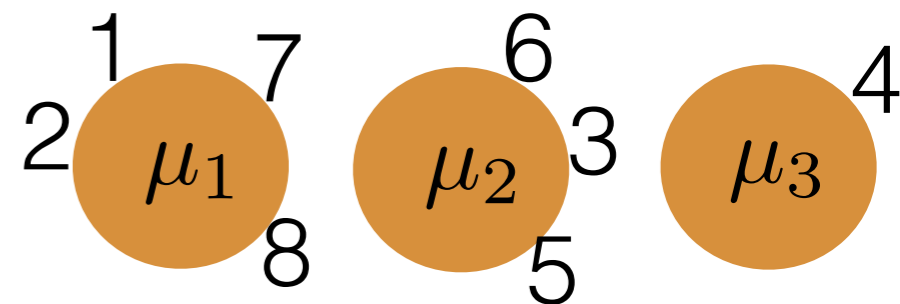


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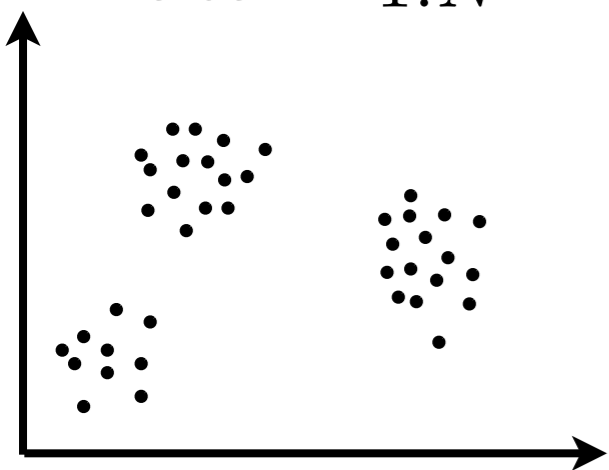
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# CRP mixture model: inference

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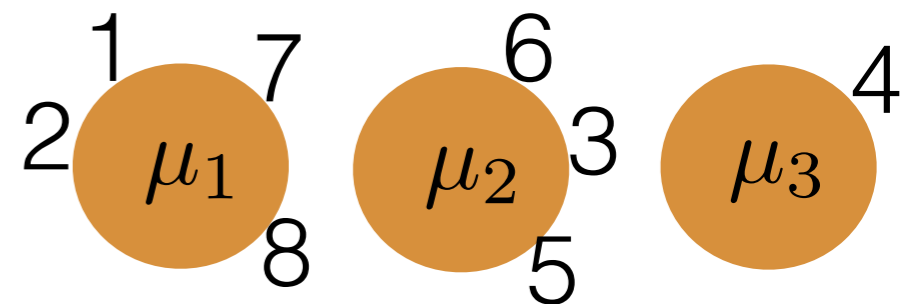


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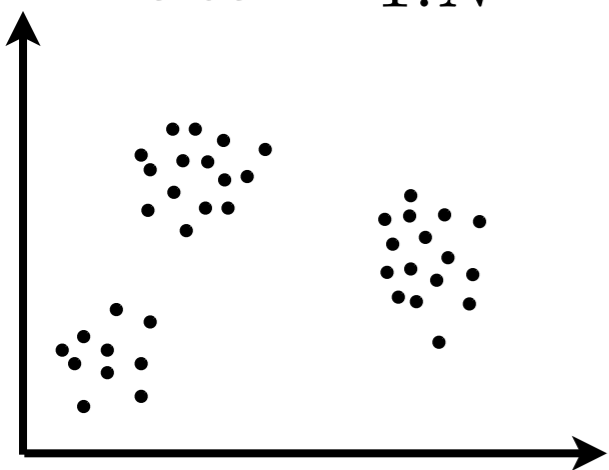
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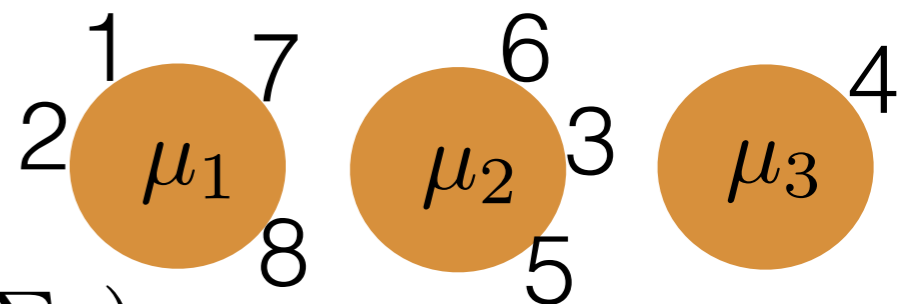


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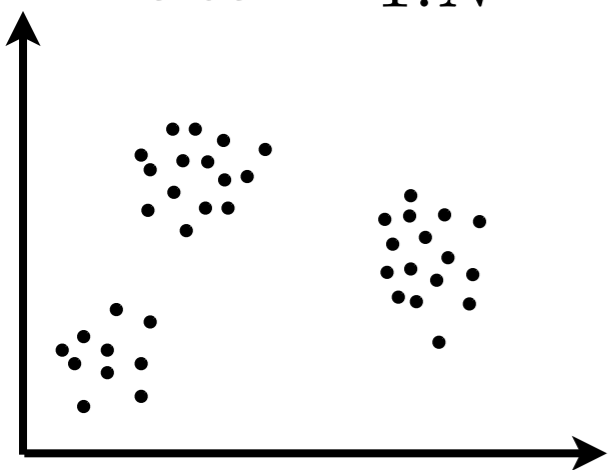
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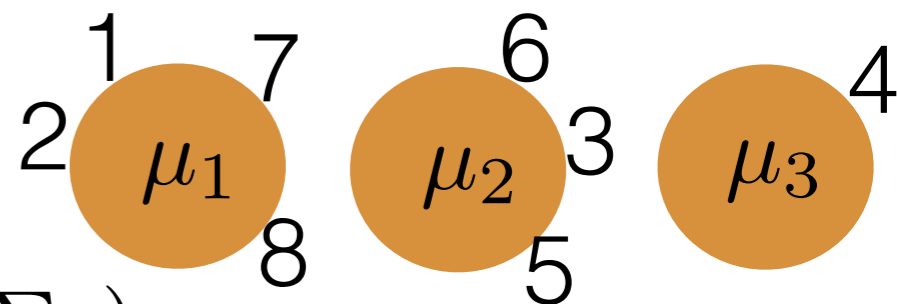


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# More Markov Chain Monte Carlo



# More Markov Chain Monte Carlo

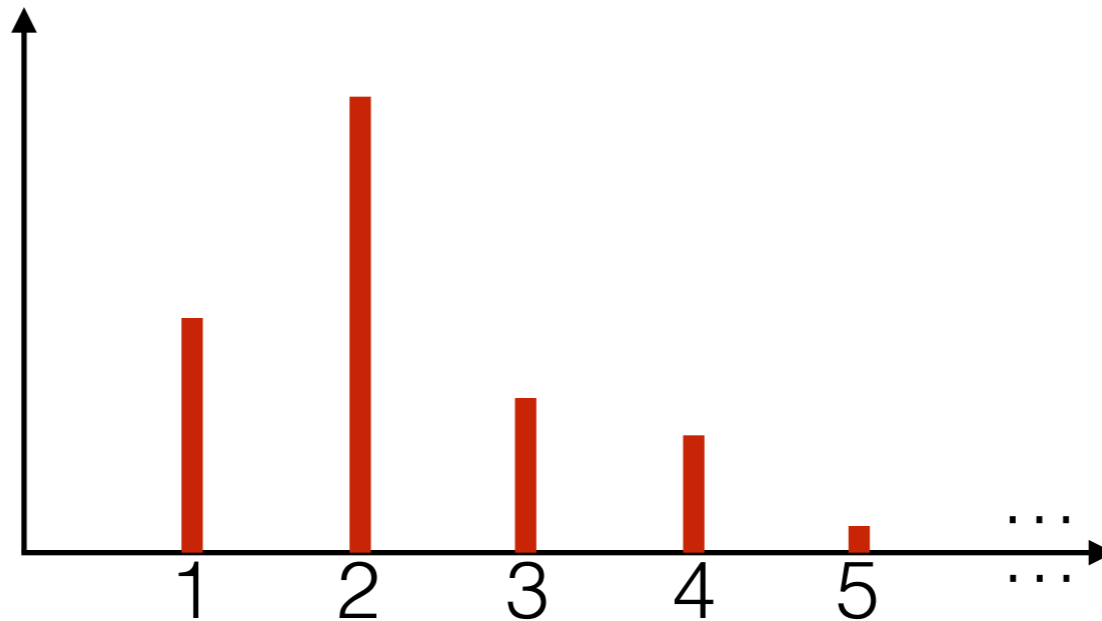
- Slice sampling

# More Markov Chain Monte Carlo

- Slice sampling
  - auxiliary variable  $\rightarrow$  finite conditionals

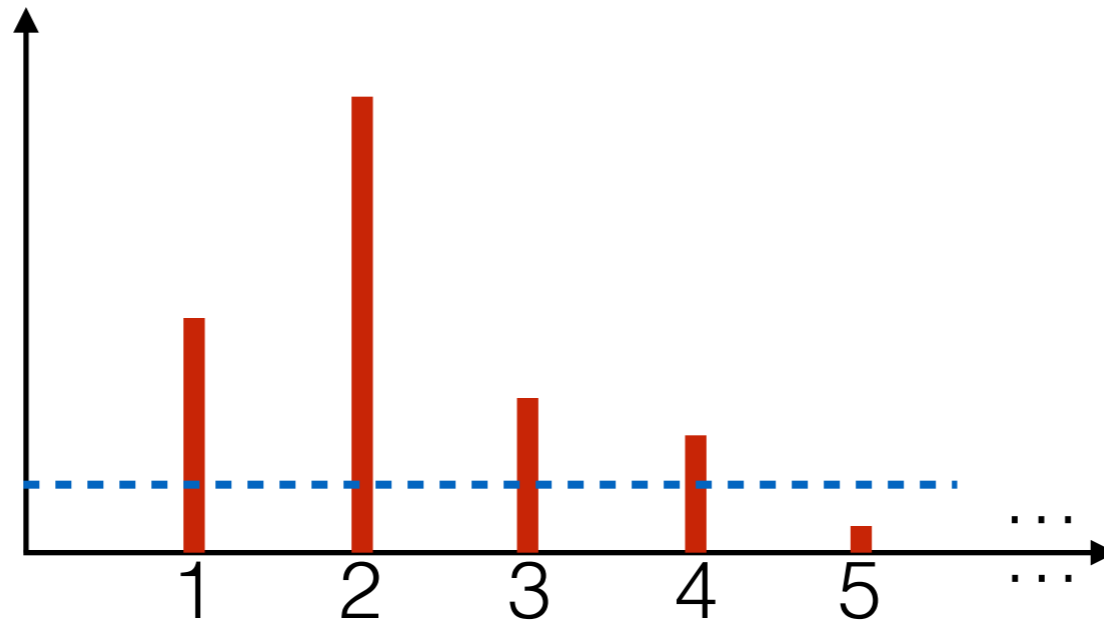
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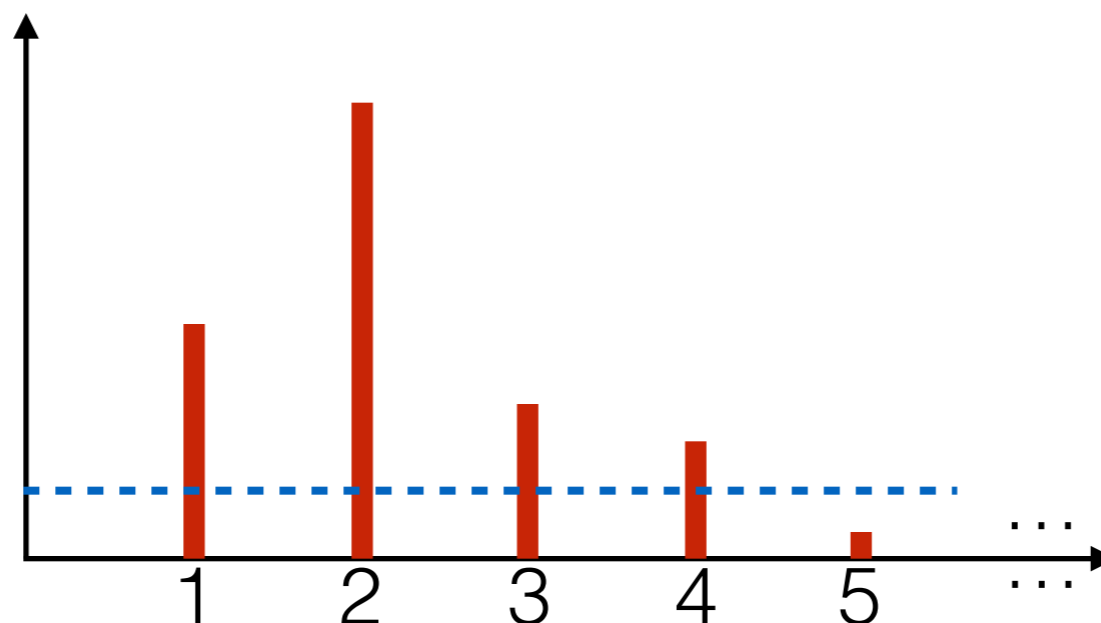
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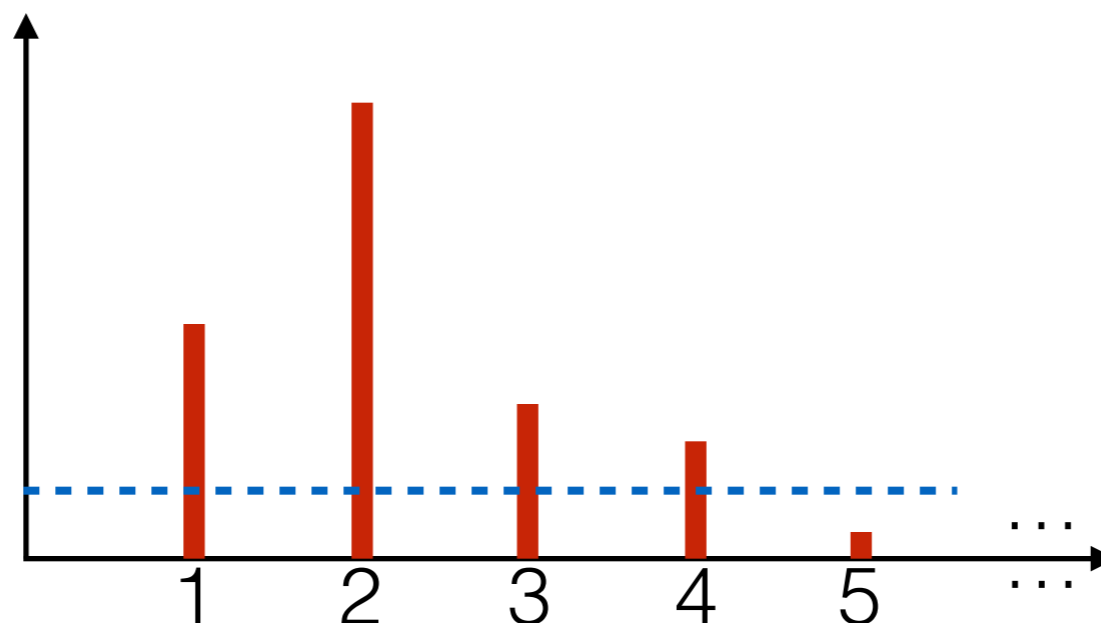
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- Approximate with truncated distribution

# More Markov Chain Monte Carlo

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  - auxiliary variable  $\rightarrow$  finite conditionals

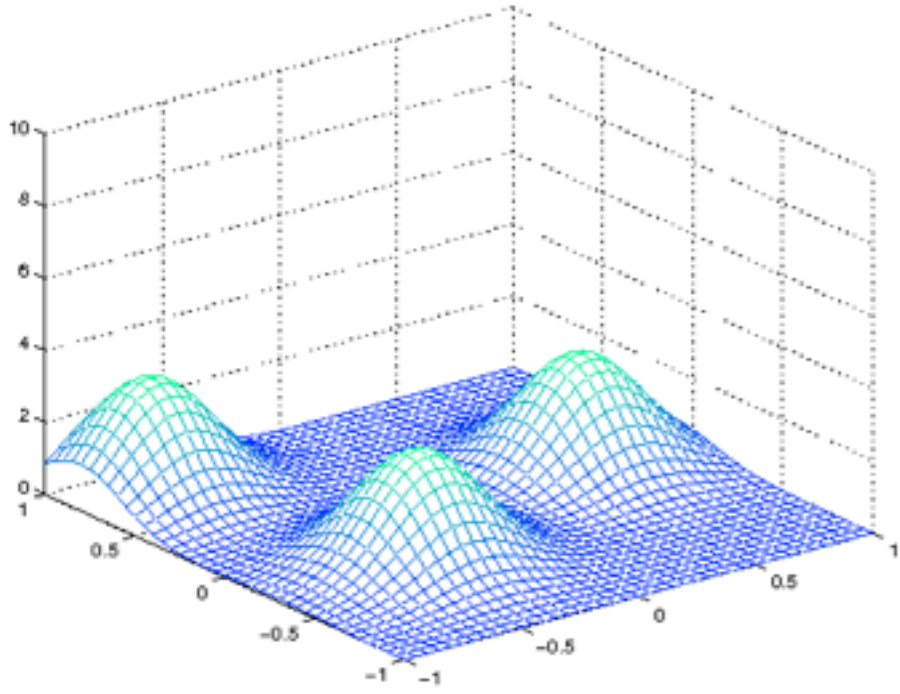


- Approximate with truncated distribution
  - E.g., Hamiltonian Monte Carlo

# Variational Bayes

# Variational Bayes

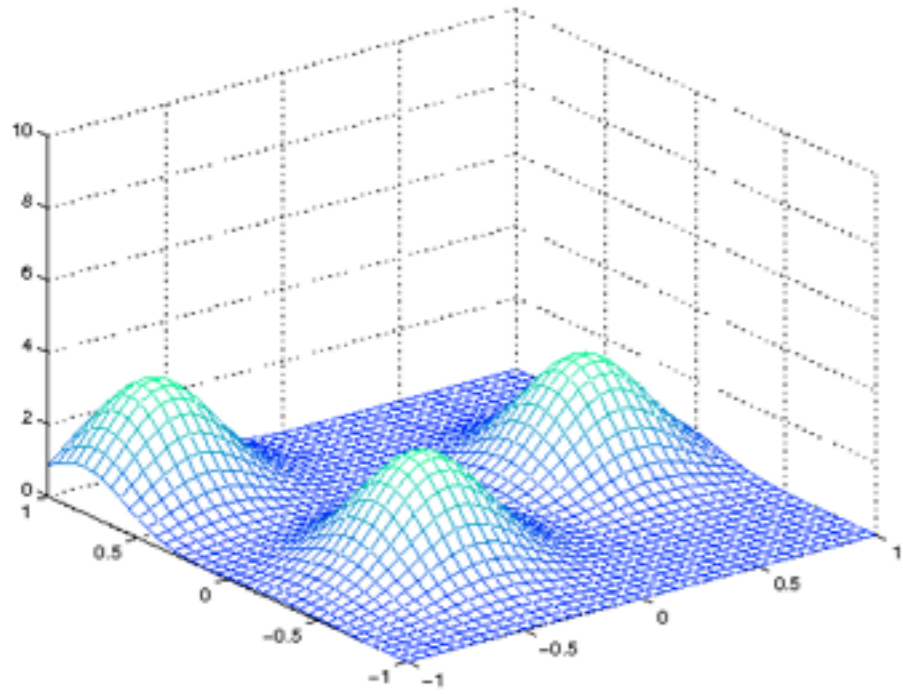
- Variational Bayes (VB)





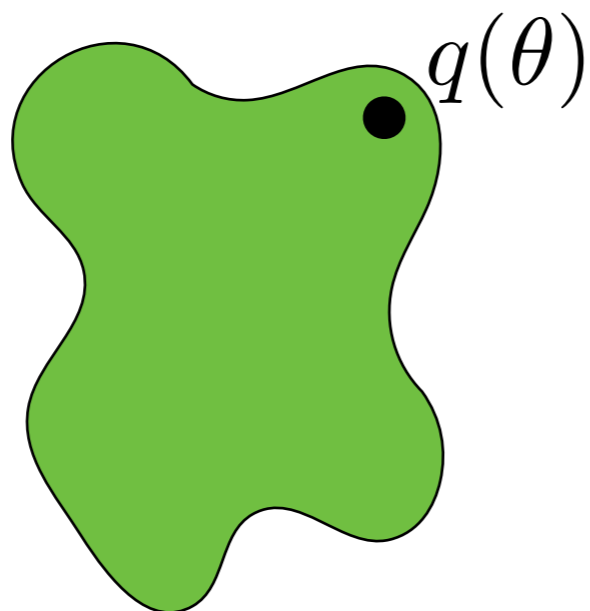
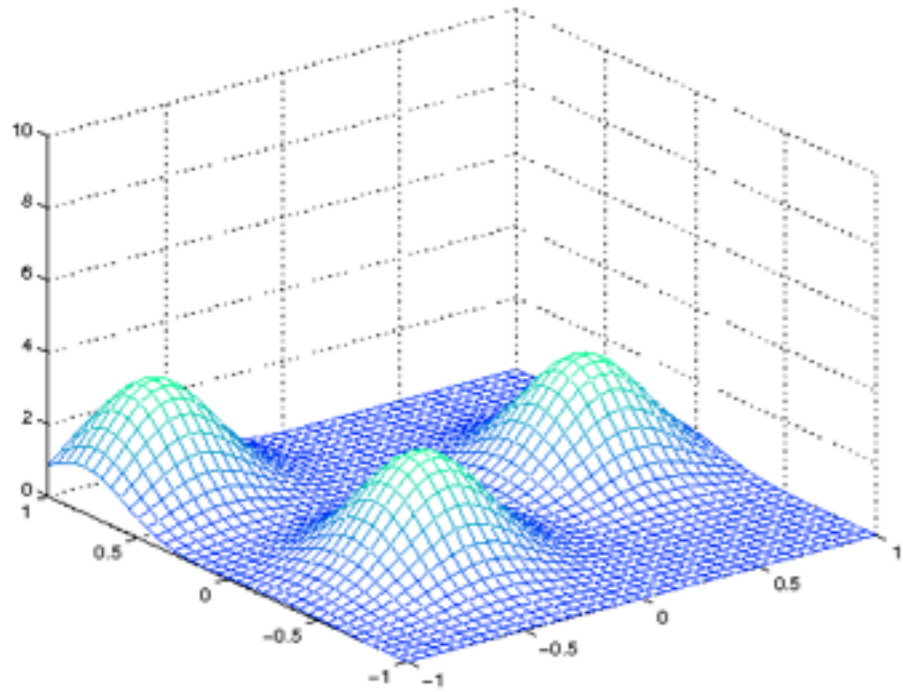
# Variational Bayes

- Variational Bayes (VB)
  - Approximation  $q^*(\theta)$  for posterior  $p(\theta|x)$



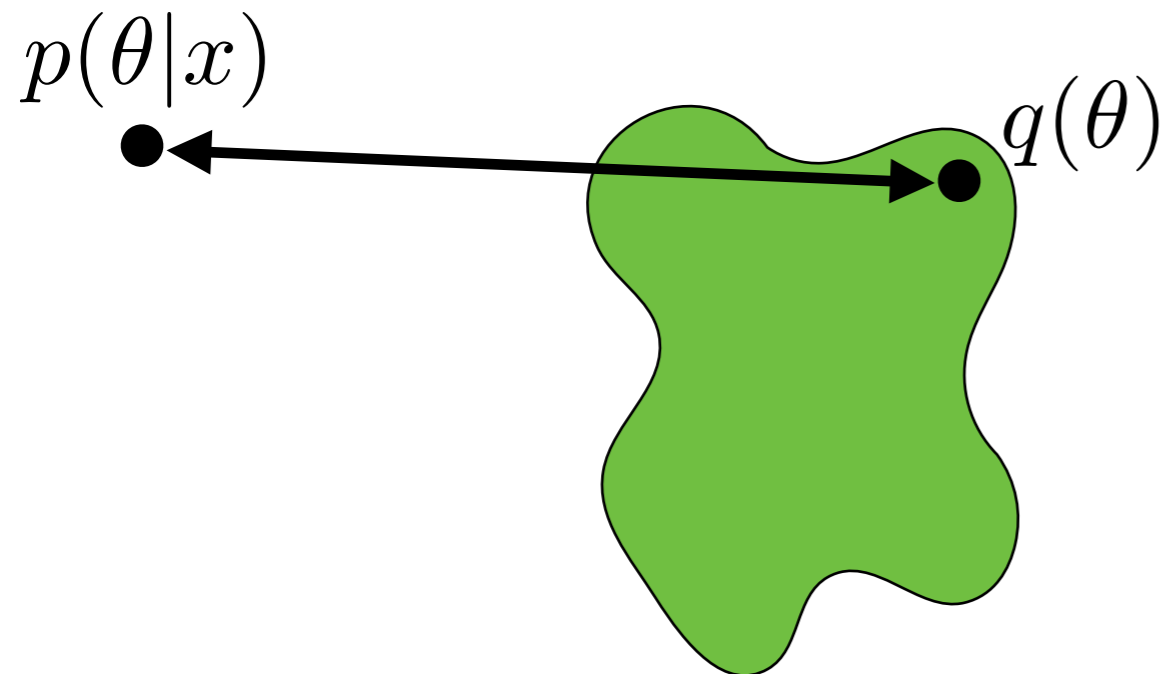
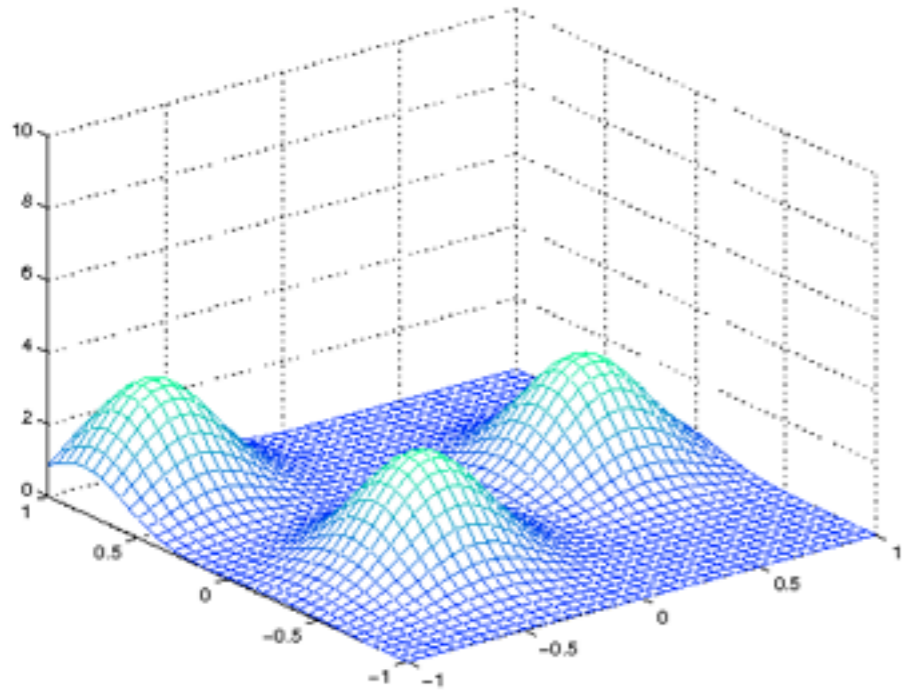
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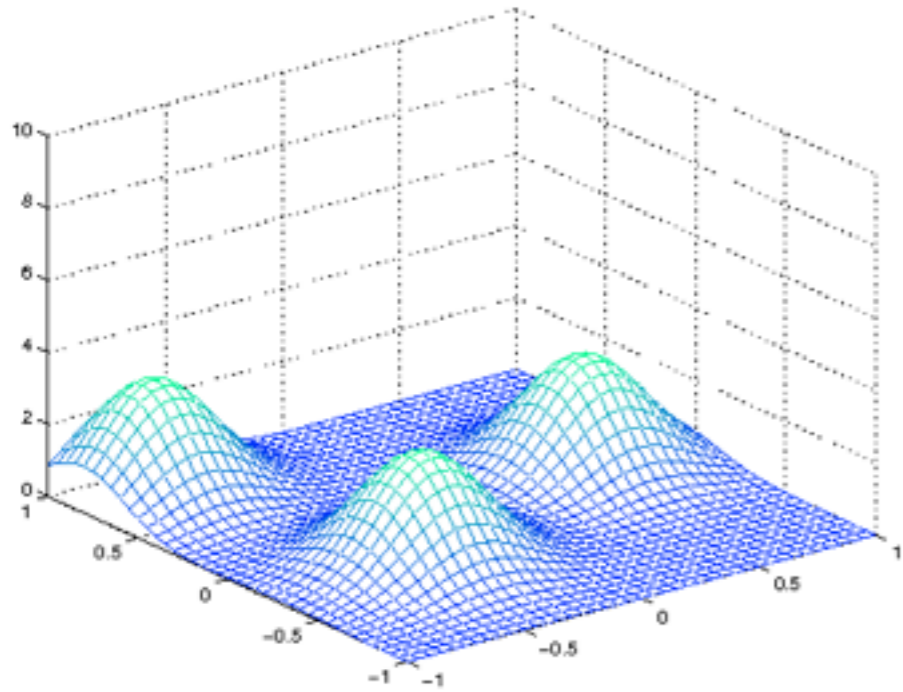
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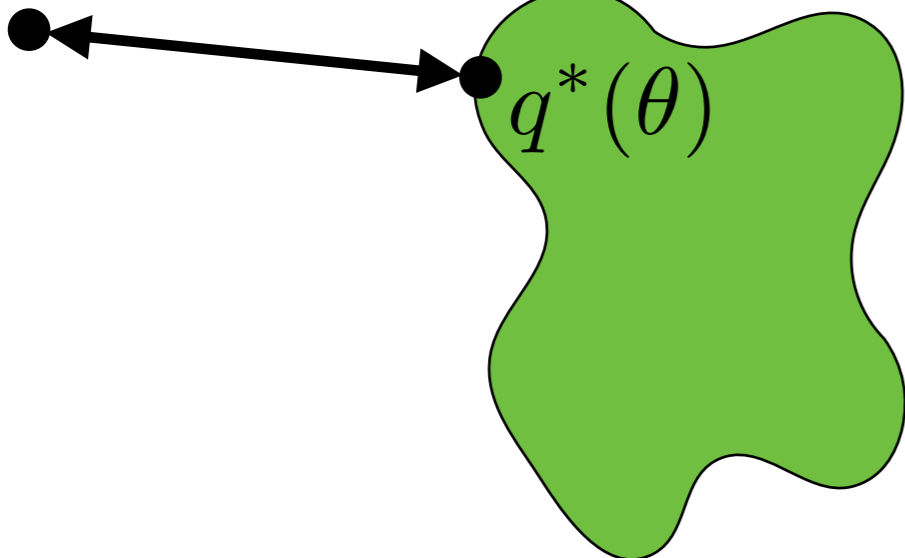


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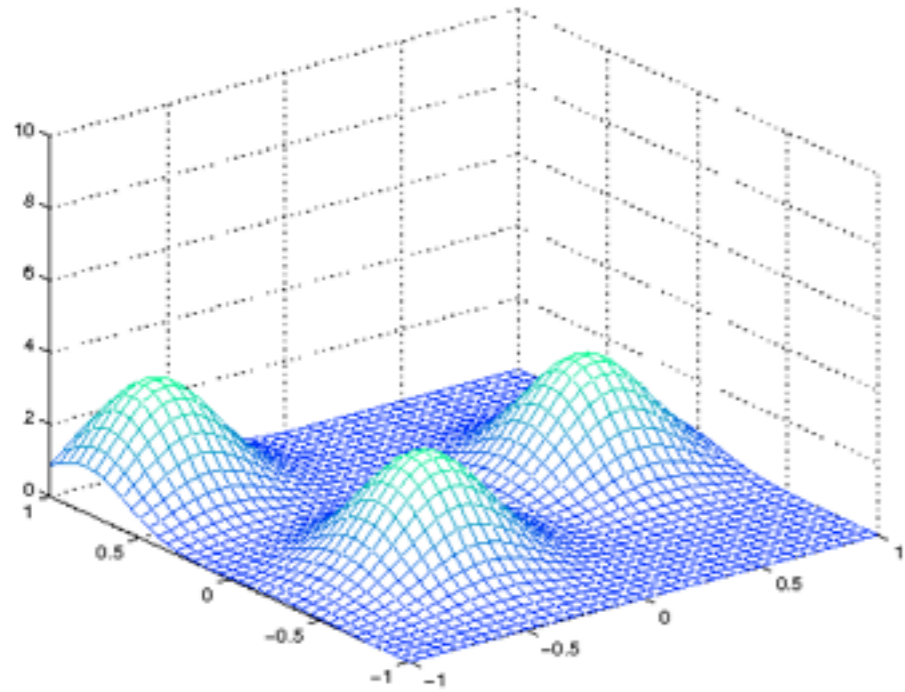
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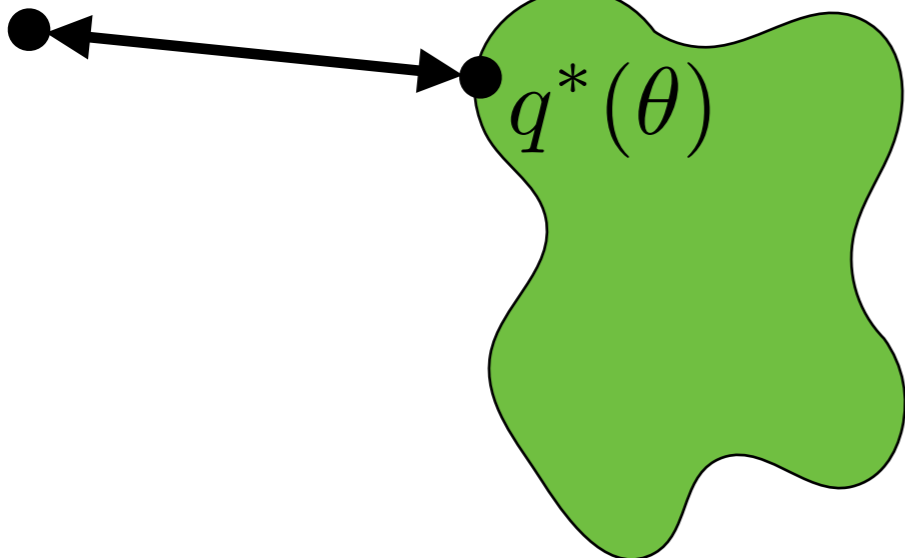


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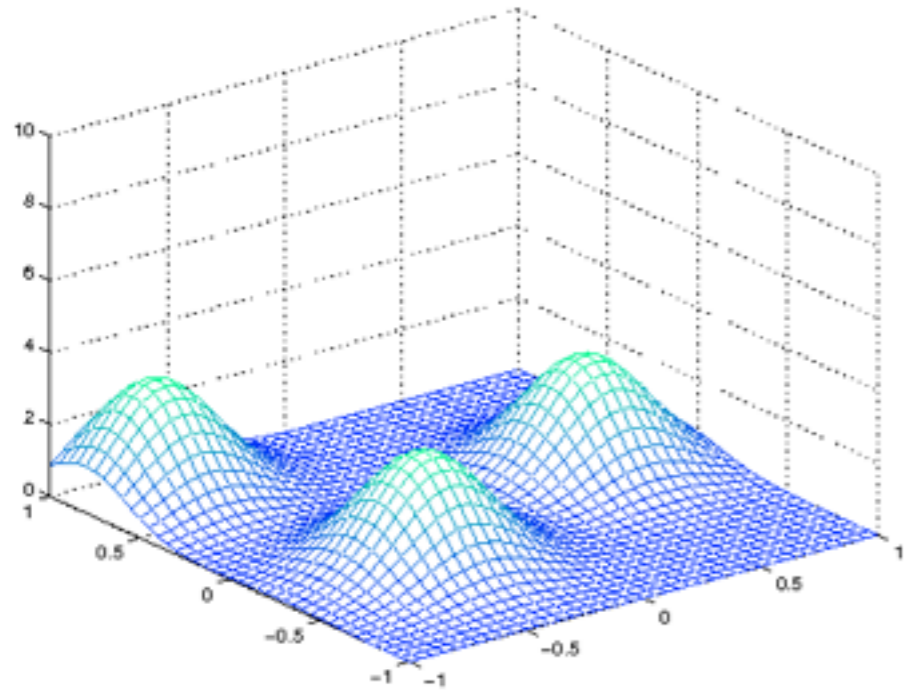


- Variational Bayes (VB)
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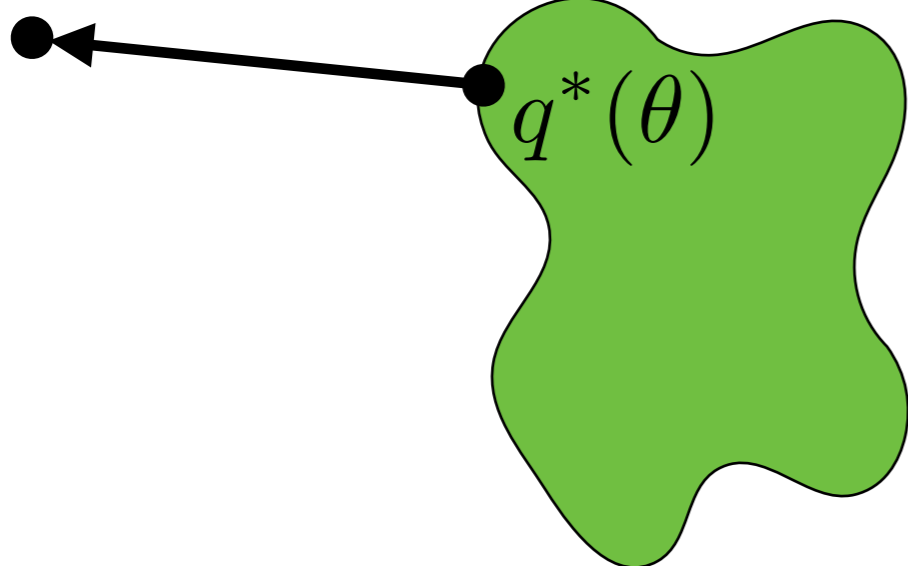


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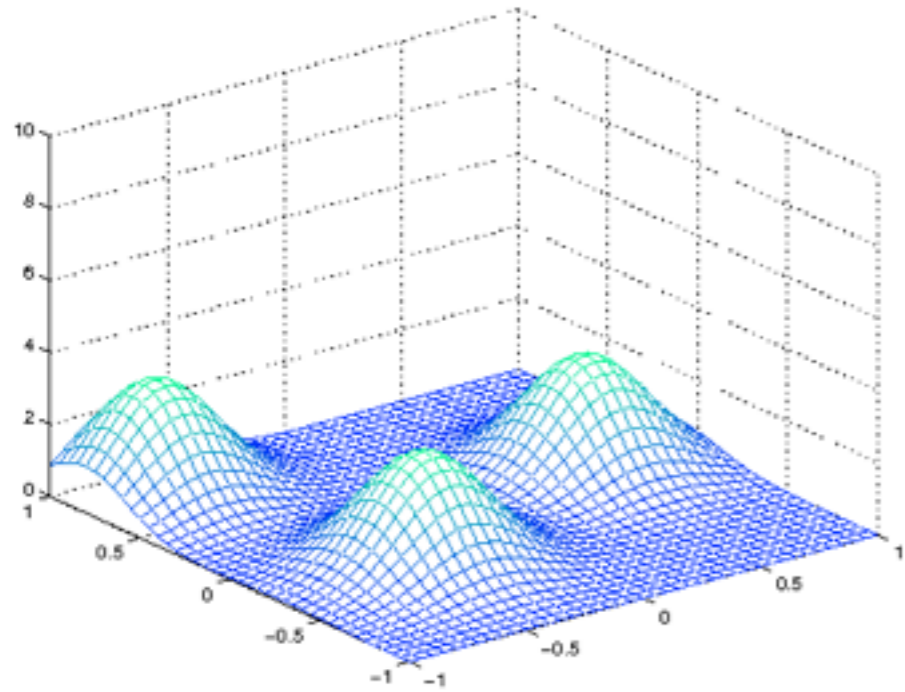


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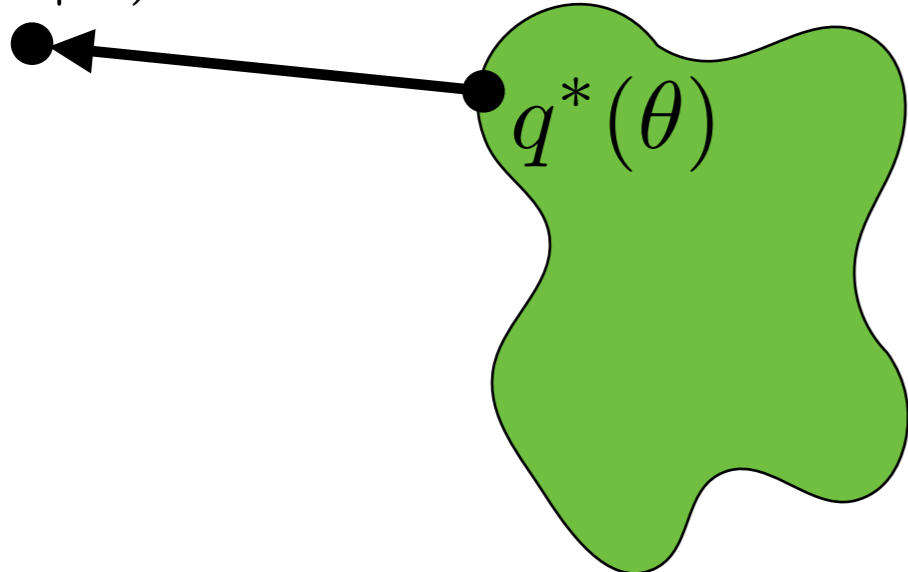


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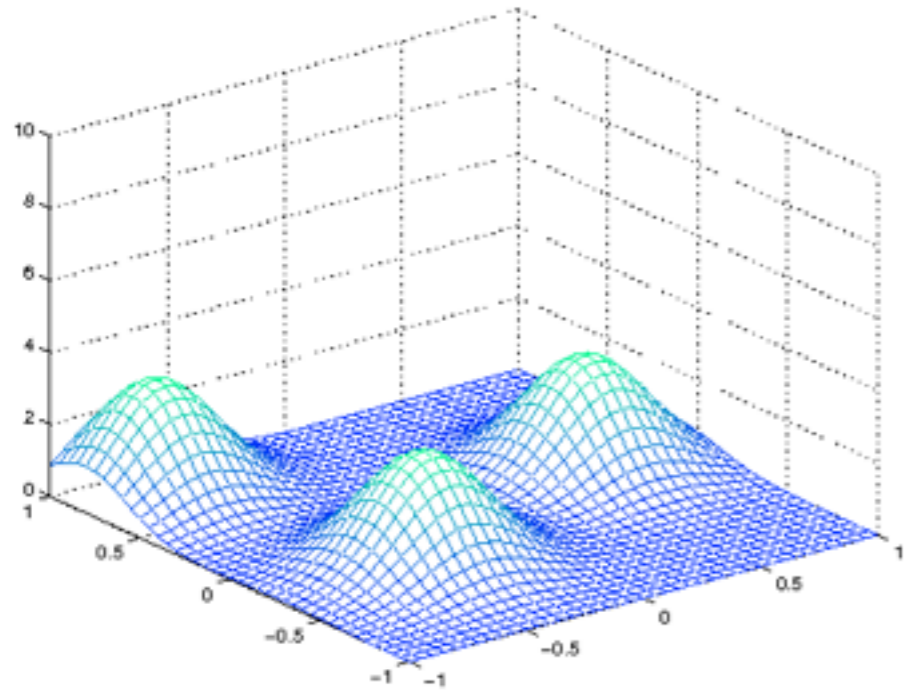


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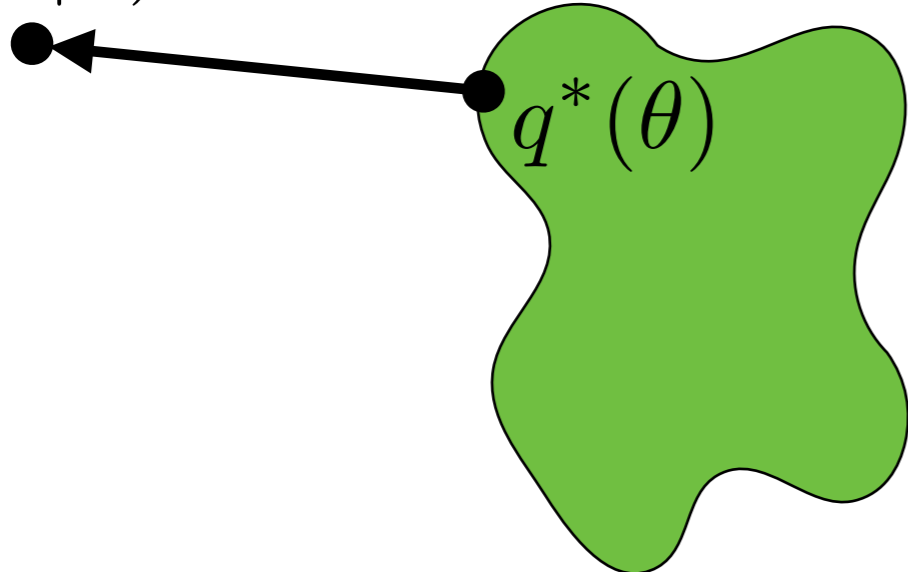
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# Variational Bayes



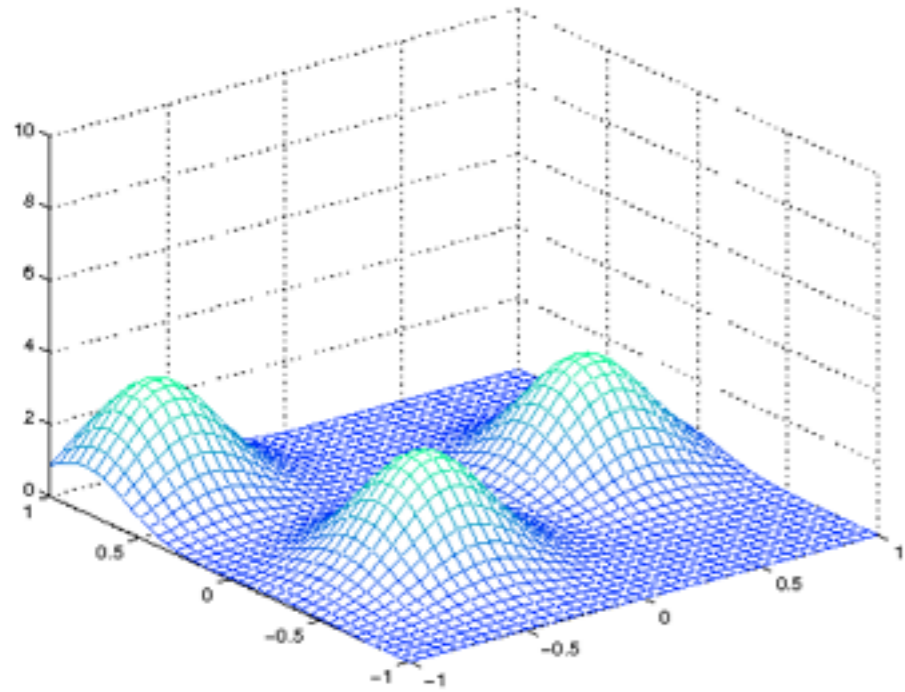
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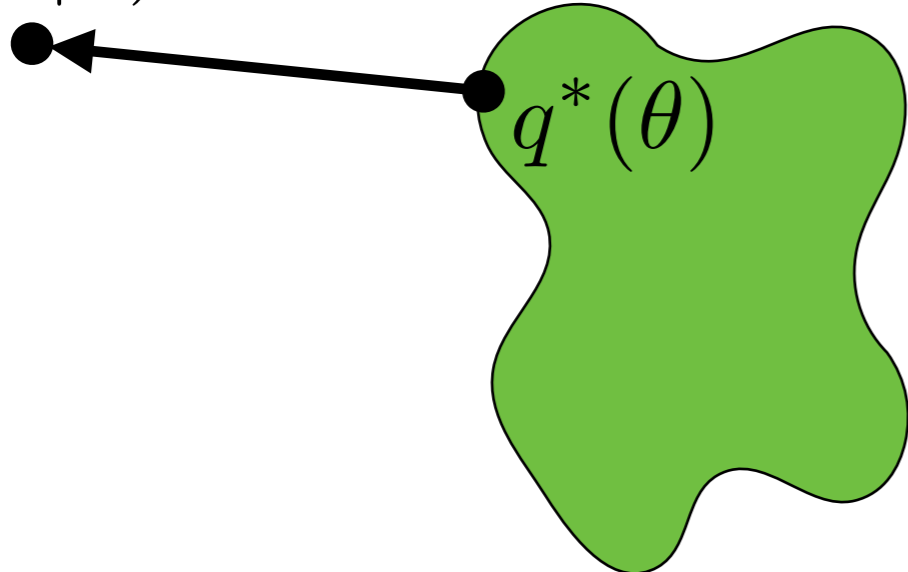
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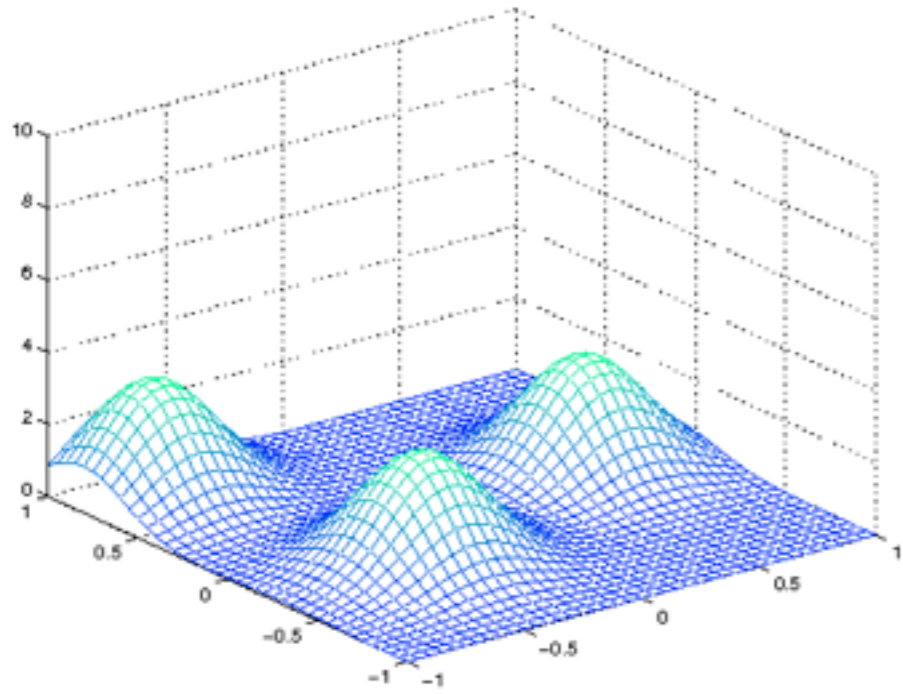


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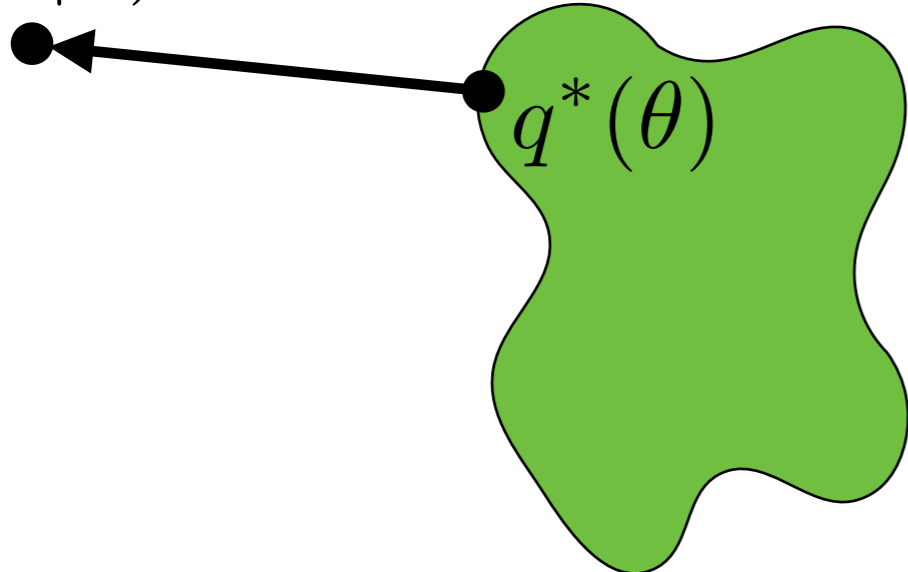


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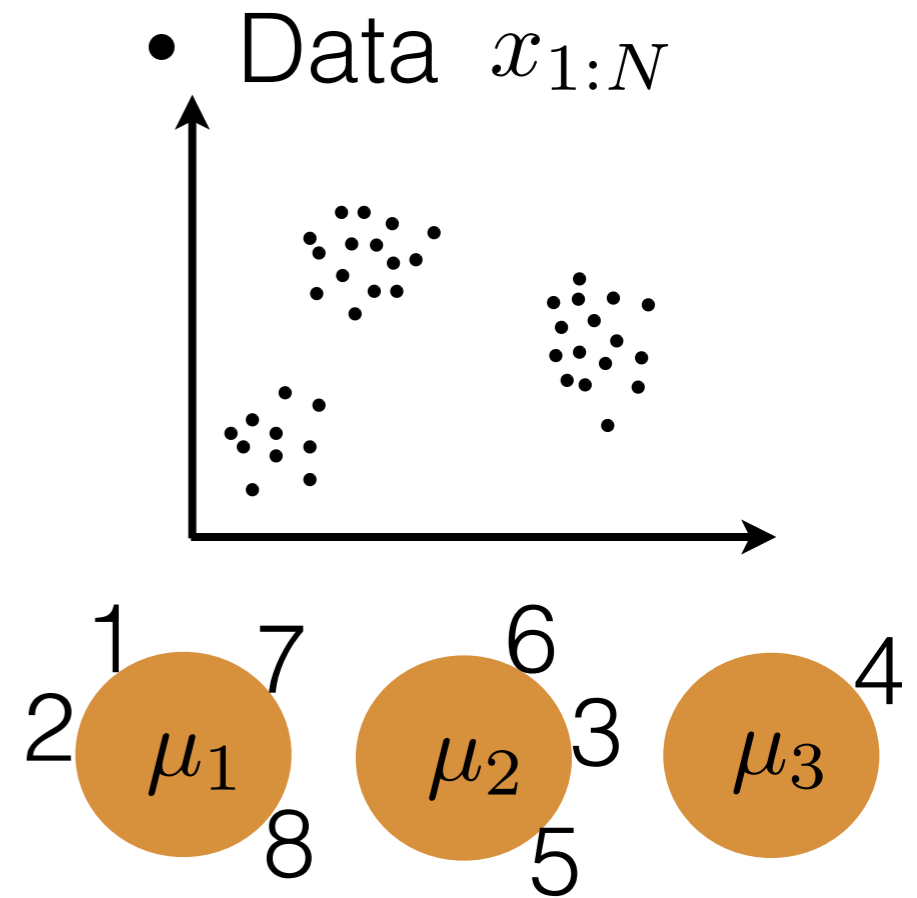


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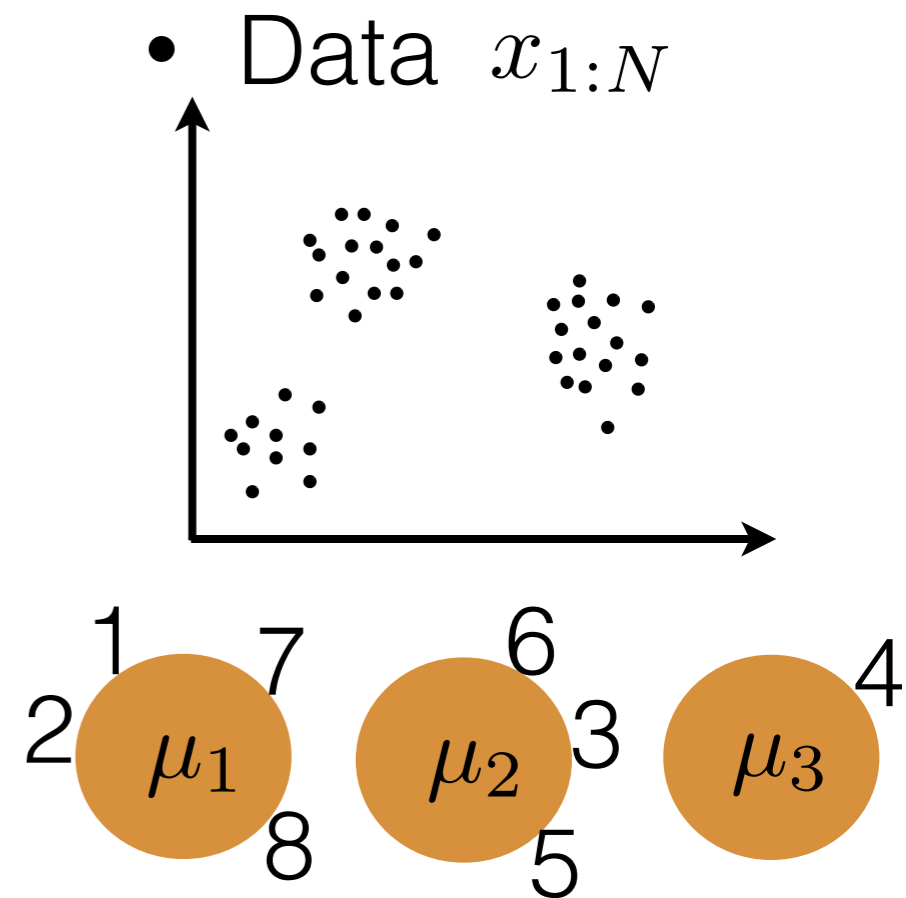
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  - fast, streaming, distributed

# Exercises



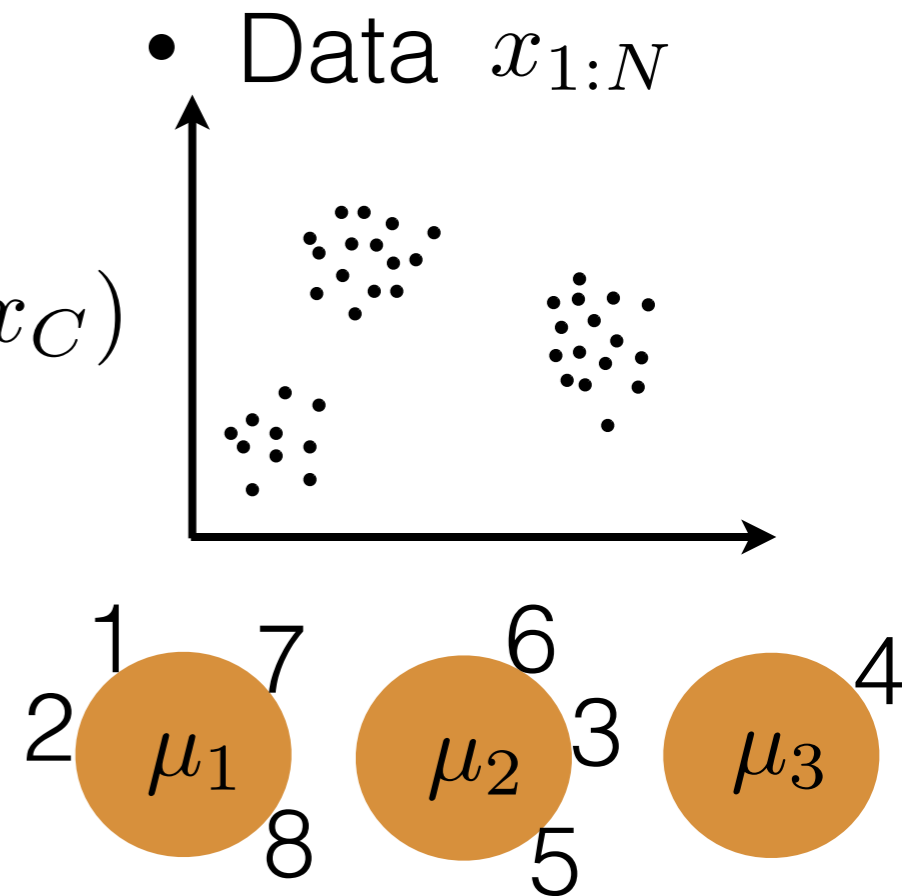
# Exercises

- Code a CRP mixture model simulator



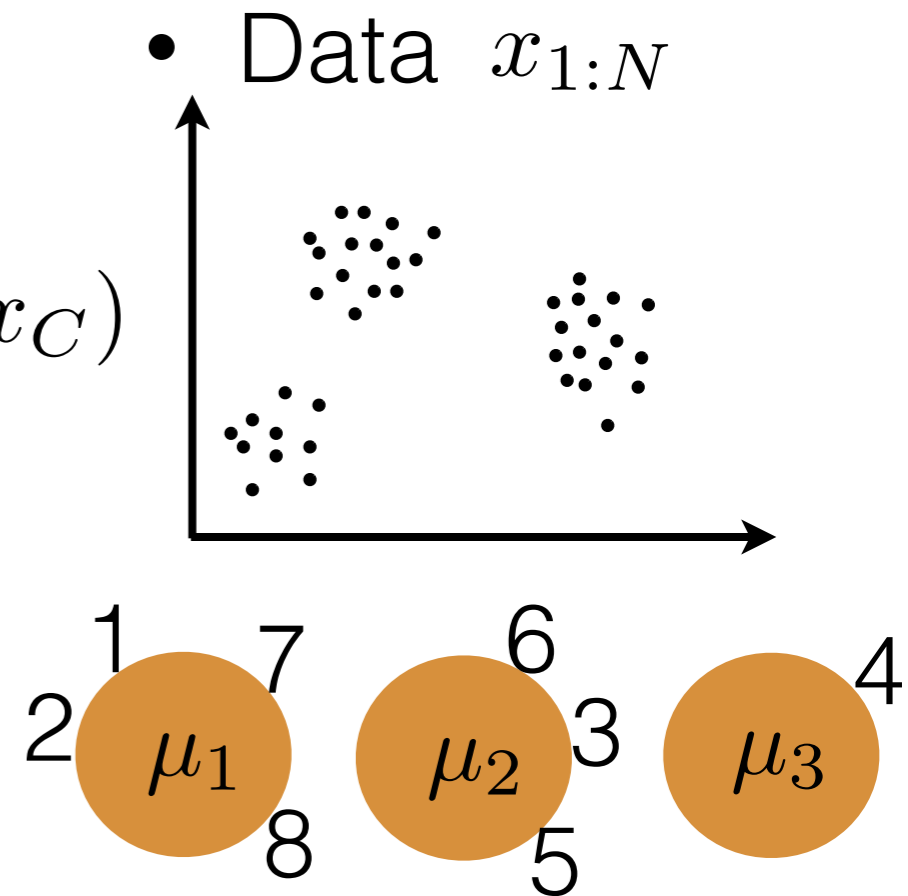
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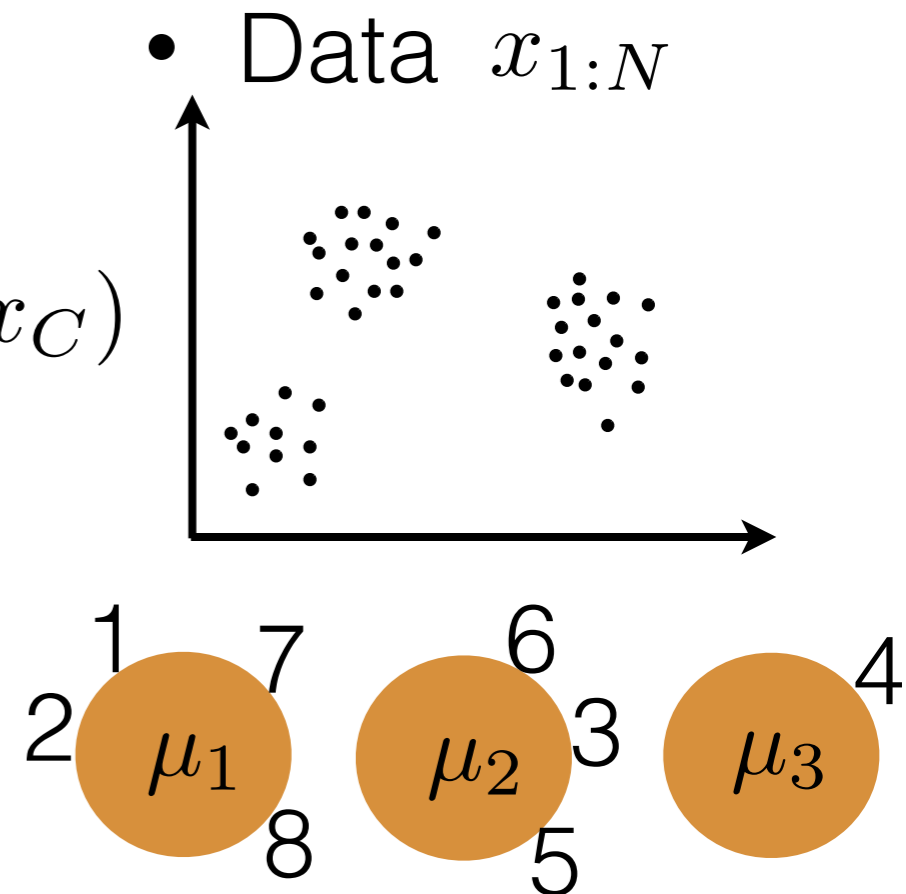
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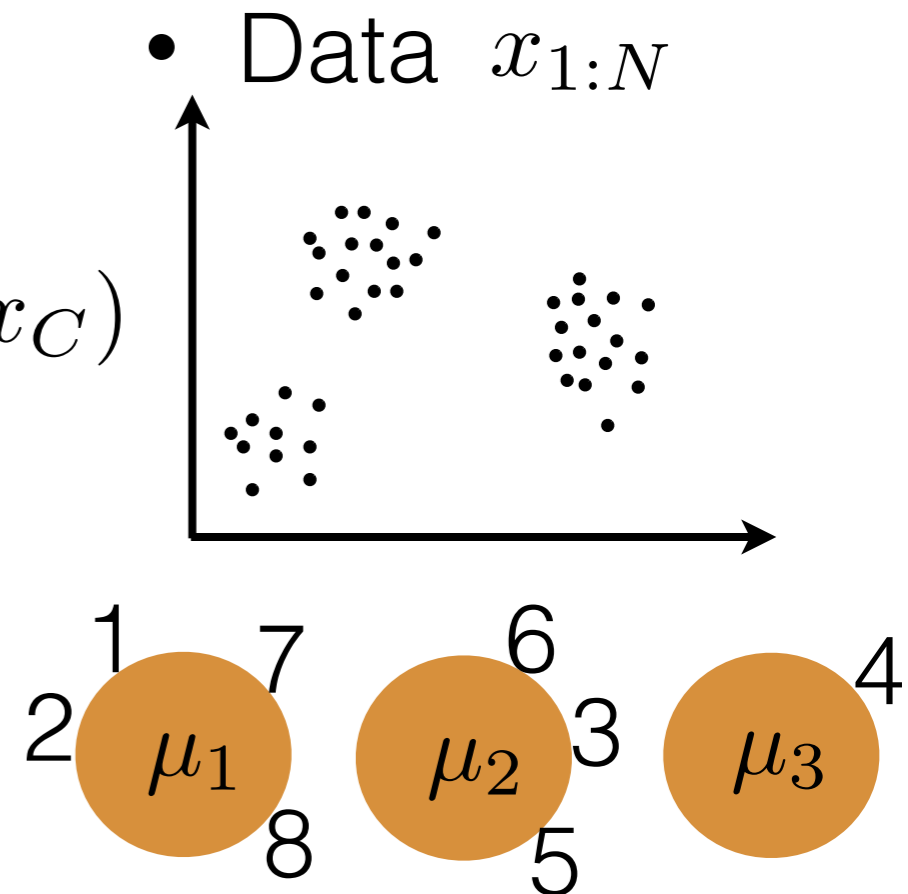
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# Exercises

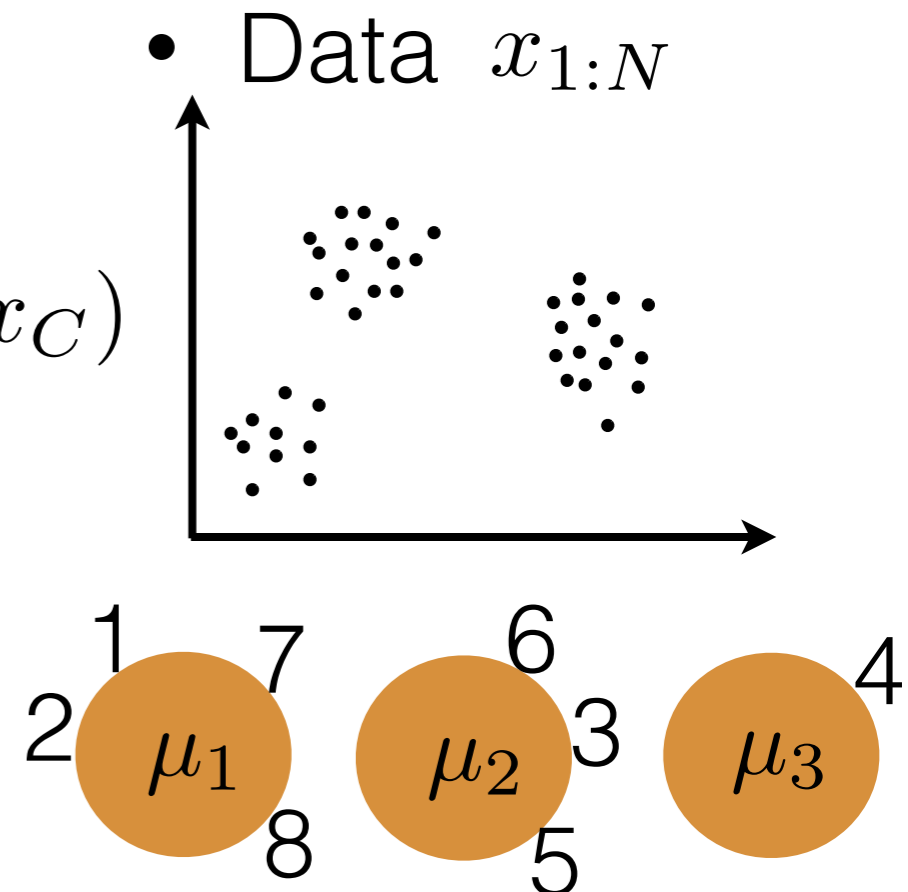
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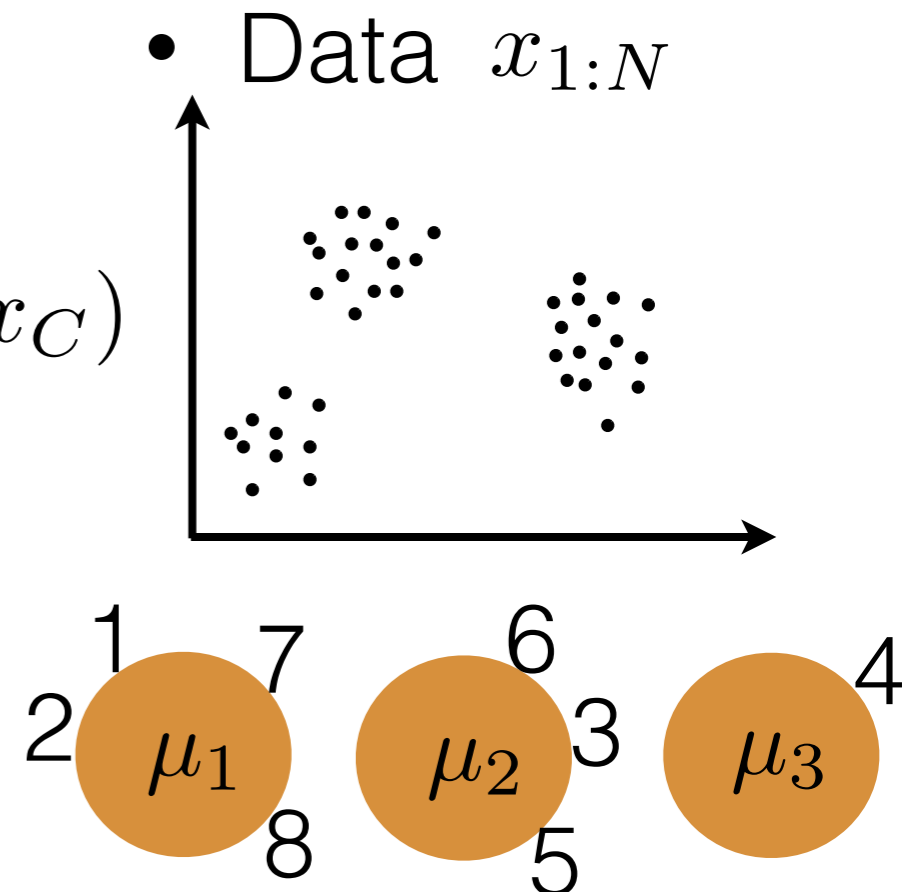
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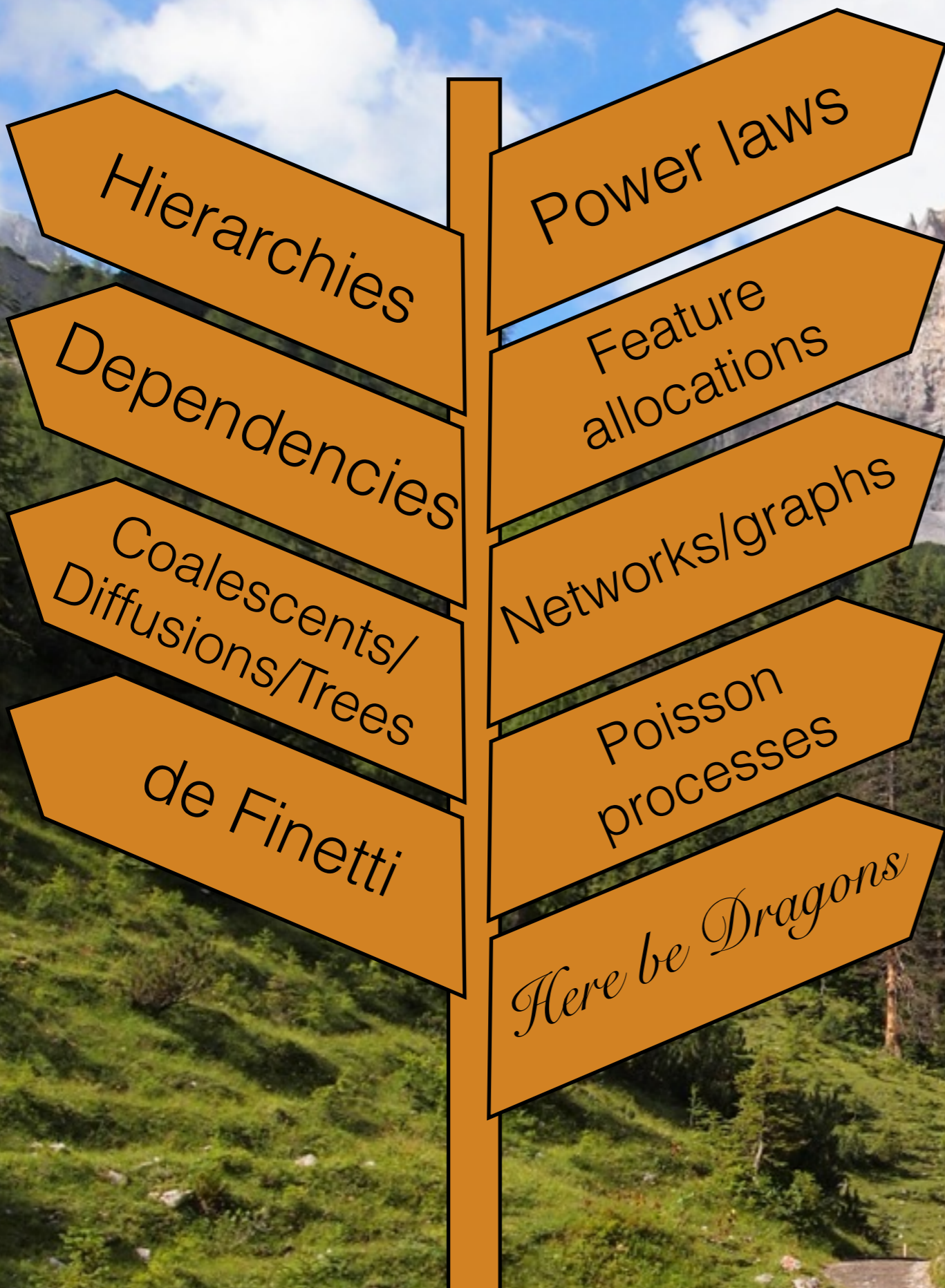
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# Exercises

- Code a CRP mixture model simulator
- Derive the CRP mixture model Gibbs sampler in the slides; derive  $p(x_{C \cup \{n\}} | x_C)$  explicitly for a Gaussian mixture
- Extend the CRP mixture model Gibbs sampler in the slides to sample the cluster-specific parameters as well
- Review Gibbs sampling, slice sampling [Neal 2003], variational Bayes [Bishop 2006]
- Read [Neal 2000] and code a DPMM Gibbs sampler
- Read [Walker 2007; Kalli, Griffin, Walker 2011] and code a DPMM slice sampler
- Read [Blei, Jordan 2006] and code variational inference for the DPMM





# Clustering

	Arts	Econ	Sports	Health	Technology
Document 1	■				
Document 2	■				
Document 3		■			
Document 4			■		
Document 5		■			
Document 6				■	
Document 7	■				

# Feature allocation

	Arts	Econ	Sports	Health	Technology
Document 1	■				■
Document 2	■			■	■
Document 3	■	■		■	■
Document 4			■	■	■
Document 5		■			■
Document 6				■	■
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- Indian buffet process

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- Beta process



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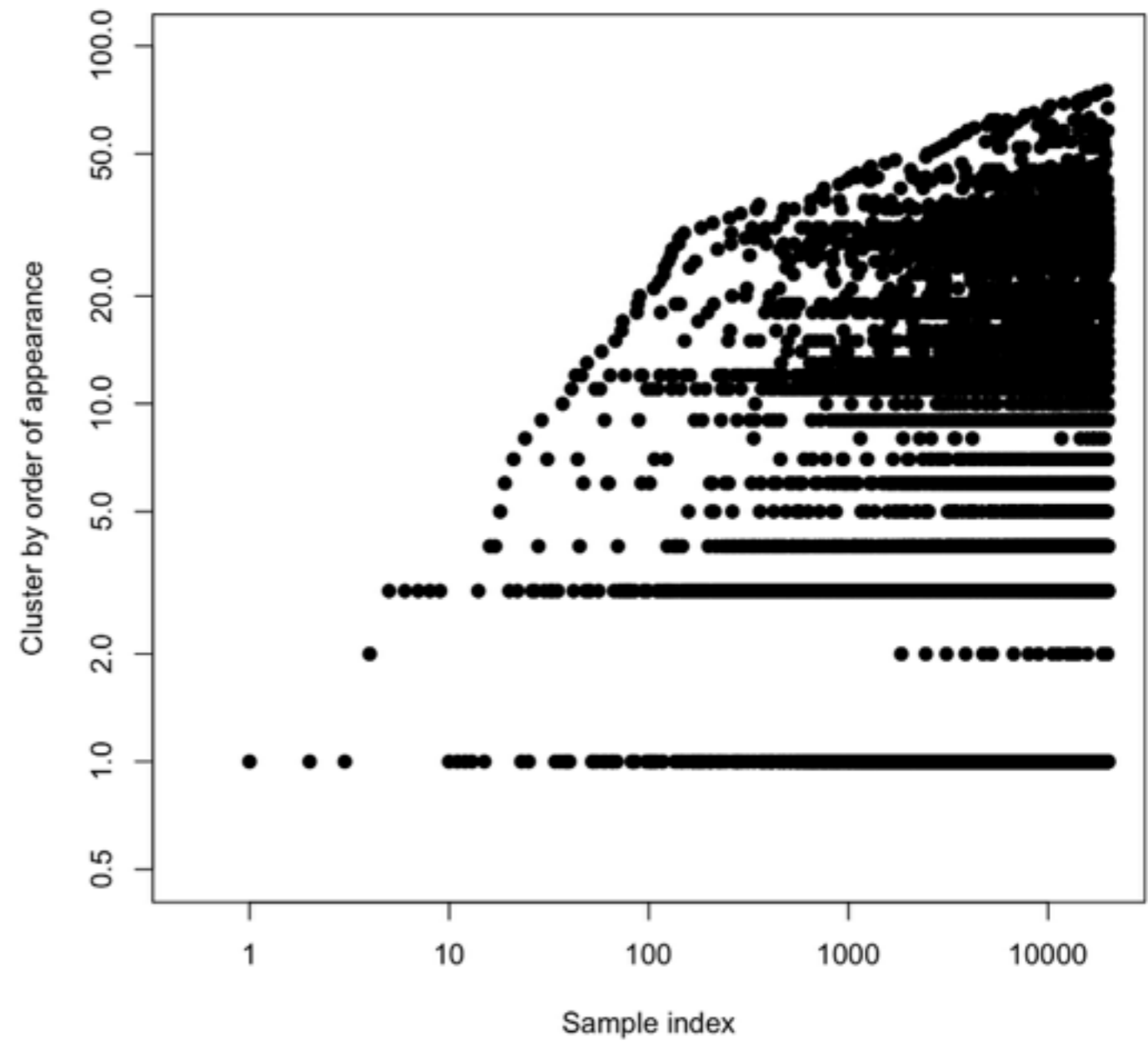
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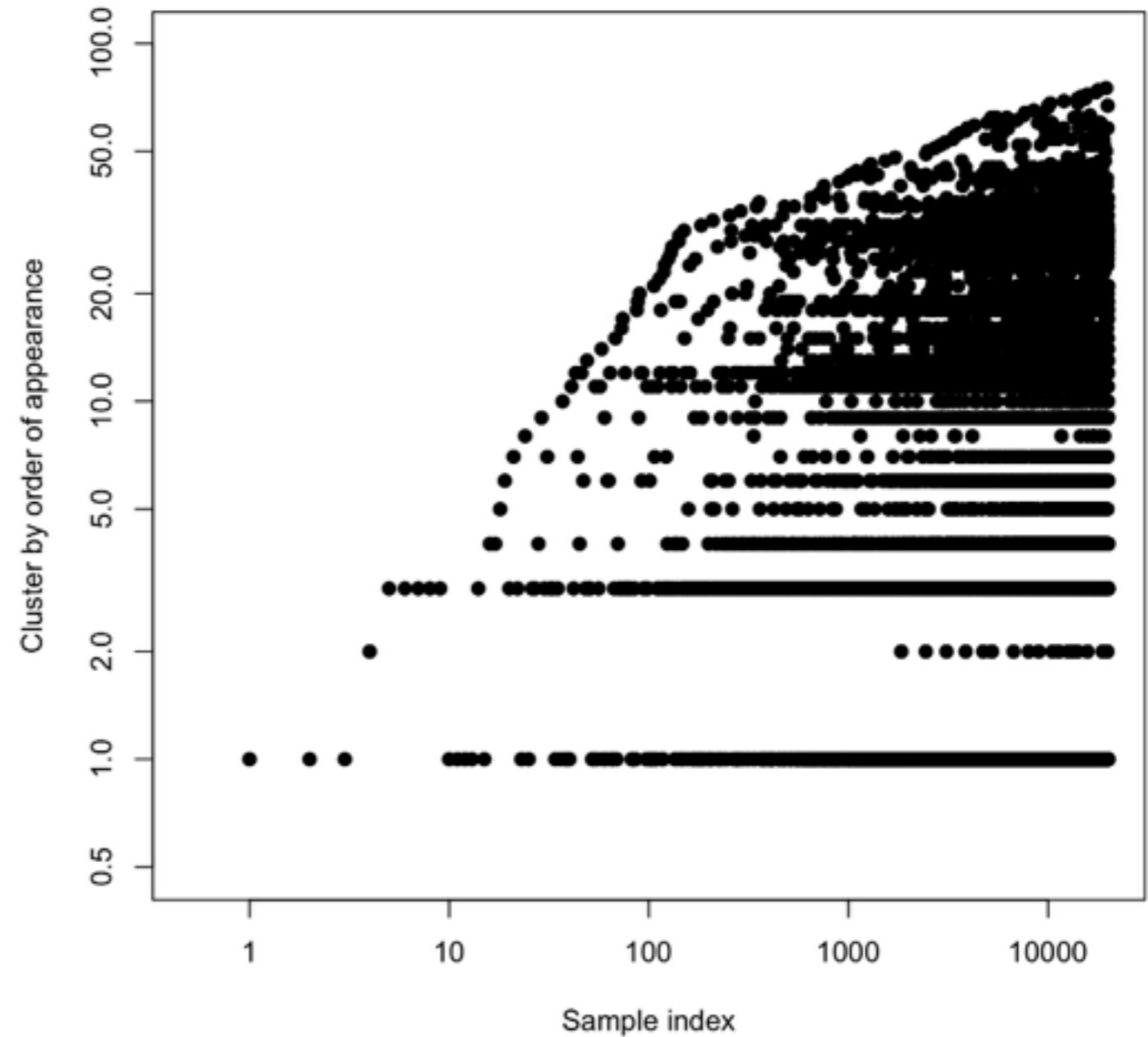
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# Power laws



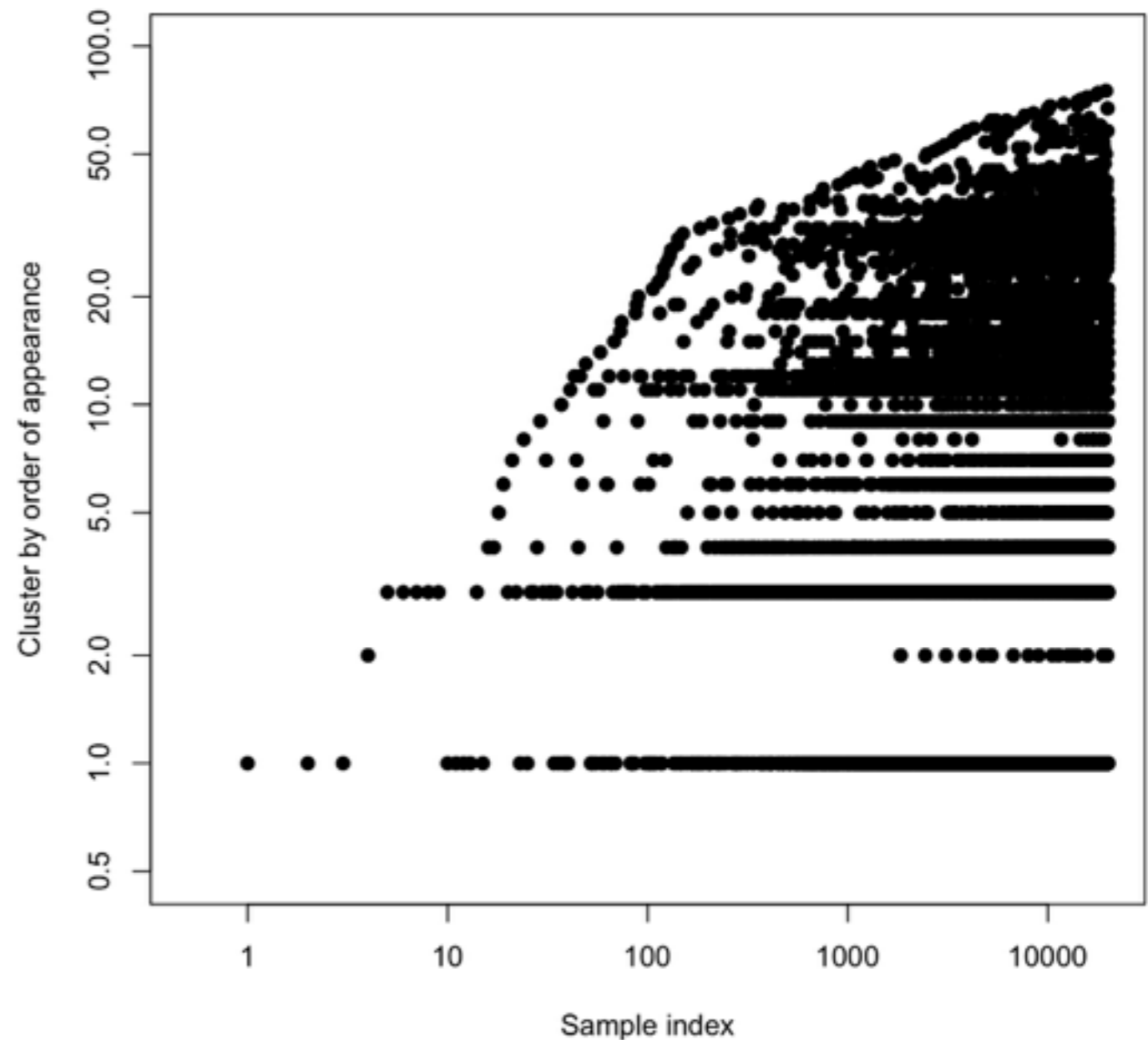
# Power laws

- $K_N := \#$  clusters occupied by  $N$  data points



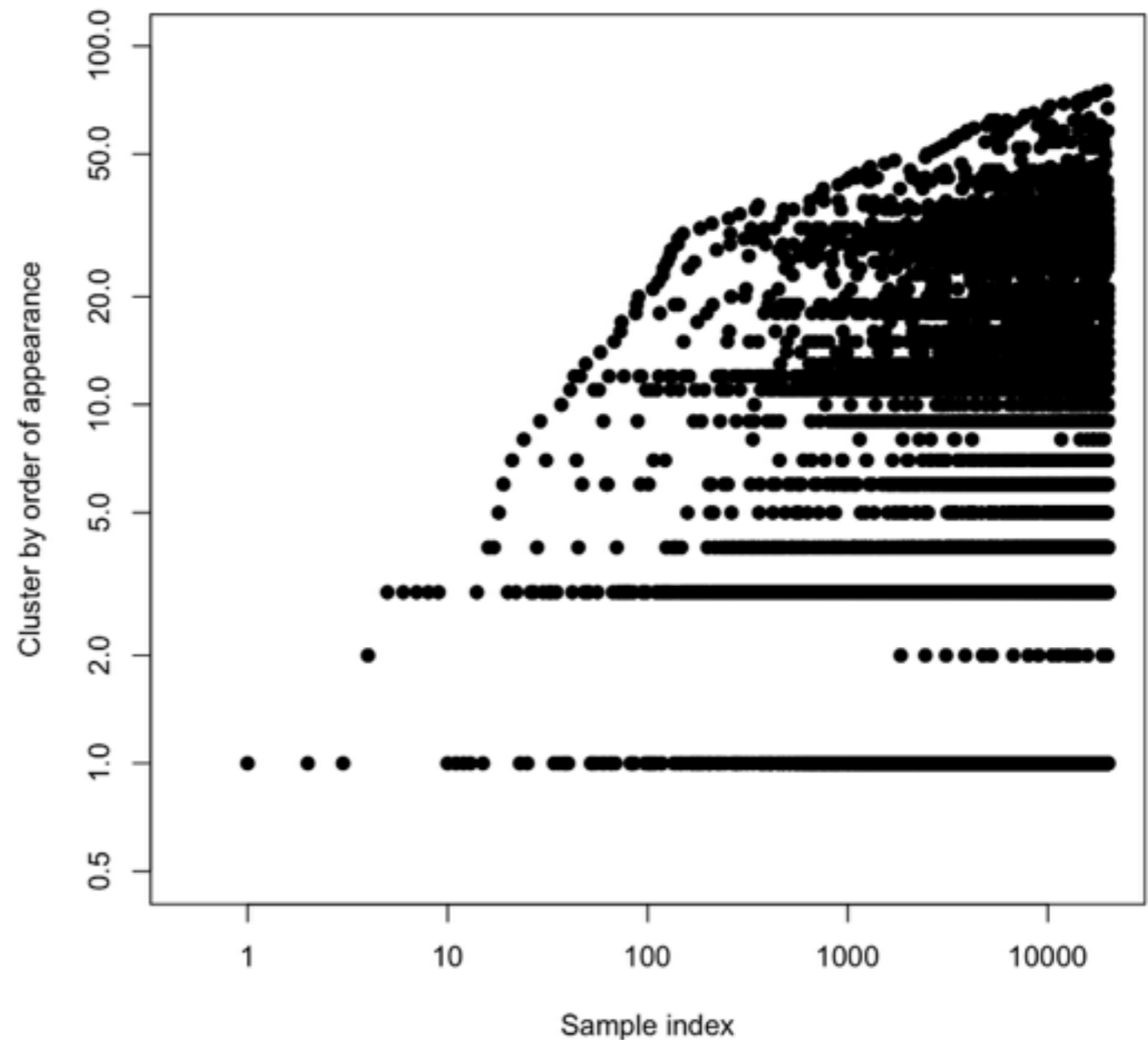
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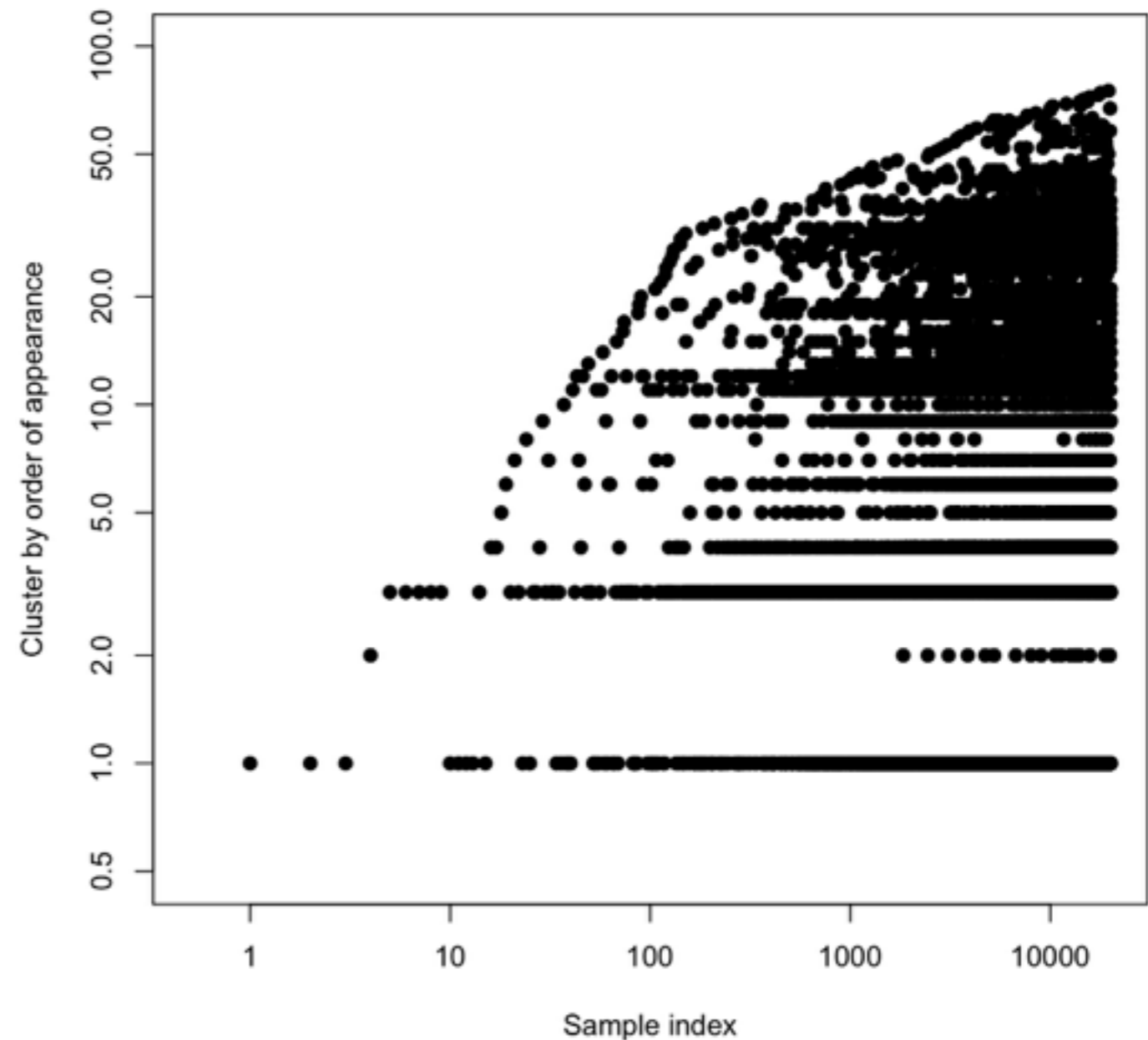
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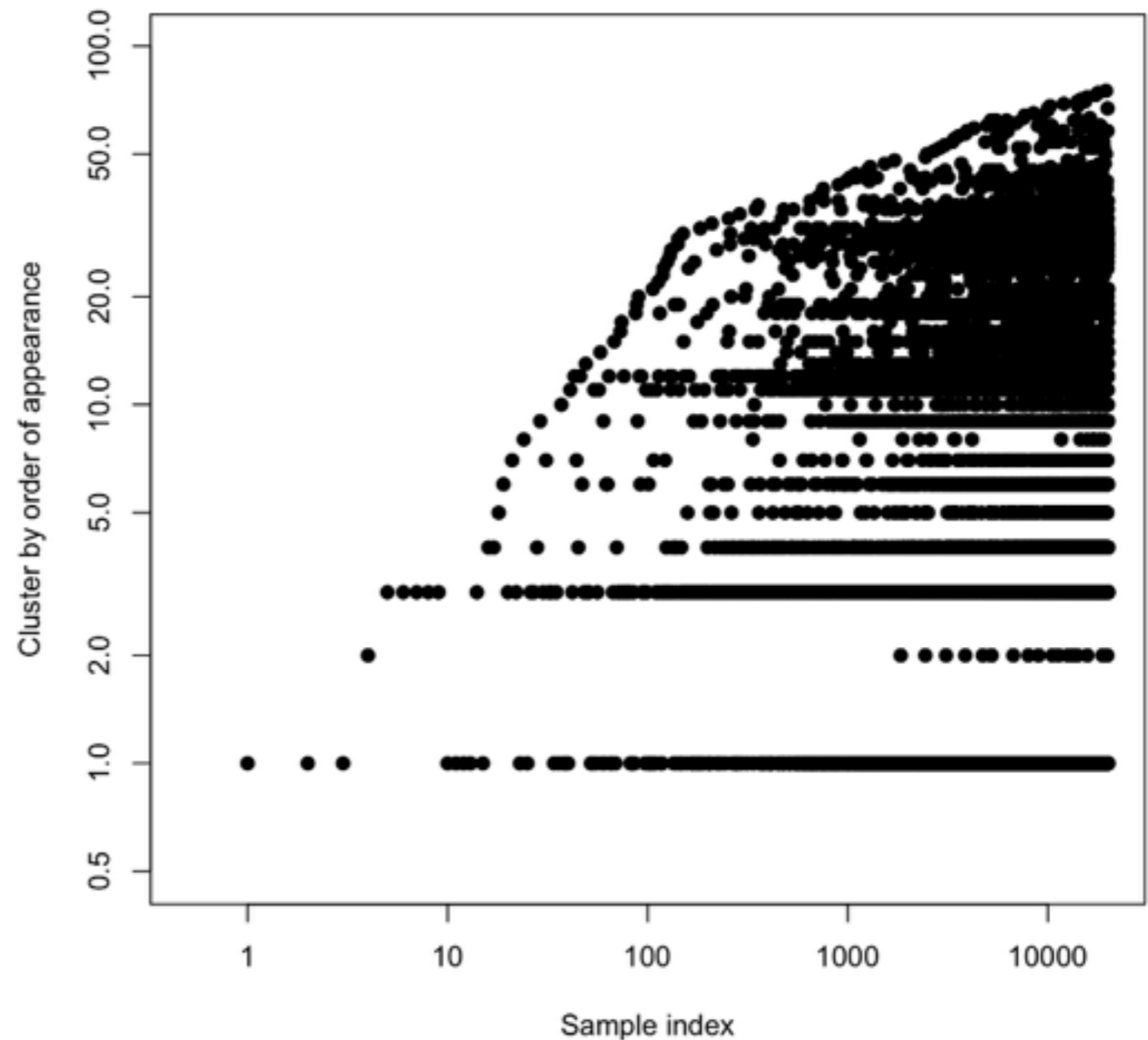
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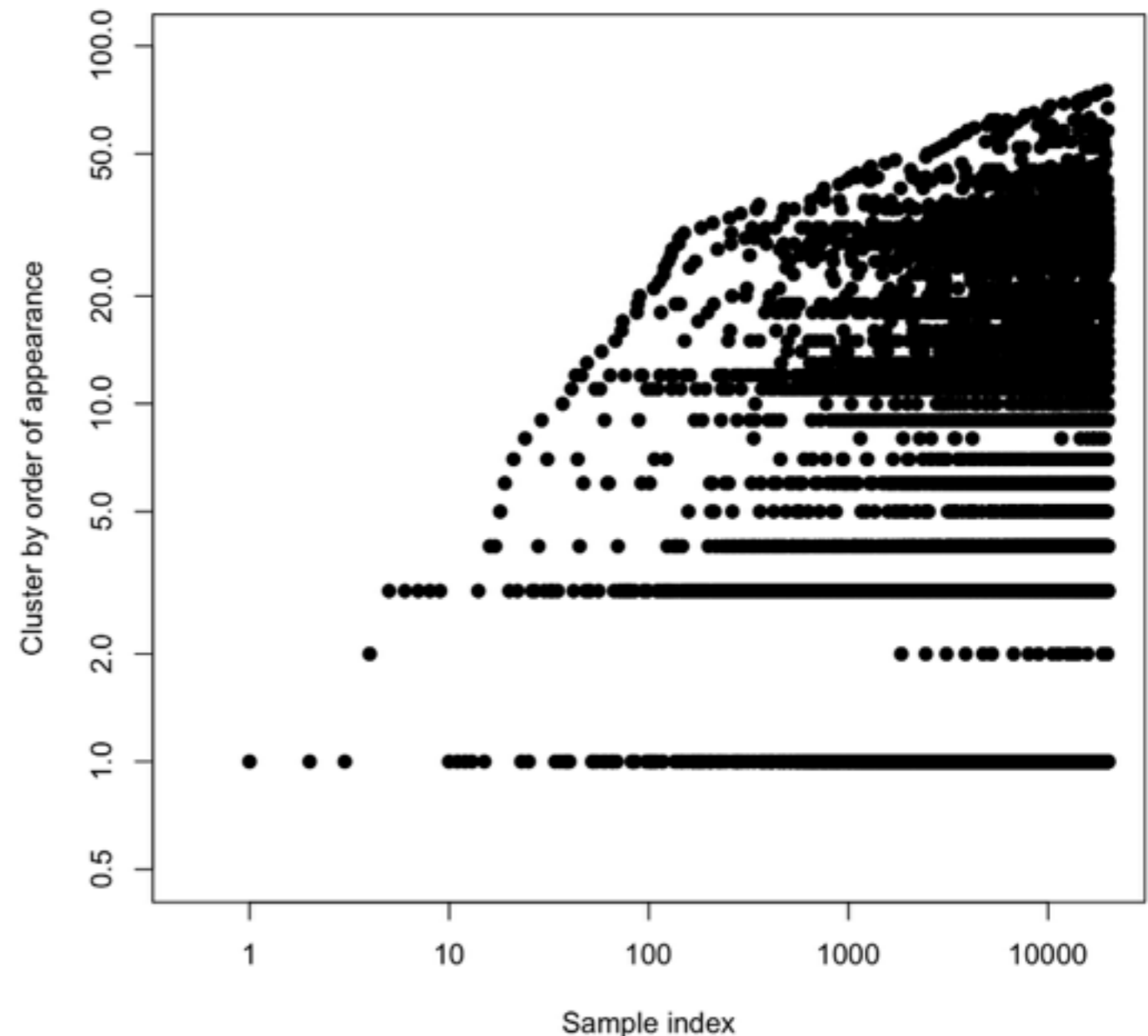
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- Pitman-Yor process:





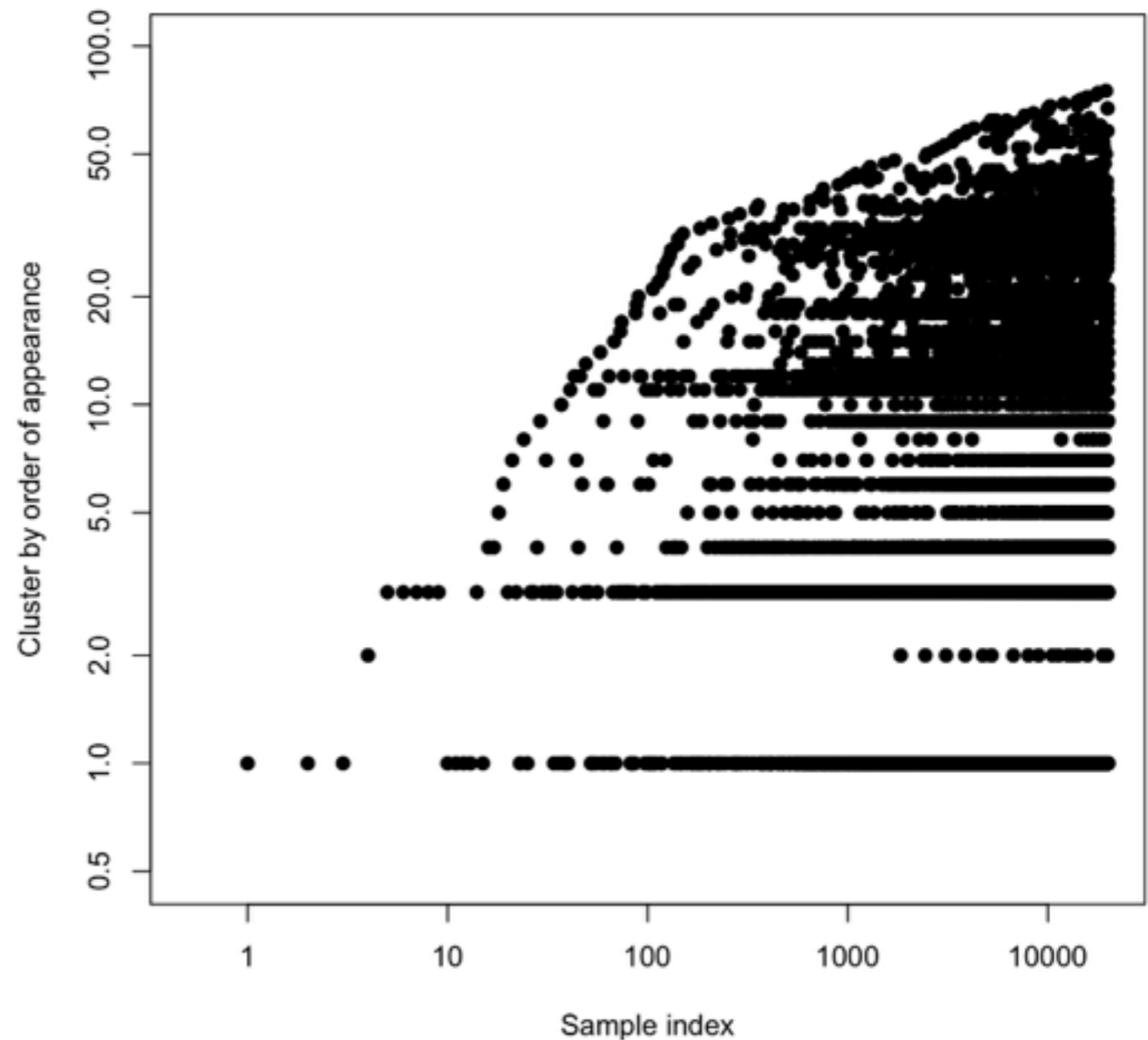
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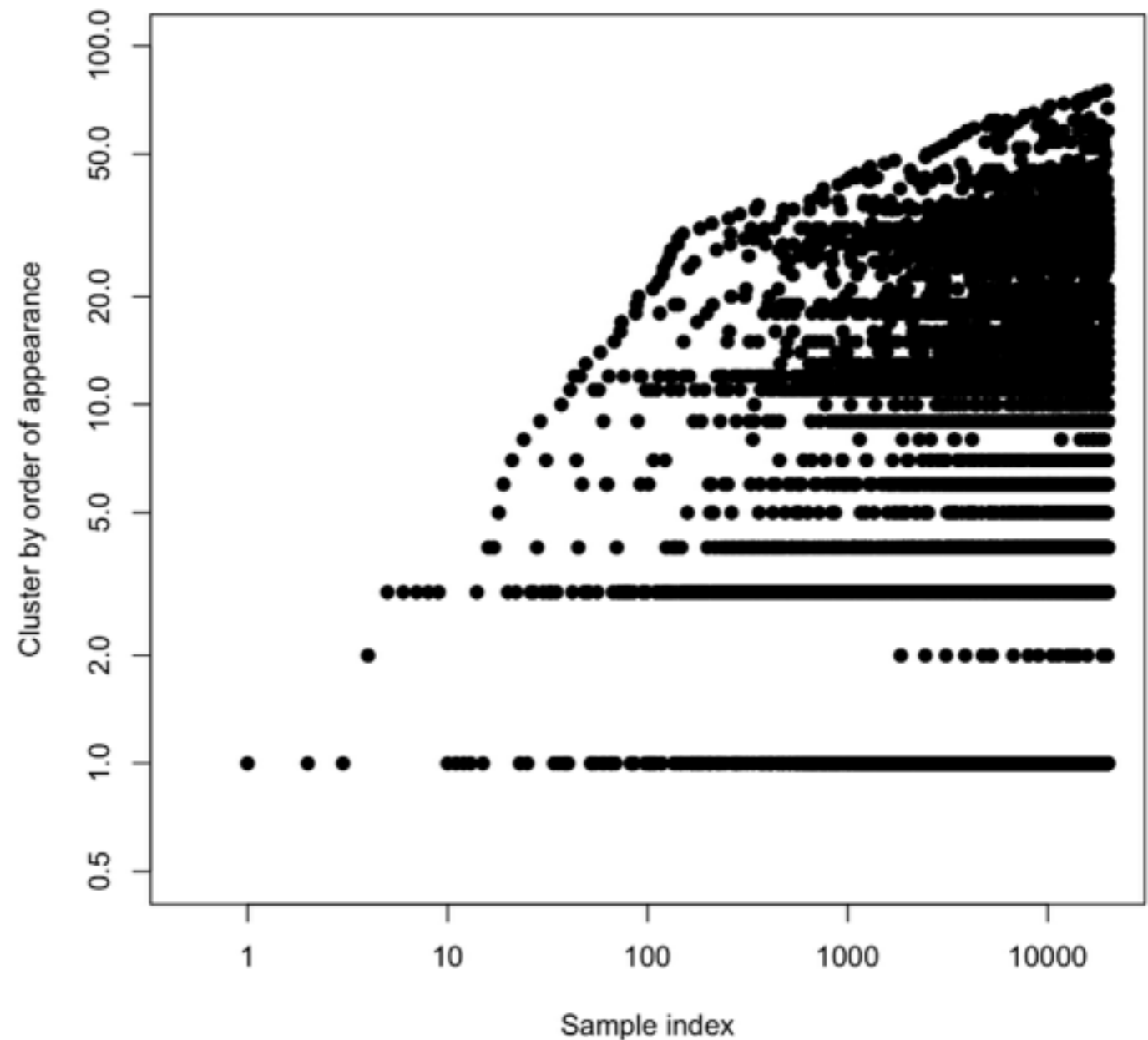
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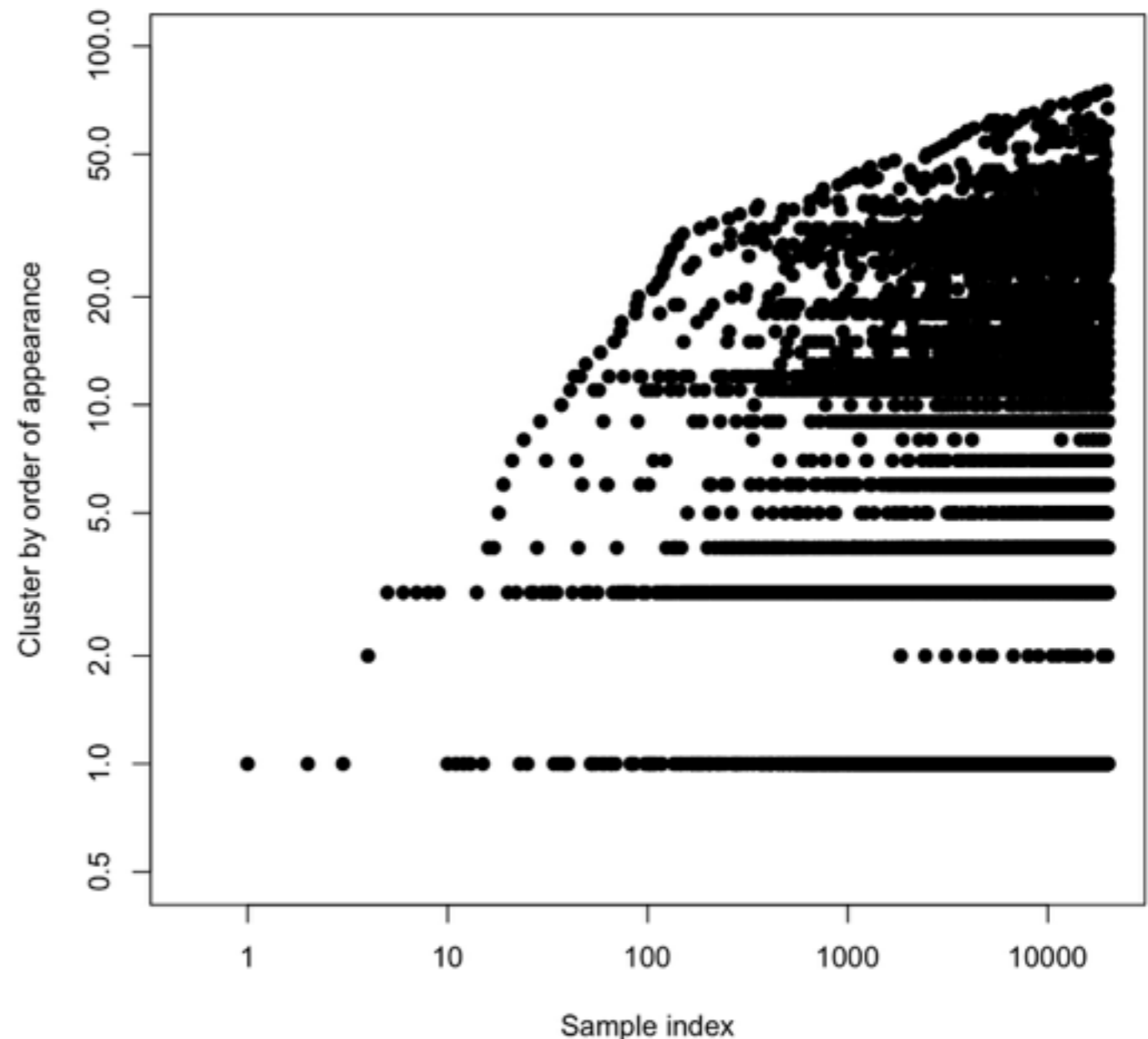
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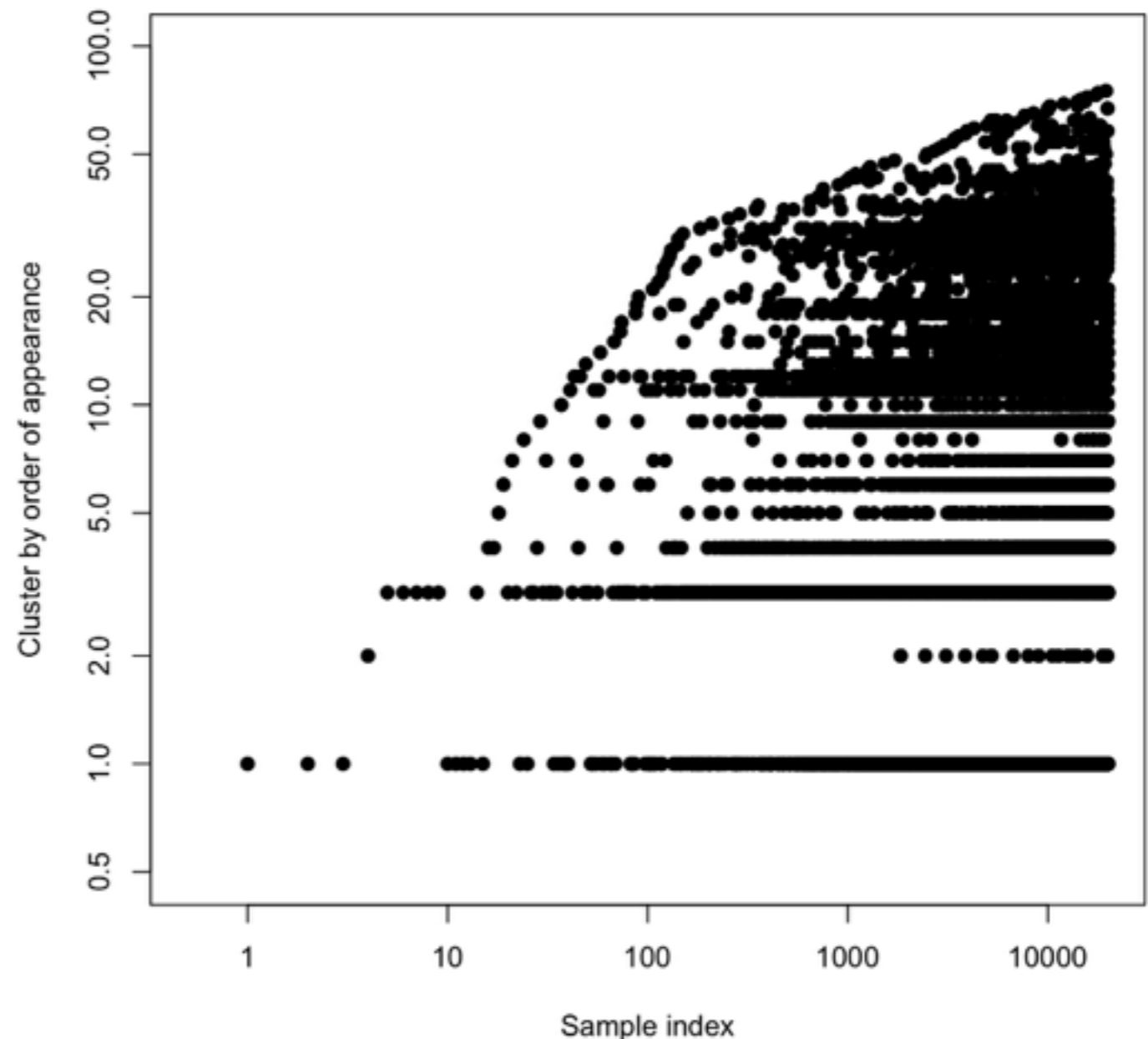
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  - related to Zipf's law (ranked frequencies)
- Not just clusters



# Hierarchies

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- Hierarchical Dirichlet process

# Hierarchies

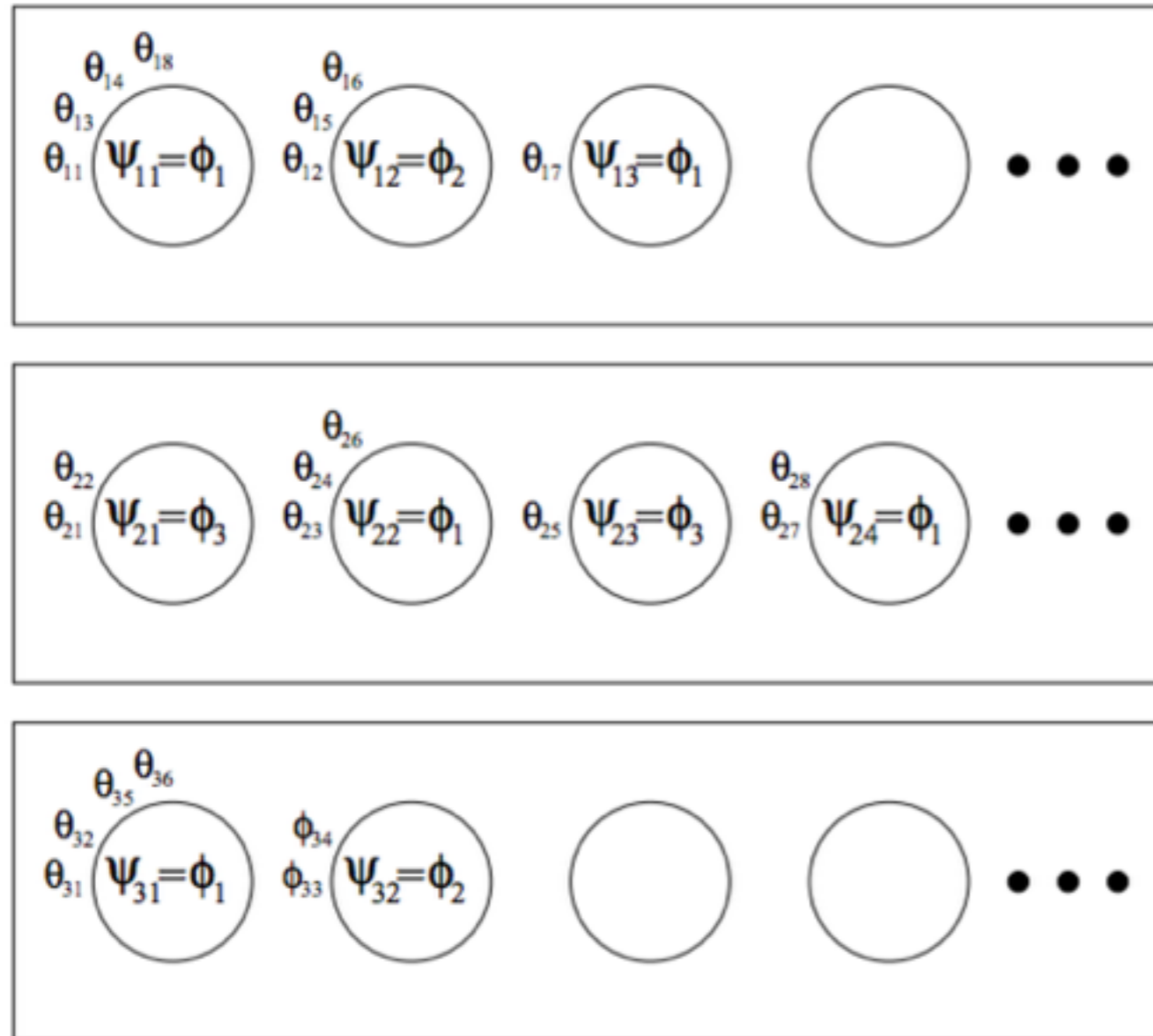
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# Hierarchies

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- Chinese restaurant franchise

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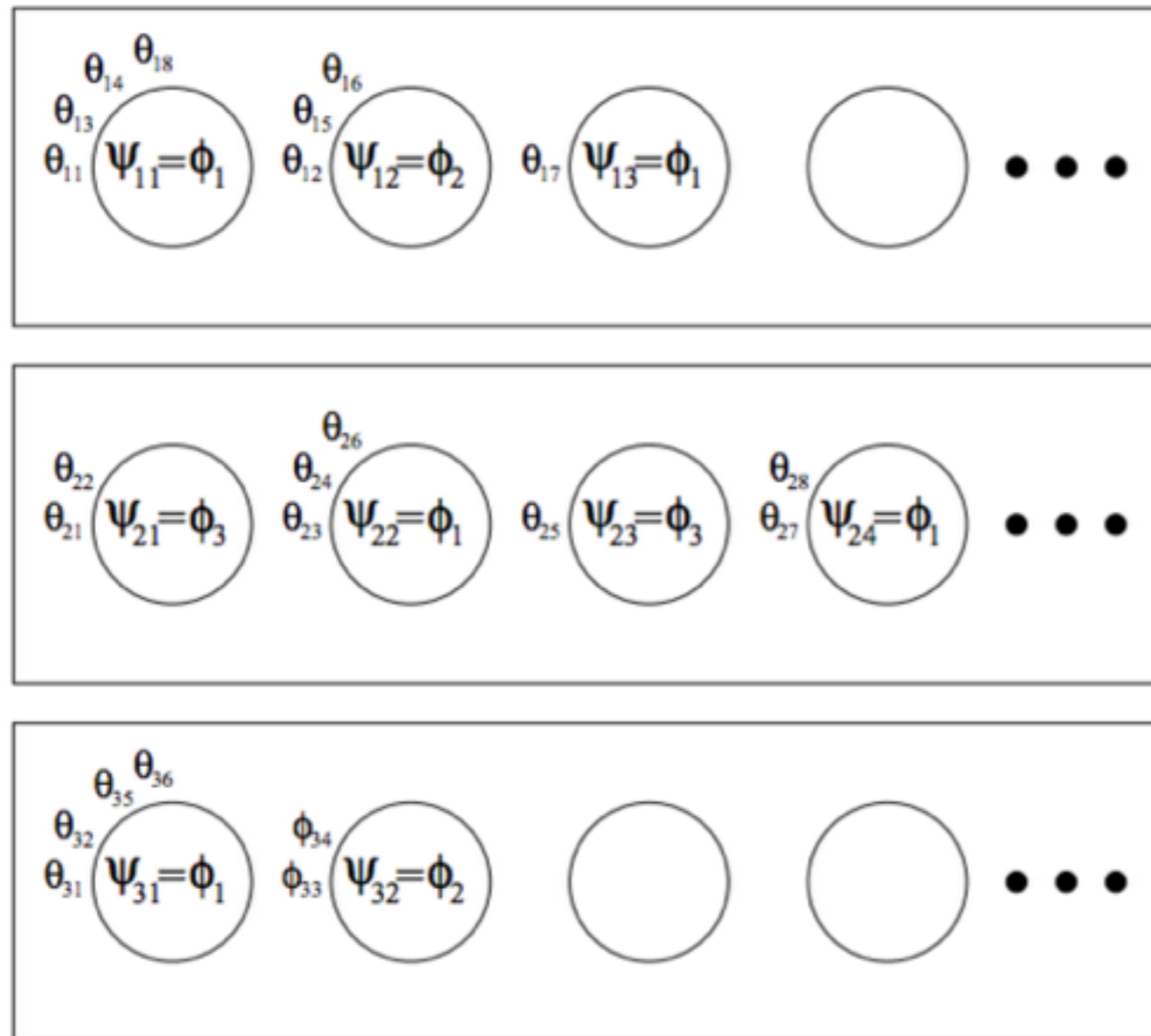


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[Teh et al 2006]

[Teh et al 2006, Rodríguez et al 2008]

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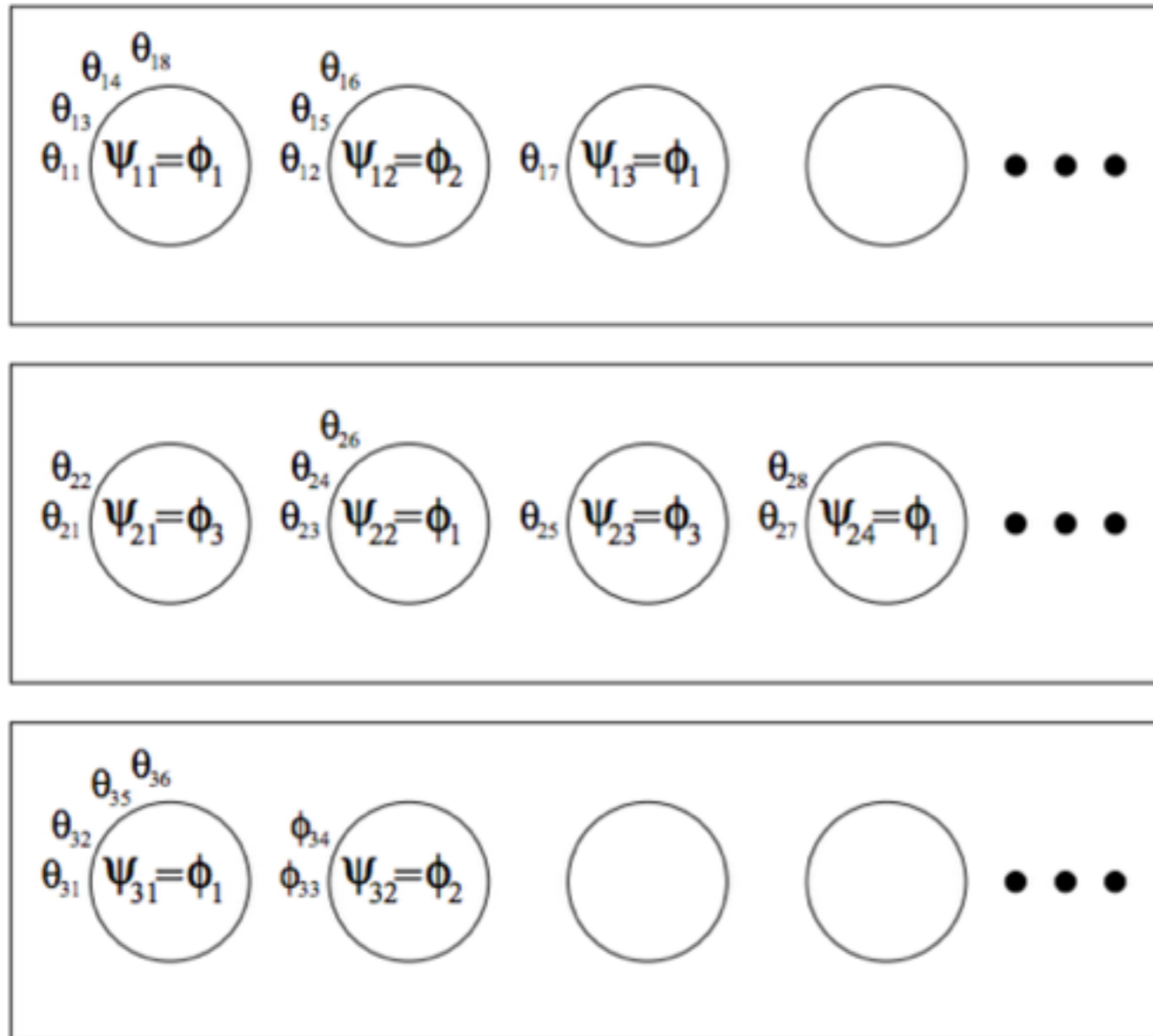


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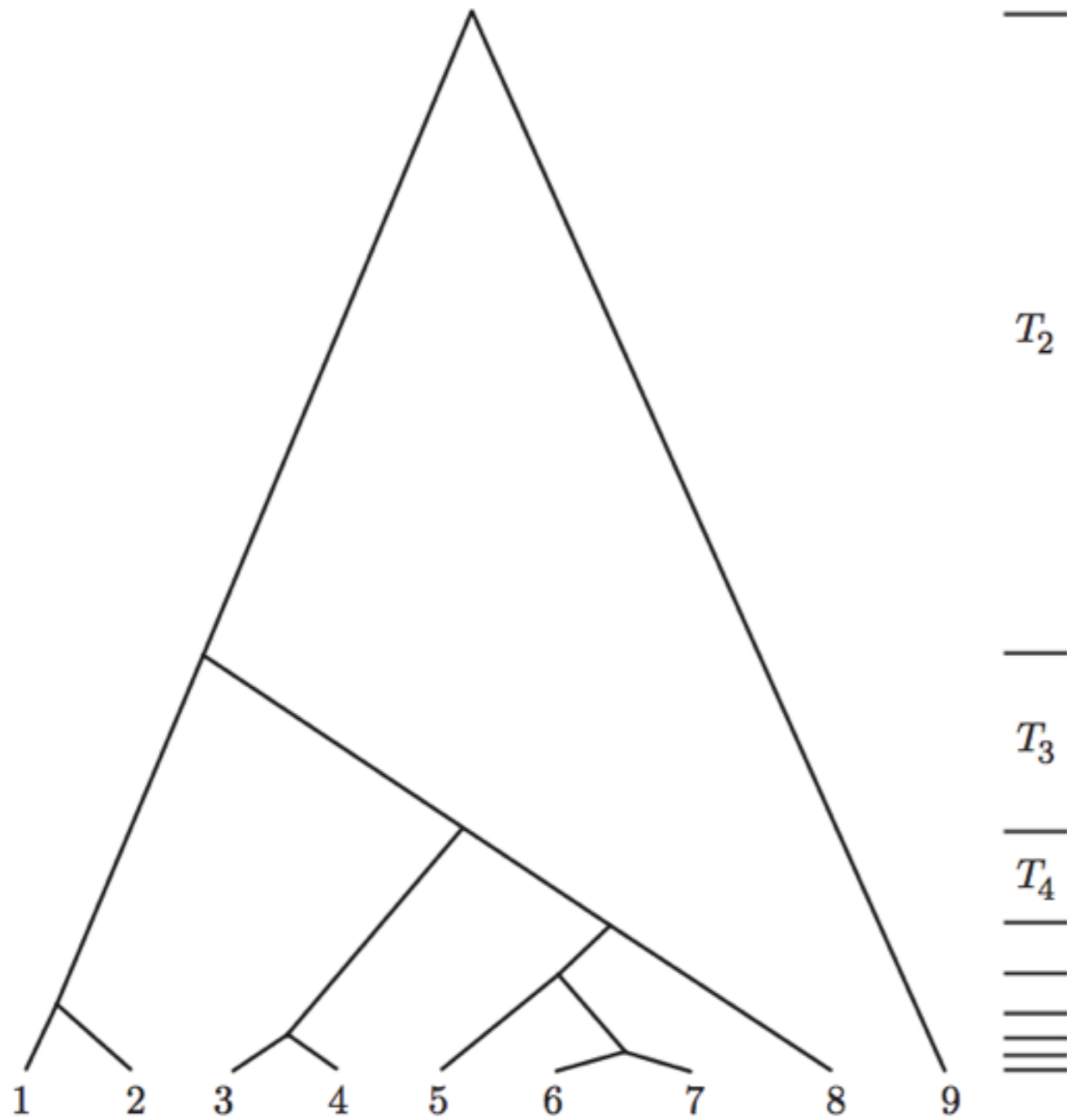
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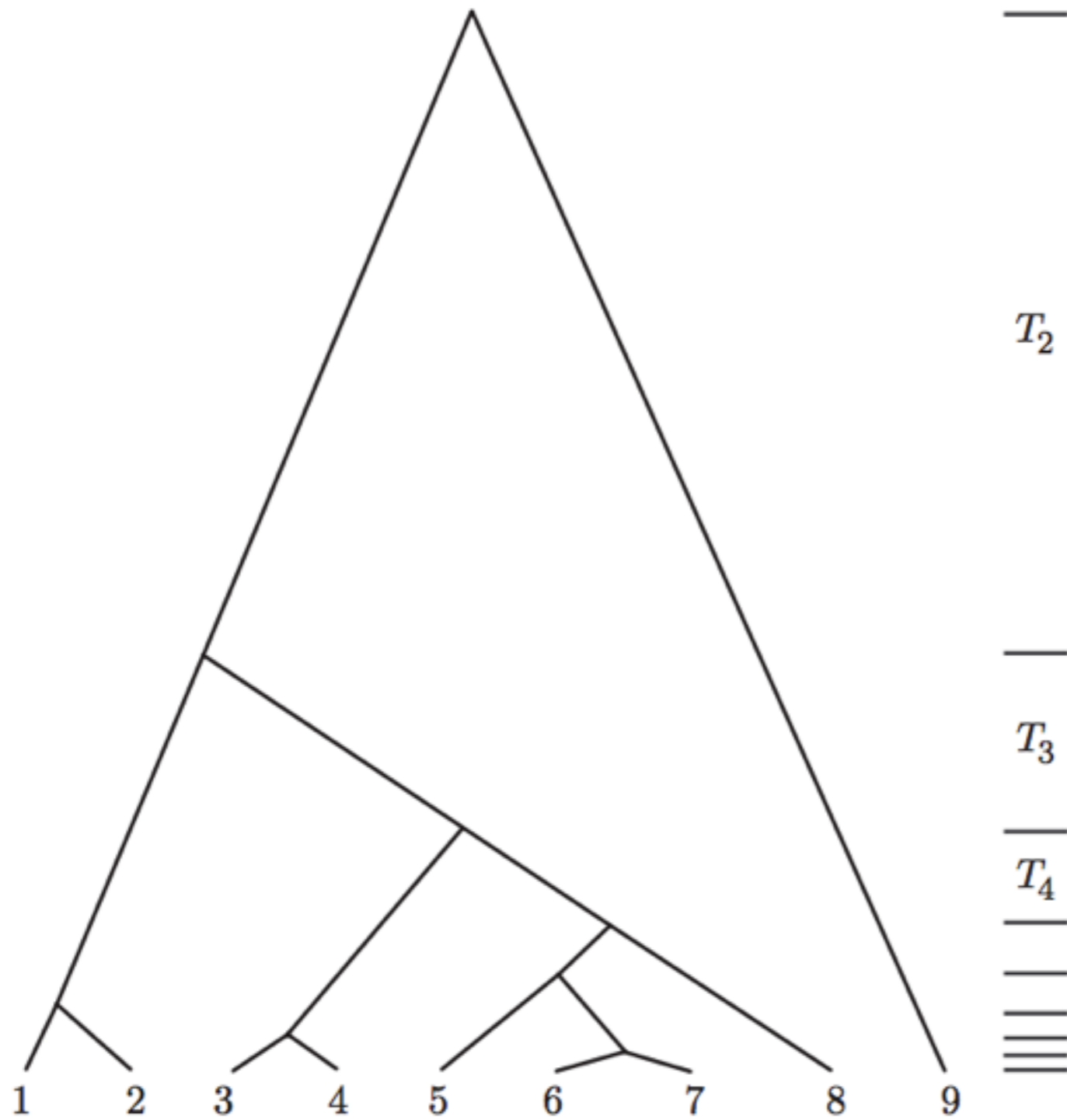
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# Genealogy, trees, beyond trees



[Wakeley 2008]

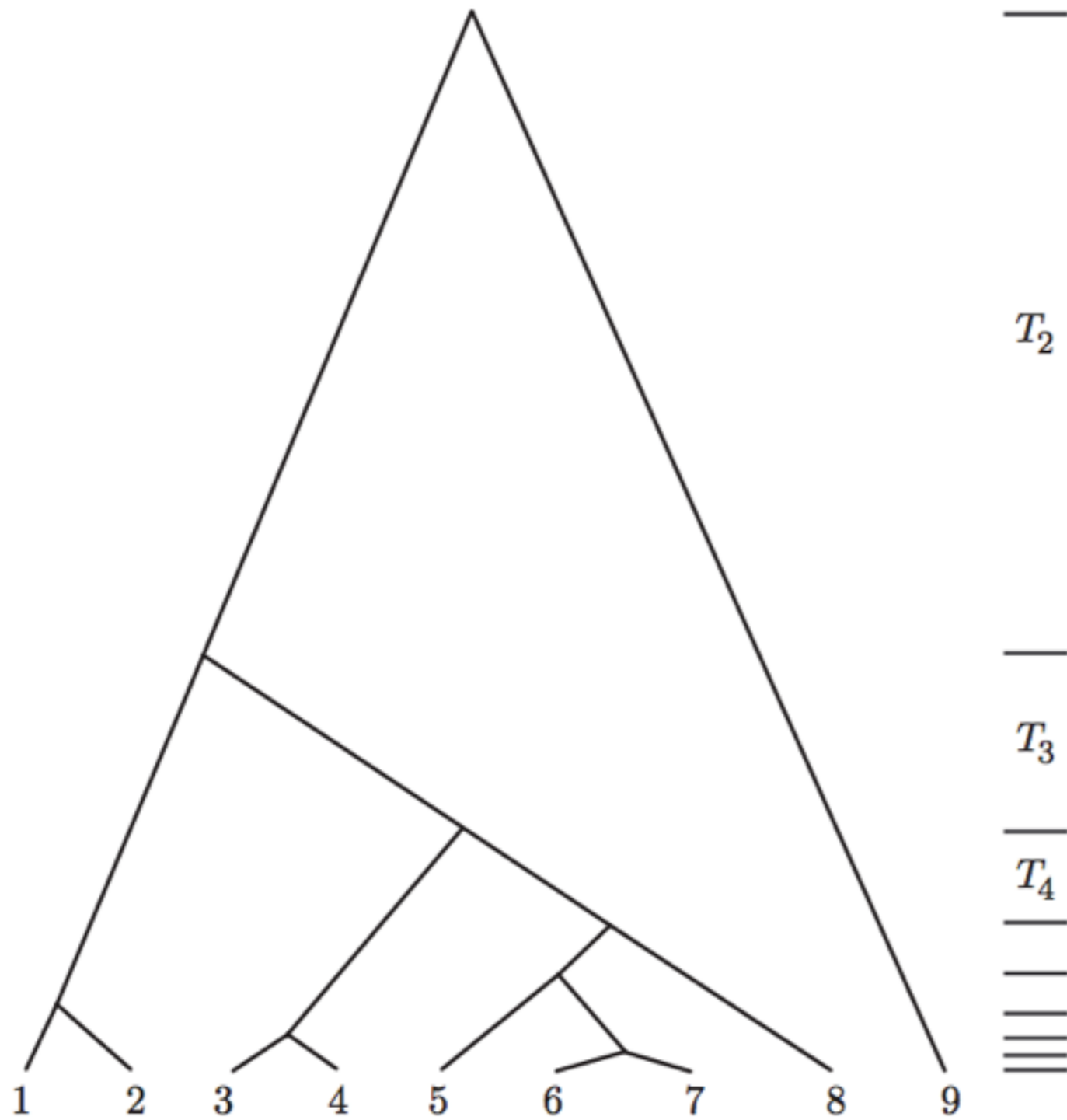
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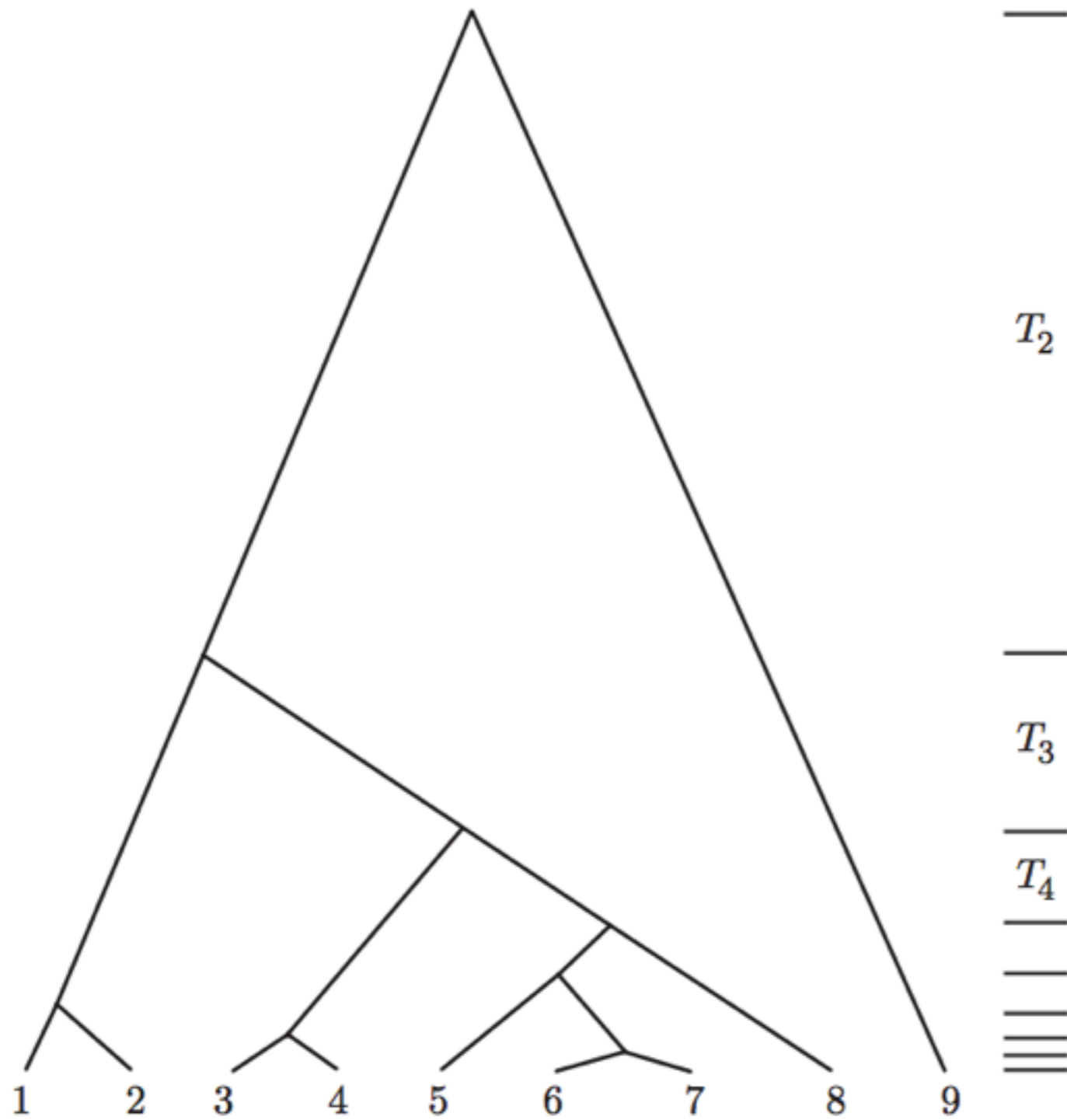


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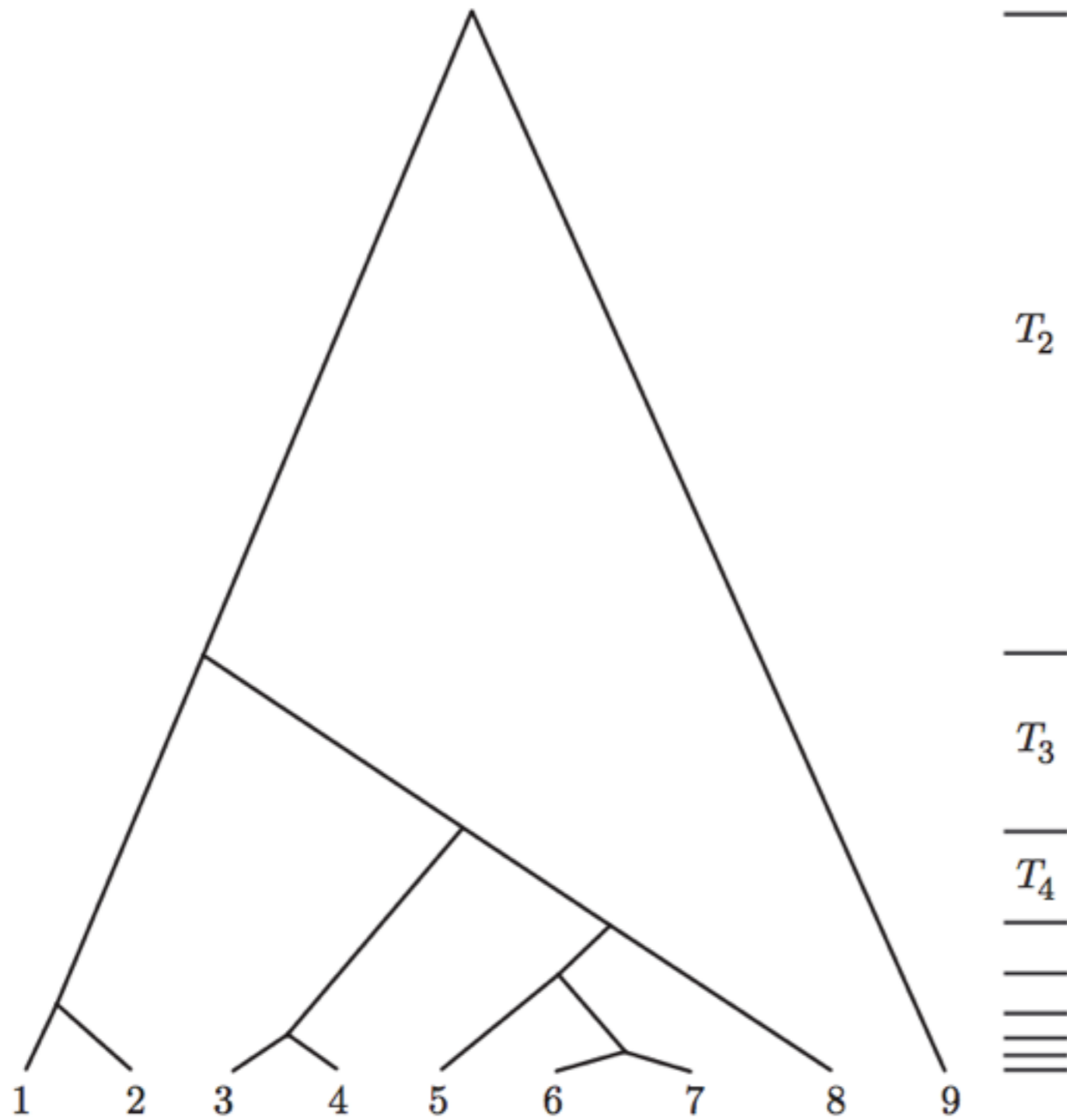
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- Fragmentation
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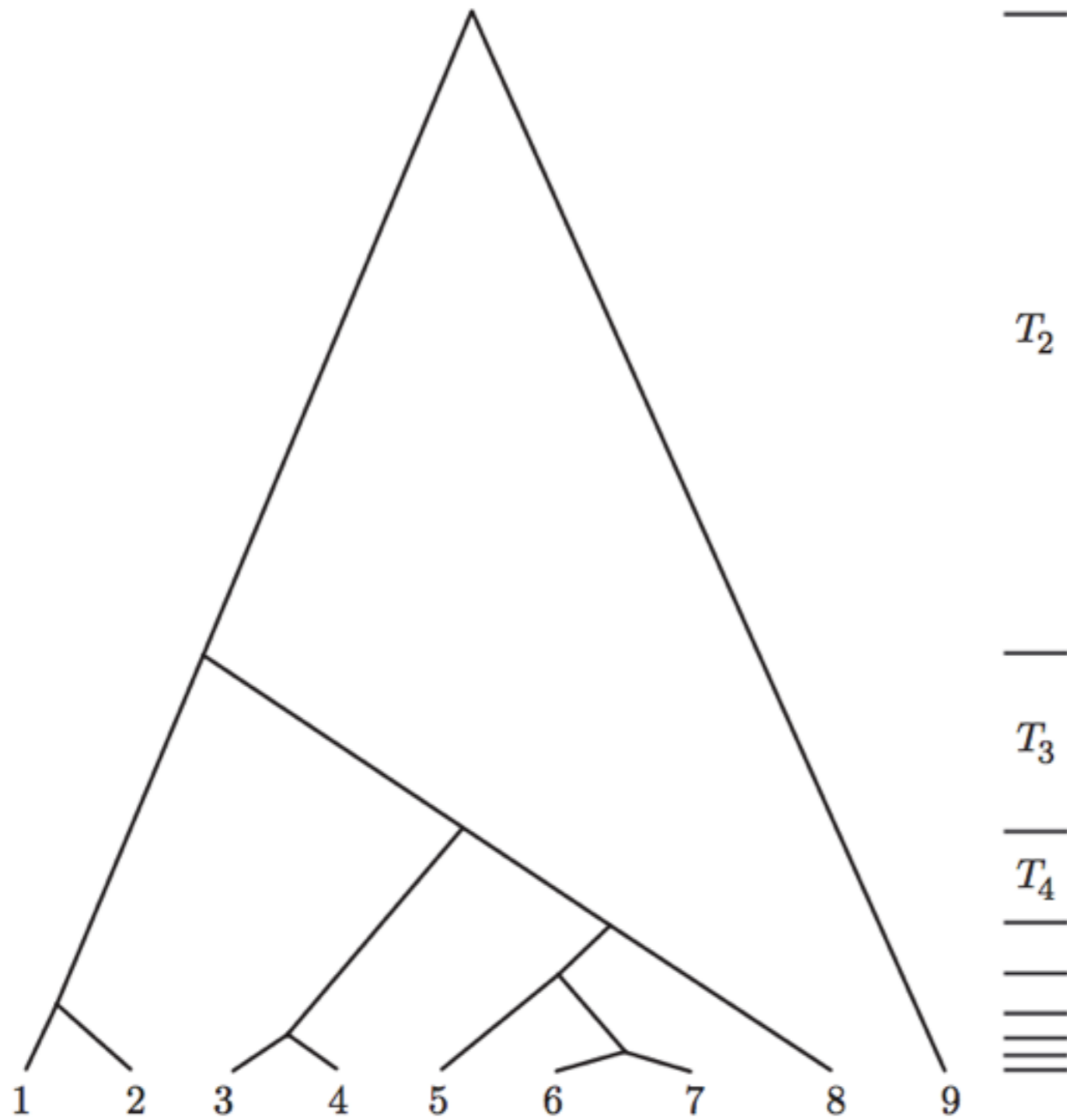


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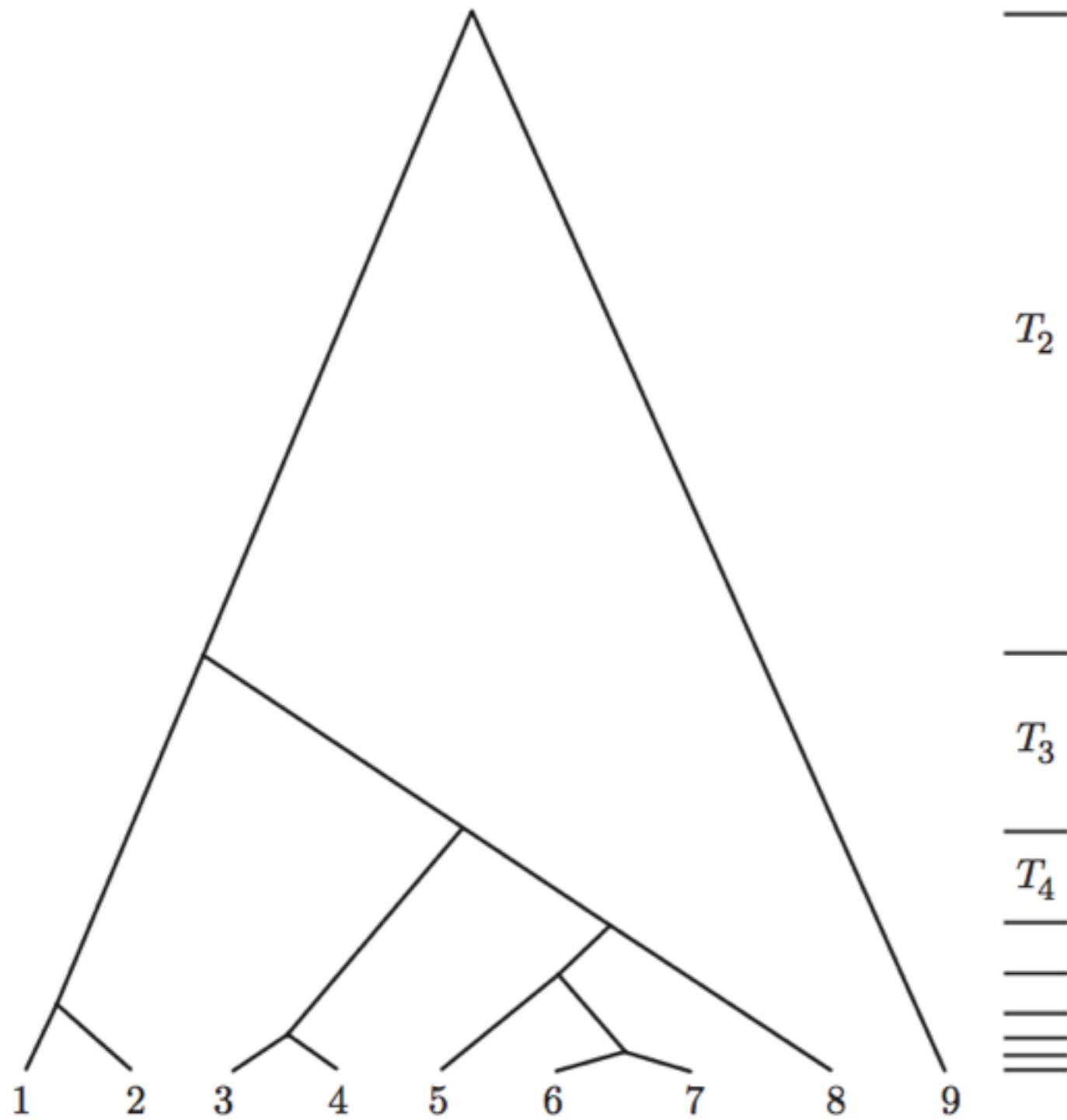


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# Conjugacy & Poisson point processes

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- Beta process, Bernoulli process (Indian buffet)

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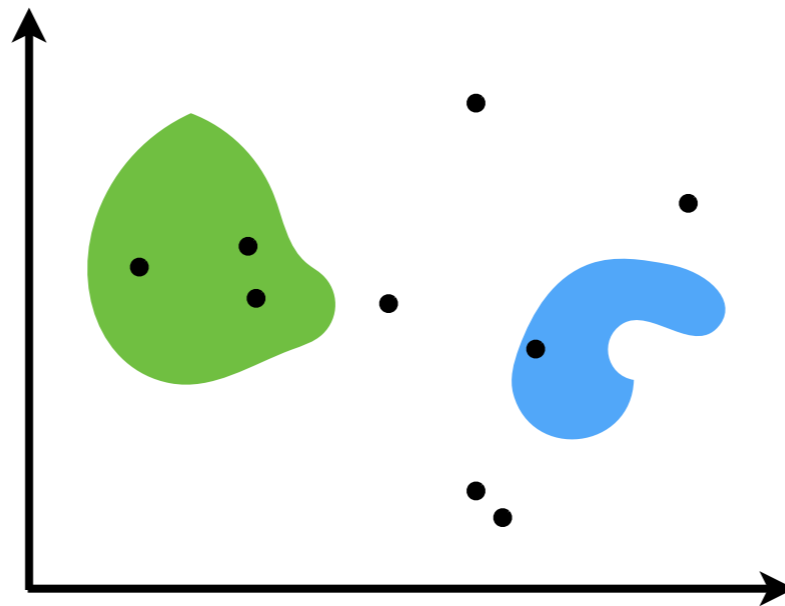
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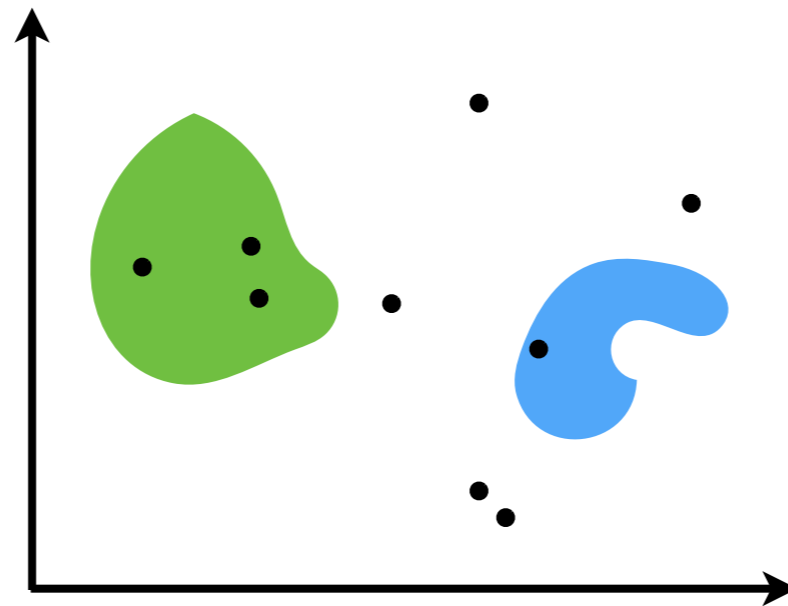
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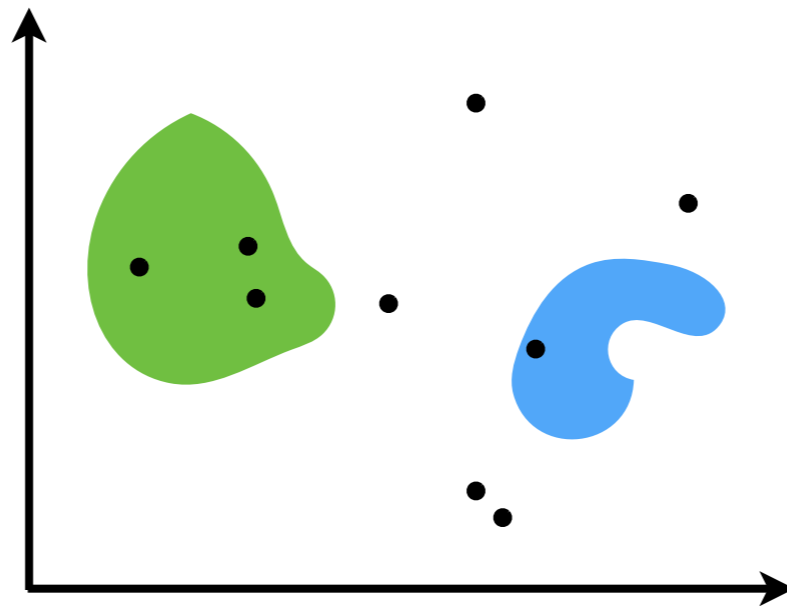
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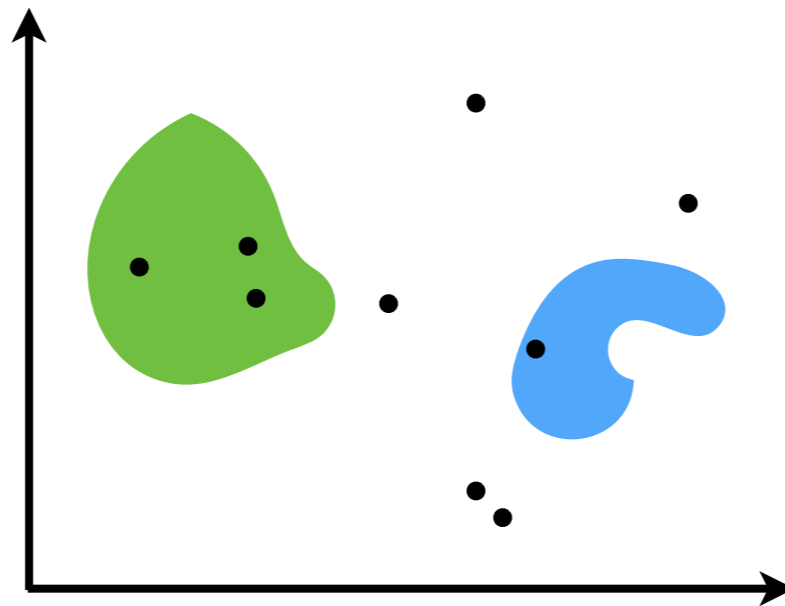
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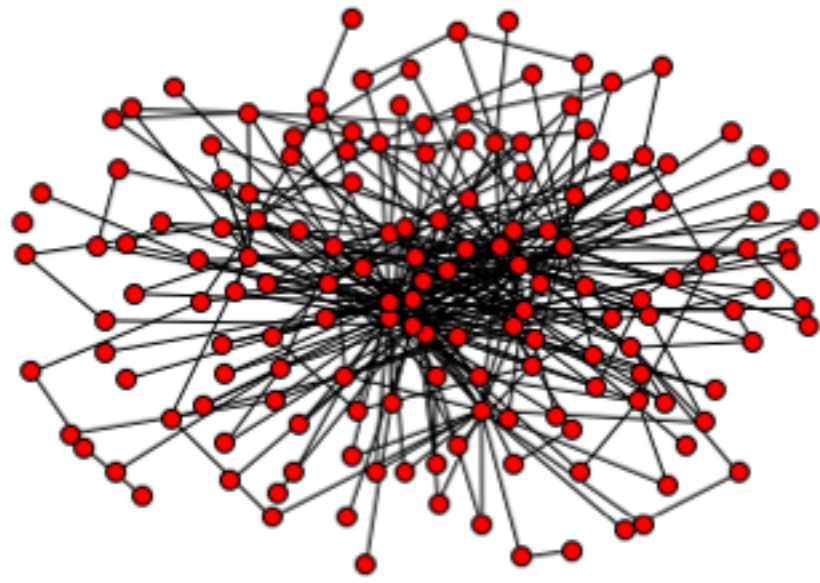
- Posteriors, conjugacy, and exponential families for completely random measures

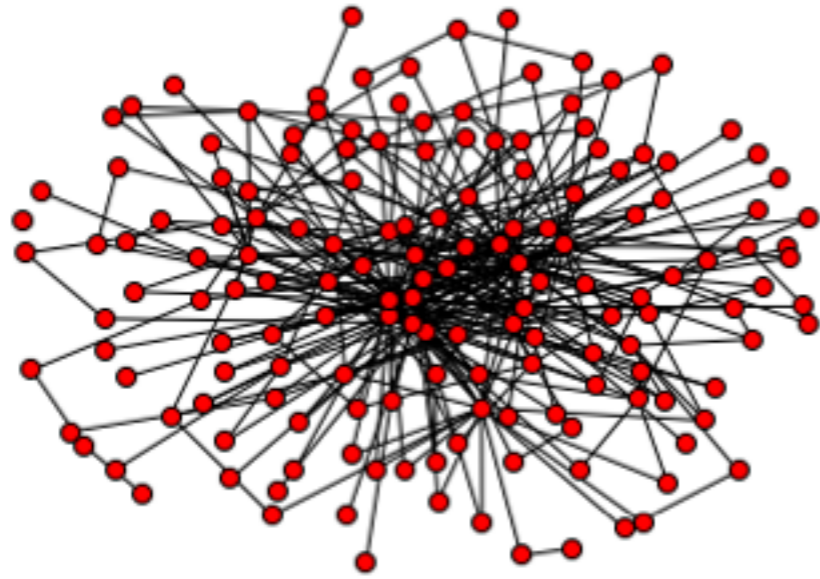
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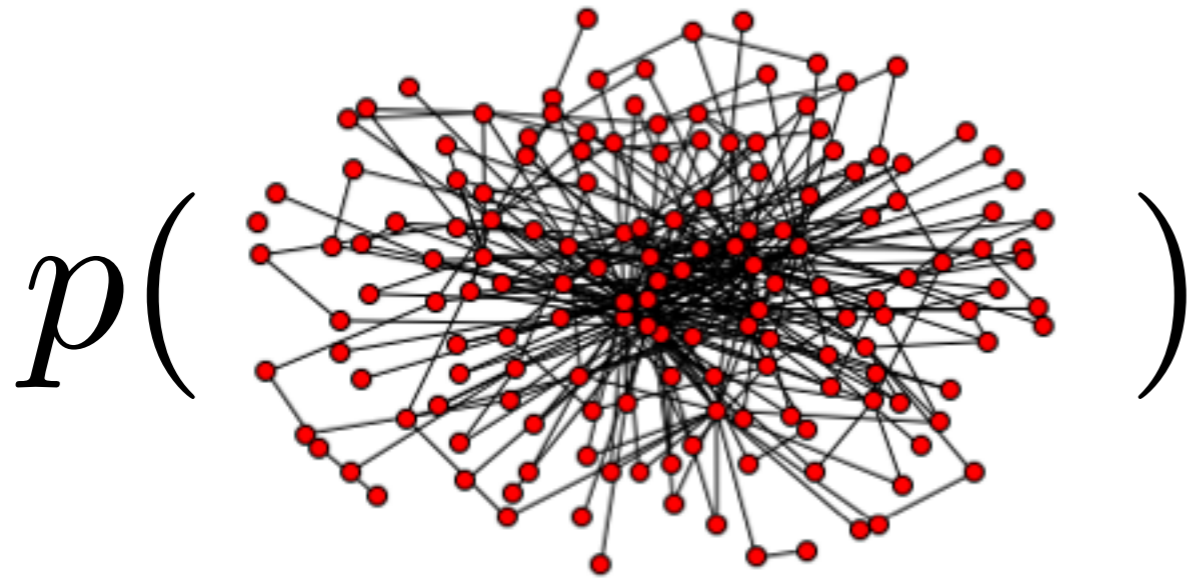
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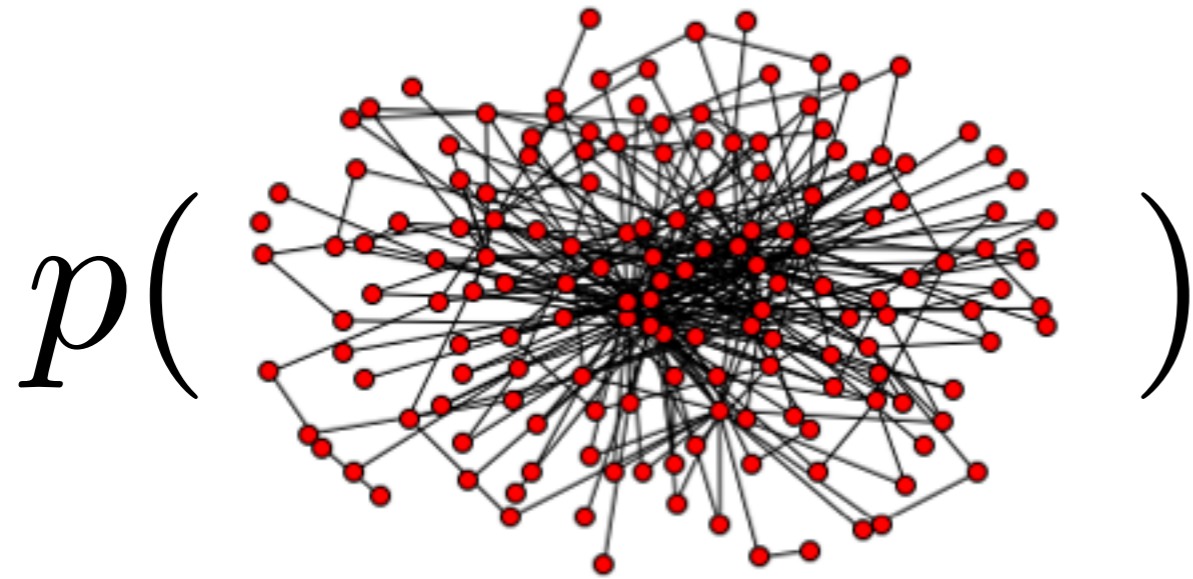
**social:** *Facebook, Twitter, email*  
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# Probabilistic models for graphs



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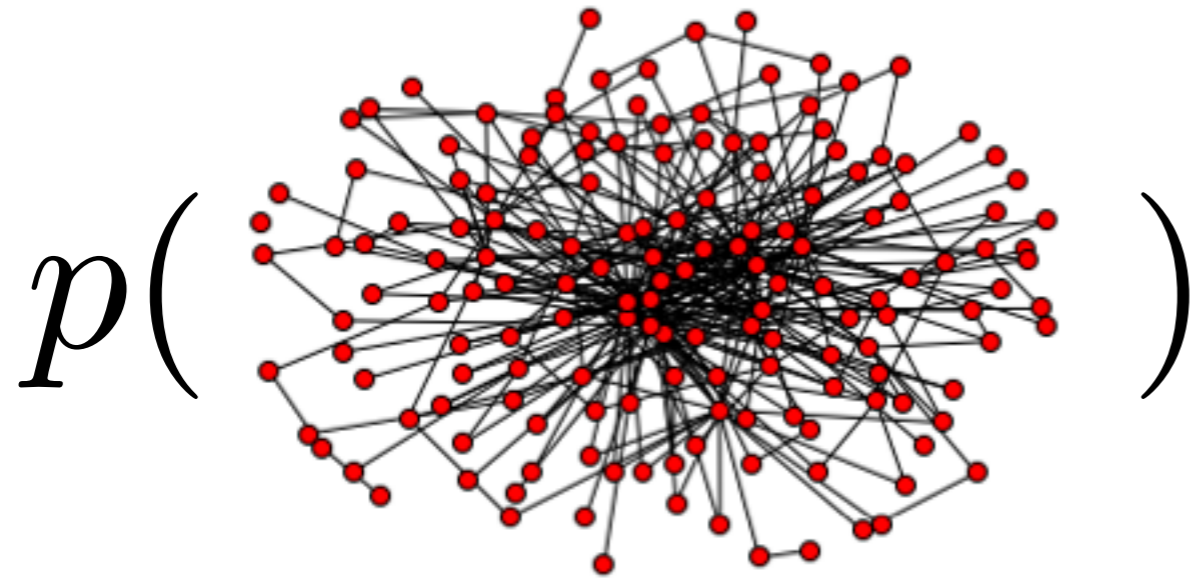
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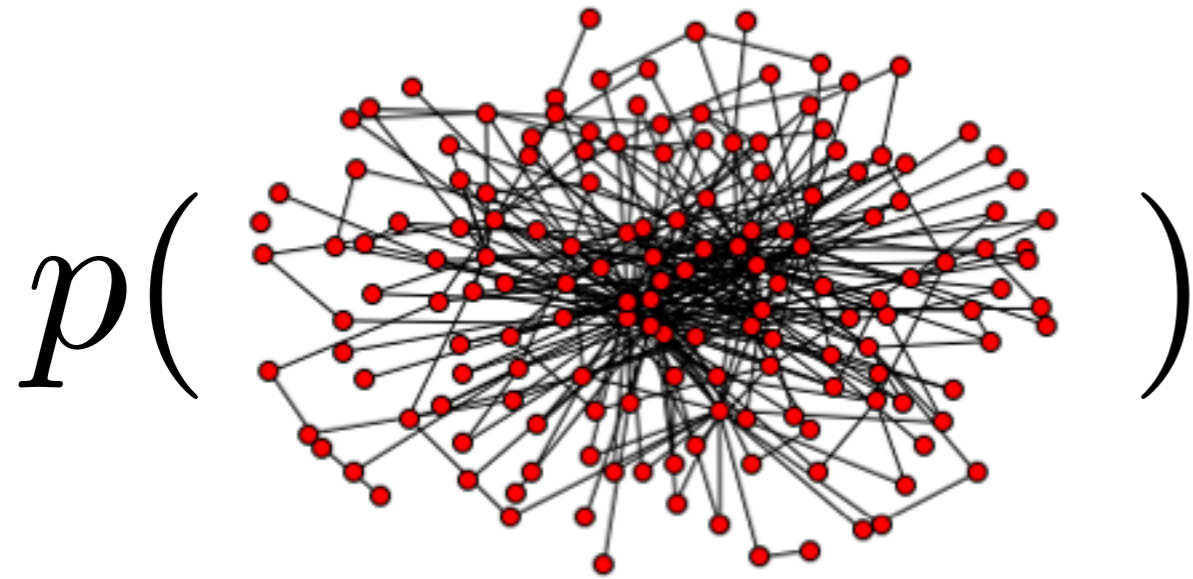


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- Example models: Stochastic block, mixed membership stochastic block, infinite relational, and many more



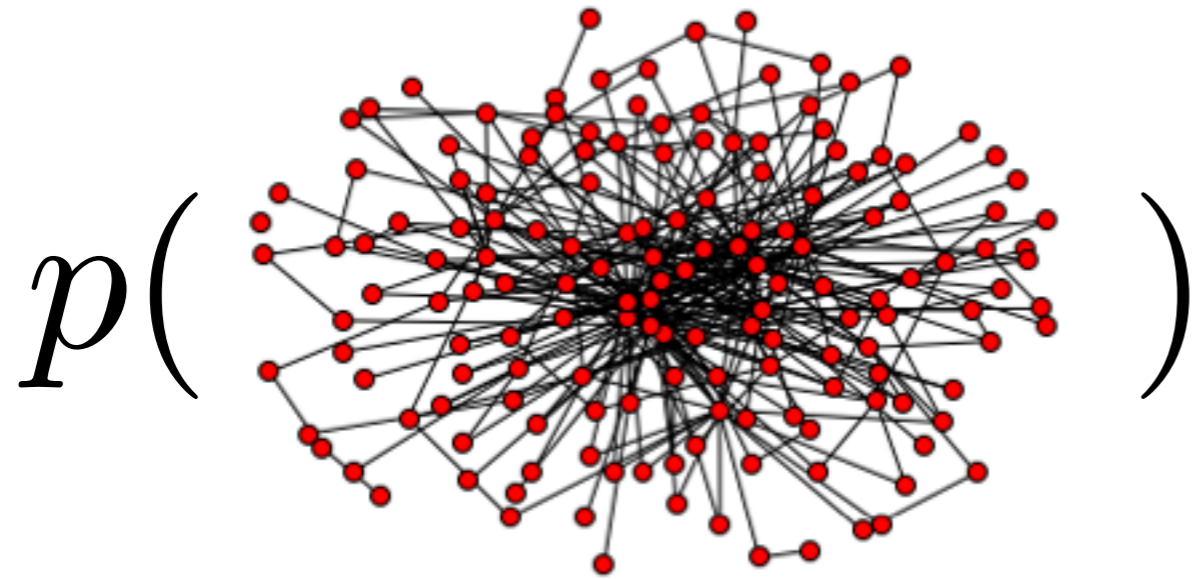
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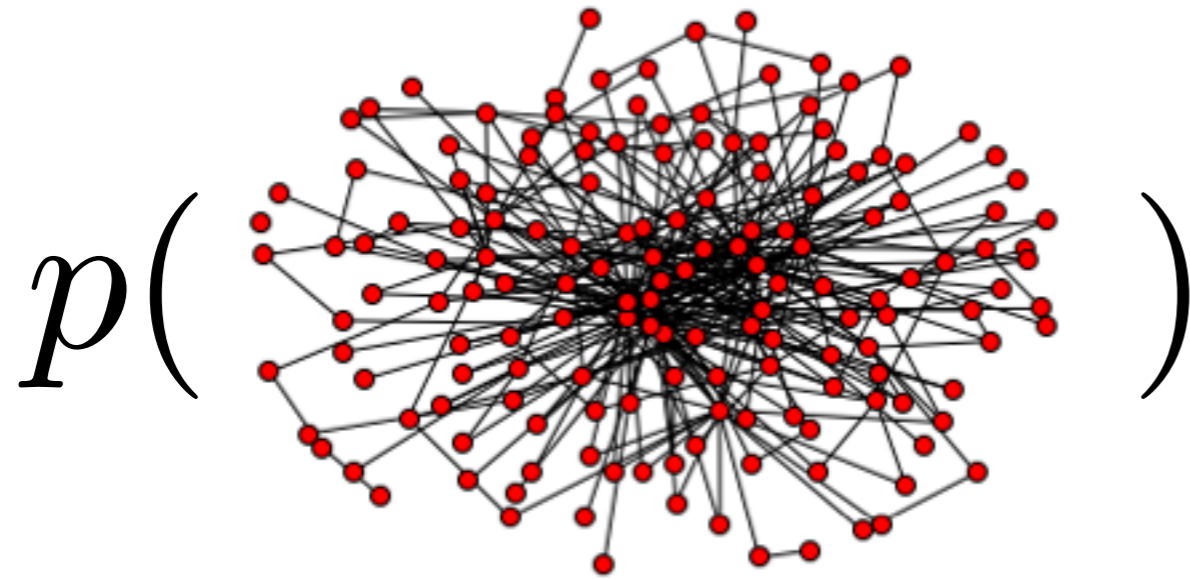
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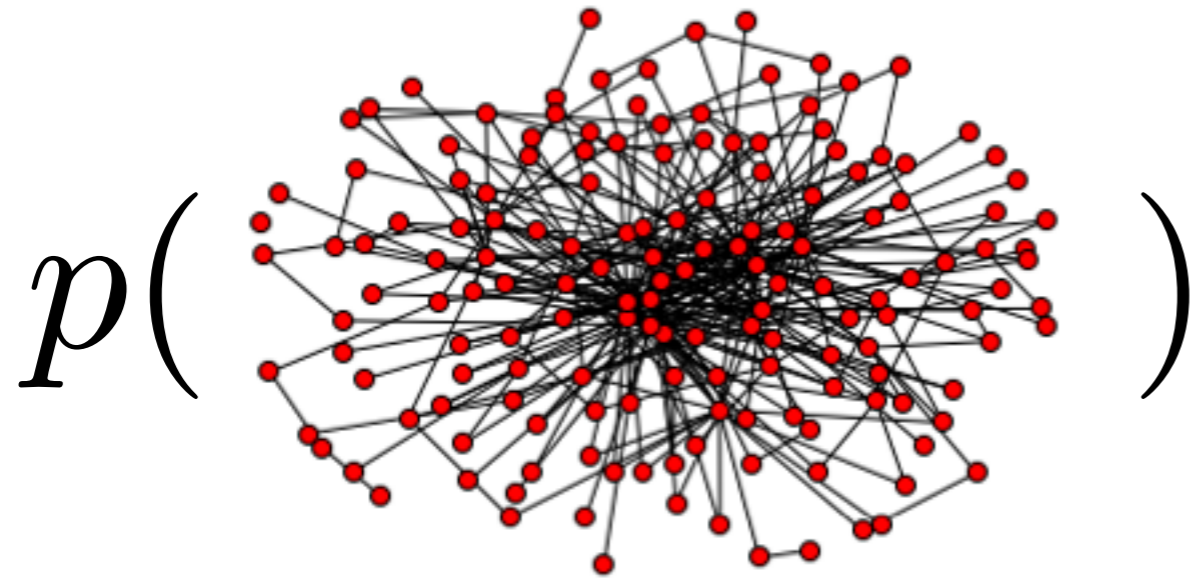
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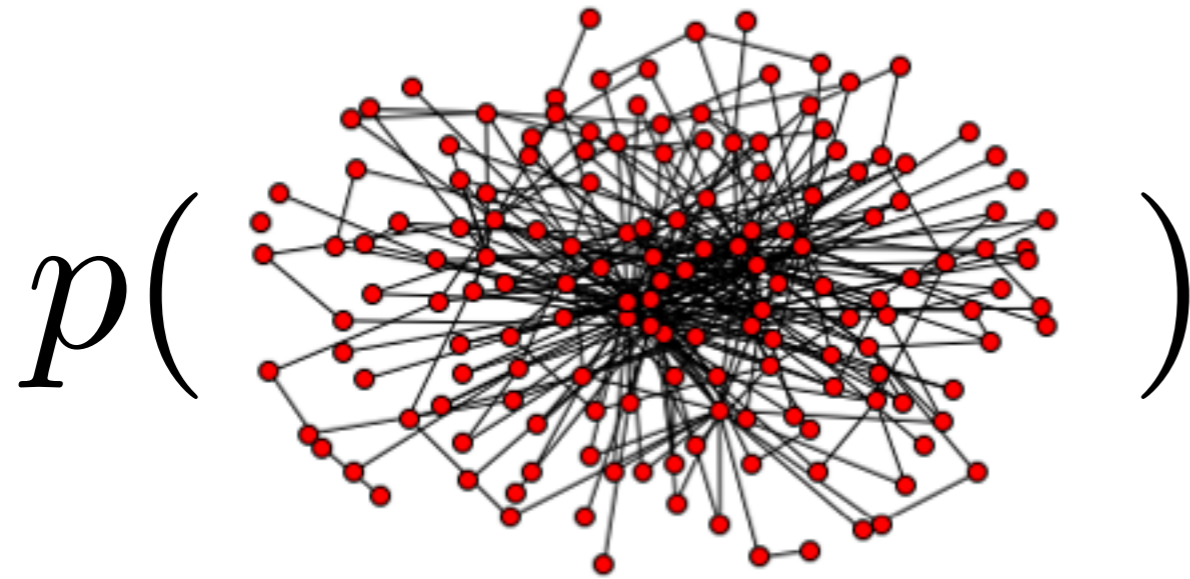
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- **Solution:** a new framework for sparse graphs

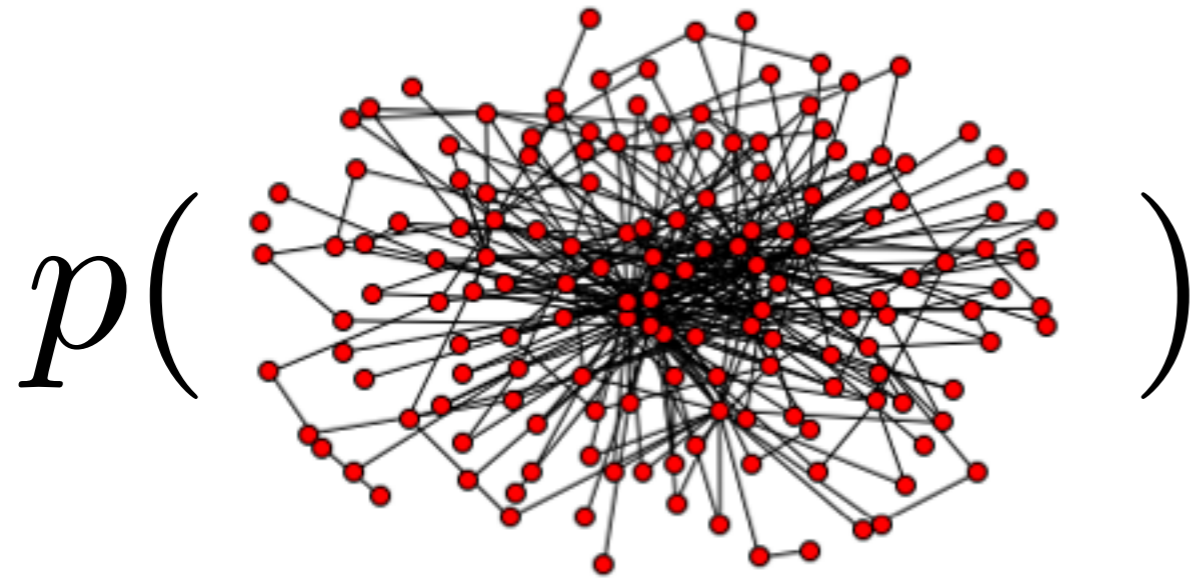
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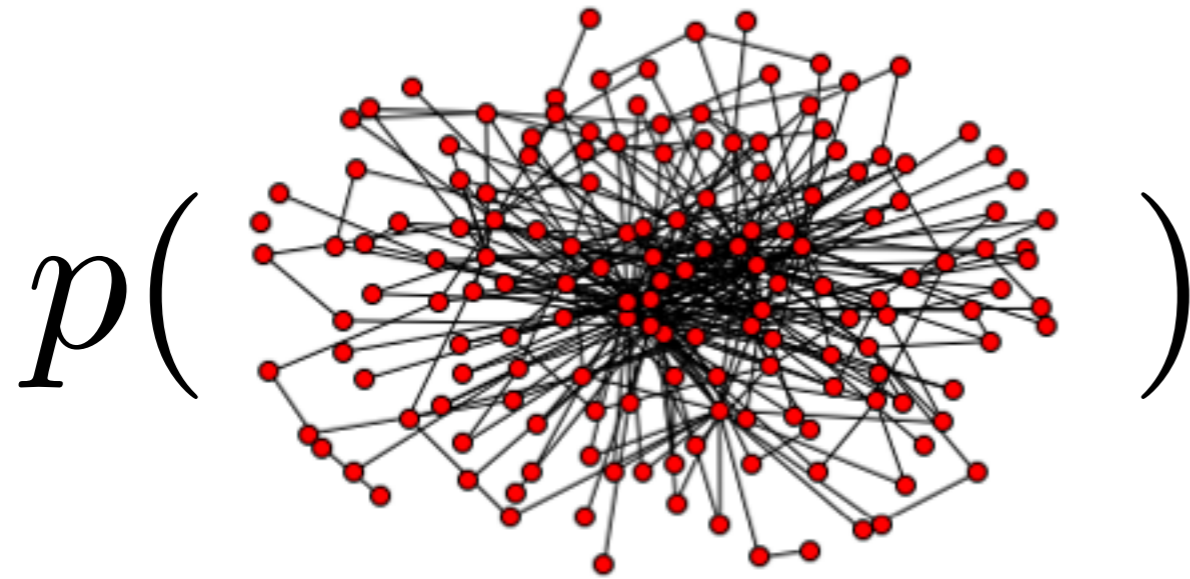
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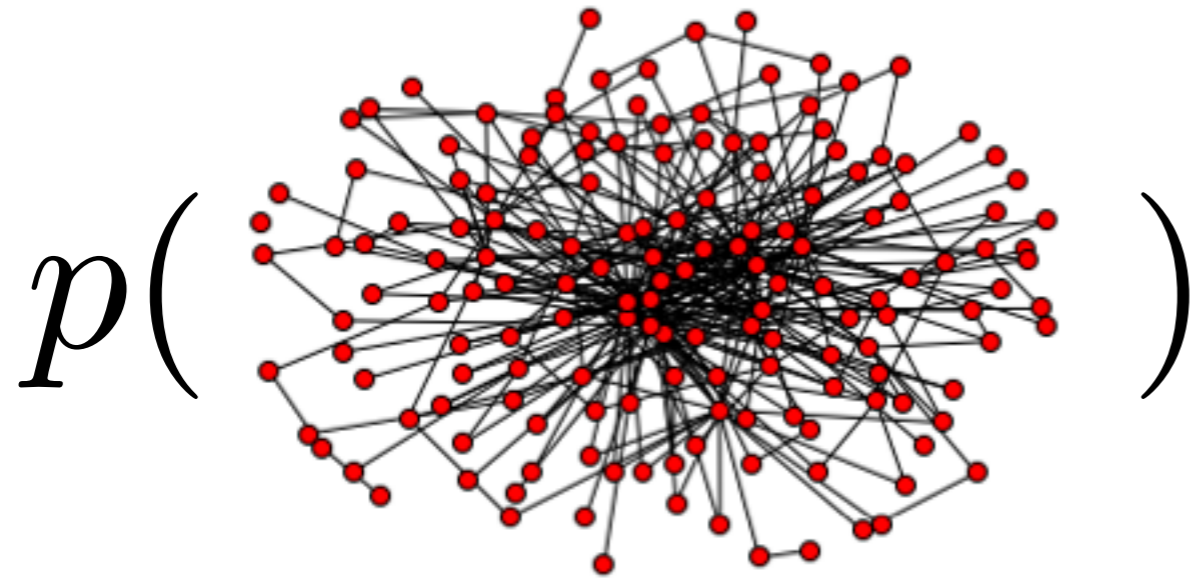
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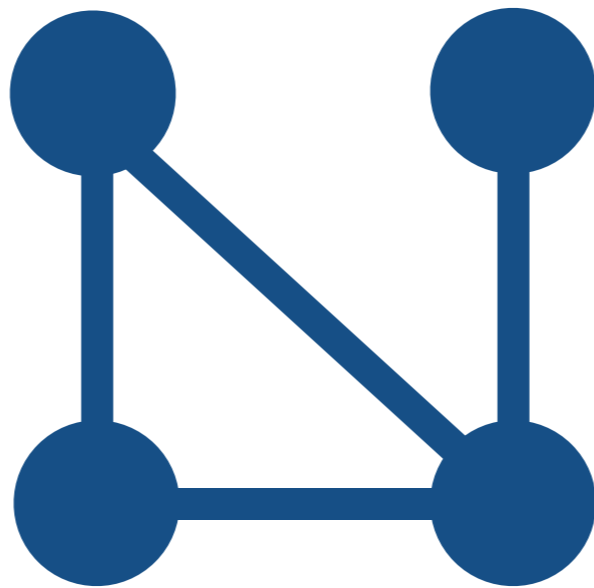


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  - Concurrent & independent graphs work by Crane & Dempsey

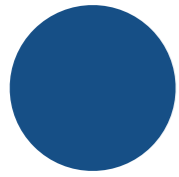


# Sequence of graphs

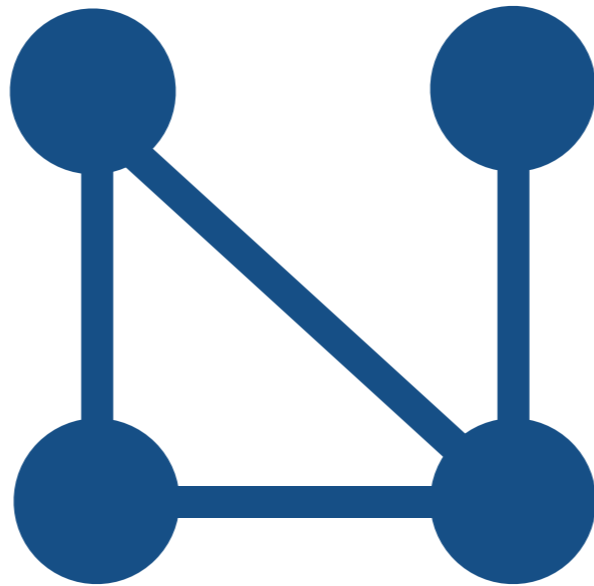


$G$

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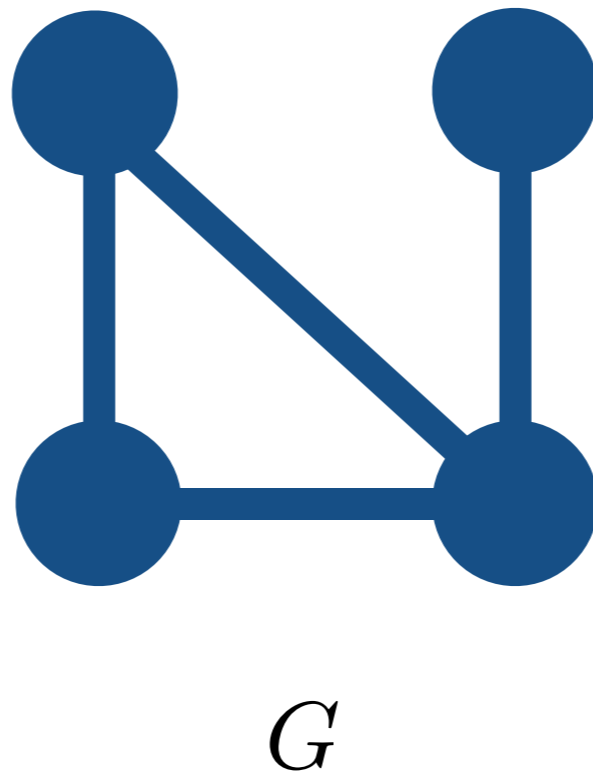
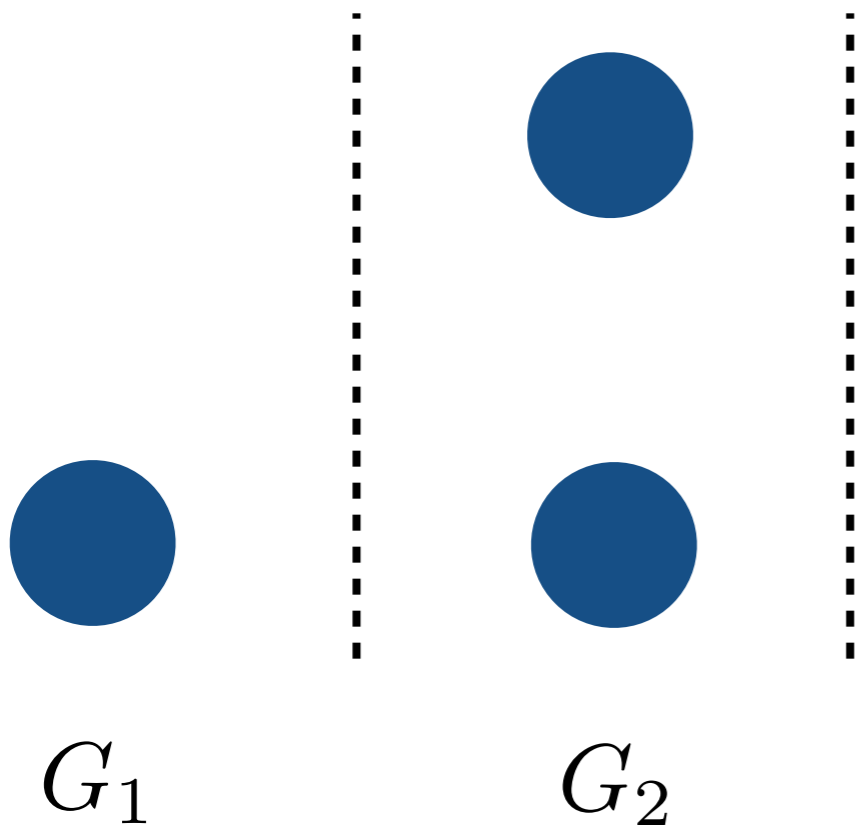


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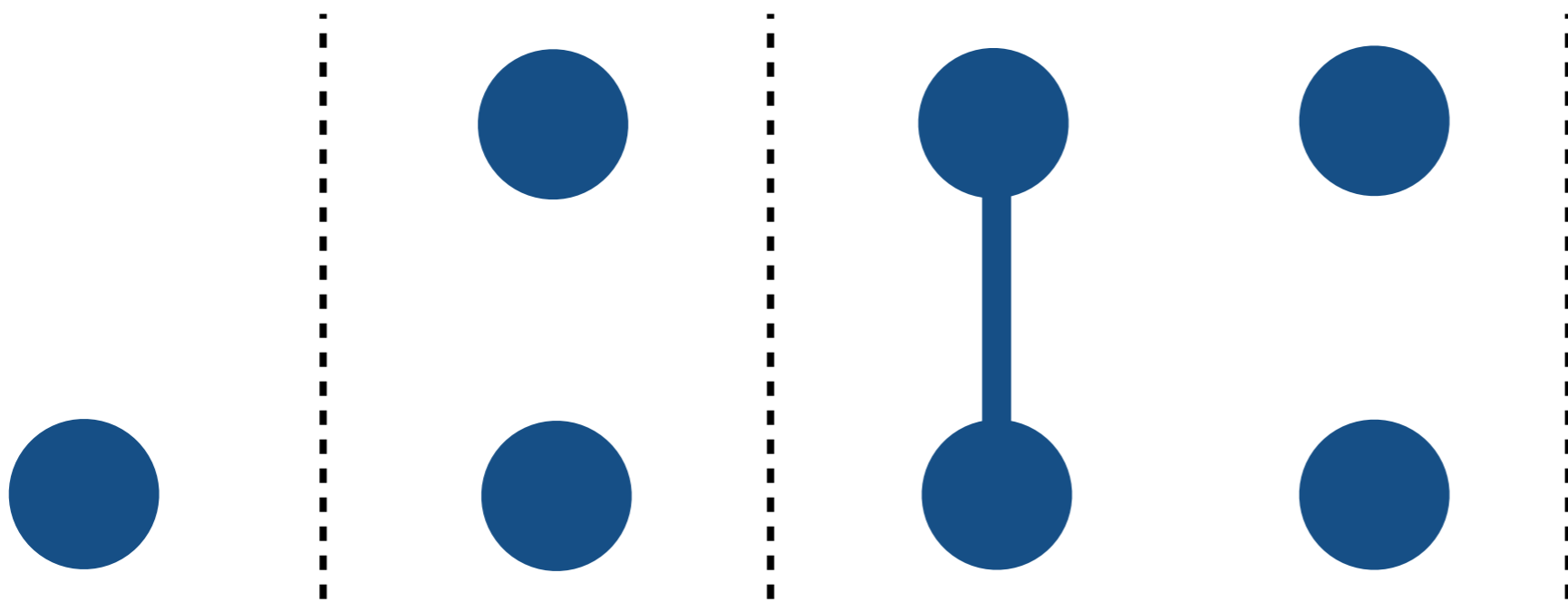


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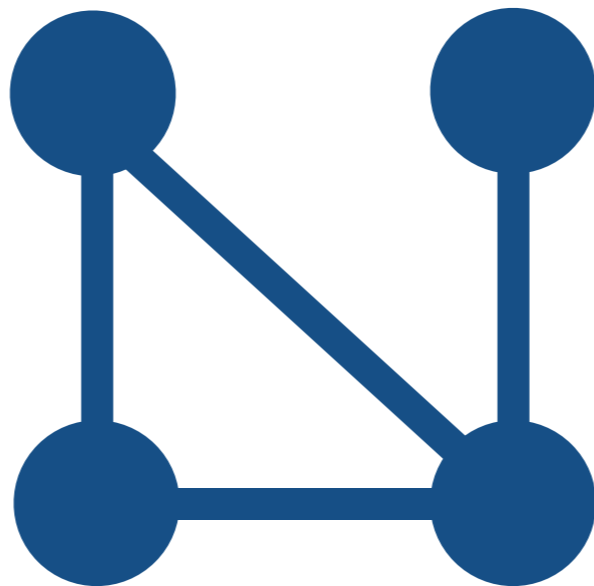
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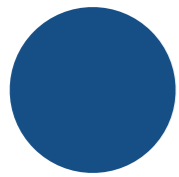
$G_2$

$G_3$

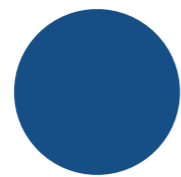
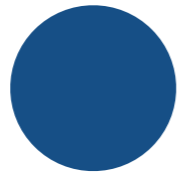


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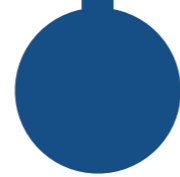
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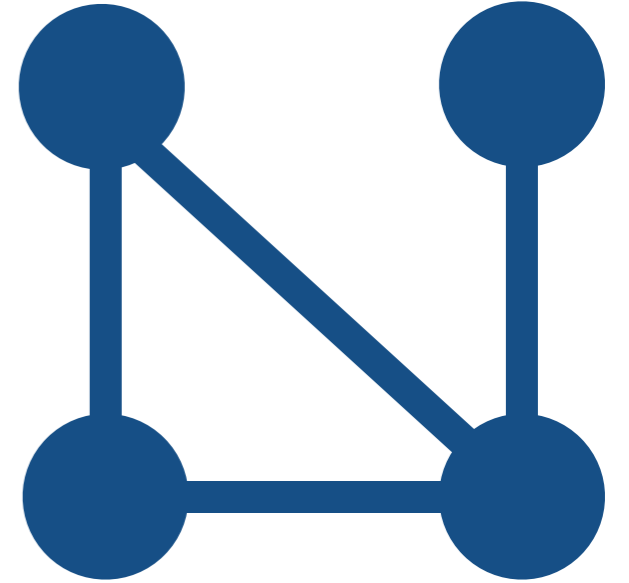
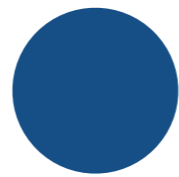
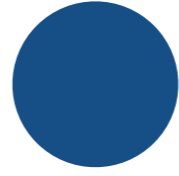
$G_1$



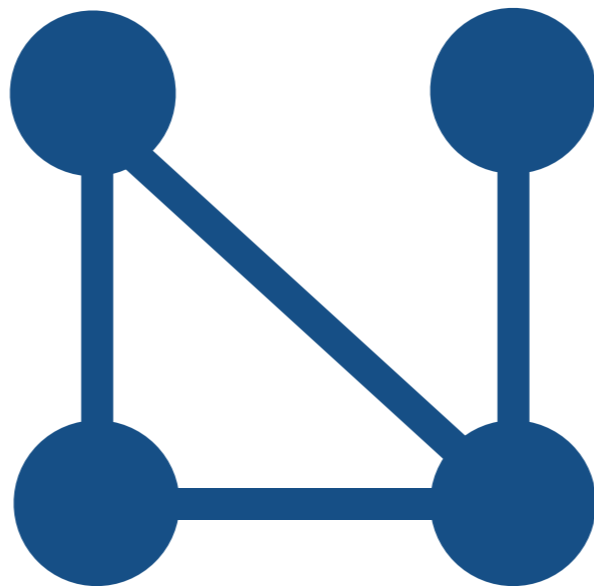
$G_2$



$G_3$

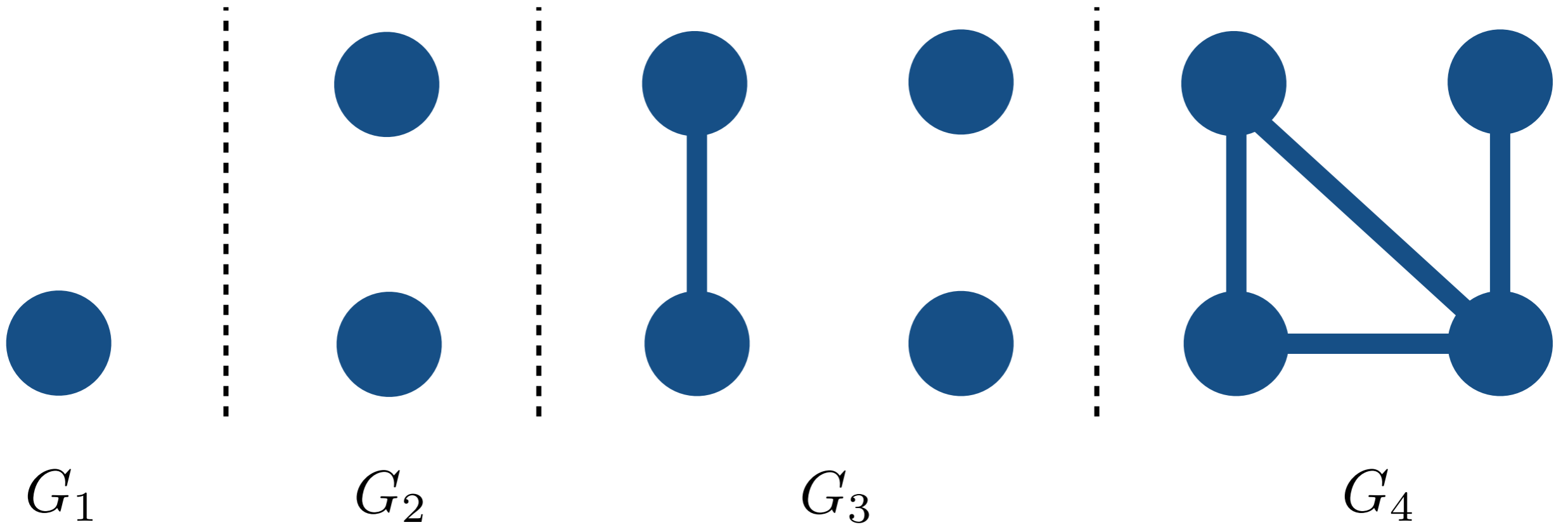


$G_4$

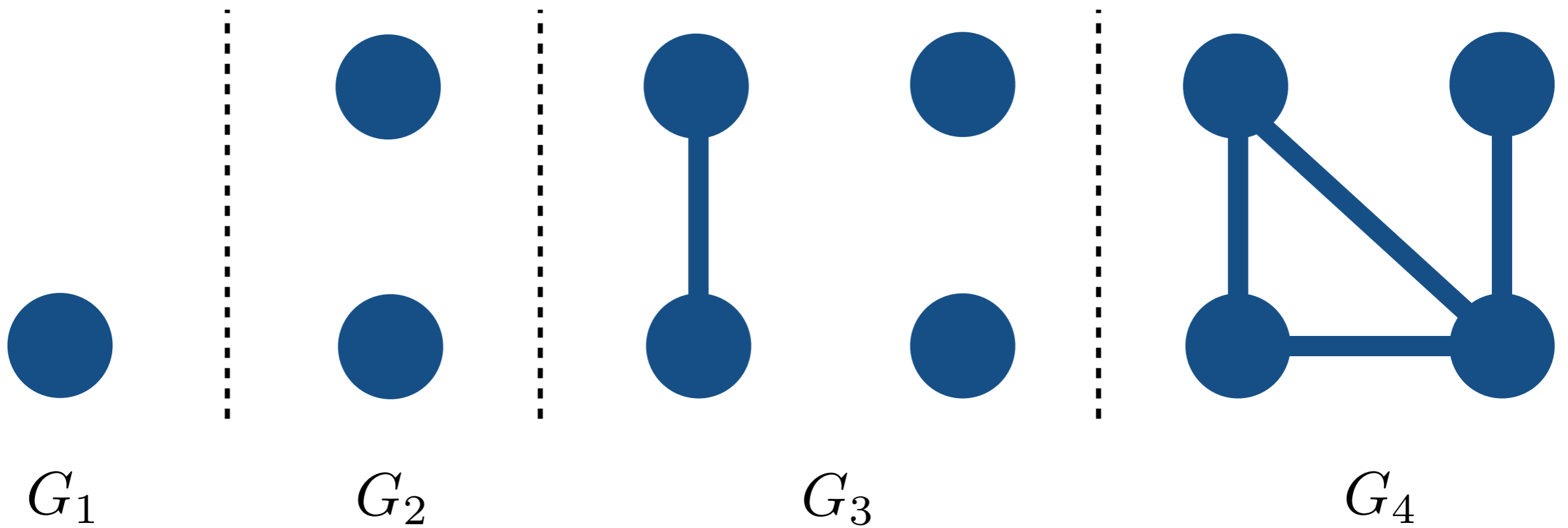


$G$

# Sequence of graphs

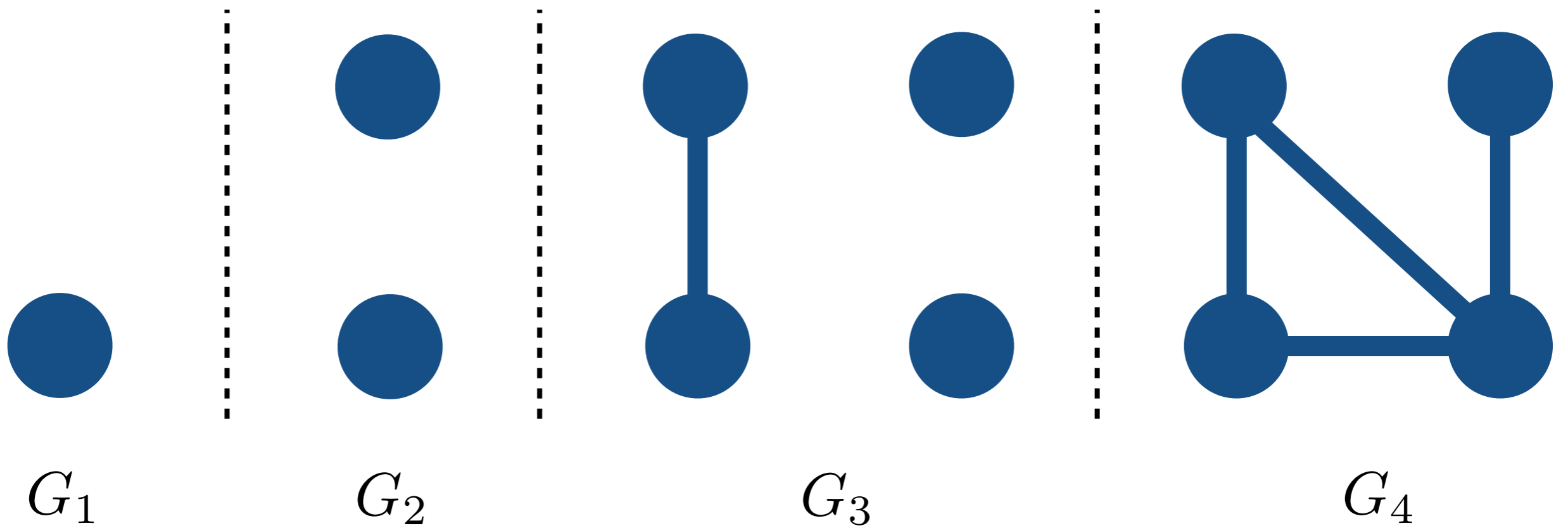


# Sequence of graphs



- *Dense* graph sequence  $\#edges(G_n) \geq c \cdot [\#nodes(G_n)]^2$

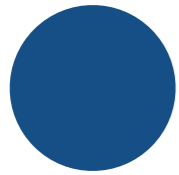
# Sequence of graphs



- *Dense* graph sequence  $\#edges(G_n) \geq c \cdot [\#nodes(G_n)]^2$
- *Sparse* graph sequence  $\#edges(G_n) \in o([\#nodes(G_n)]^2)$



# The Old Way: Nodes



$G_1$



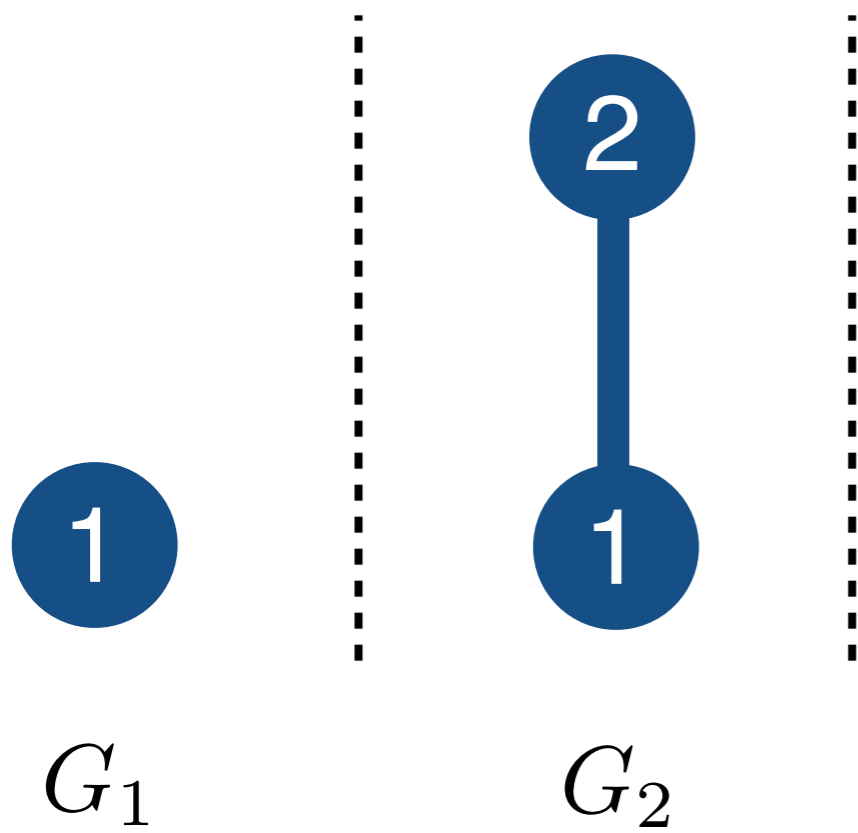
# The Old Way: Nodes

1

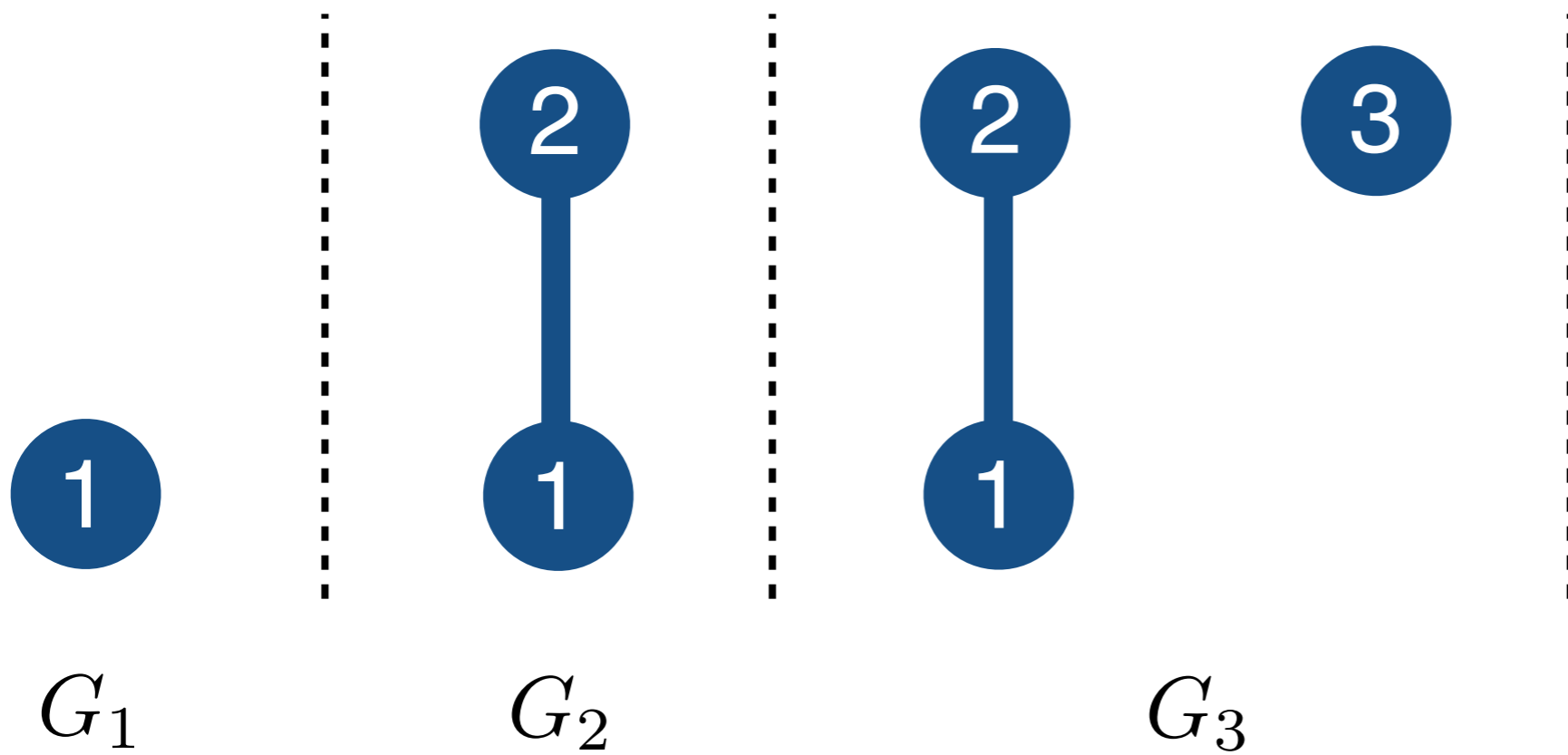
$G_1$



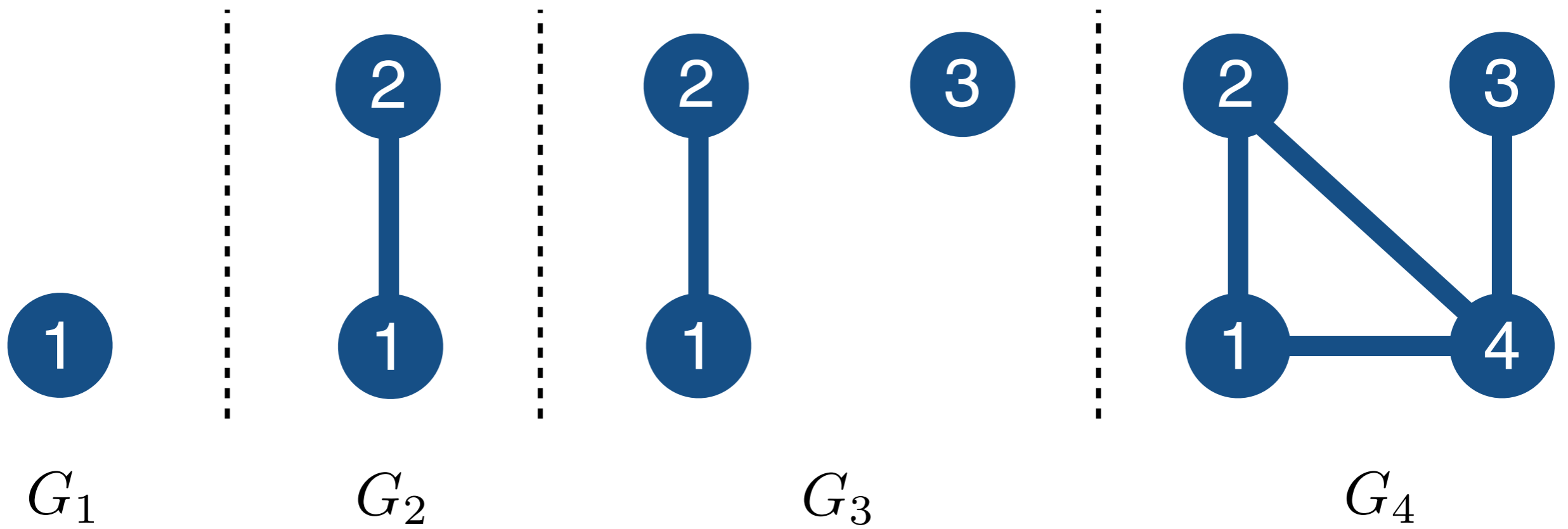
# The Old Way: Nodes



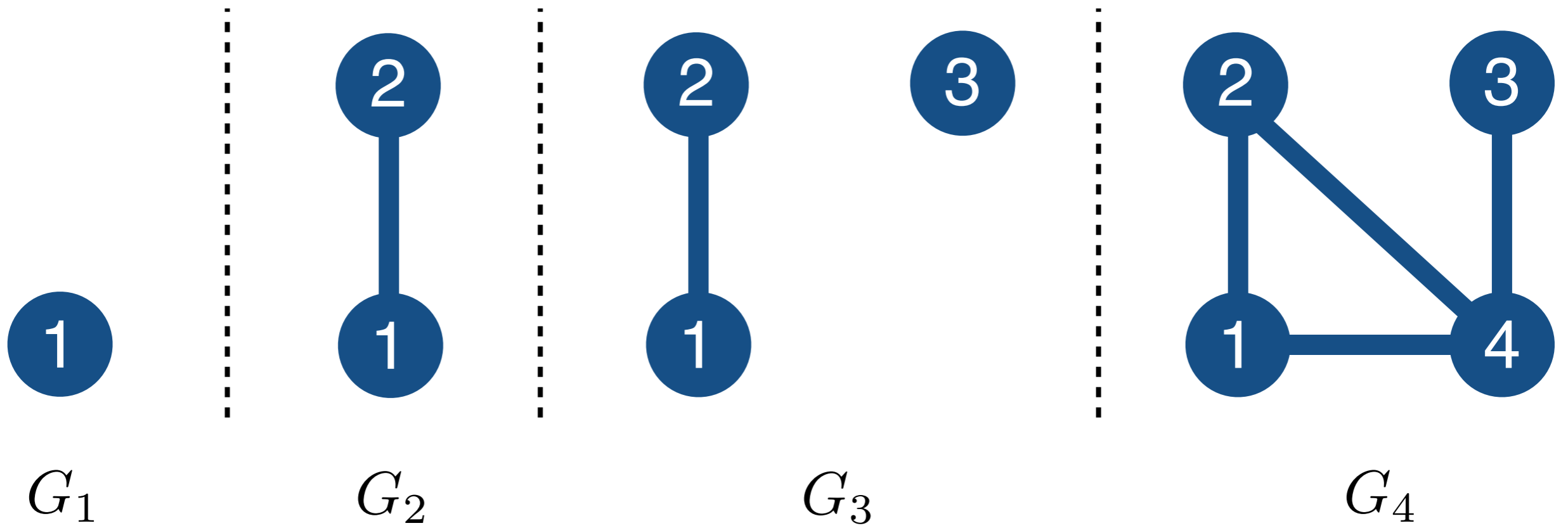
# The Old Way: Nodes



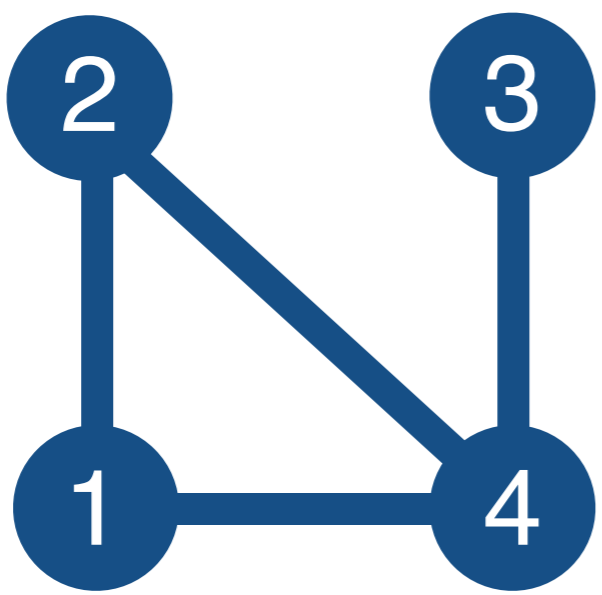
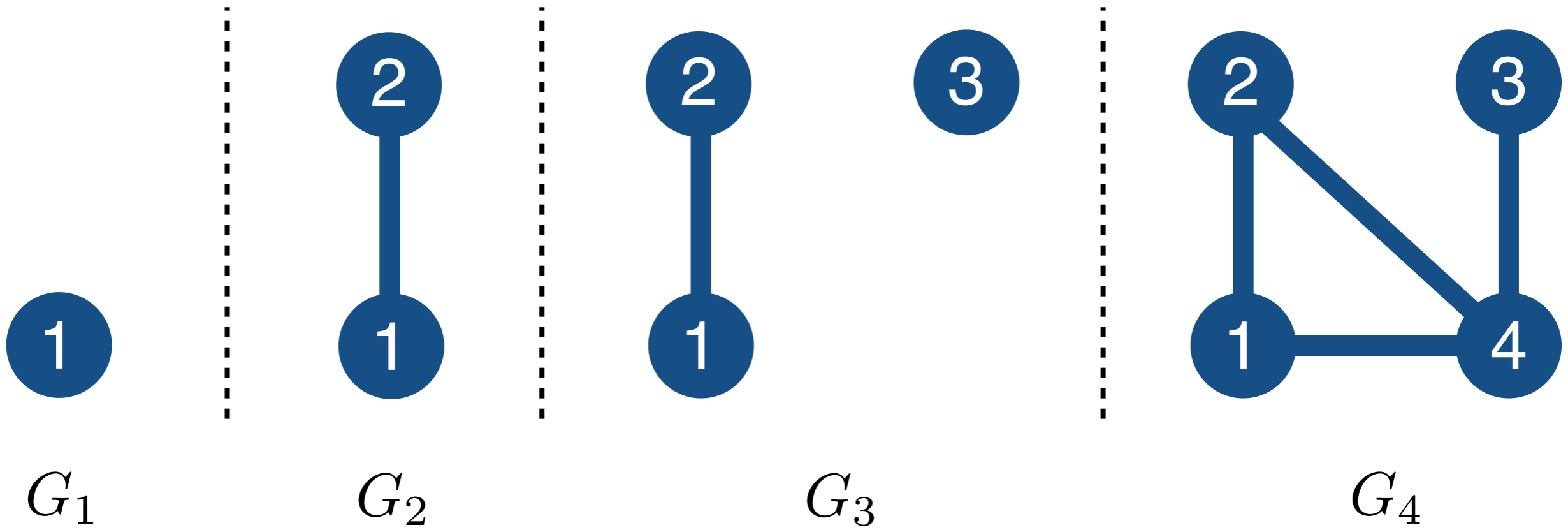
# The Old Way: Nodes



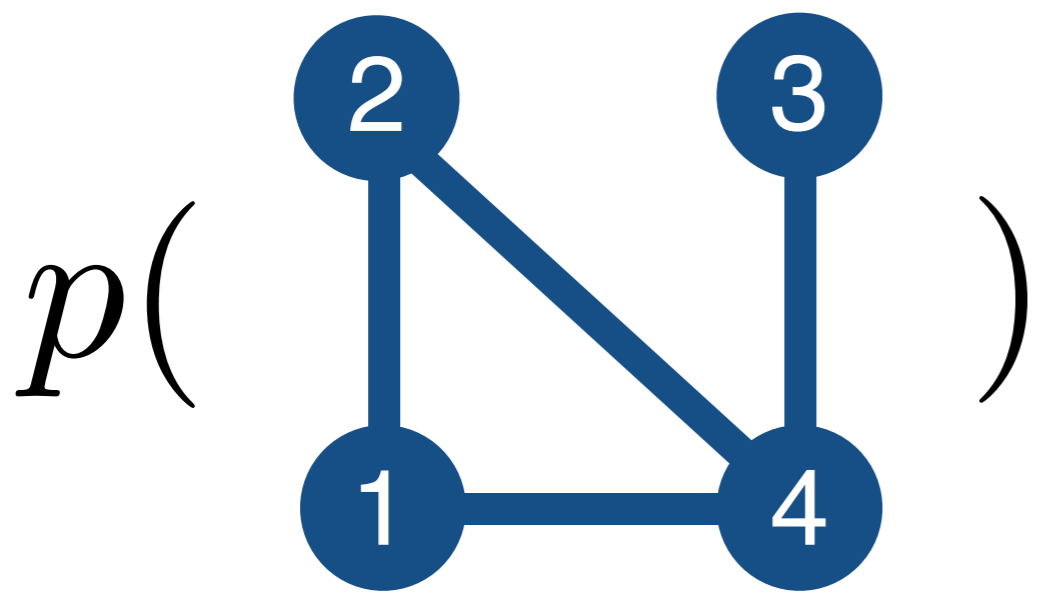
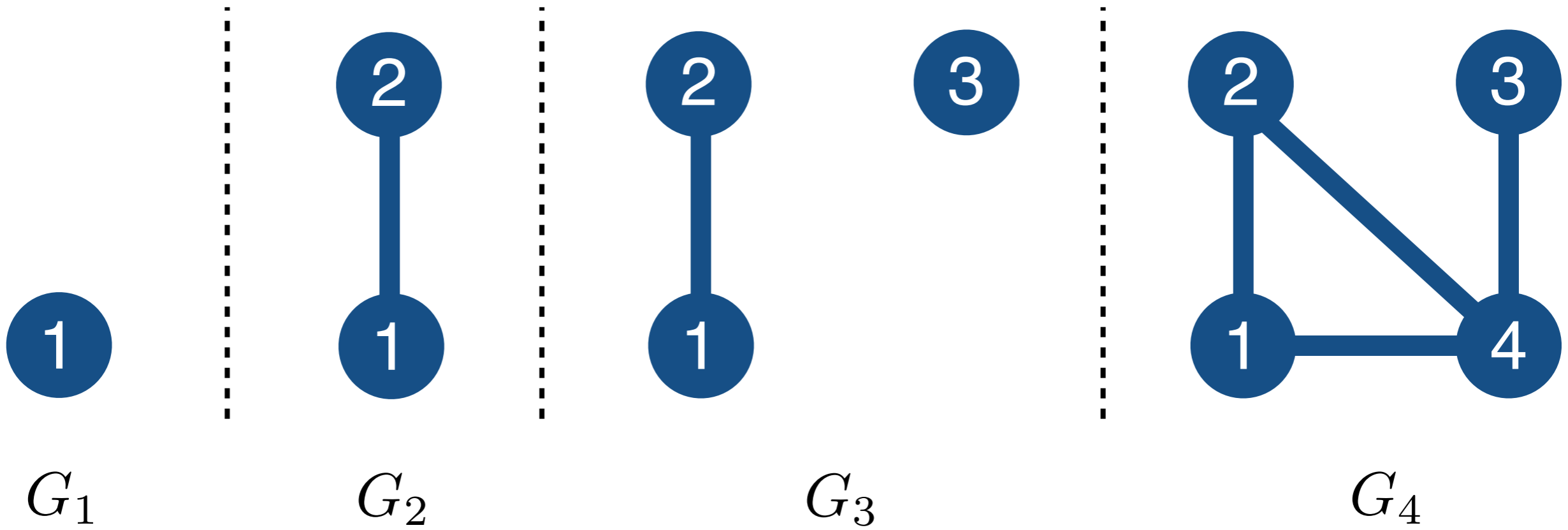
# Exchangeability



# Exchangeability

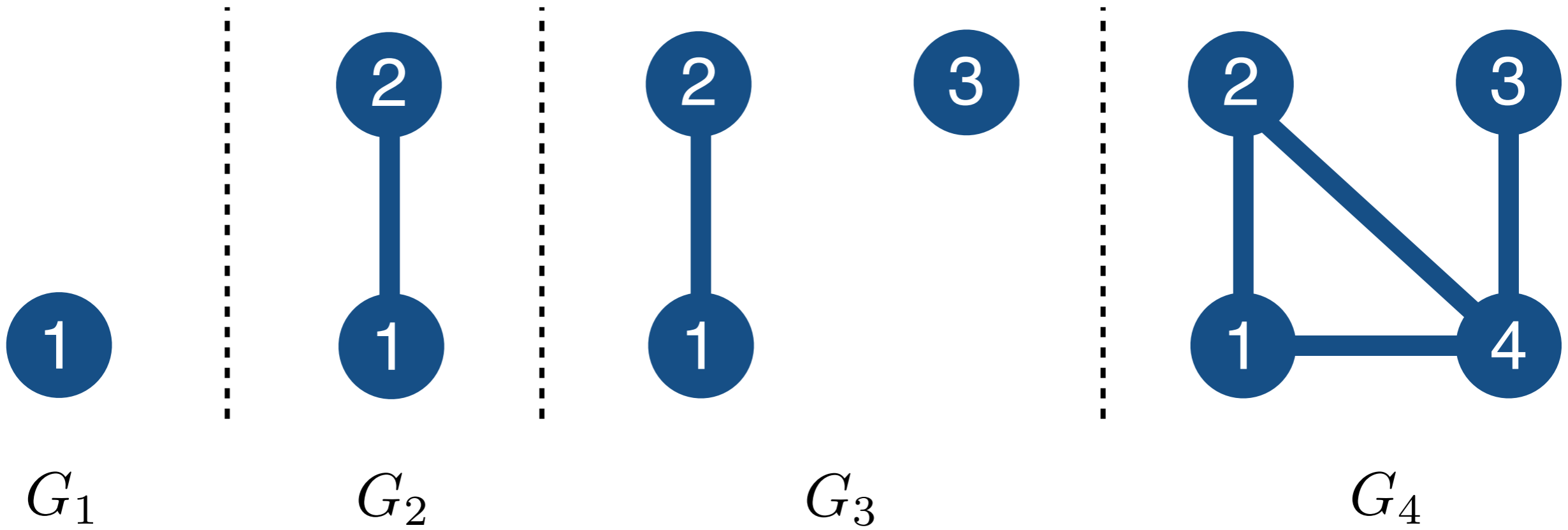


# Exchangeability



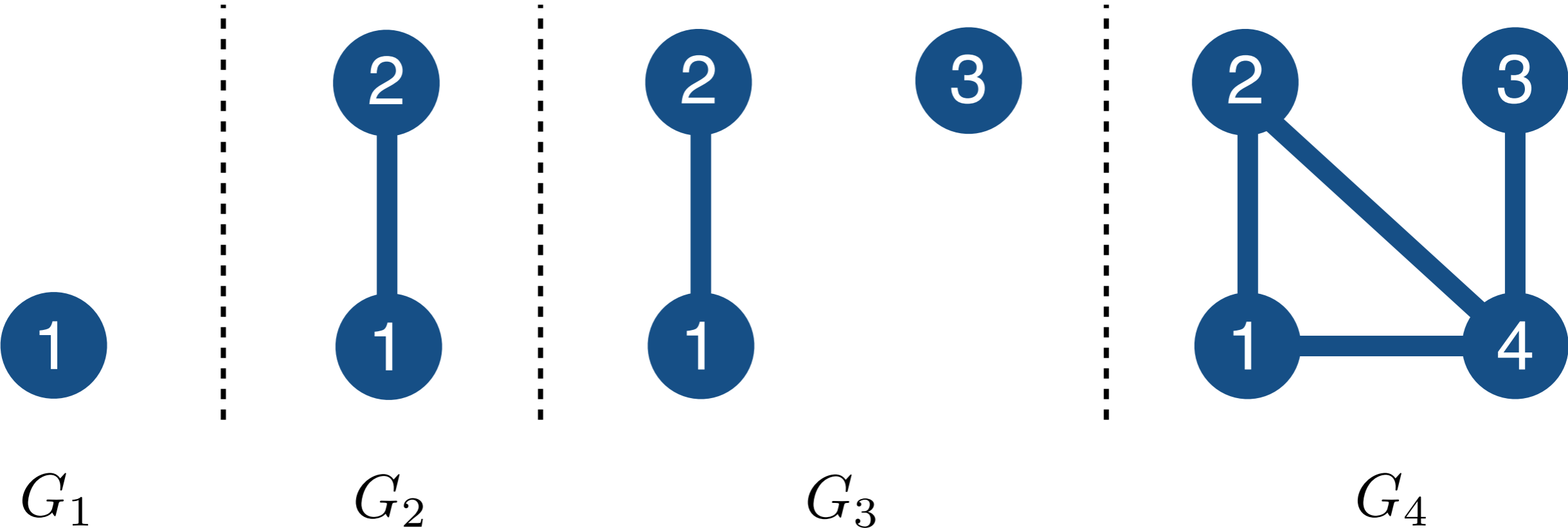


# Exchangeability



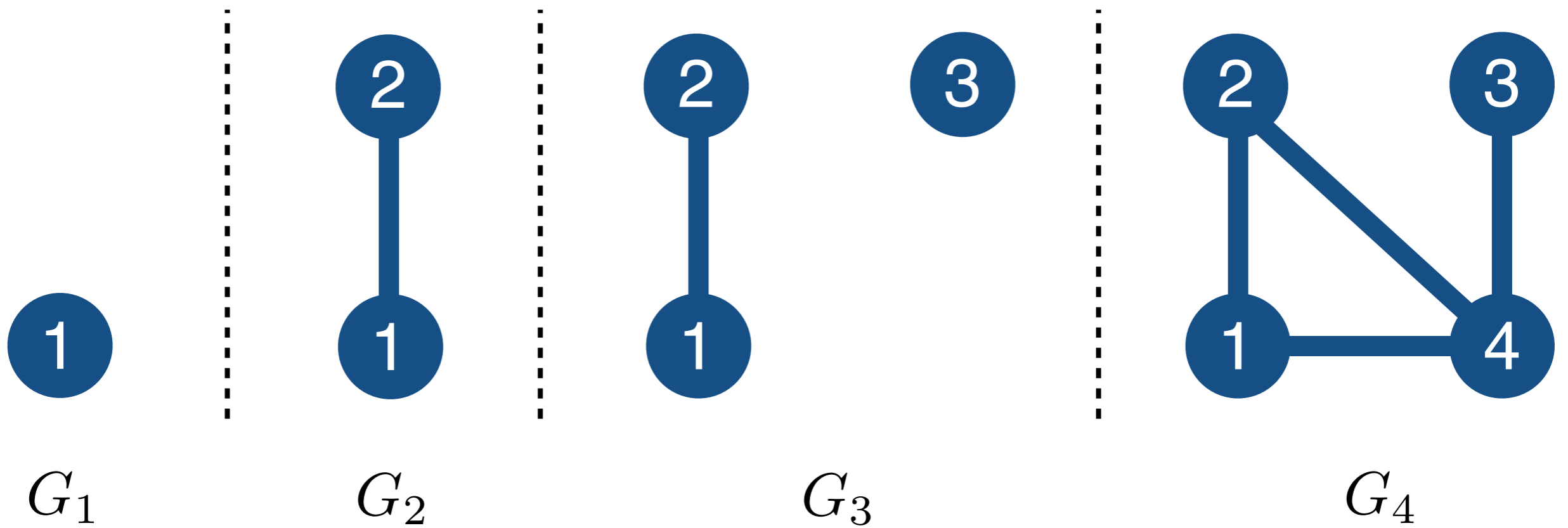
$$p(\text{graph with nodes } 1, 2, 3, 4 \text{ and edges } (1,2), (1,4), (2,4), (3,4))) = p(\text{graph with nodes } 2, 3, 4, 1 \text{ and edges } (2,3), (2,4), (3,4), (4,1)))$$

# Node exchangeability



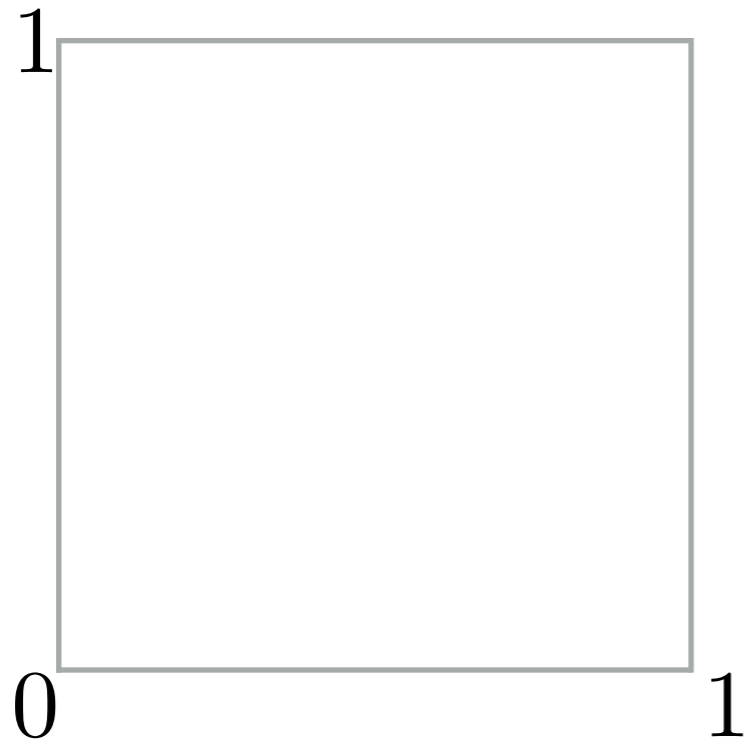
$$p(\text{graph with nodes 1, 2, 3, 4 and edges (1,2), (1,4), (2,4)}) = p(\text{graph with nodes 1, 2, 3, 4 and edges (2,3), (2,4), (3,4)})$$

# The Old Way: Node exchangeability

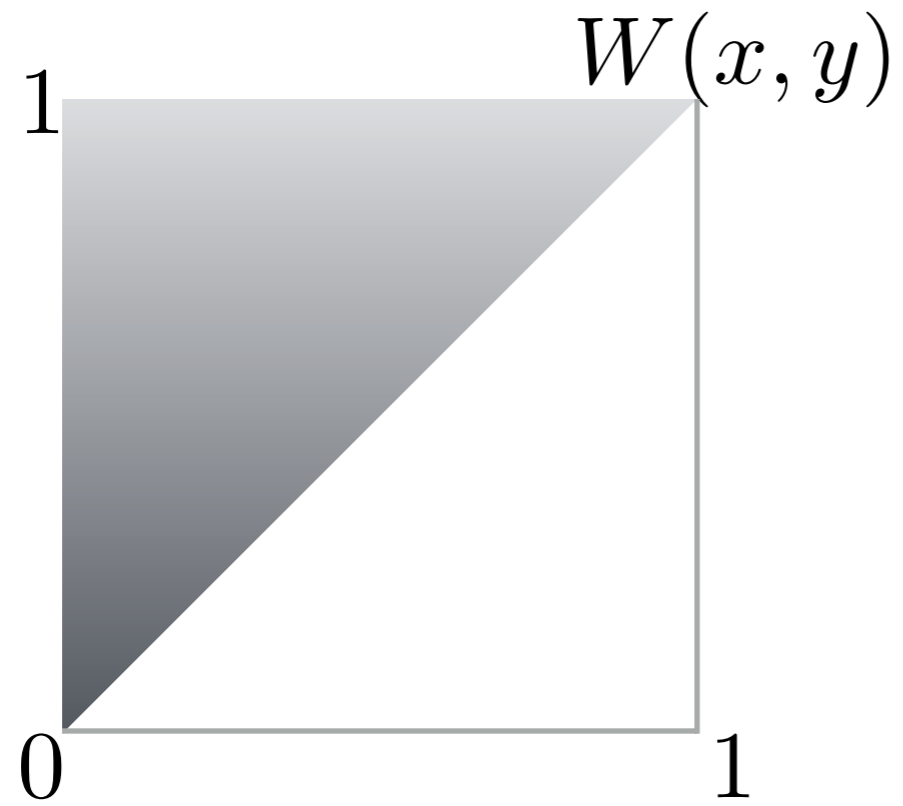


$$p(\text{graph with nodes 1, 2, 3, 4 and edges (1,2), (1,4), (2,4), (3,4)}) = p(\text{graph with nodes 1, 2, 3, 4 and edges (1,2), (1,4), (2,4), (3,4)})$$

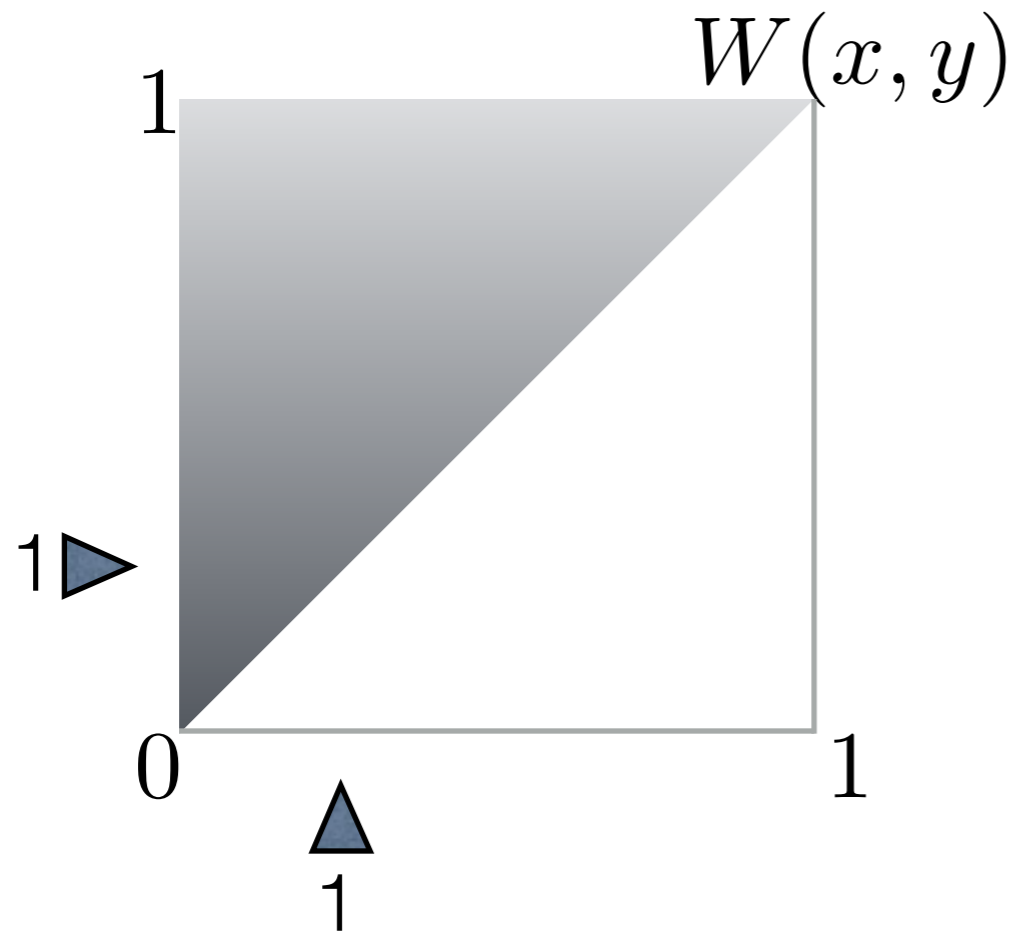
# Aldous-Hoover



# Aldous-Hoover

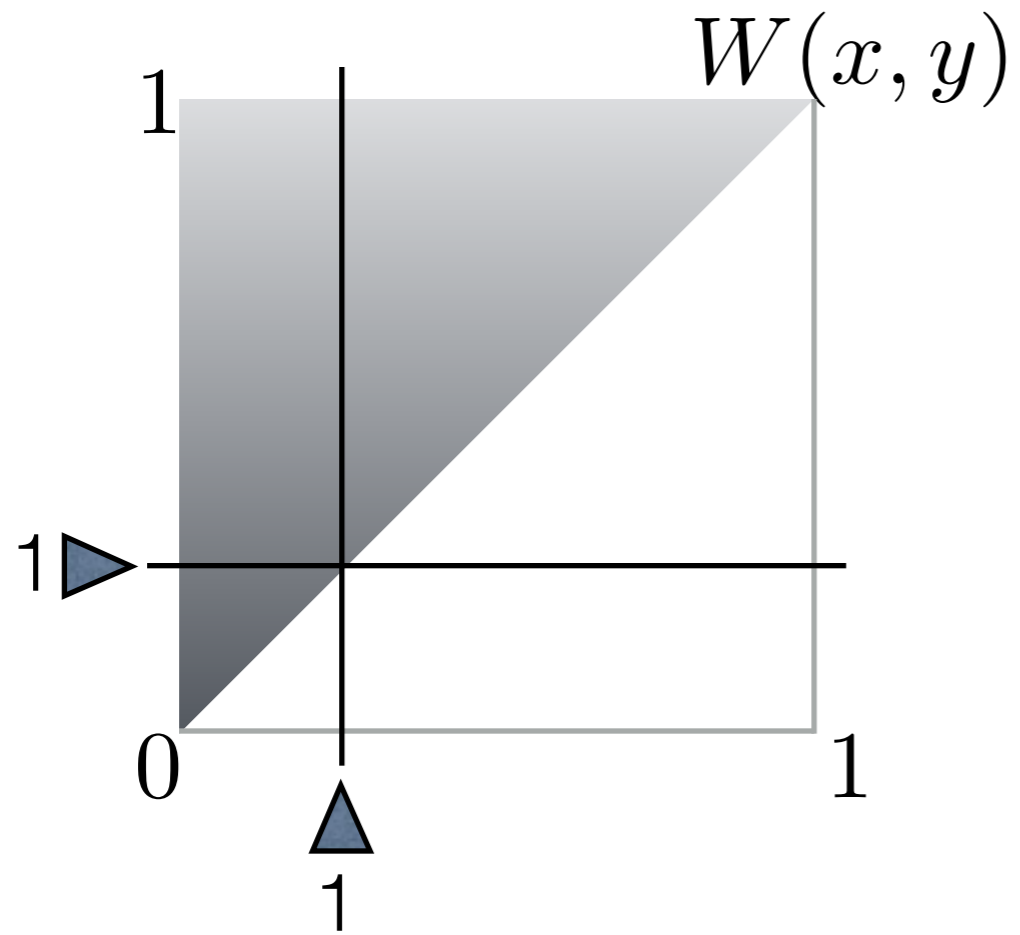


# Aldous-Hoover



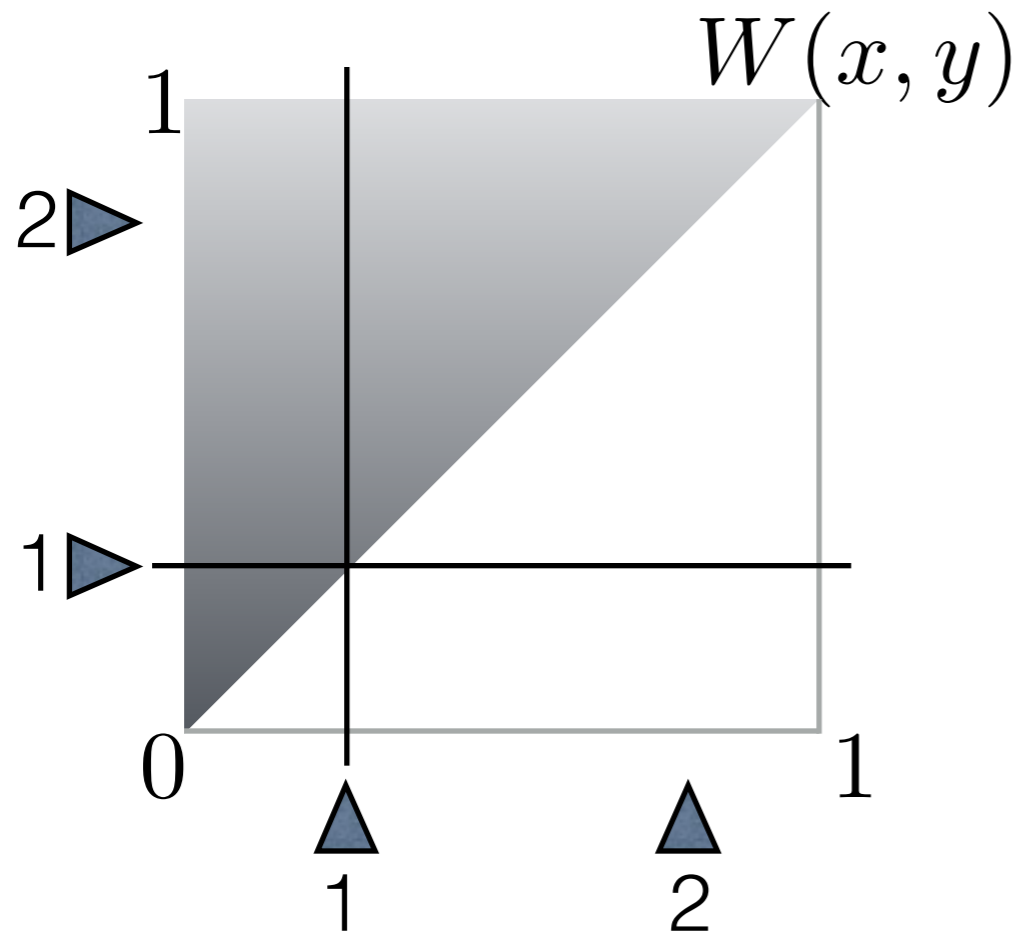
1

# Aldous-Hoover



1

# Aldous-Hoover

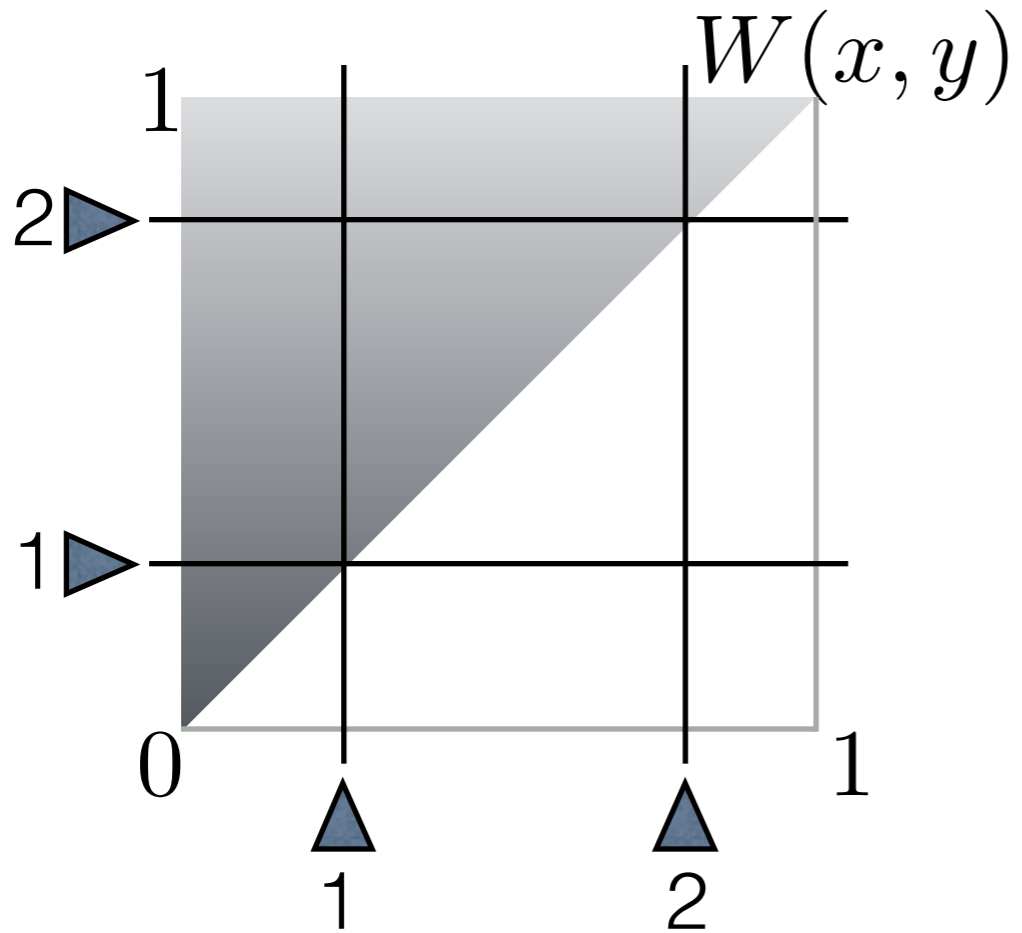


2

1



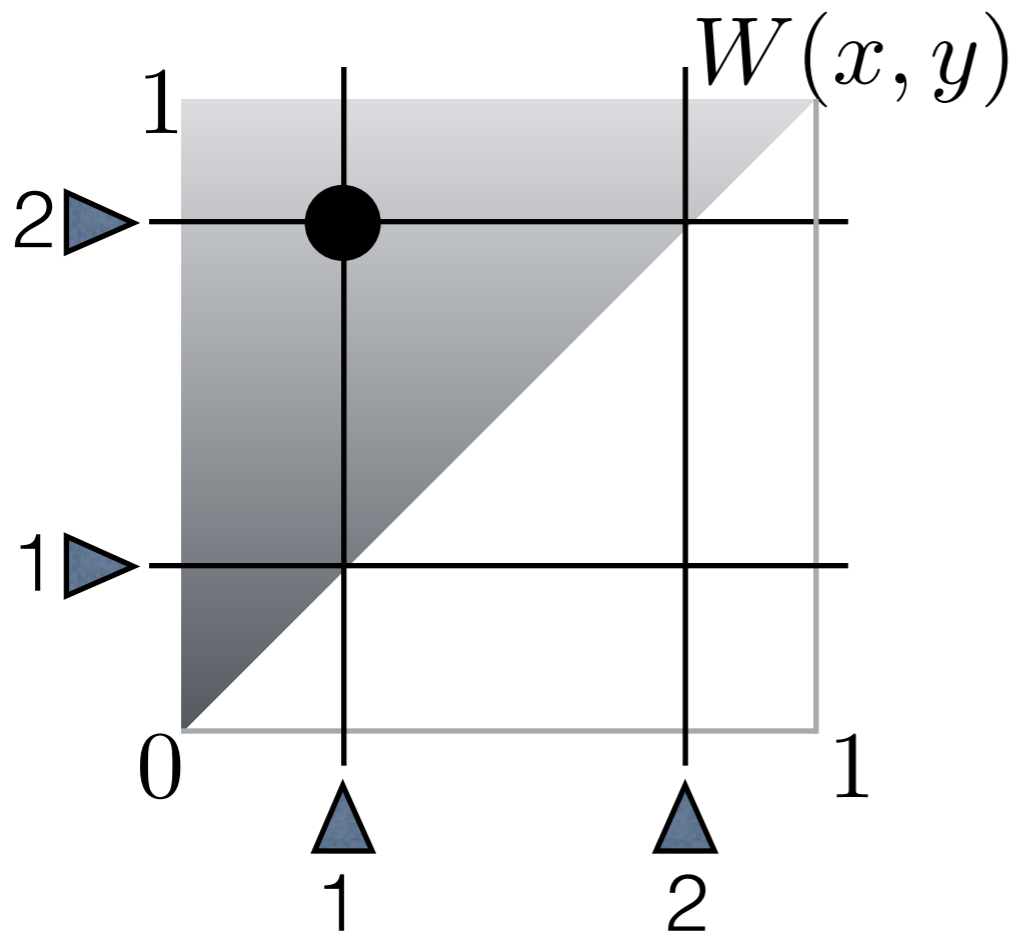
# Aldous-Hoover



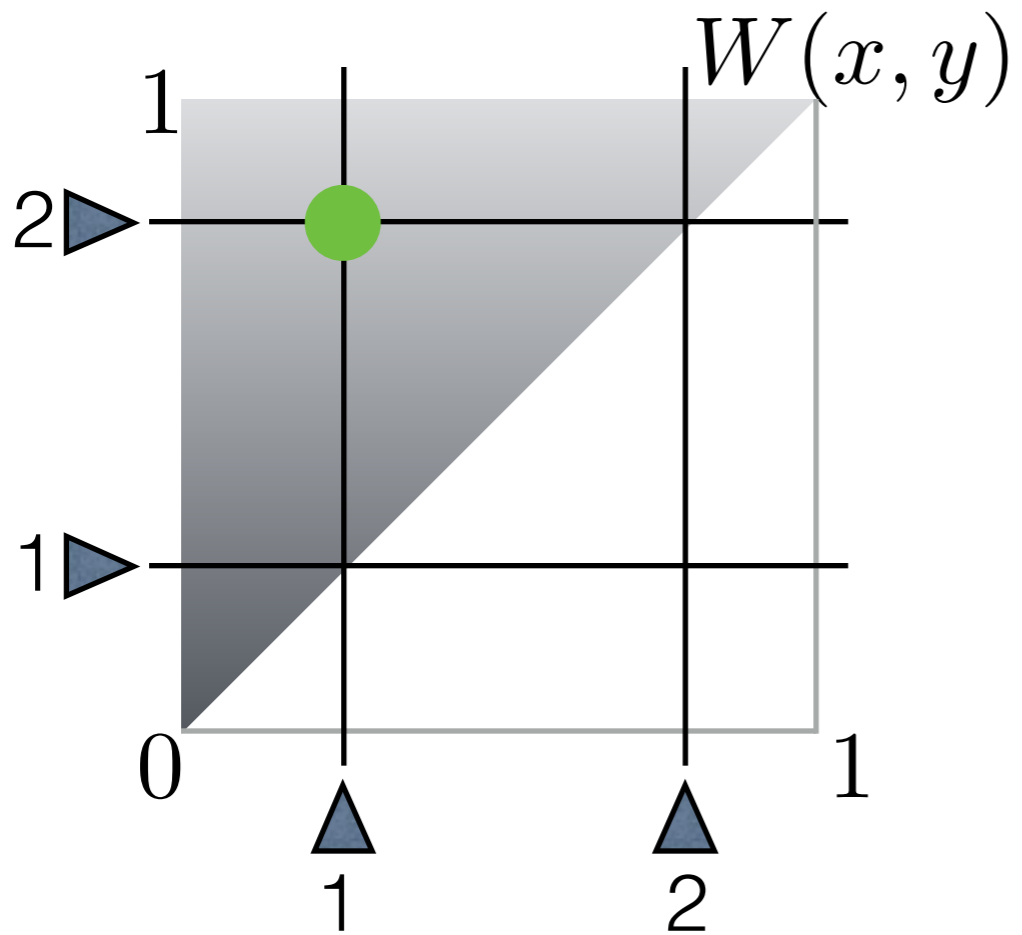
2

1

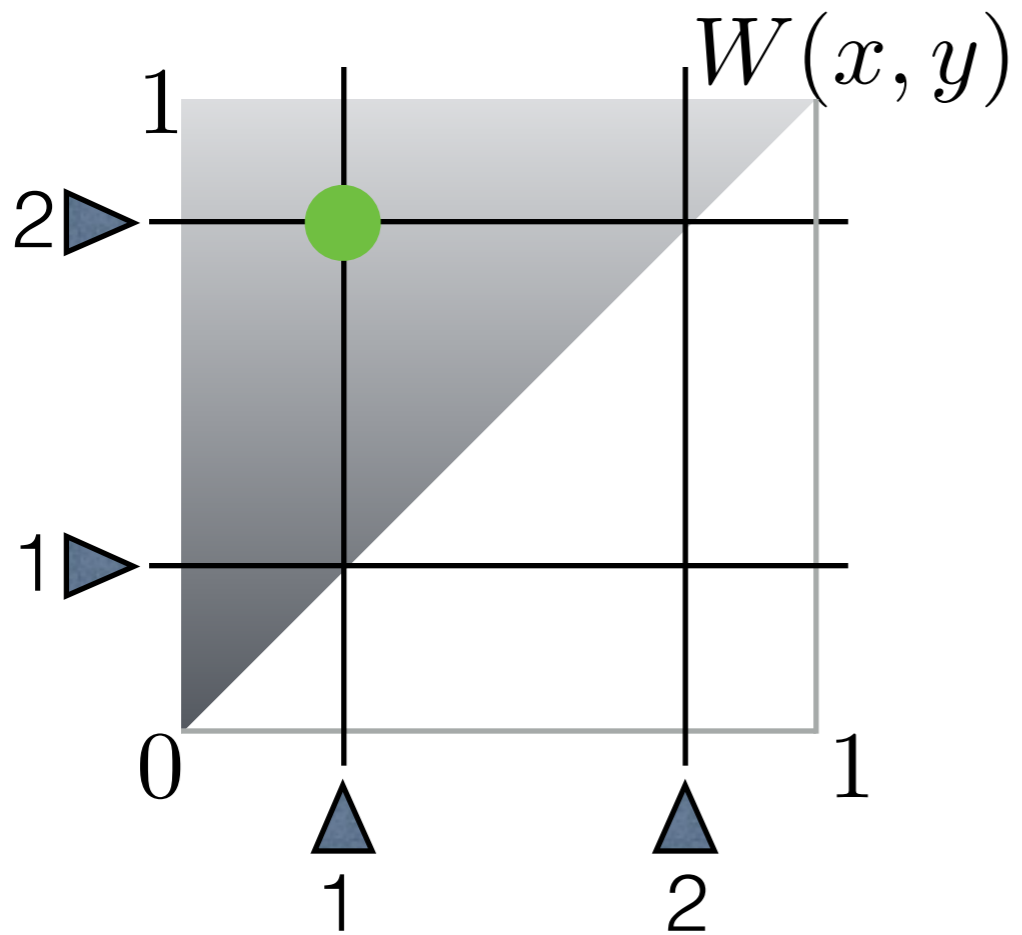
# Aldous-Hoover



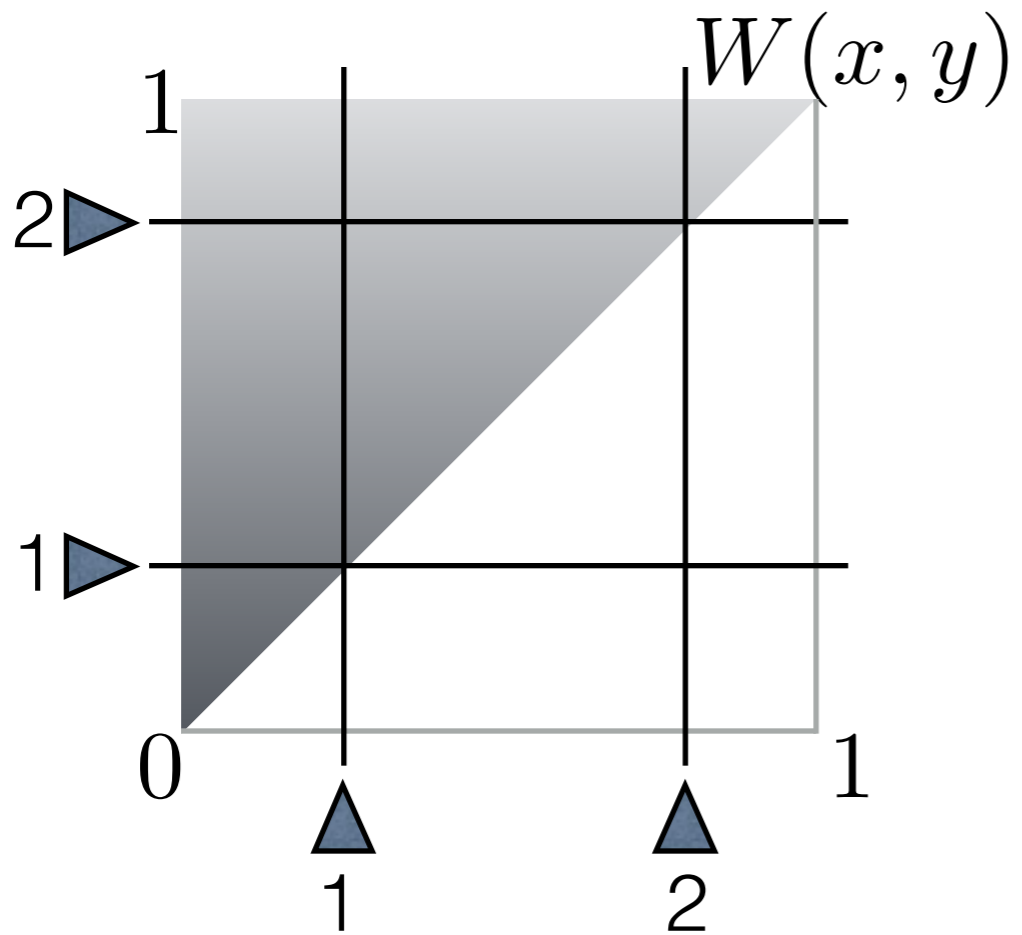
# Aldous-Hoover



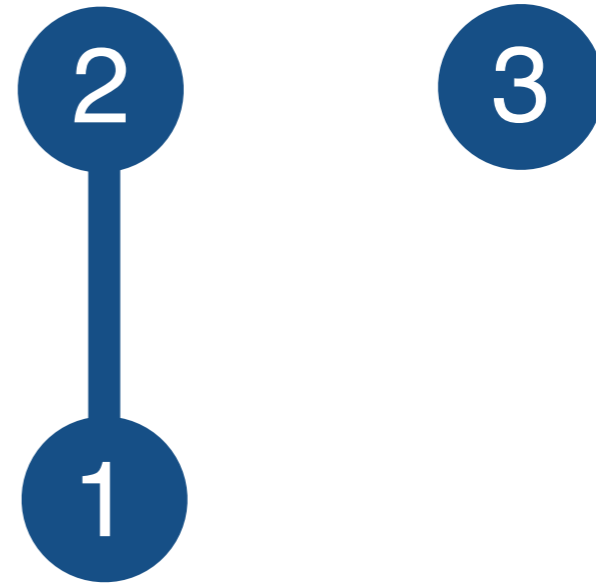
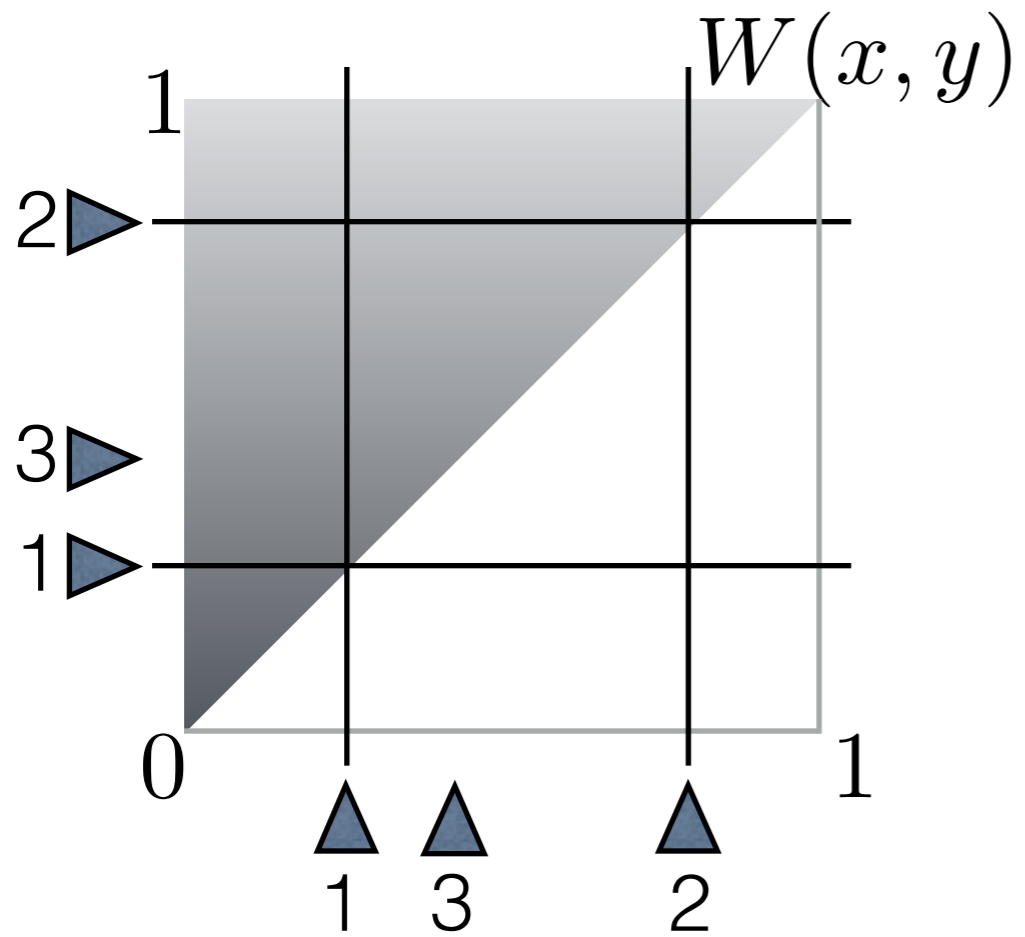
# Aldous-Hoover



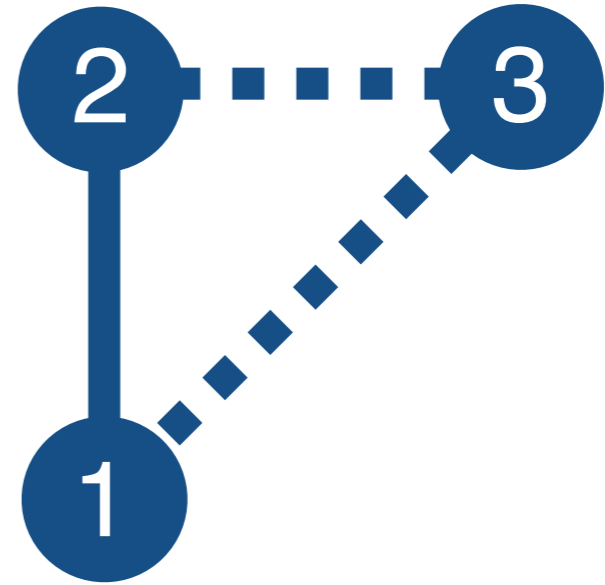
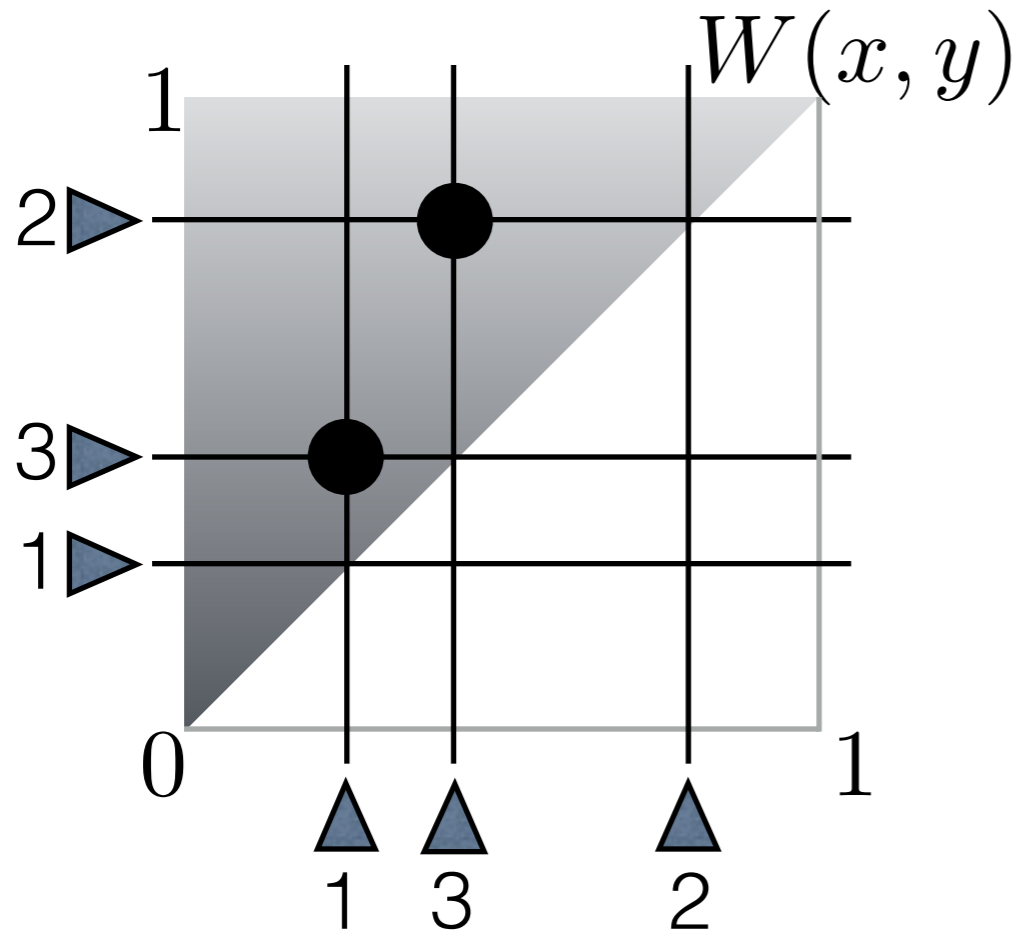
# Aldous-Hoover



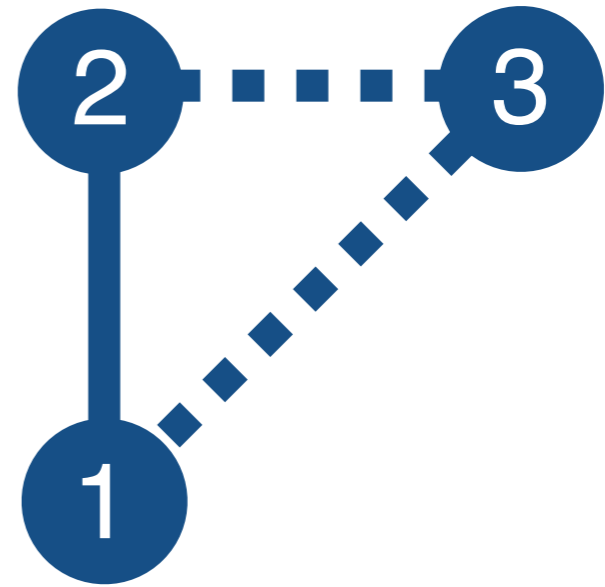
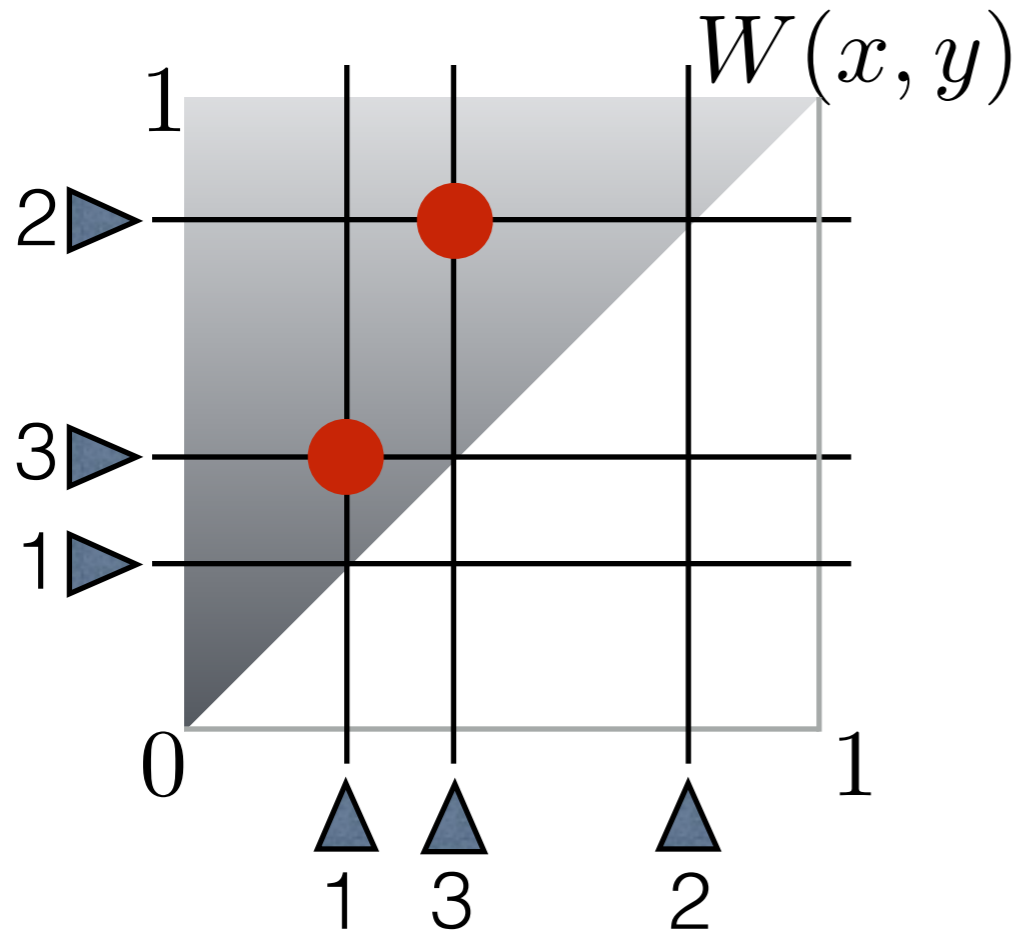
# Aldous-Hoover



# Aldous-Hoover

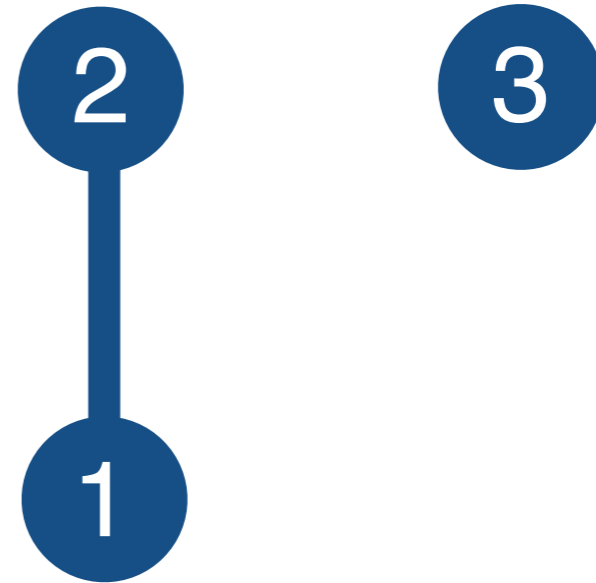
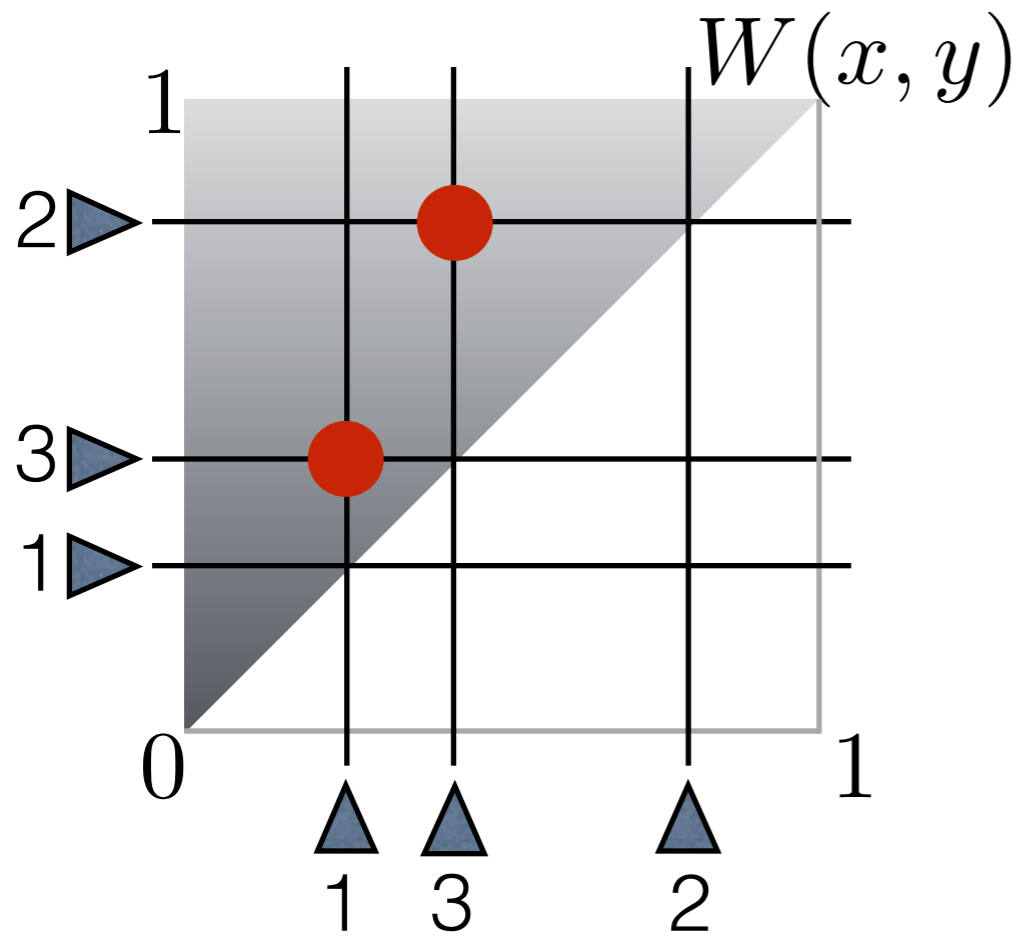


# Aldous-Hoover

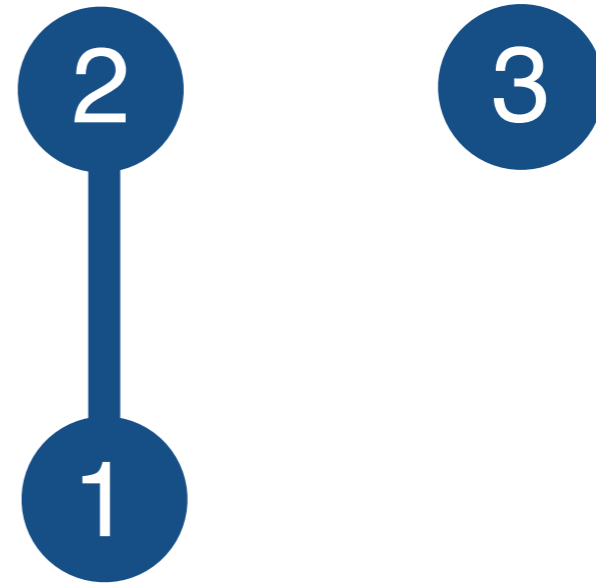
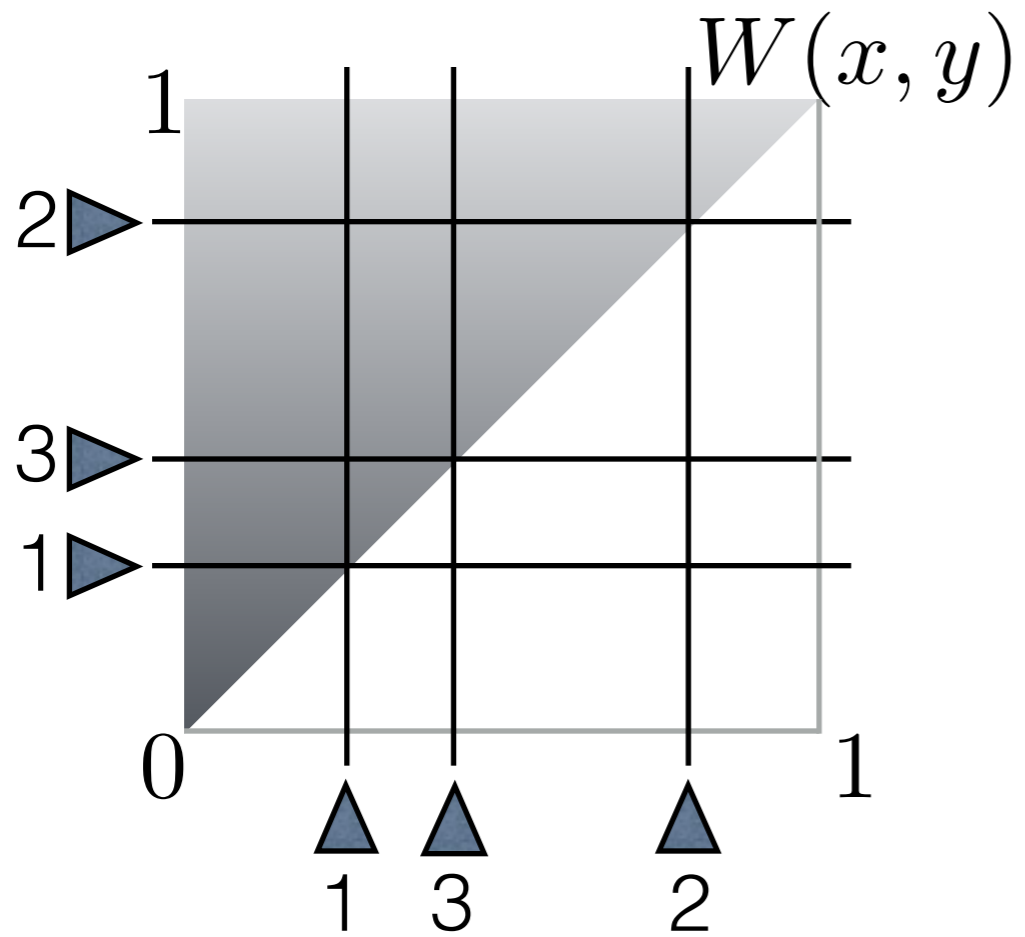




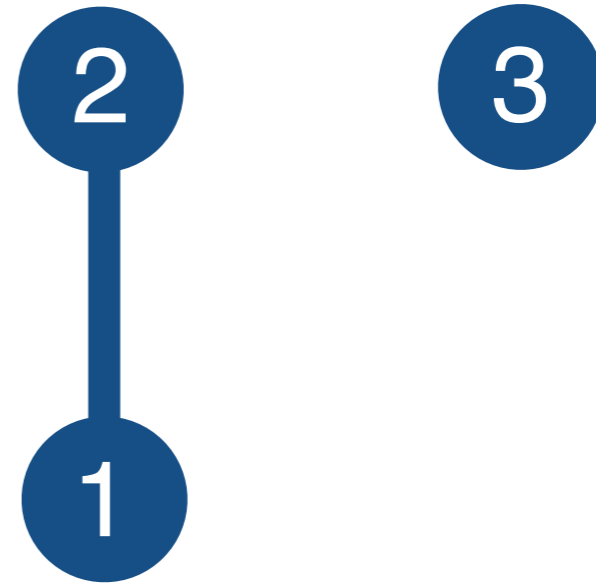
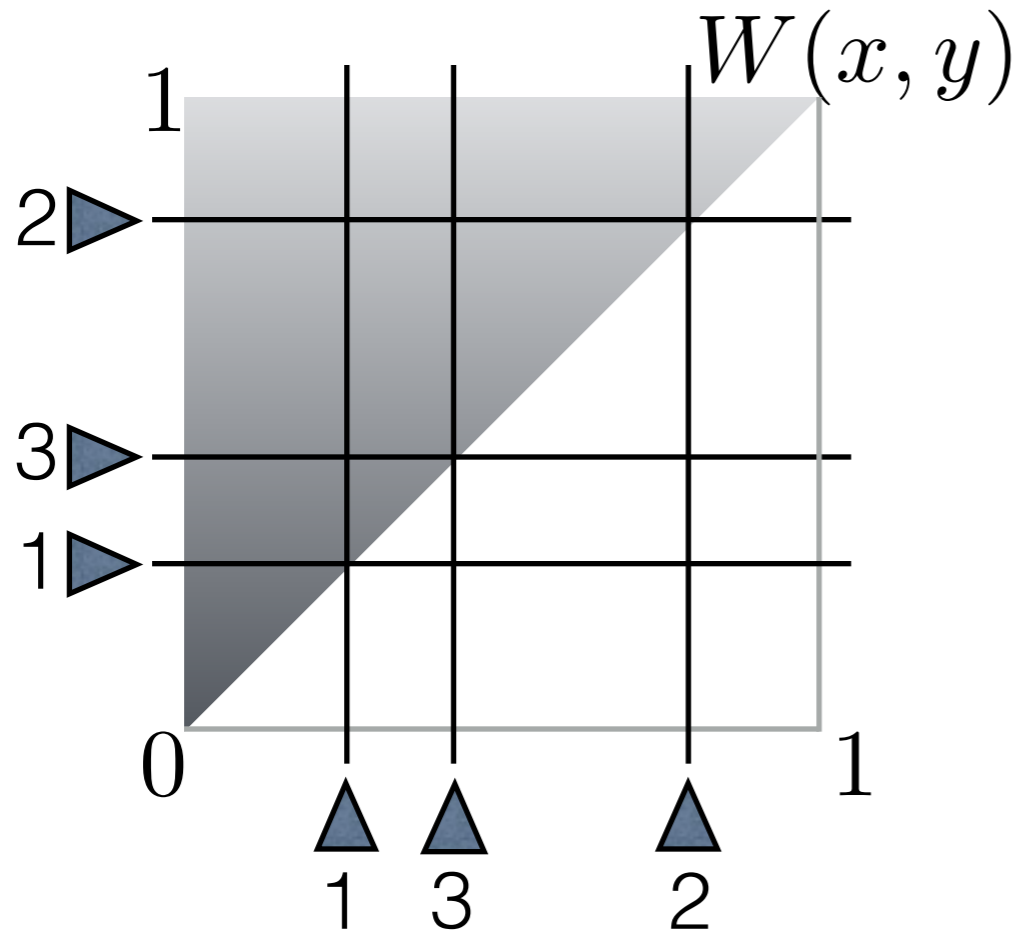
# Aldous-Hoover



# Aldous-Hoover

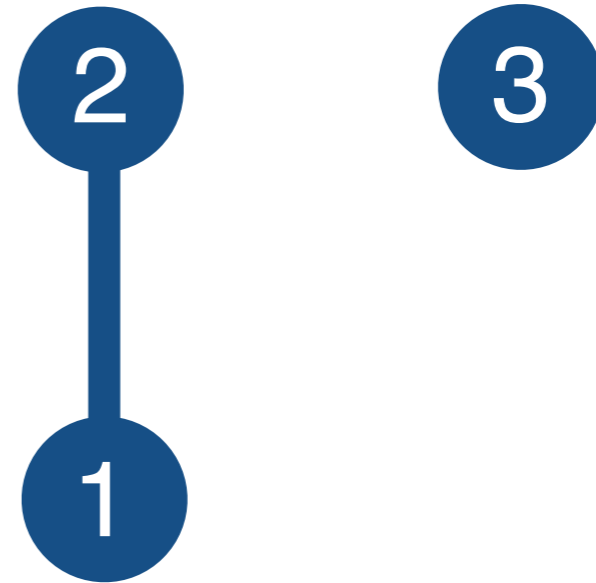
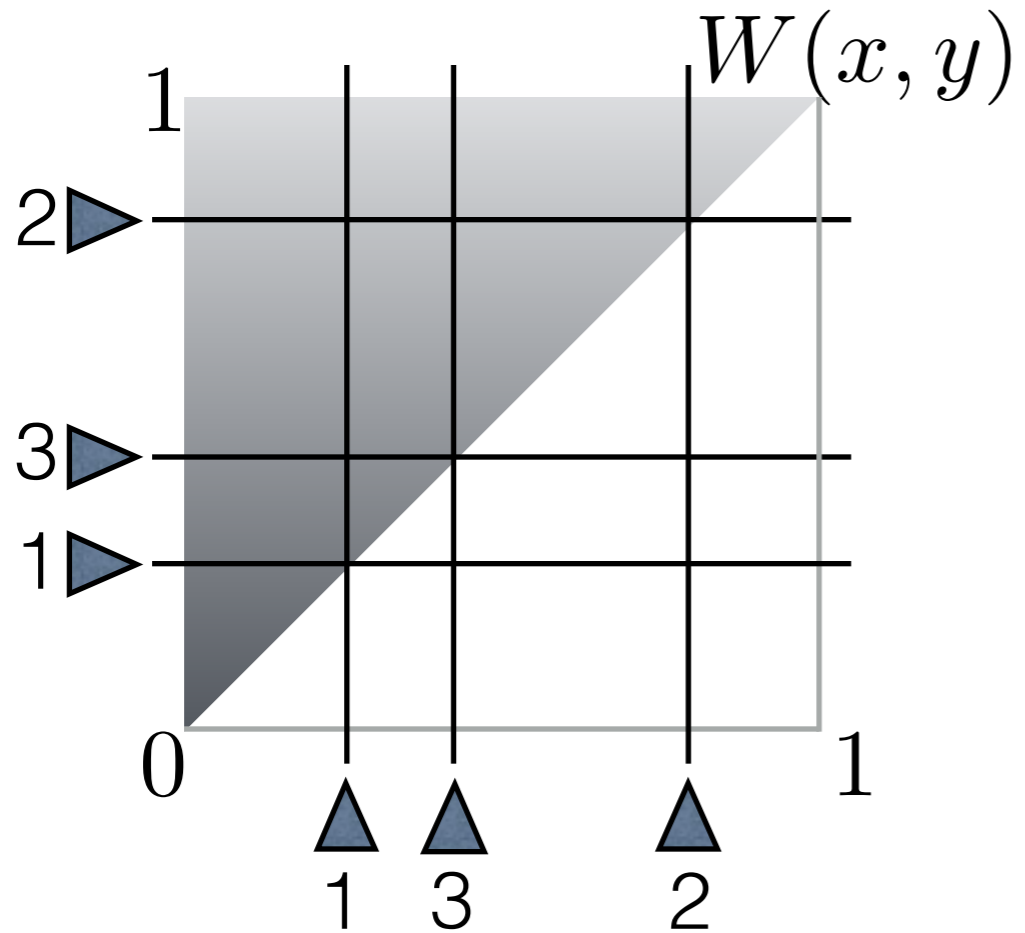


# Aldous-Hoover



Every node-exchangeable graph has a *graphon* rep

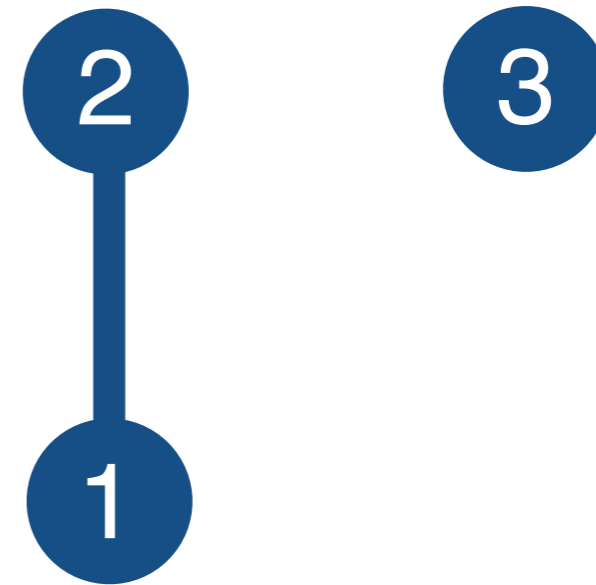
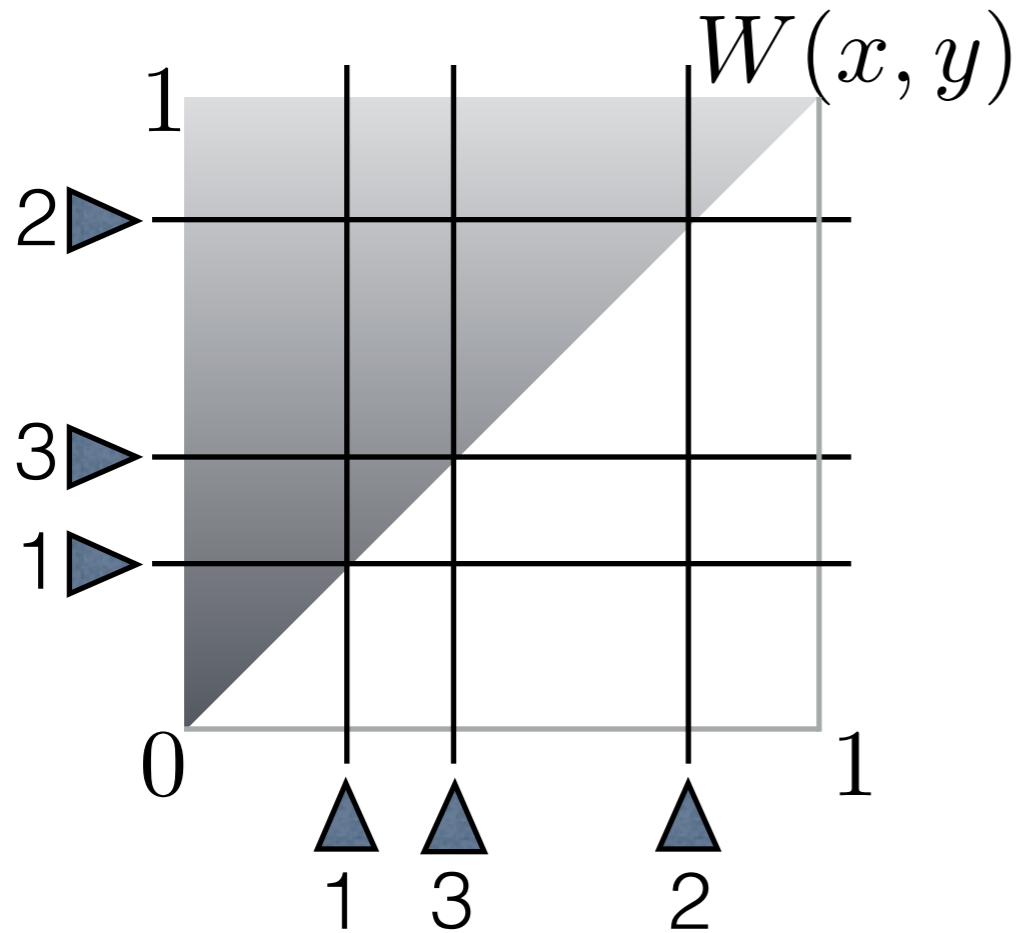
# Aldous-Hoover



Every node-exchangeable graph has a graphon rep

$$\mathbb{E}[\#\text{edges}(G_n)]$$

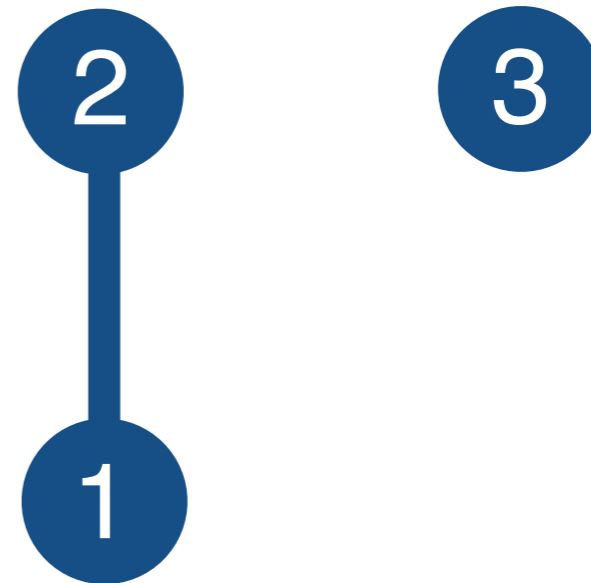
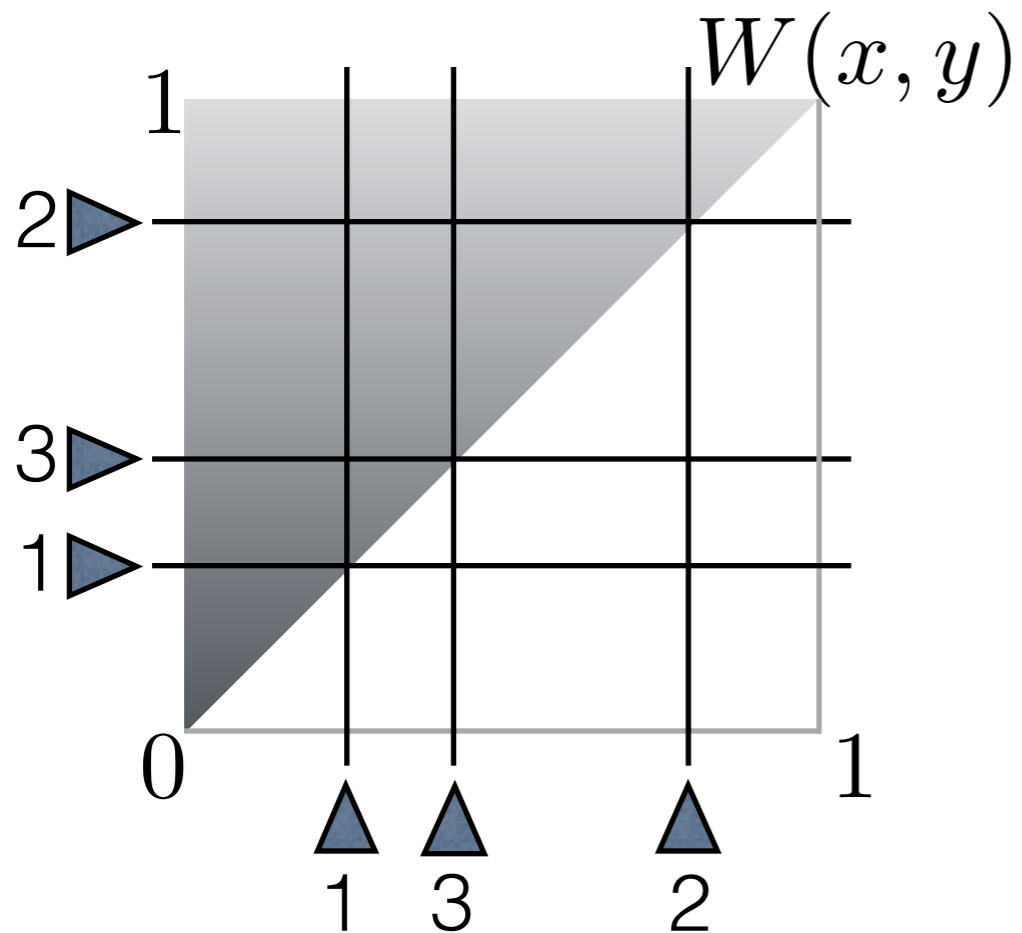
# Aldous-Hoover



Every node-exchangeable graph has a graphon rep

$$\mathbb{E}[\#\text{edges}(G_n)] = \mathbb{E} \left[ \binom{n}{2} \frac{1}{2} \int_0^1 \int_0^1 W(x, y) dx dy \right]$$

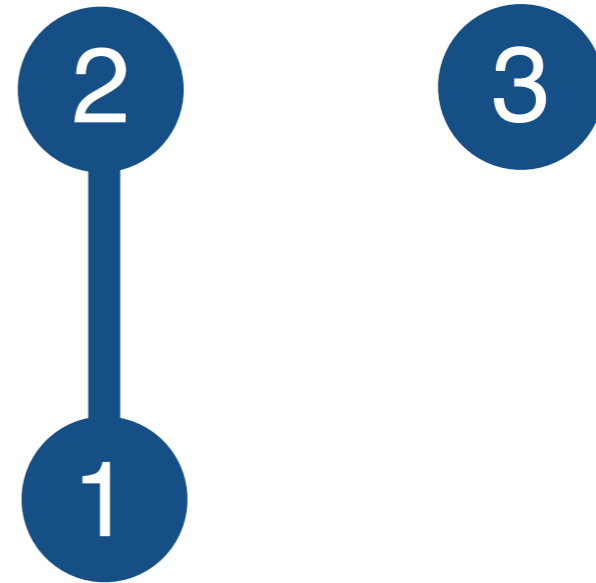
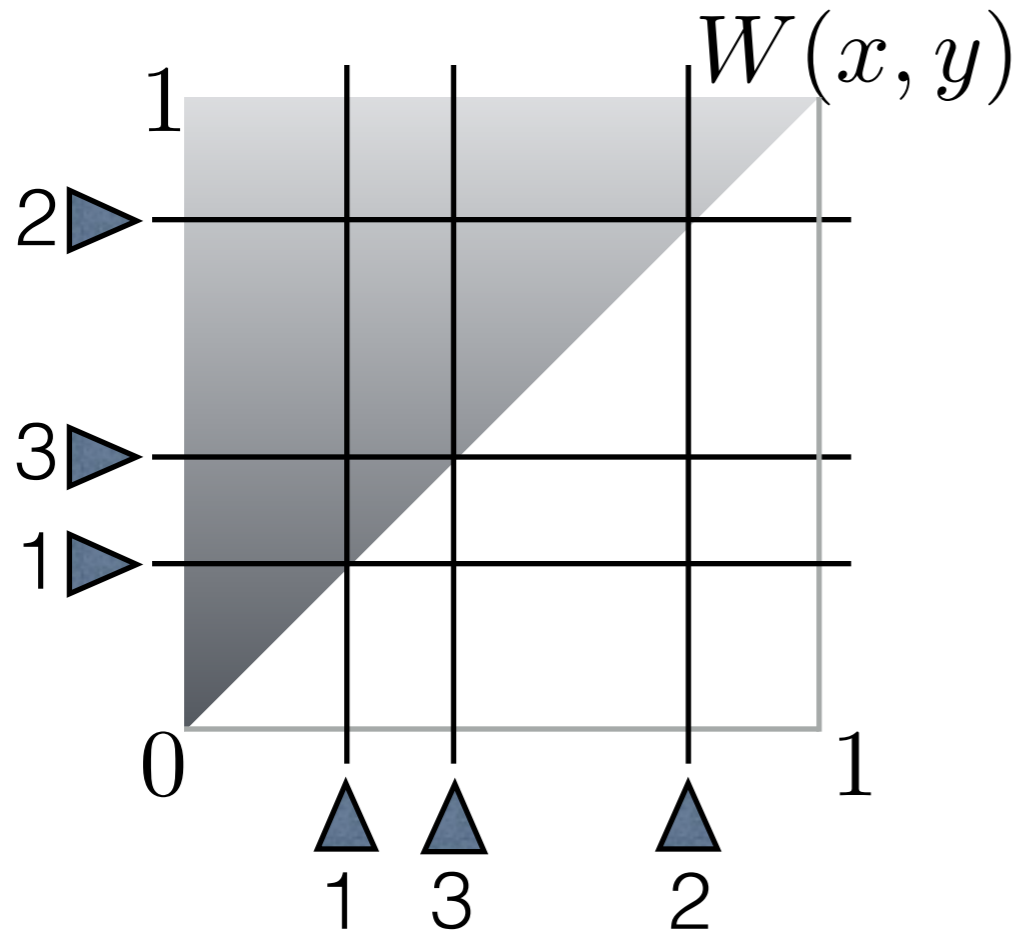
# Aldous-Hoover



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$$\sim cn^2$$

# Aldous-Hoover

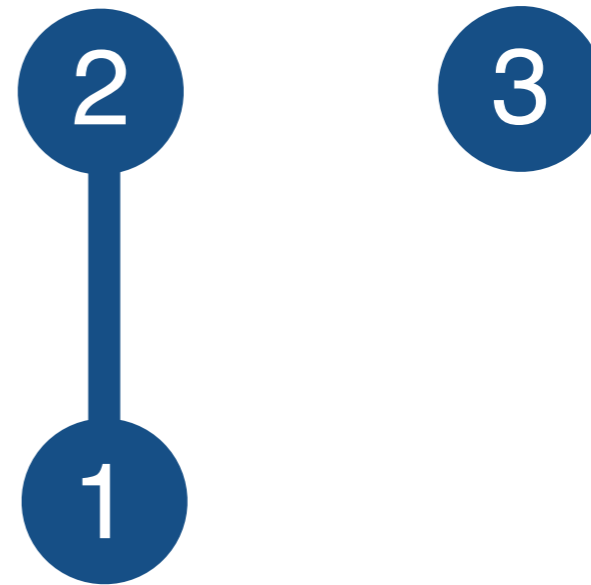
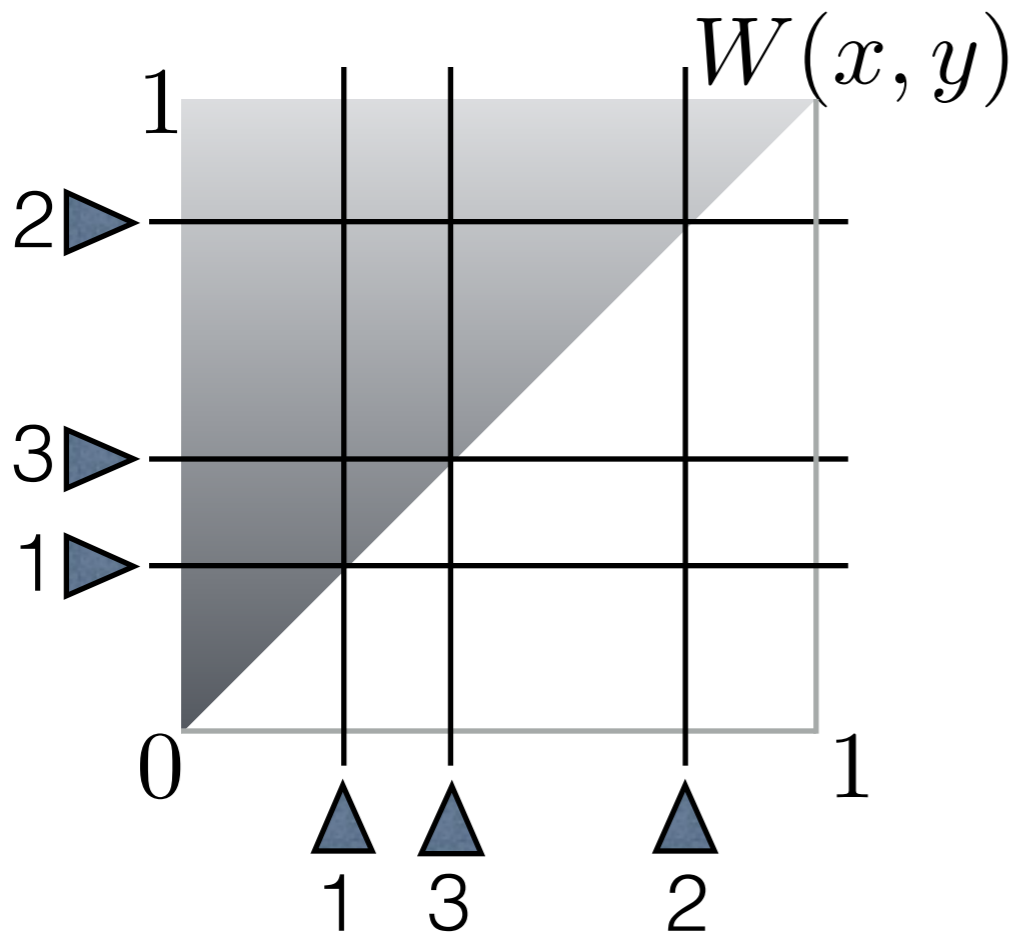


Every node-exchangeable graph has a graphon rep

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$$\sim cn^2 = c \cdot [\#\text{nodes}(G_n)]^2$$

# Aldous-Hoover



Every node-exchangeable graph has a graphon rep

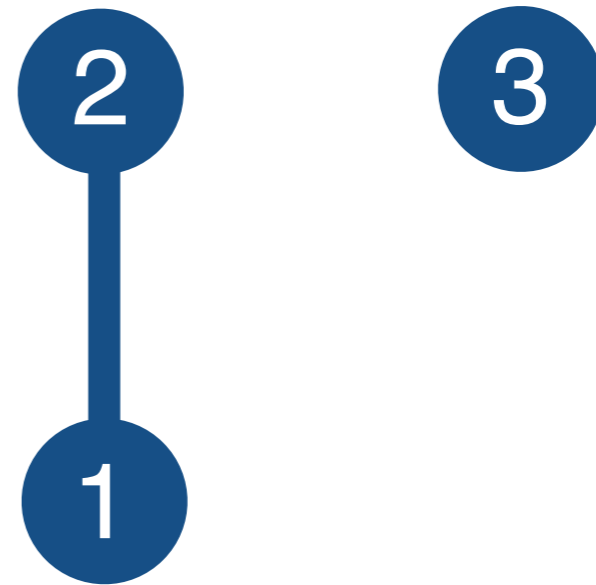
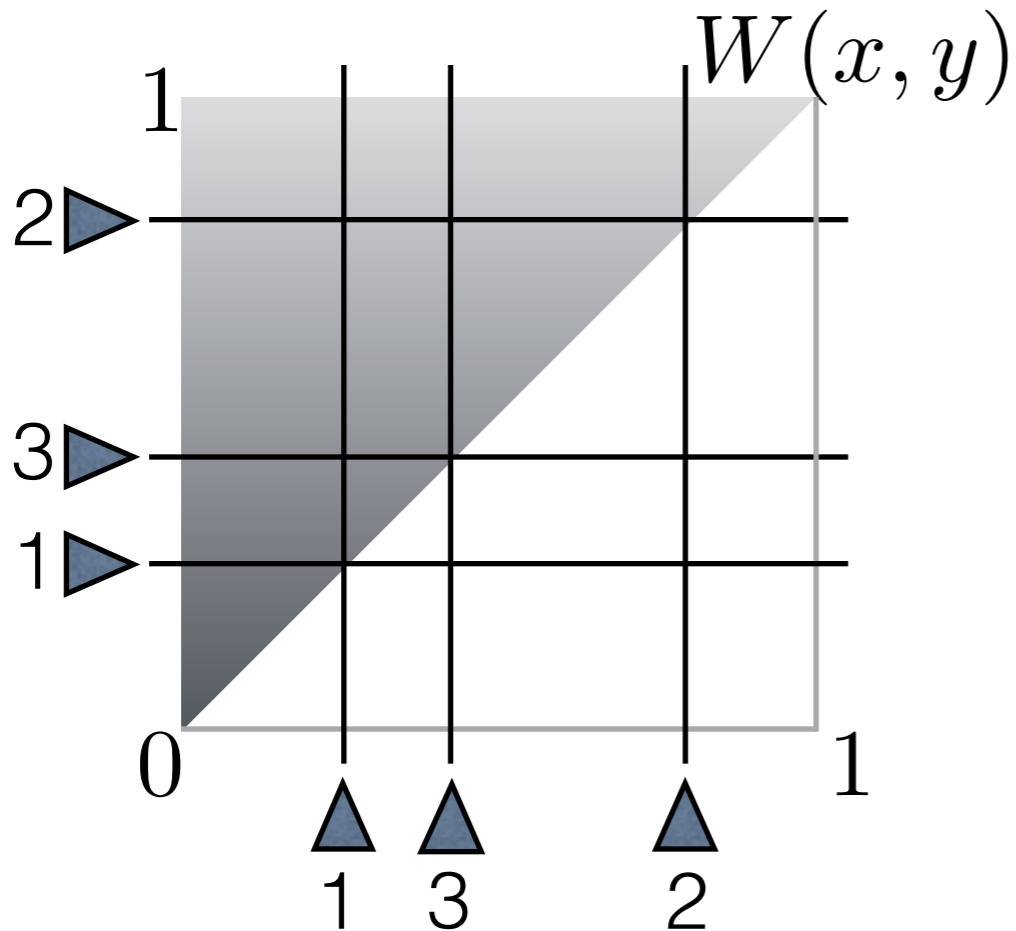
$$\mathbb{E}[\#\text{edges}(G_n)] = \mathbb{E} \left[ \binom{n}{2} \frac{1}{2} \int_0^1 \int_0^1 W(x, y) dx dy \right]$$

$$\sim cn^2 = c \cdot [\#\text{nodes}(G_n)]^2$$

Every node-exch graph sequence is dense (or empty)



# Aldous-Hoover



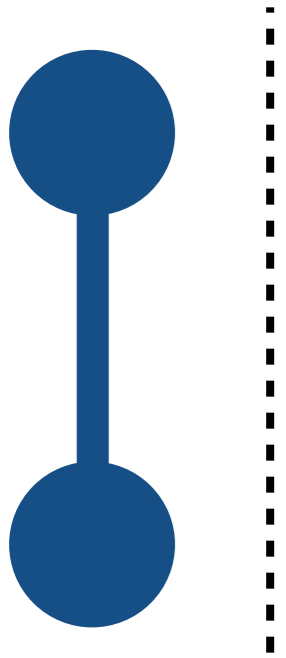
Every node-exchangeable graph has a graphon rep

$$\mathbb{E}[\#\text{edges}(G_n)] = \mathbb{E} \left[ \binom{n}{2} \frac{1}{2} \int_0^1 \int_0^1 W(x, y) dx dy \right]$$

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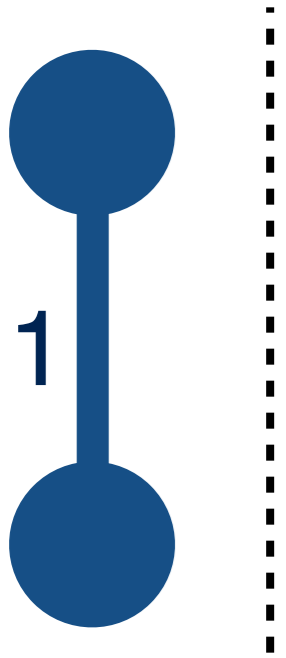
Every node-exch graph sequence is dense (or empty)

# A New Way: Edges



$G_1$

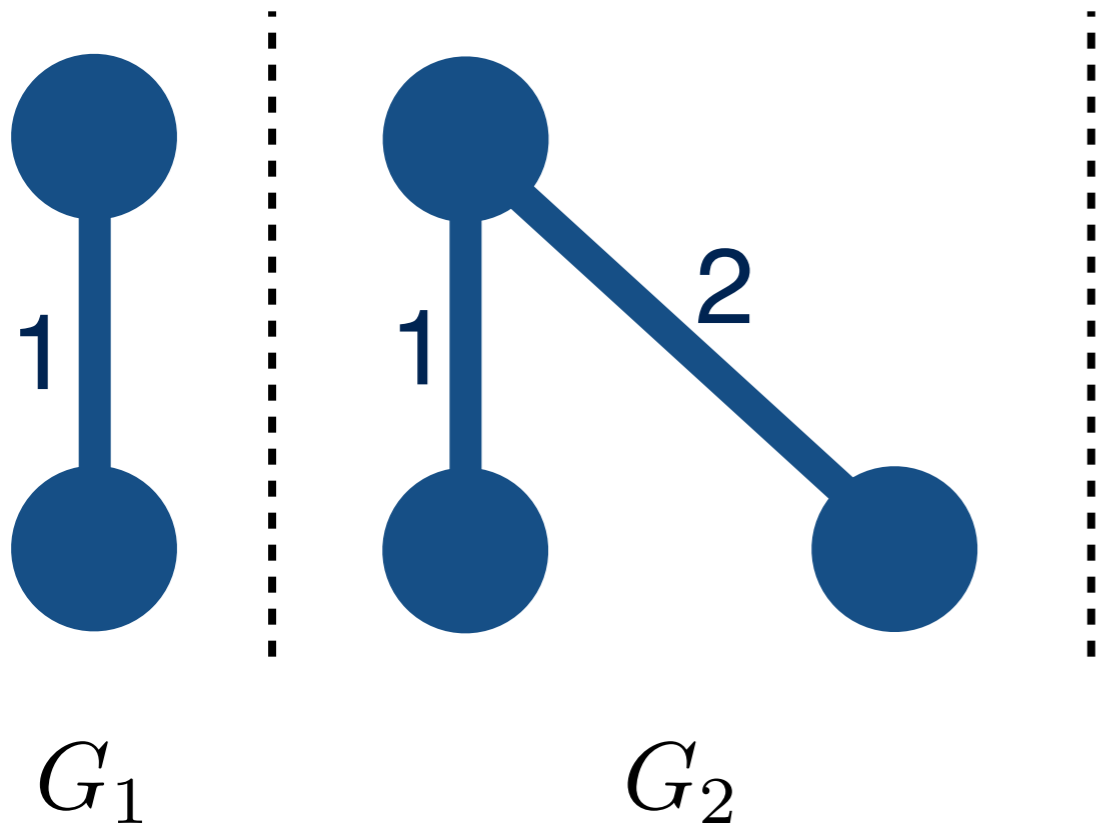
# A New Way: Edges



1

$G_1$

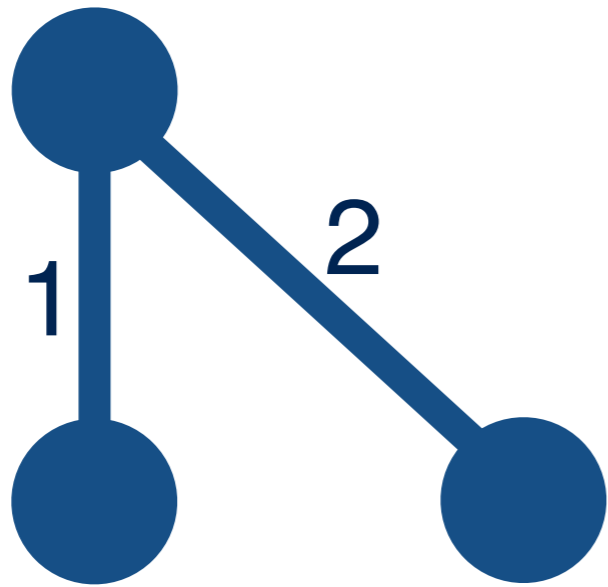
# A New Way: Edges



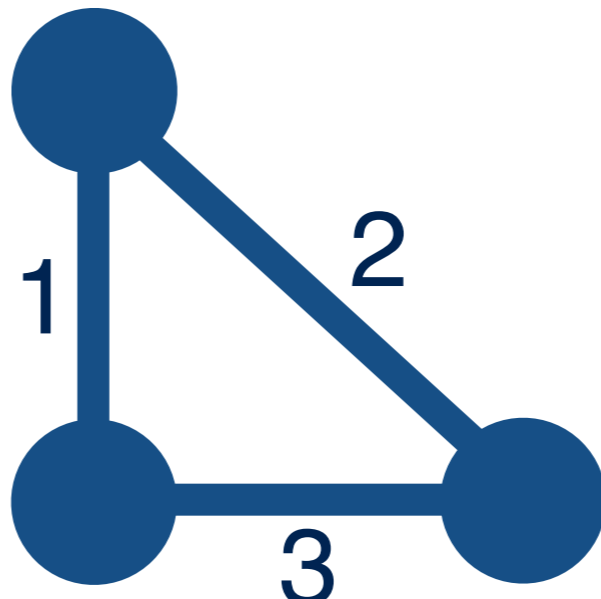
# A New Way: Edges



$G_1$



$G_2$



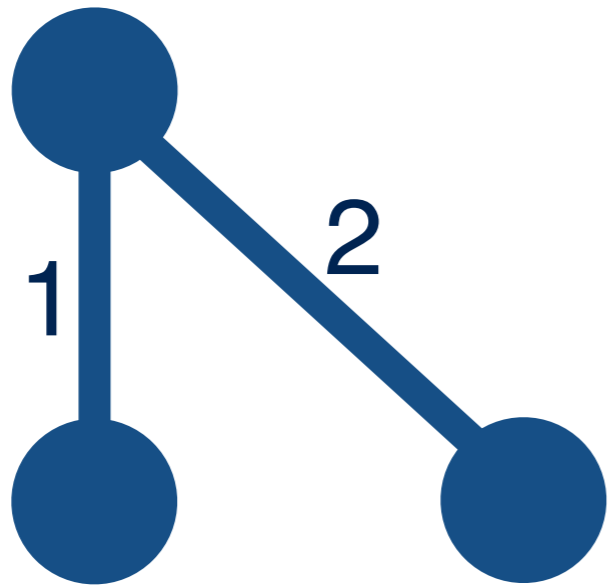
$G_3$



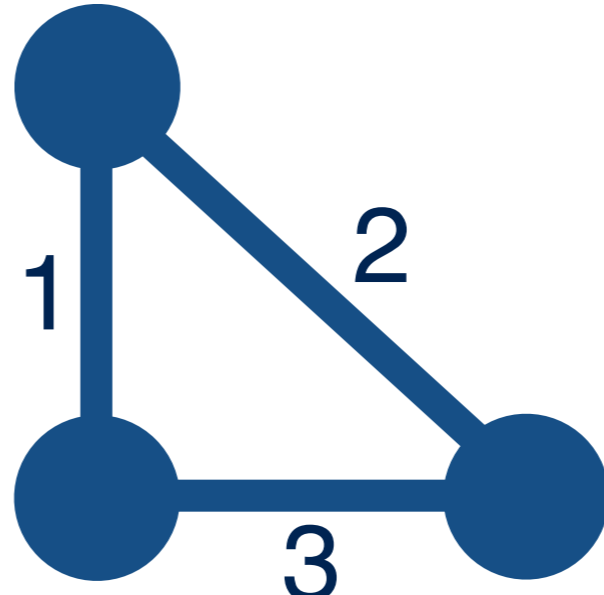
# A New Way: Edges



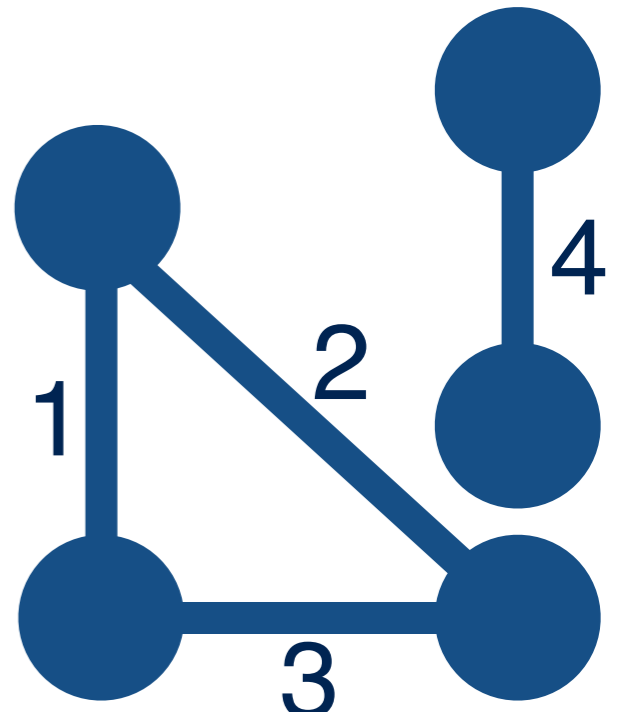
$G_1$



$G_2$

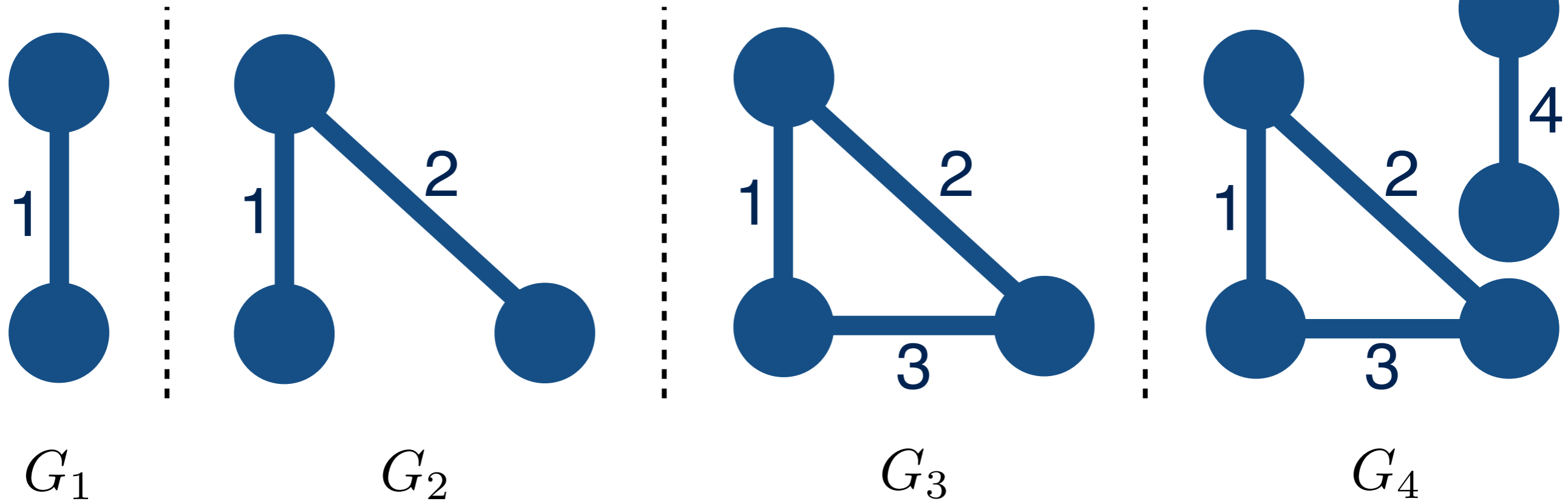


$G_3$



$G_4$

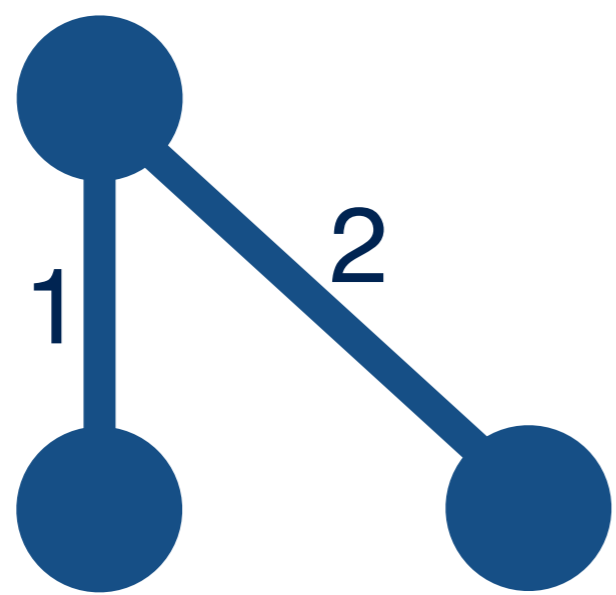
# Edge exchangeability



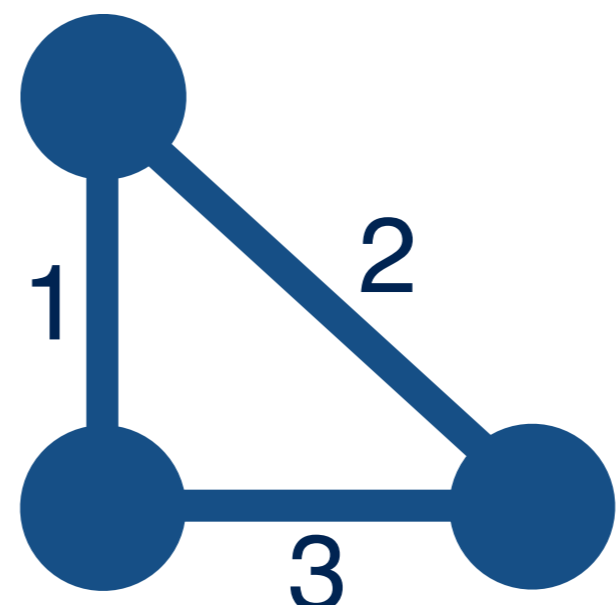
# Edge exchangeability



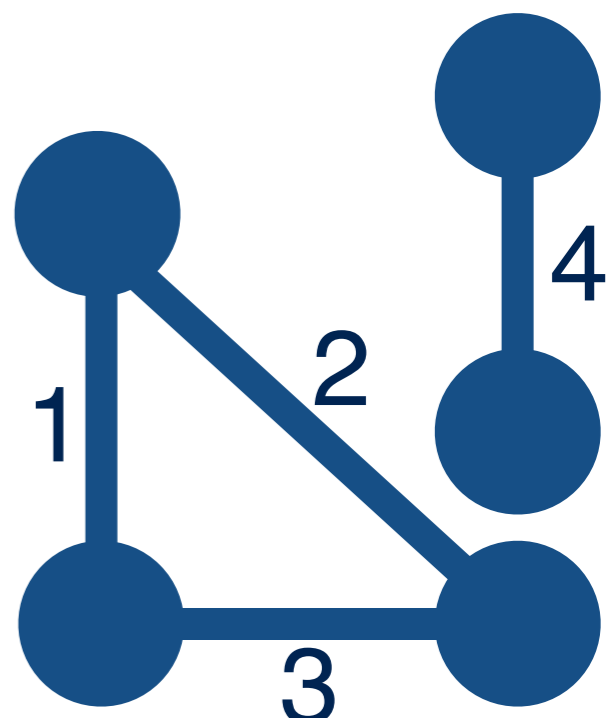
$G_1$



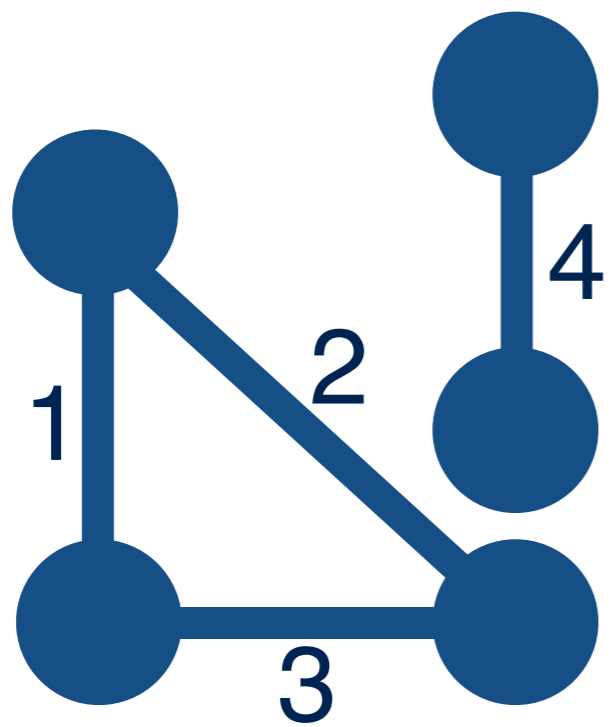
$G_2$



$G_3$



$G_4$

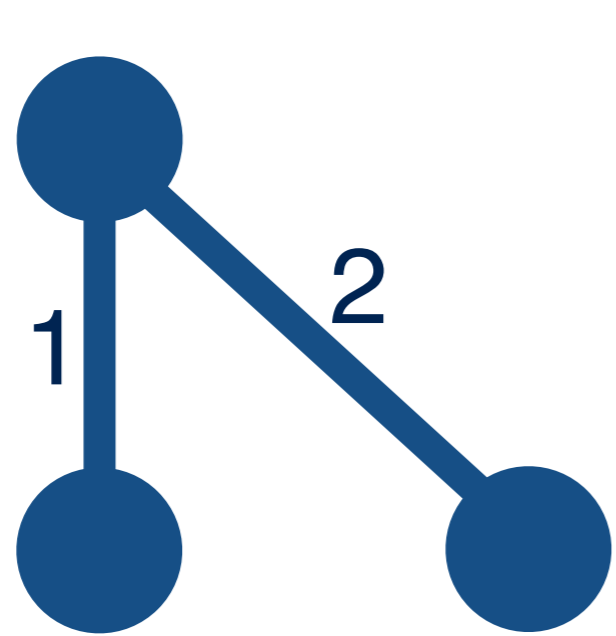




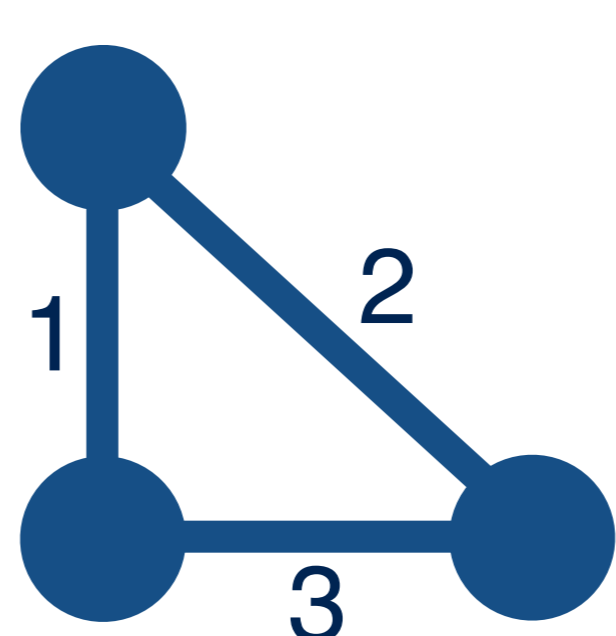
# Edge exchangeability



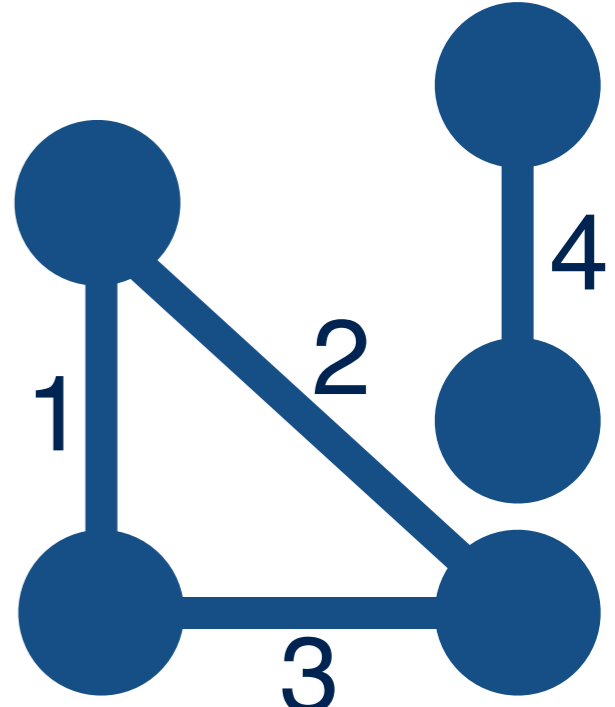
$G_1$



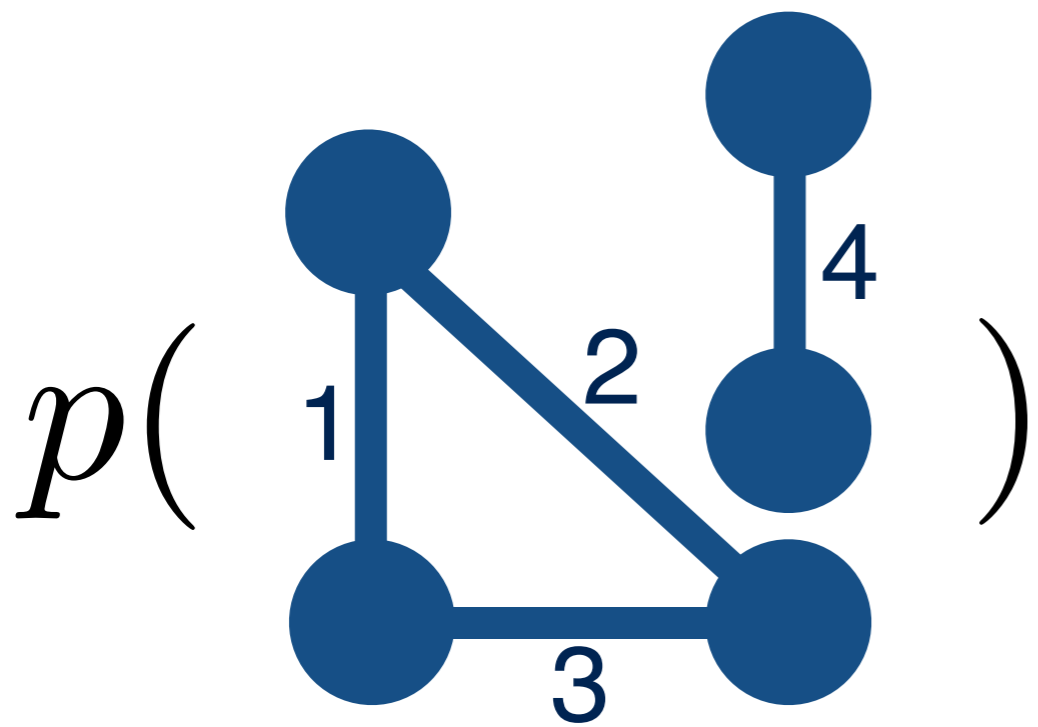
$G_2$



$G_3$



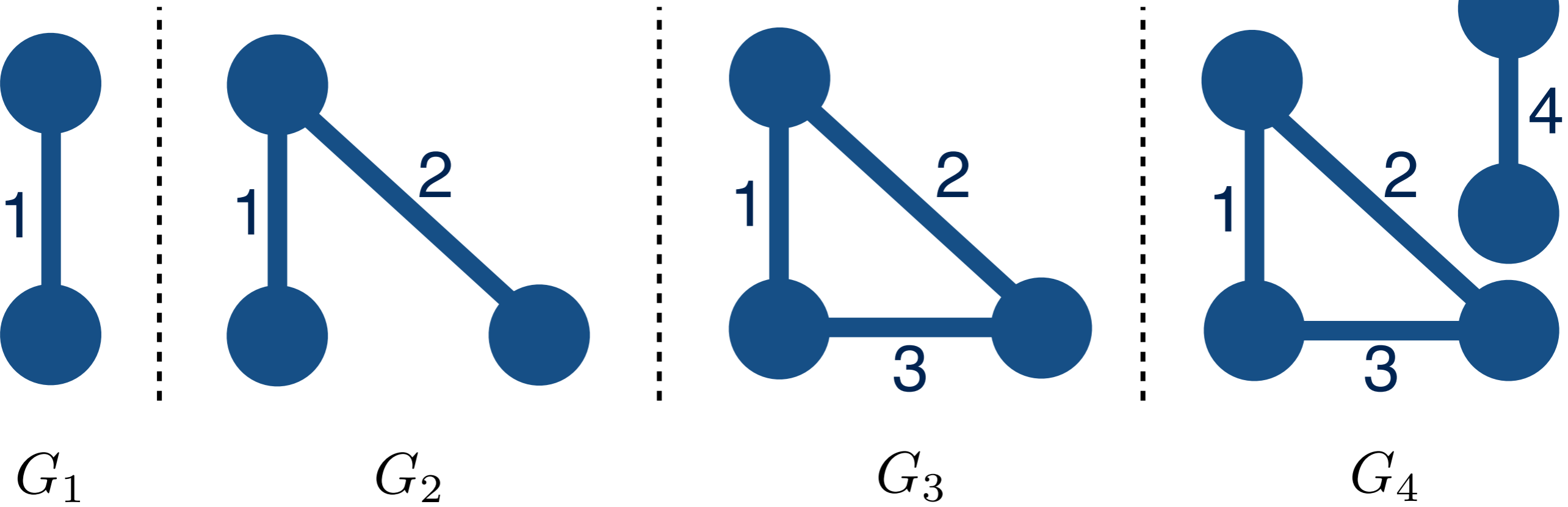
$G_4$



$p($

$)$

# Edge exchangeability



$$p\left( \begin{array}{c} \text{Graph with edges } 1, 2, 3, 4 \end{array} \right) = p\left( \begin{array}{c} \text{Graph with edges } 2, 4, 1, 3 \end{array} \right)$$

# Edge exchangeability



**Thm. A wide range of edge-exchangeable graph sequences are sparse**

$G_1$                        $G_2$                        $G_3$                        $G_4$

**Thm. A paintbox-style characterization for edge-exchangeable graph sequences**

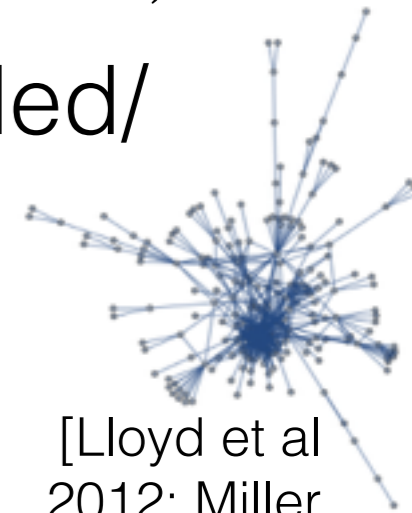
$$p\left( \begin{array}{c} \text{1} \quad \text{2} \\ \text{---} \quad \text{---} \\ \text{---} \quad \text{---} \\ \text{3} \end{array} \right) = p\left( \begin{array}{c} \text{2} \quad \text{4} \\ \text{---} \quad \text{---} \\ \text{---} \quad \text{---} \\ \text{1} \end{array} \right)$$

# Nonparametric Bayes

- Bayesian methods that are not parametric
- Bayesian

$$\mathbb{P}(\text{parameters}|\text{data}) \propto \mathbb{P}(\text{data}|\text{parameters})\mathbb{P}(\text{parameters})$$

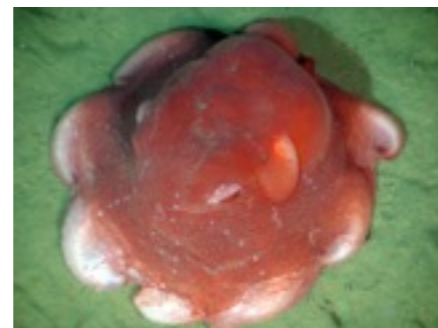
- Not parametric (i.e. not finite parameter, unbounded/growing/infinite number of parameters)



[Lloyd et al 2012; Miller et al, 2010]



[wikipedia.org]

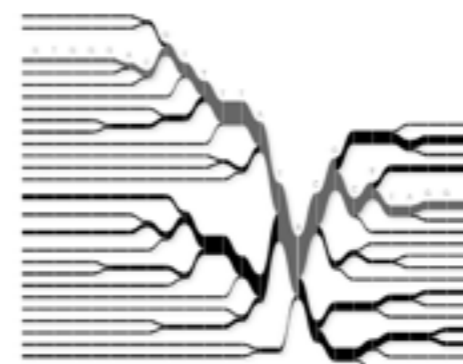
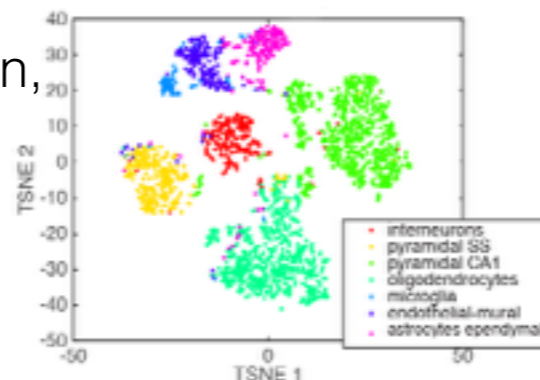


[Ed Bowlby, NOAA]

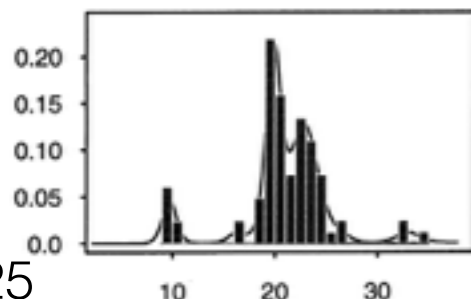


[Fox, et al 2014]

[Prabhakaran, Azizi, Carr, Pe'er 2016]

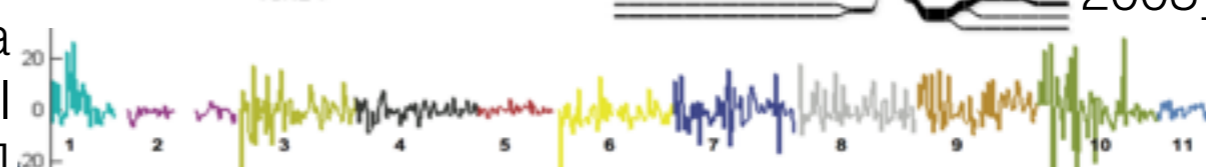


[Ewens, 1972; Hartl, Clark 2003]



[Escobar, West 1995; Ghosal, et al 1999]

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