

# 6.036/6.862: Introduction to Machine Learning

Lecture: starts Tuesdays 9:35am (Boston time zone)

Course website: introml.odl.mit.edu

Who's talking? Prof. Tamara Broderick

Questions? discourse.odl.mit.edu ("Lecture 3" category)

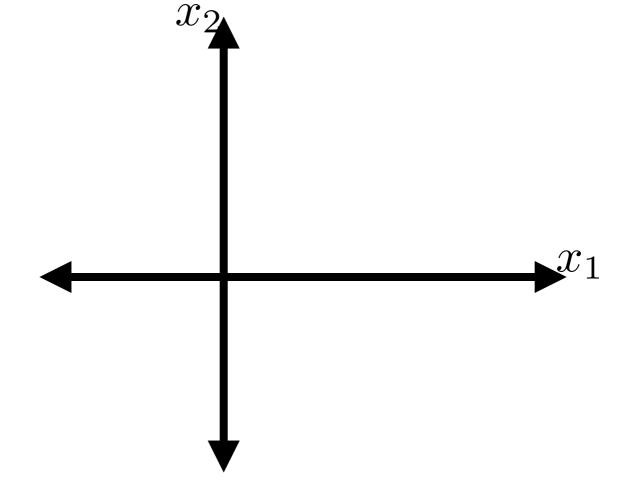
Materials: Will all be available at course website

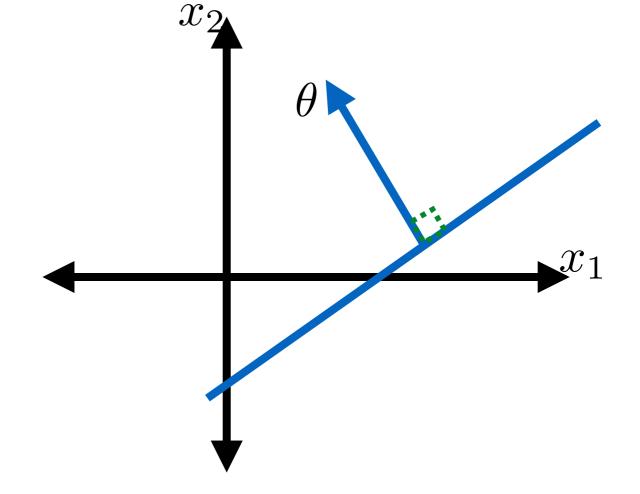
#### Last Time(s)

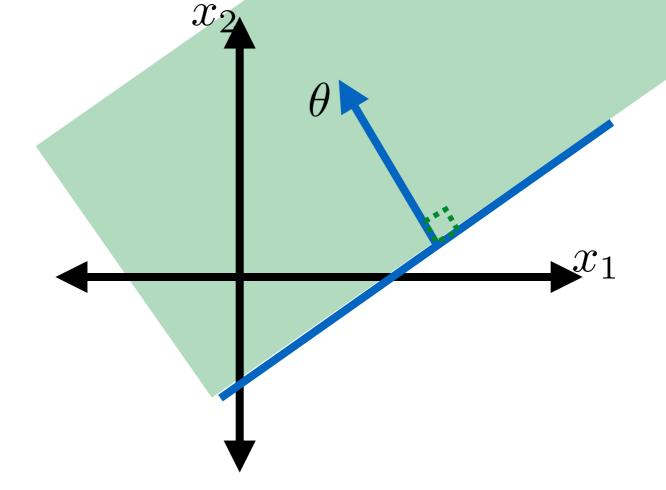
- I. Linear classifiers
- II. Perceptron algorithm
- III. Linear separability
- IV. Perceptron theorem

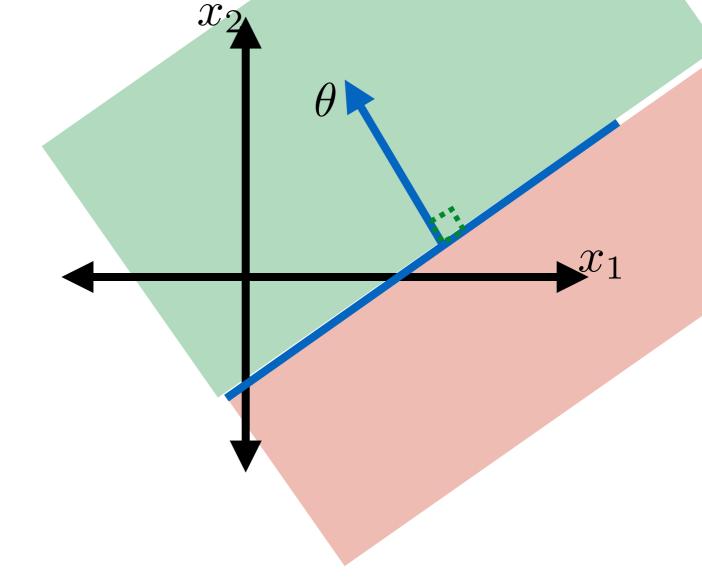
#### Today's Plan

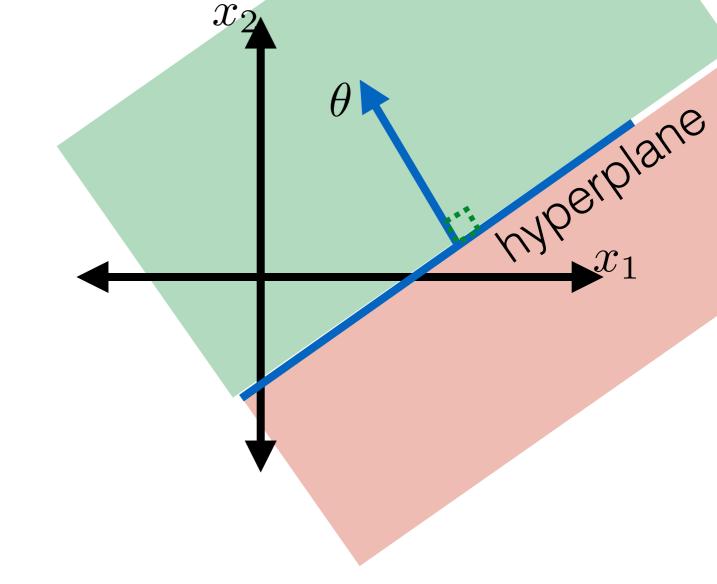
- I. A more-complete ML analysis
- II. Choosing good features
- III. Evaluation





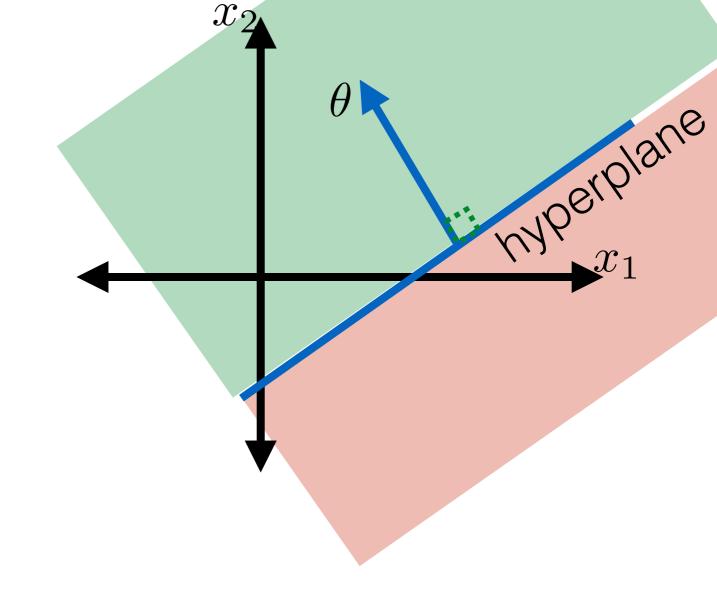






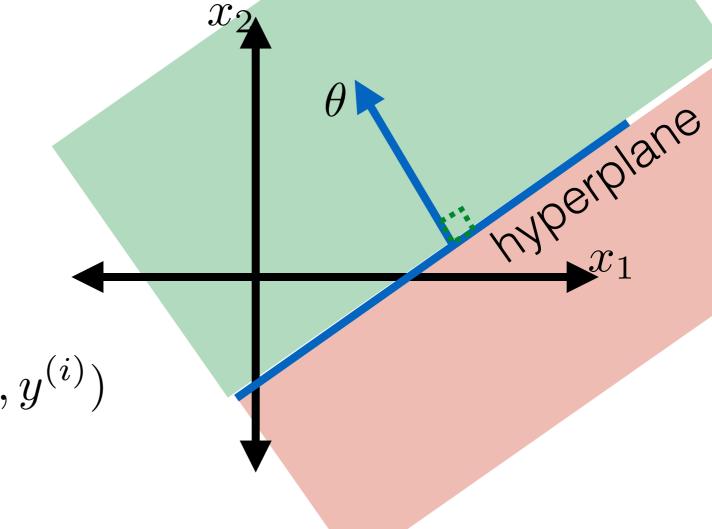
• Linear classifier *h* 

• 0-1 Loss 
$$L(g,a) = \begin{cases} 0 \text{ if } g = a \\ 1 \text{ else} \end{cases}$$



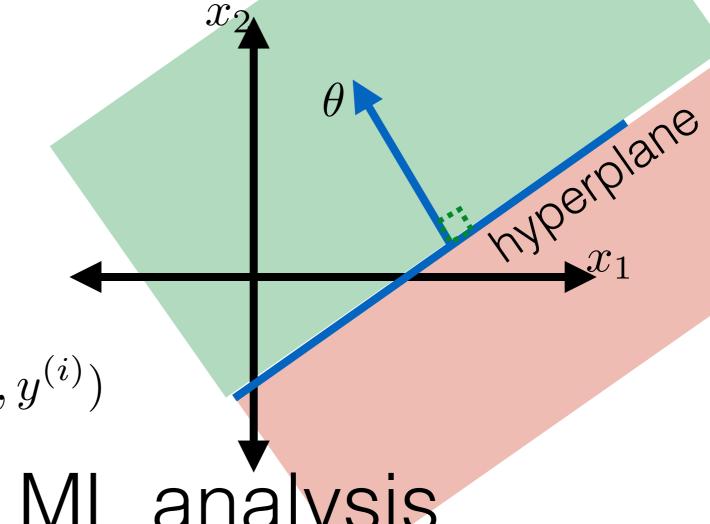
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- 0-1 Loss  $L(g,a) = \begin{cases} 0 \text{ if } g = a \\ 1 \text{ else} \end{cases}$

• Training error 
$$\mathcal{E}_n(h) = \frac{1}{n} \sum_{i=1}^n L(h(x^{(i)}), y^{(i)})$$



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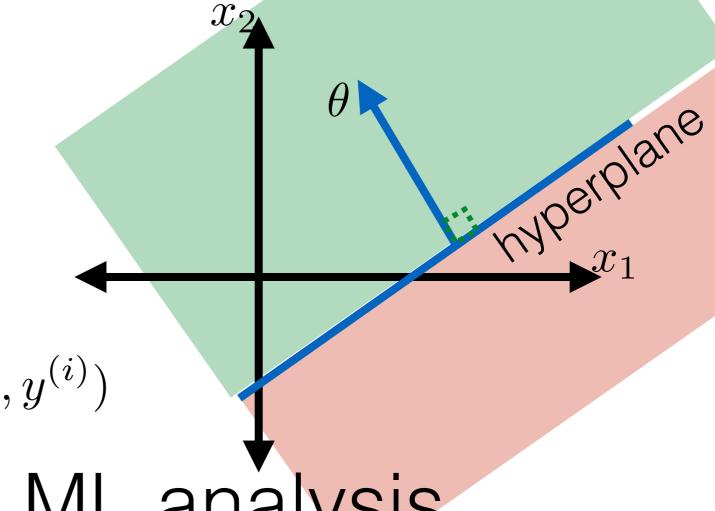


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### A more-complete ML analysis

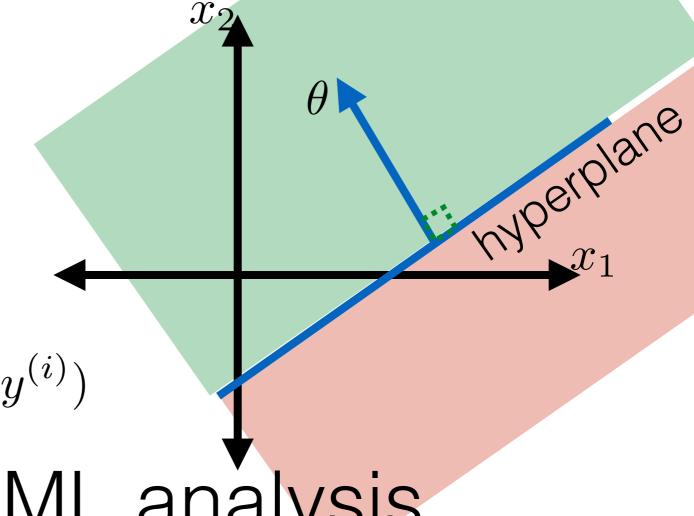
1. Establish a goal & find data



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  - Example goal: diagnose whether people have heart disease based on their available information



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- 4. Interpretation & evaluation

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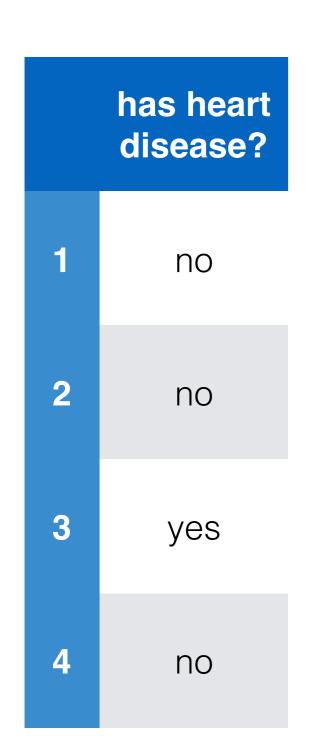
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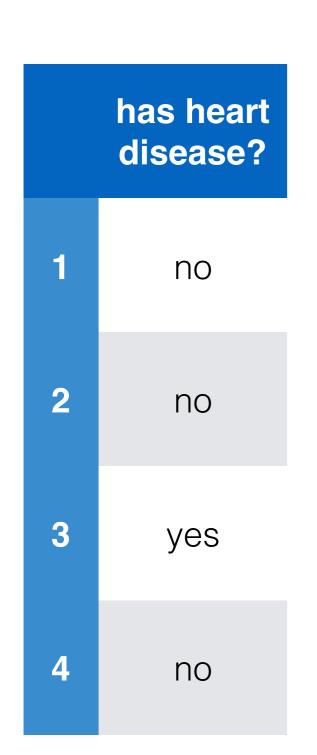
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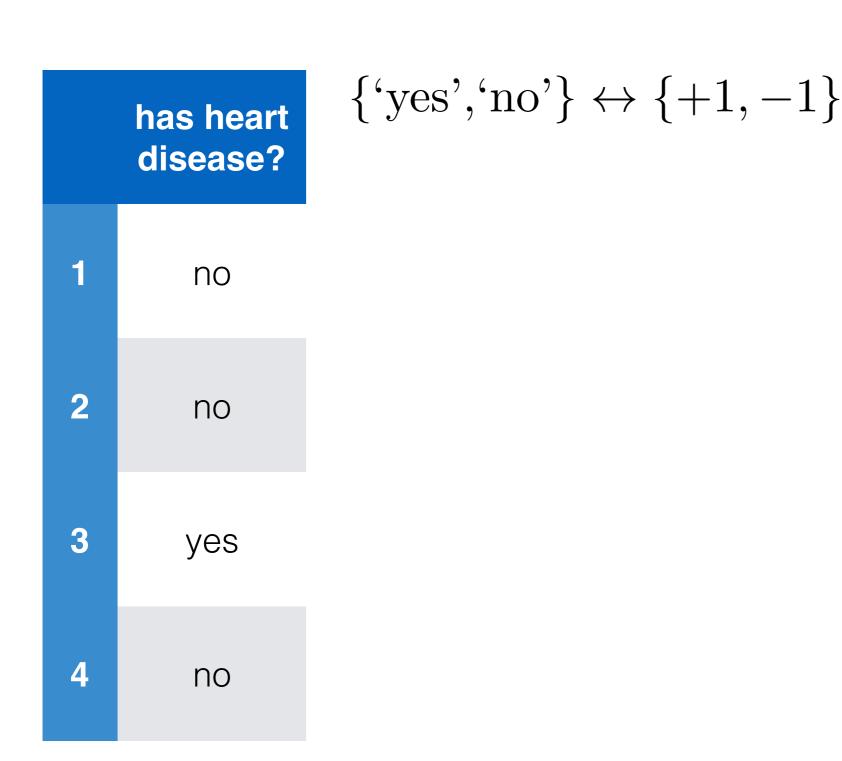
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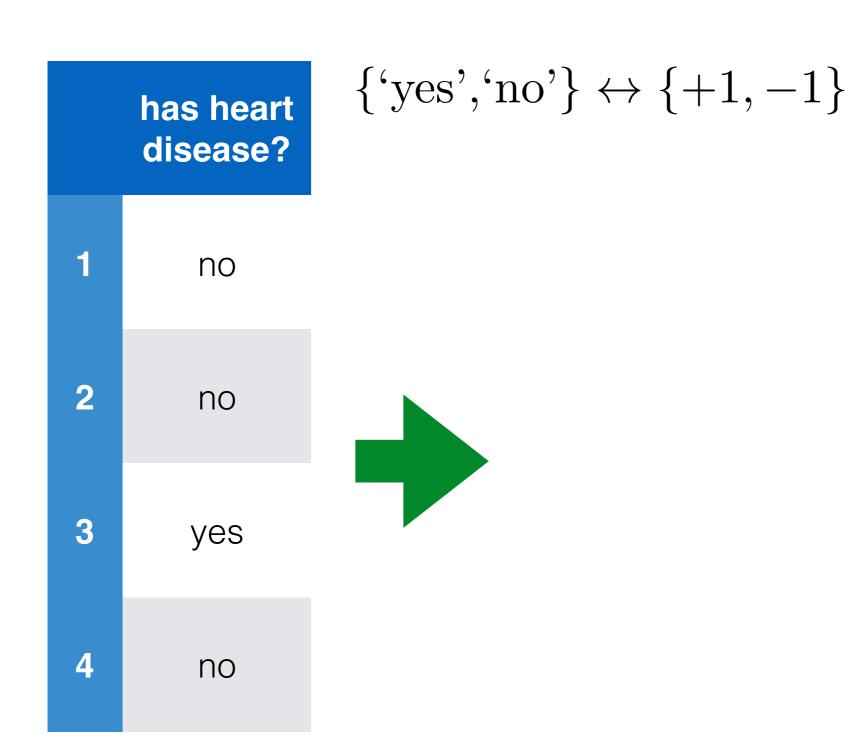
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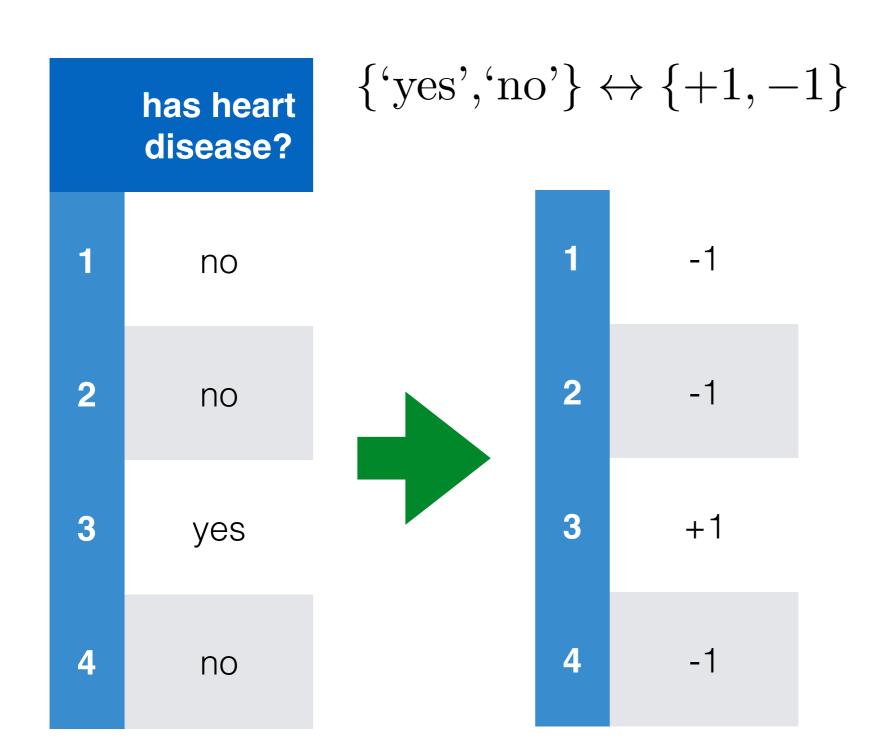
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3	yes
4	no

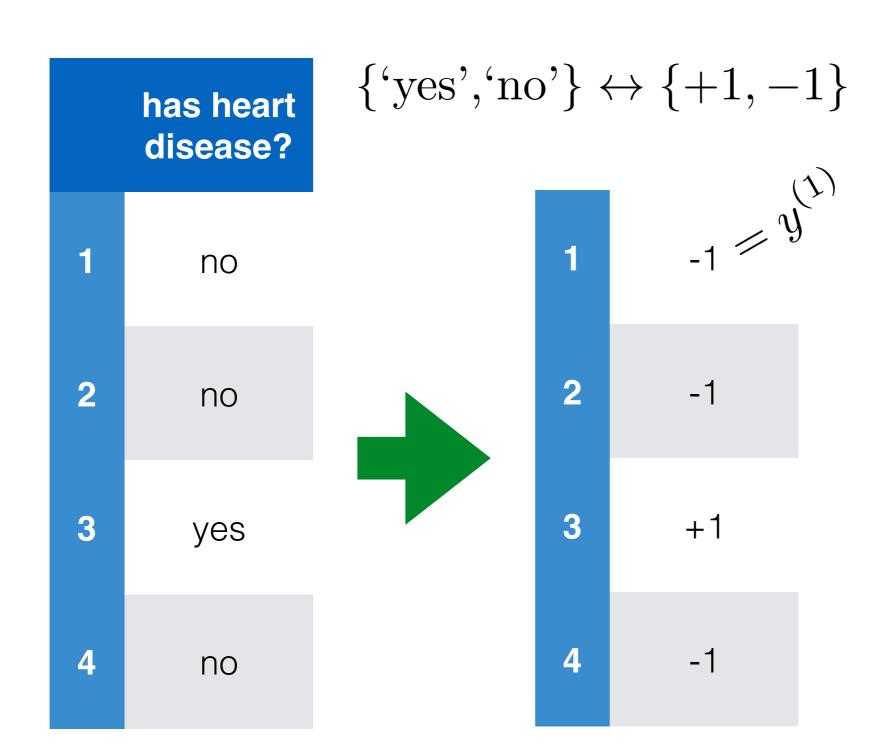




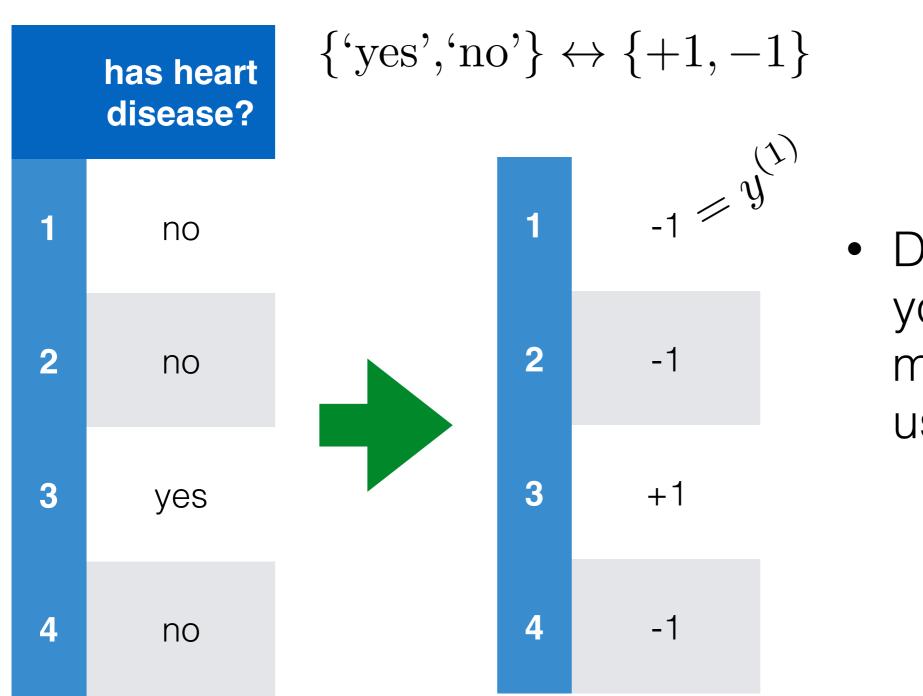




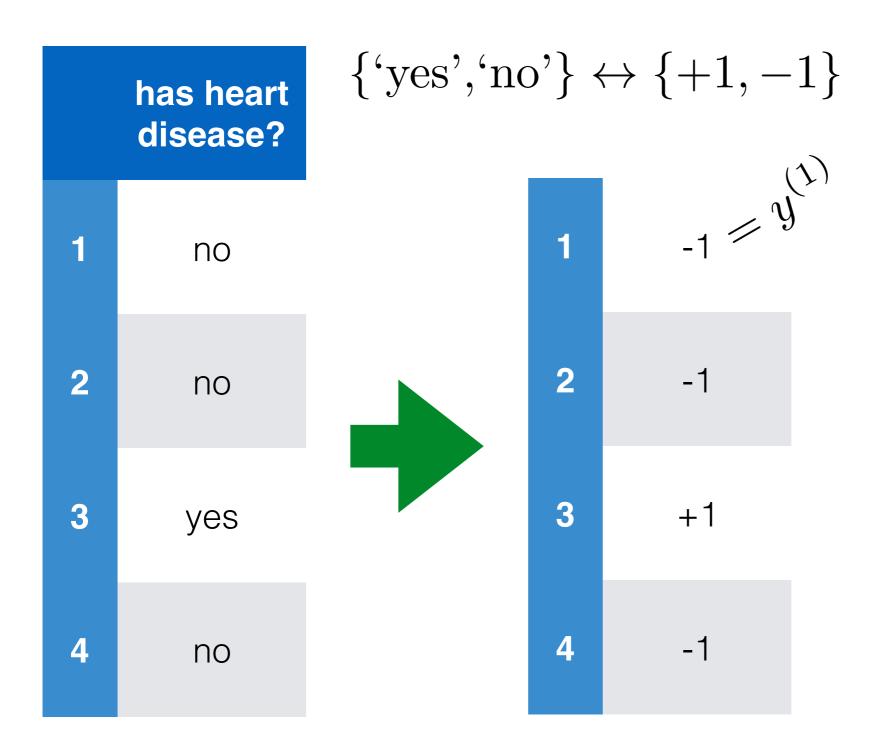




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- Save mapping to recover predictions of new points

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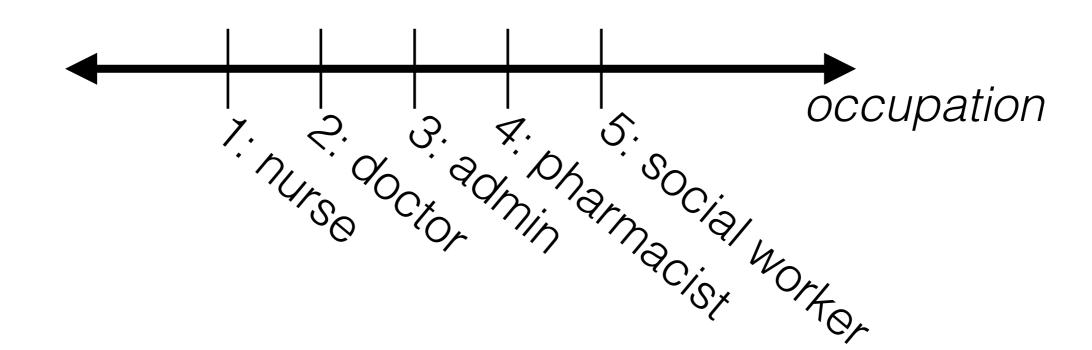
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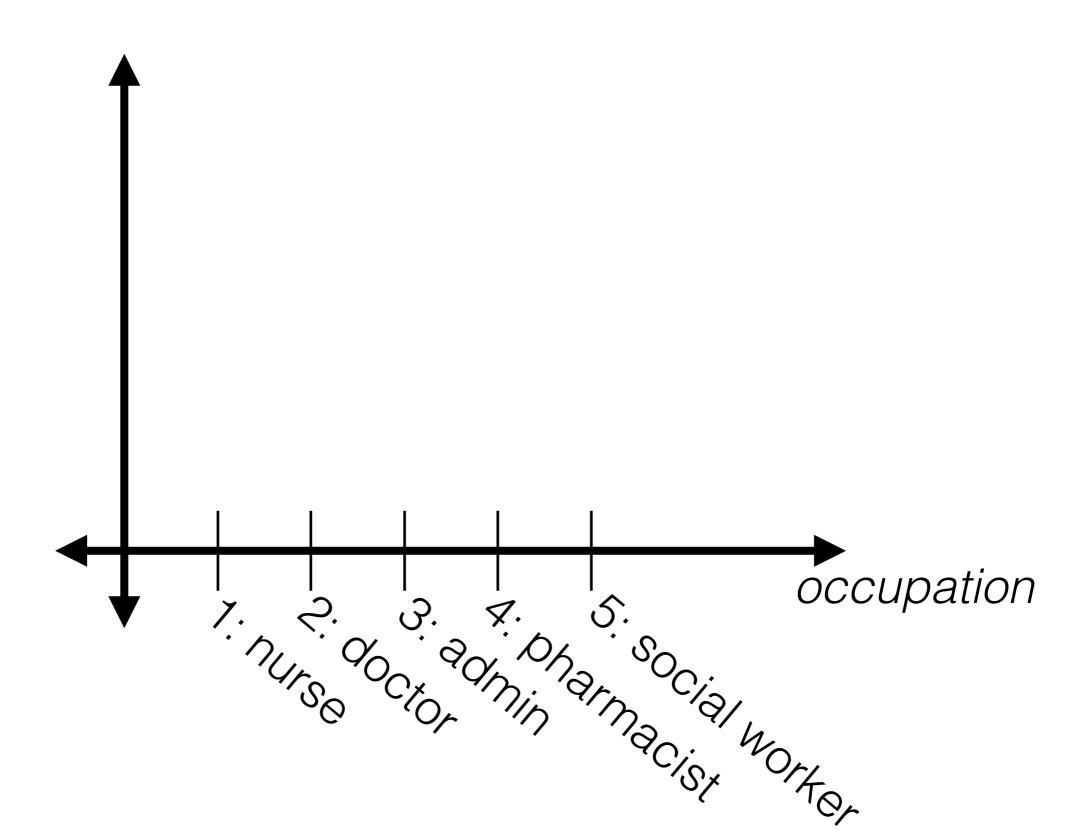
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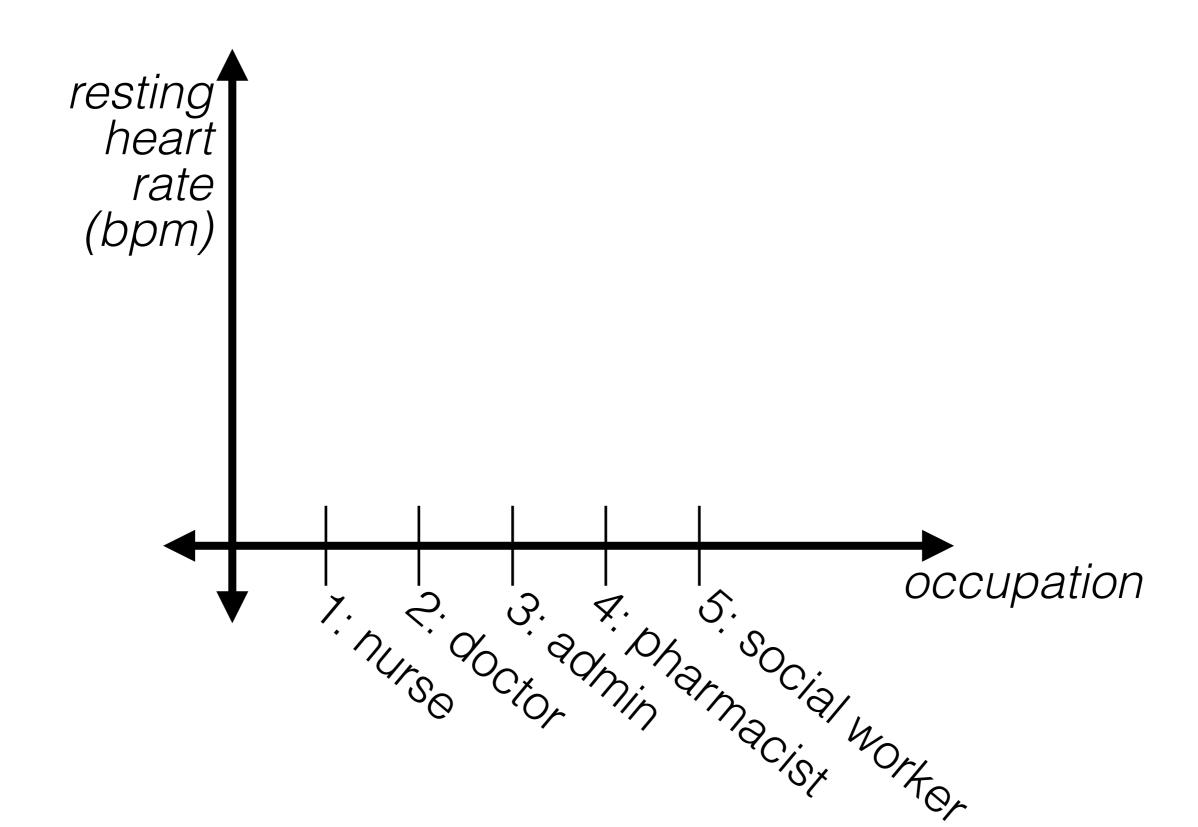
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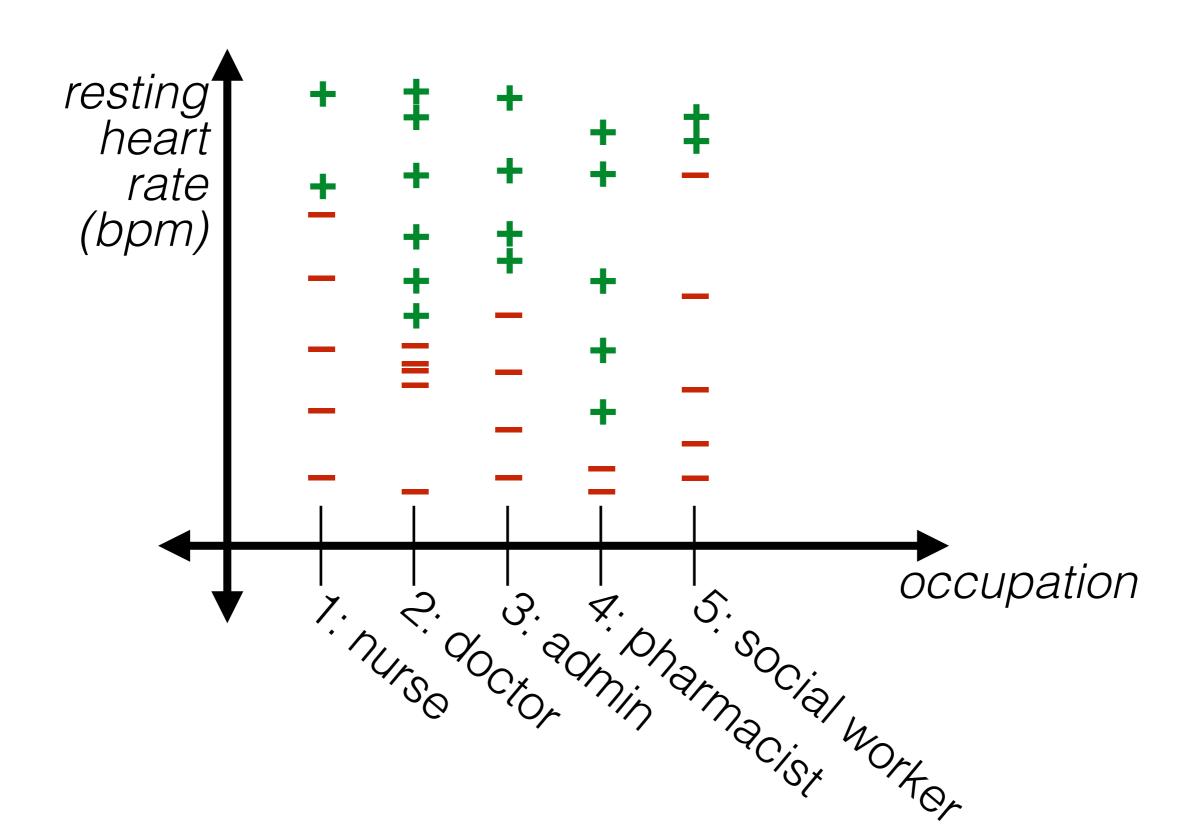
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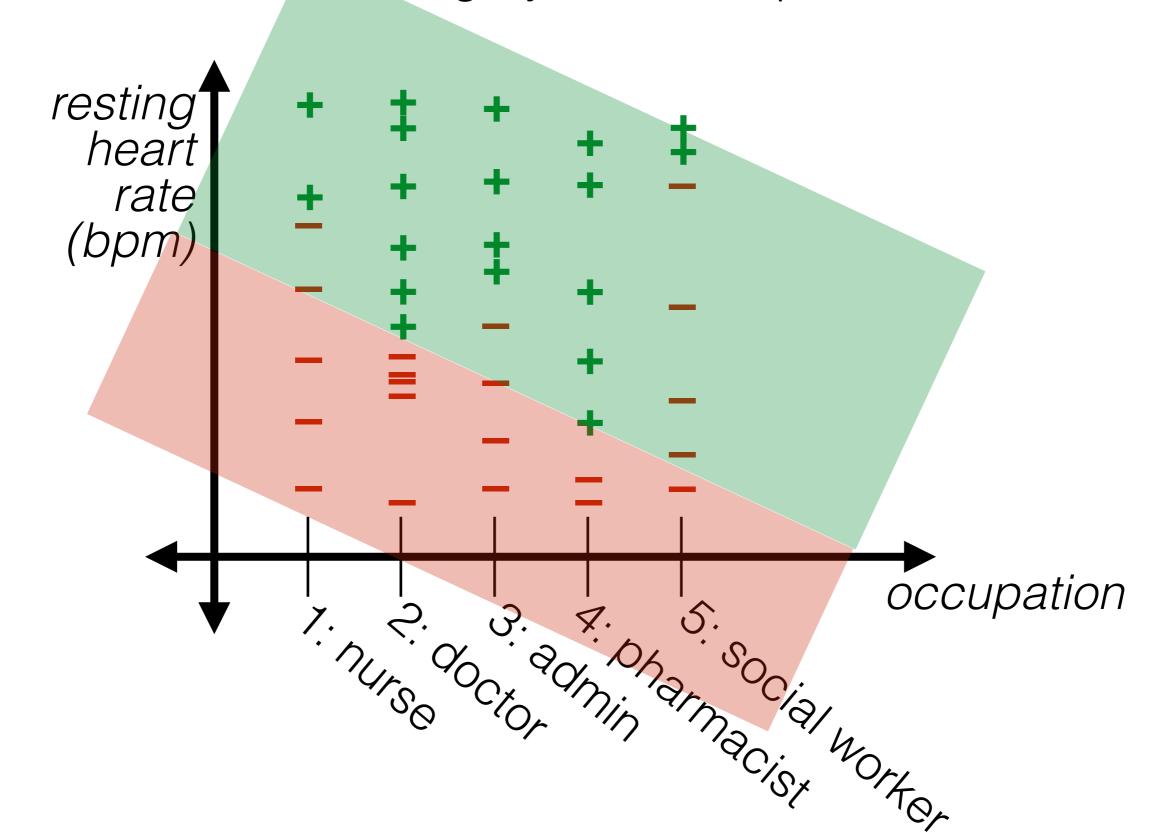
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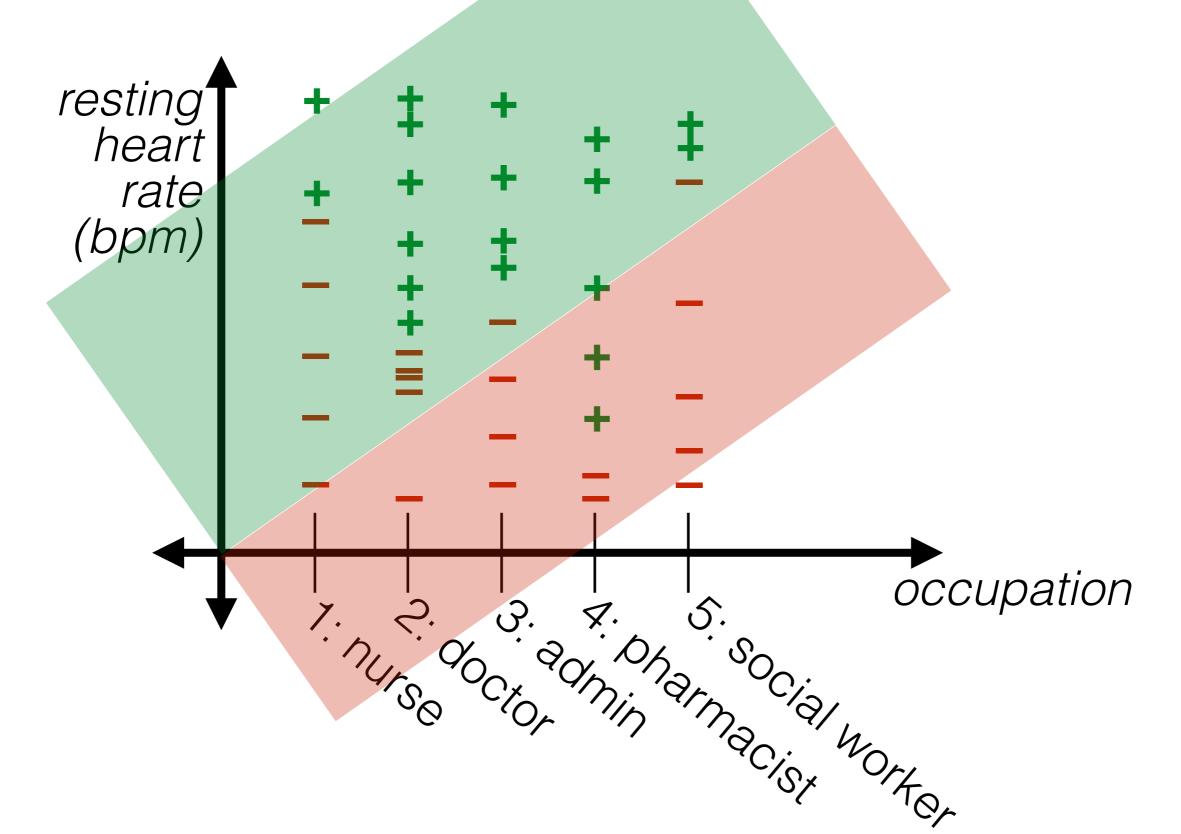


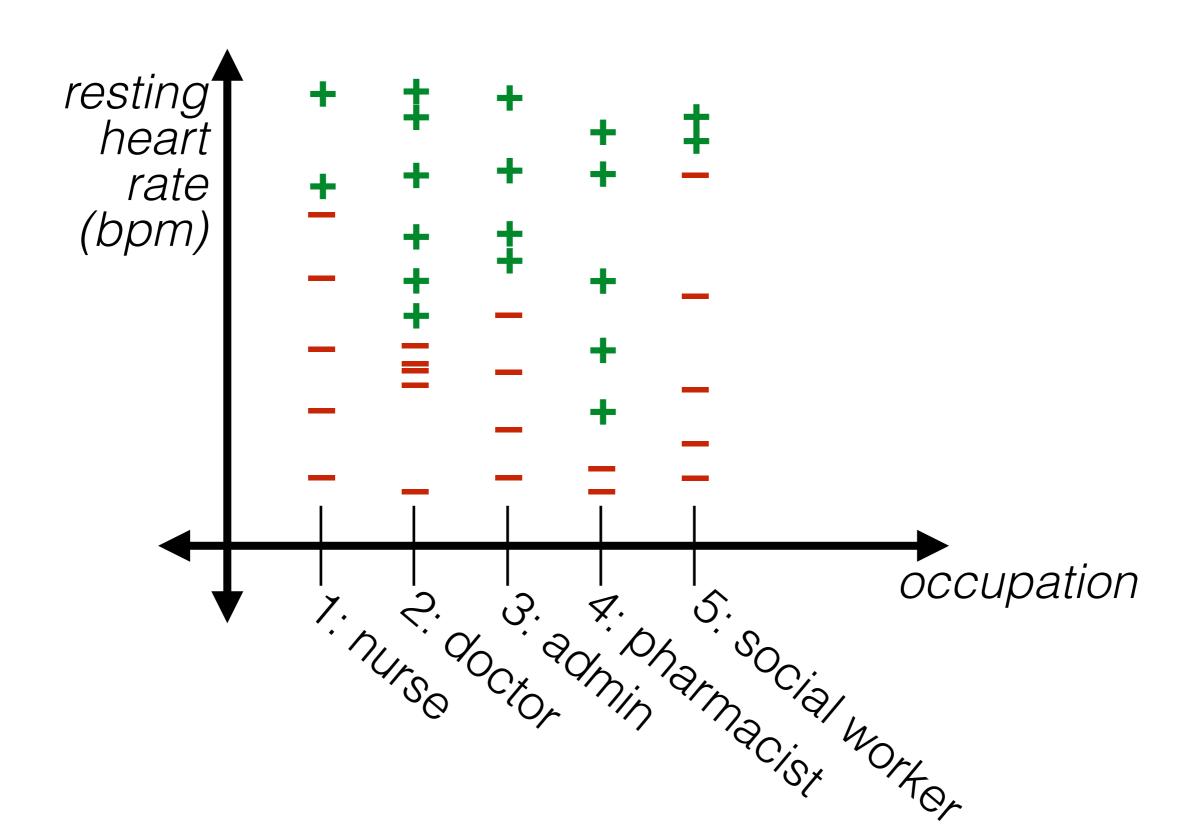


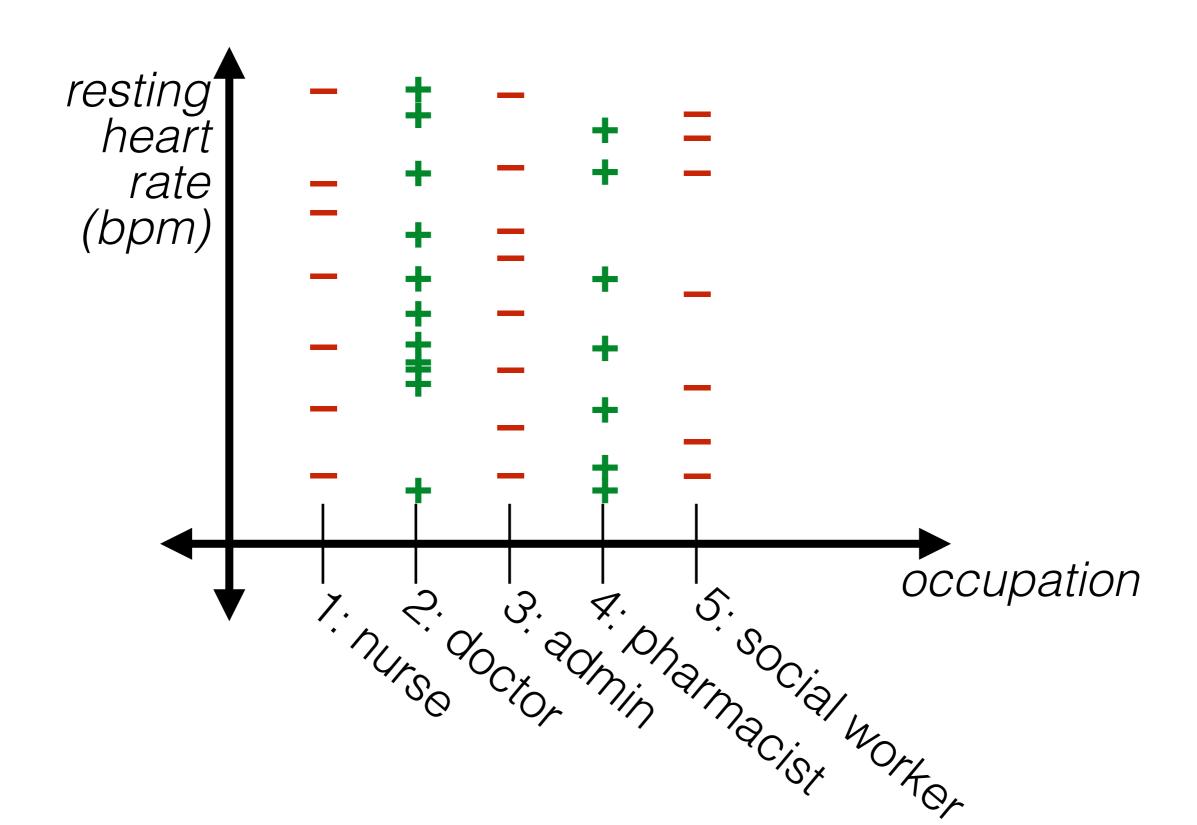


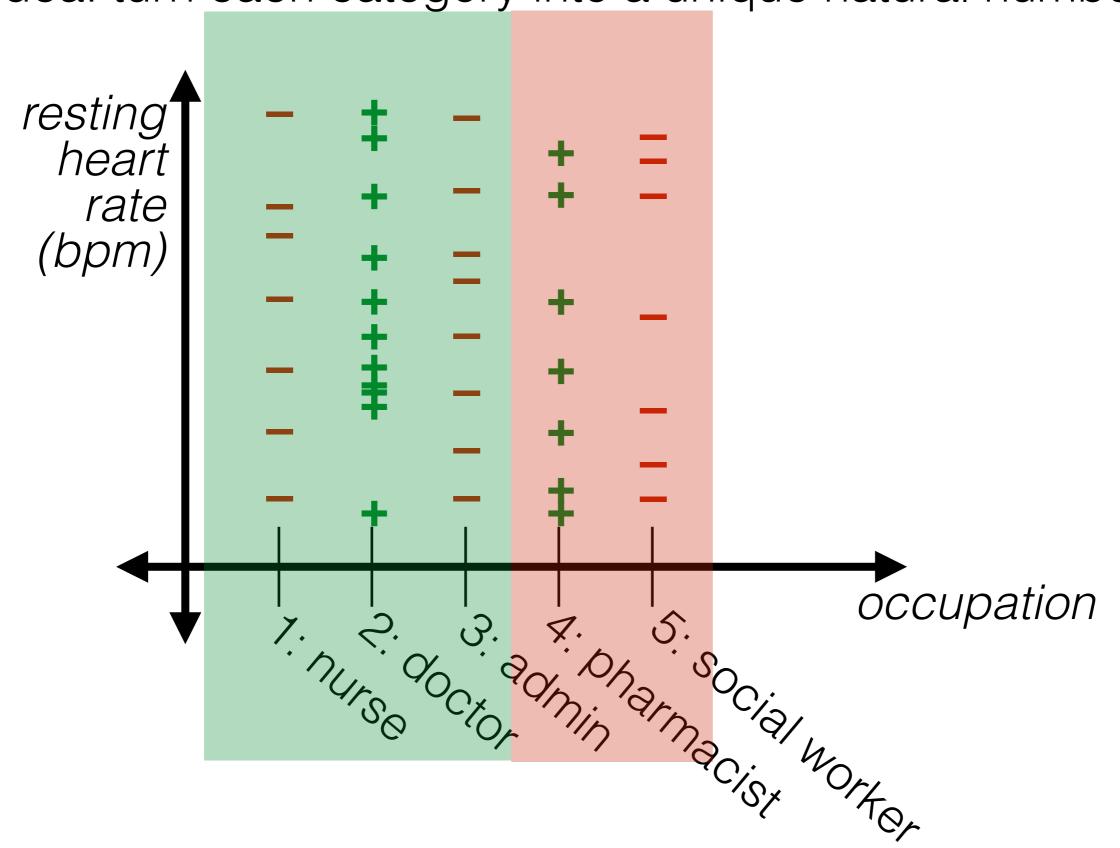






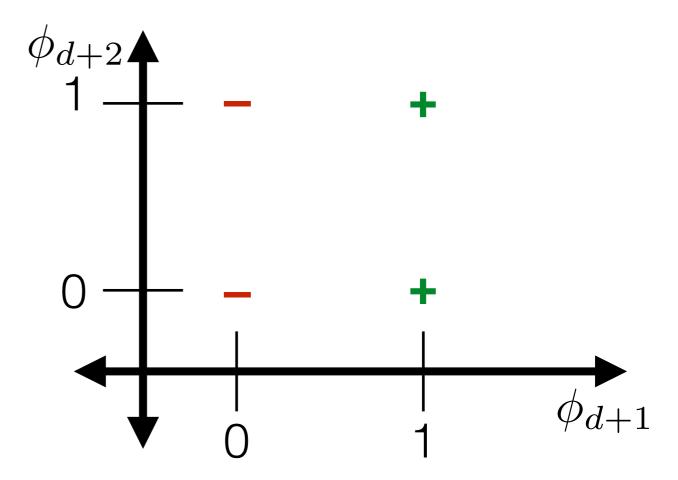




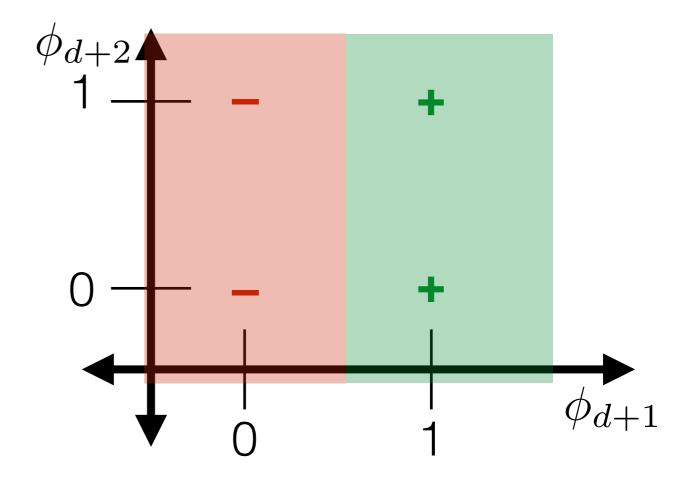


	$\phi_d$	$\phi_{d+1}$	$\phi_{d+2}$
nurse	0	0	0
admin	0	O	1
pharmacist	0	1	0
doctor	0	1	1
social worker	1	0	0

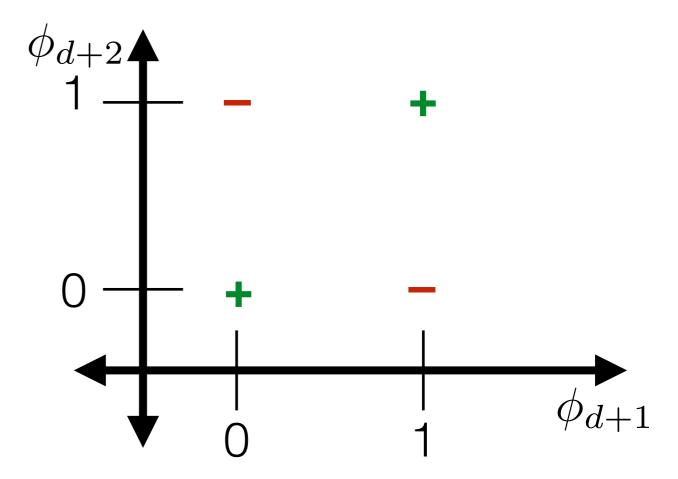
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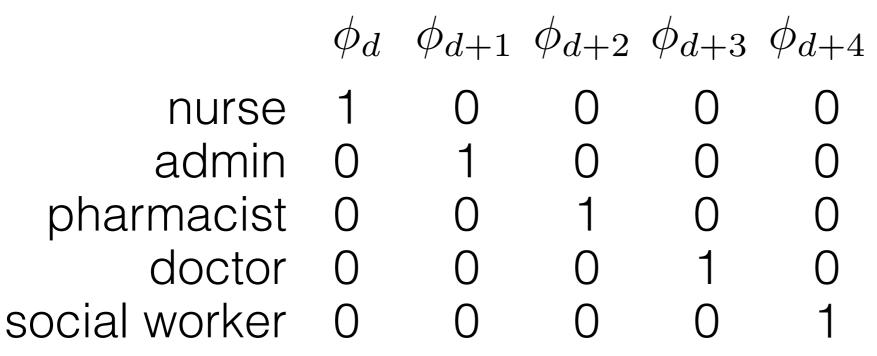


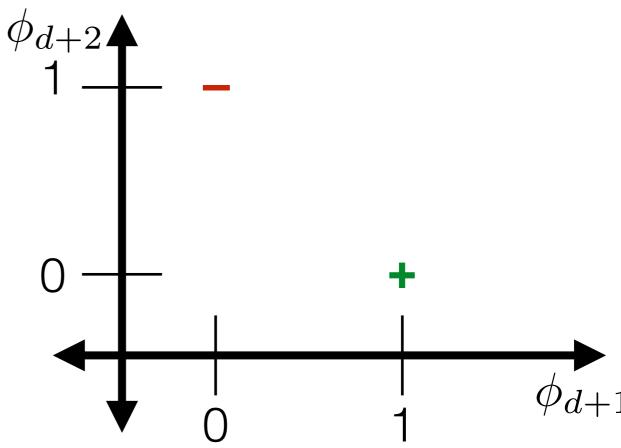
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	$\phi_d$	$\phi_{d+1}$	$\phi_{d+2}$	$\phi_{d+3}$	$\phi_{d+4}$
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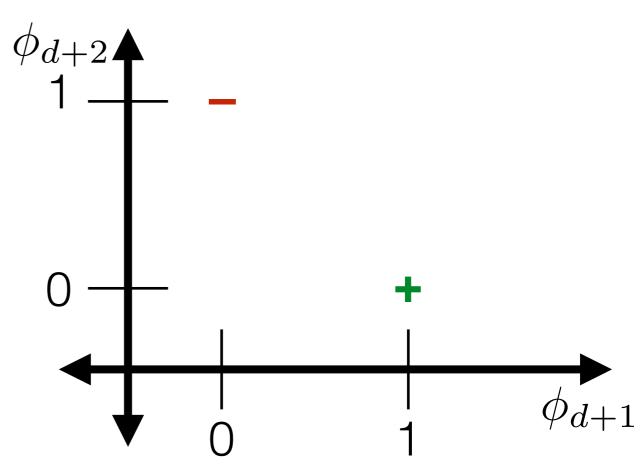




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• "one-hot encoding"



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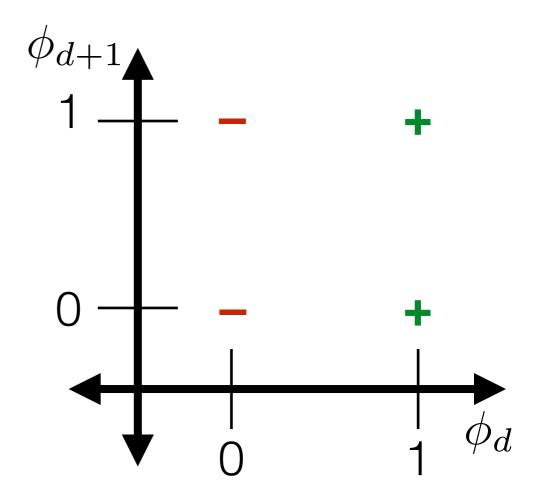
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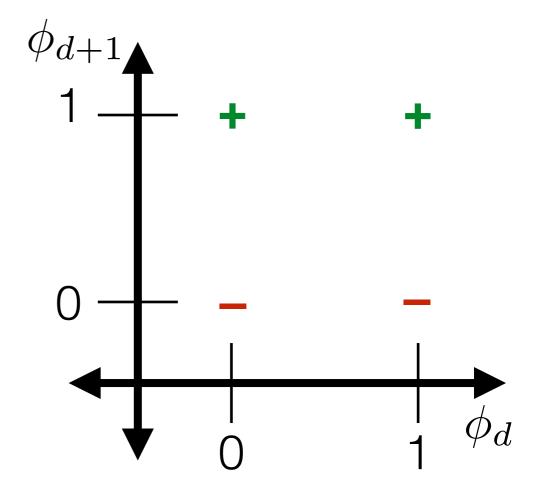
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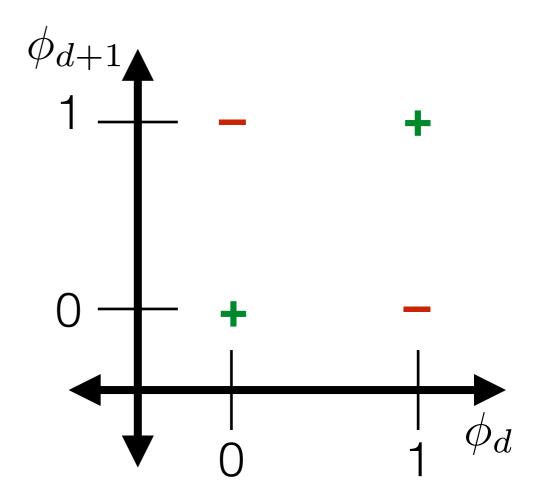
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3	89	1	1,0,0,0,0	beta blockers	50s	40000
4	67	0	0,0,0,1,0	none	50s	120000

	resting heart rate (bpm)	pain?	j1,j2,j3,j4,j5	m1, m2	age	family income (USD)
1	55	0	1,0,0,0,0	1,0	40s	133000
2	71	0	0,1,0,0,0	1,1	20s	34000
3	89	1	1,0,0,0,0	0,1	50s	40000
4	67	0	0,0,0,1,0	0,0	50s	120000

	resting heart rate (bpm)	pain?	j1,j2,j3,j4,j5	m1, m2	age	family income (USD)
1	55	0	1,0,0,0,0	1,0	40s	133000
2	71	0	0,1,0,0,0	1,1	20s	34000
3	89	1	1,0,0,0,0	0,1	50s	40000
4	67	0	0,0,0,1,0	0,0	50s	120000

	resting heart rate (bpm)	pain?	j1,j2,j3,j4,j5	m1, m2	age	family income (USD)
1	55	0	1,0,0,0,0	1,0	45	133000
2	71	0	0,1,0,0,0	1,1	25	34000
3	89	1	1,0,0,0,0	0,1	55	40000
4	67	0	0,0,0,1,0	0,0	55	120000

age

 Potential pitfall: level of detail might be treated as meaningful (by you or others using the data)

55

14

 Potential pitfall: level of detail might be treated as meaningful (by you or others using the data)

age

45

25

55

55



#### **TECH MYSTERIES**

How an internet mapping glitch turned a random Kansas farm into a digital hell

Kashmir Hill 4/10/16 10 AM

- Potential pitfall: level of detail might be treated as meaningful (by you or others using the data)
- A way to diagnose many problems: plot your data!

age

45

25

55

55



#### **TECH MYSTERIES**

How an internet mapping glitch turned a random Kansas farm into a digital hell

Kashmir Hill 4/10/16 10 AM

	resting heart rate (bpm)	pain?	j1,j2,j3,j4,j5	m1, m2	age	family income (USD)
1	55	0	1,0,0,0,0	1,0	45	133000
2	71	0	0,1,0,0,0	1,1	25	34000
3	89	1	1,0,0,0,0	0,1	55	40000
4	67	0	0,0,0,1,0	0,0	55	120000

	resting heart rate (bpm)	pain?	j1,j2,j3,j4,j5	m1, m2	decade	family income (USD)
1	55	0	1,0,0,0,0	1,0	4	133000
2	71	0	0,1,0,0,0	1,1	2	34000
3	89	1	1,0,0,0,0	0,1	5	40000
4	67	0	0,0,0,1,0	0,0	5	120000

 Numerical data: order on data values, and differences in value are meaningful

- Numerical data: order on data values, and differences in value are meaningful
- Categorical data: no order on data values

- Numerical data: order on data values, and differences in value are meaningful
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- Ordinal data: order on data values, but differences not meaningful

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Ordinal data: order on data values, but differences not

meaningful

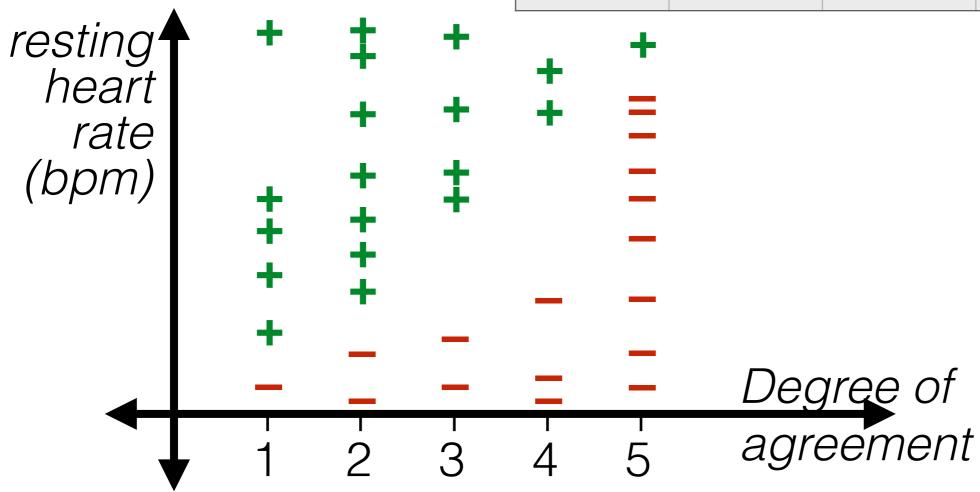
Strongly disagree	Disagree	Neutral	Agree	Strongly agree
1	2	3	4	5

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Strongly disagree	Disagree	Neutral	Agree	Strongly agree
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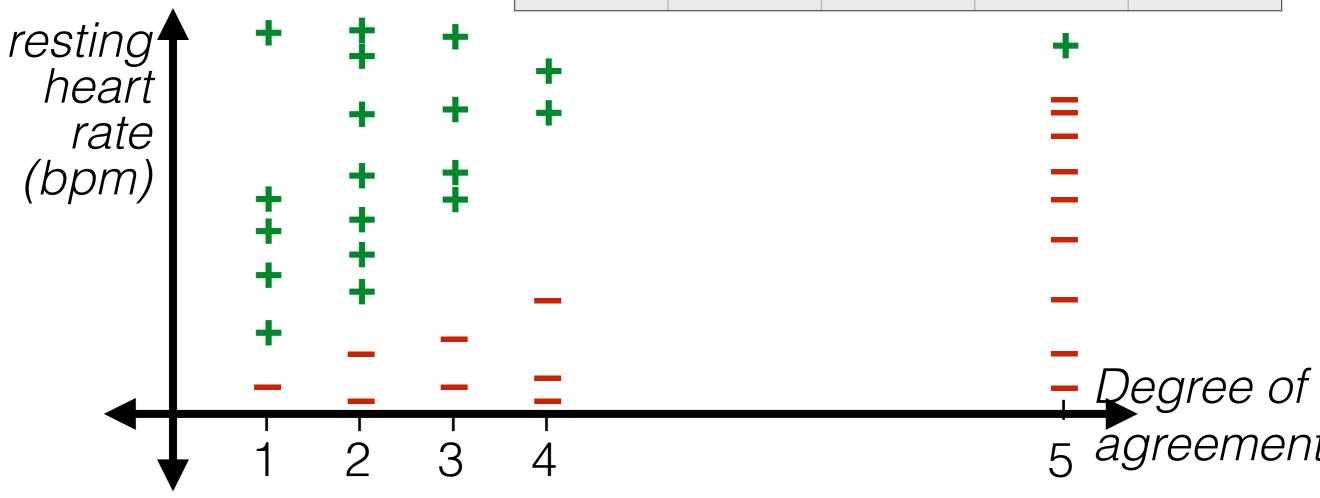


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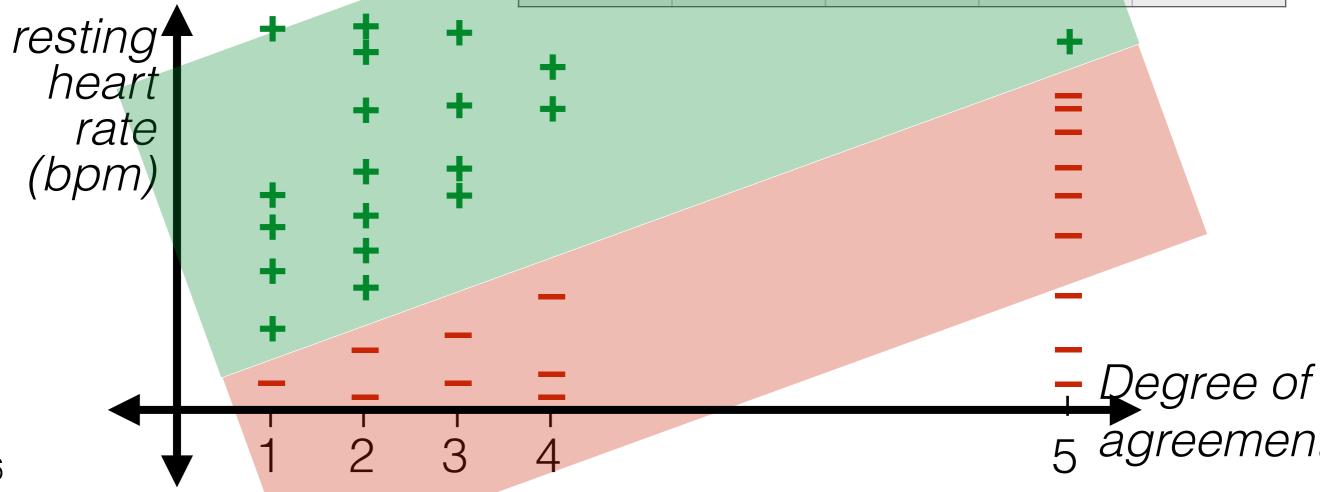
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1		2	3	4		5

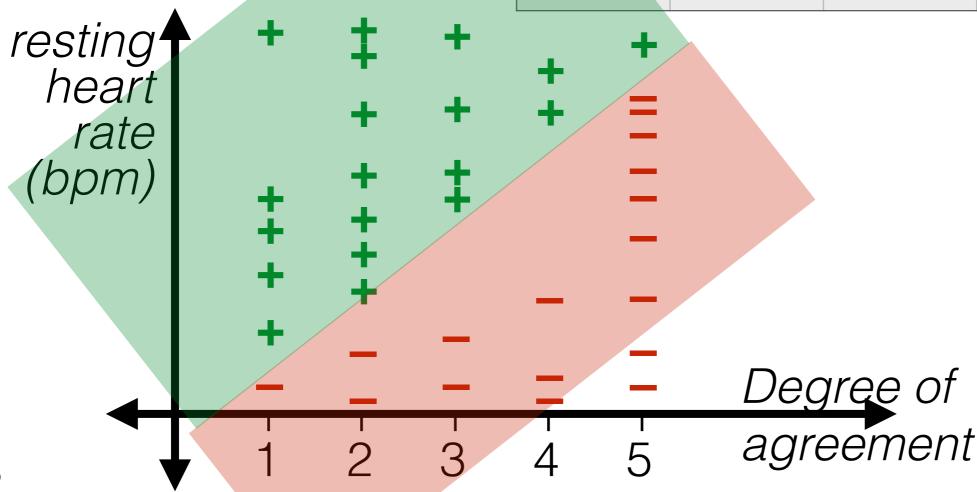


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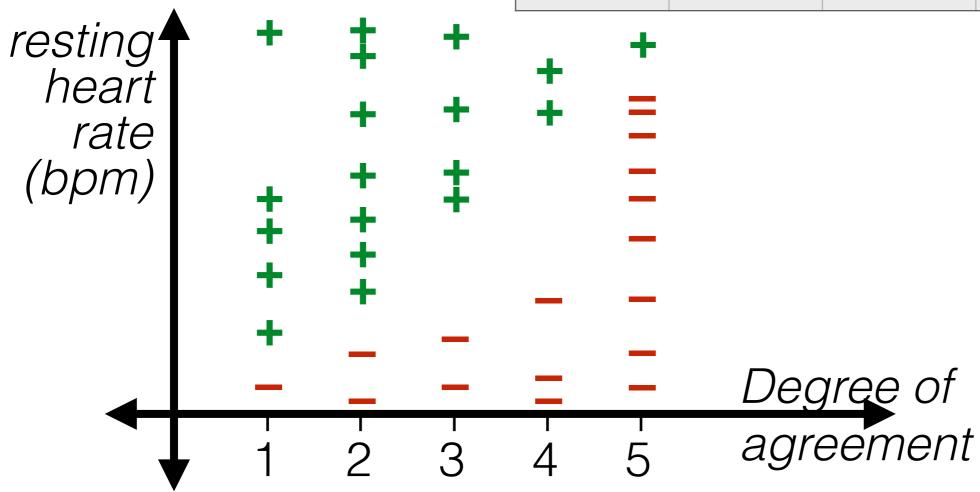


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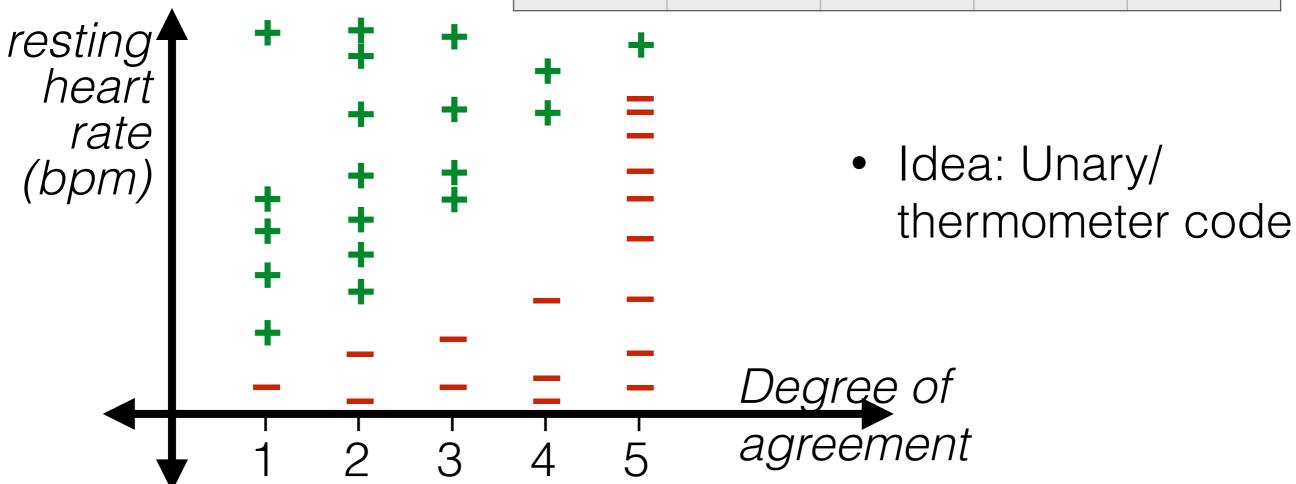


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1	2	3	4	5

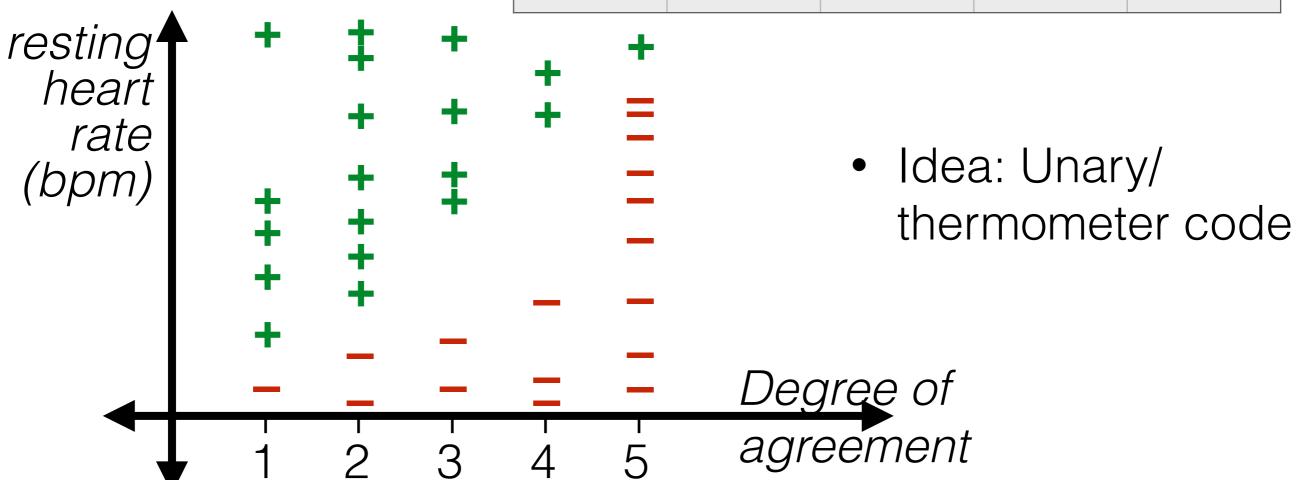


- Numerical data: order on data values, and differences in value are meaningful
- Categorical data: no order on data values

Ordinal data: order on data values, but differences not

meaningful

Strongly disagree	Disagree	Neutral	Agree	Strongly agree
1,0,0,0,0	1,1,0,0,0	1,1,1,0,0	1,1,1,1,0	1,1,1,1,1



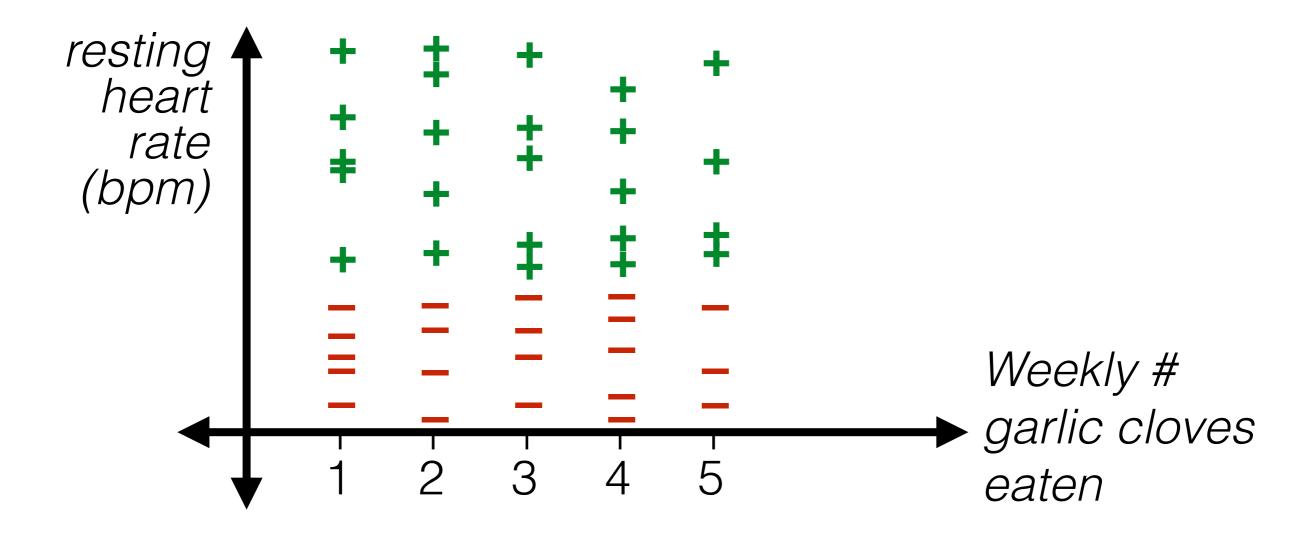
	resting heart rate (bpm)	pain?	j1,j2,j3,j4,j5	m1, m2	decade	family income (USD)
1	55	0	1,0,0,0,0	1,0	4	133000
2	71	0	0,1,0,0,0	1,1	2	34000
3	89	1	1,0,0,0,0	0,1	5	40000
4	67	0	0,0,0,1,0	0,0	5	120000

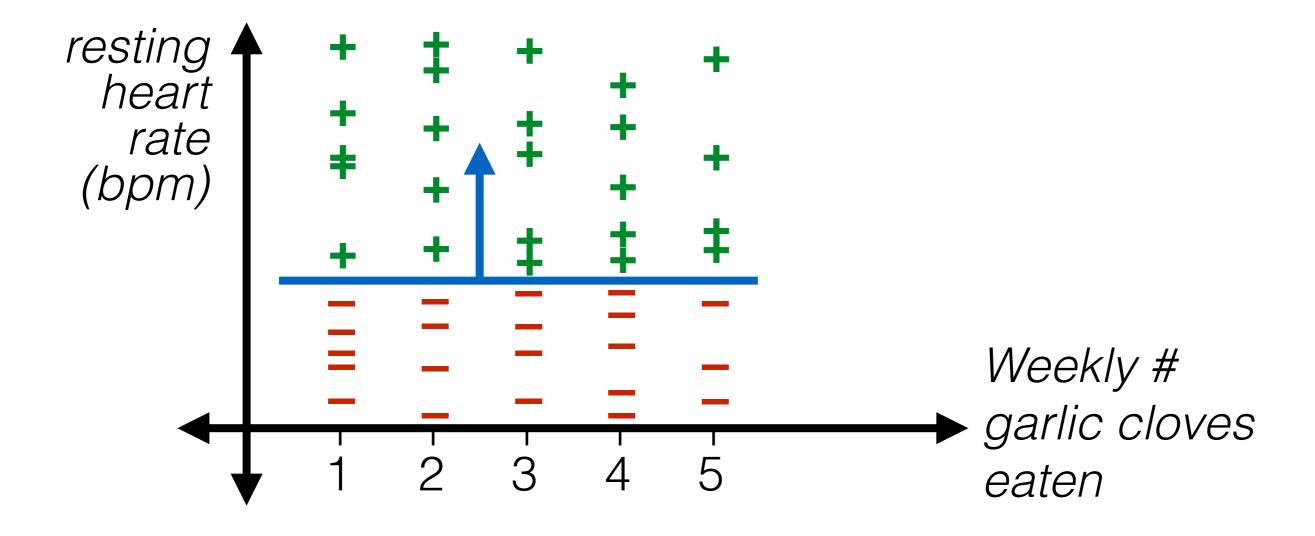
	resting heart rate (bpm)	pain?	j1,j2,j3,j4,j5	m1, m2	decade	family income (USD)
1	55	0	1,0,0,0,0	1,0	4	133000
2	71	0	0,1,0,0,0	1,1	2	34000
3	89	1	1,0,0,0,0	0,1	5	40000
4	67	0	0,0,0,1,0	0,0	5	120000

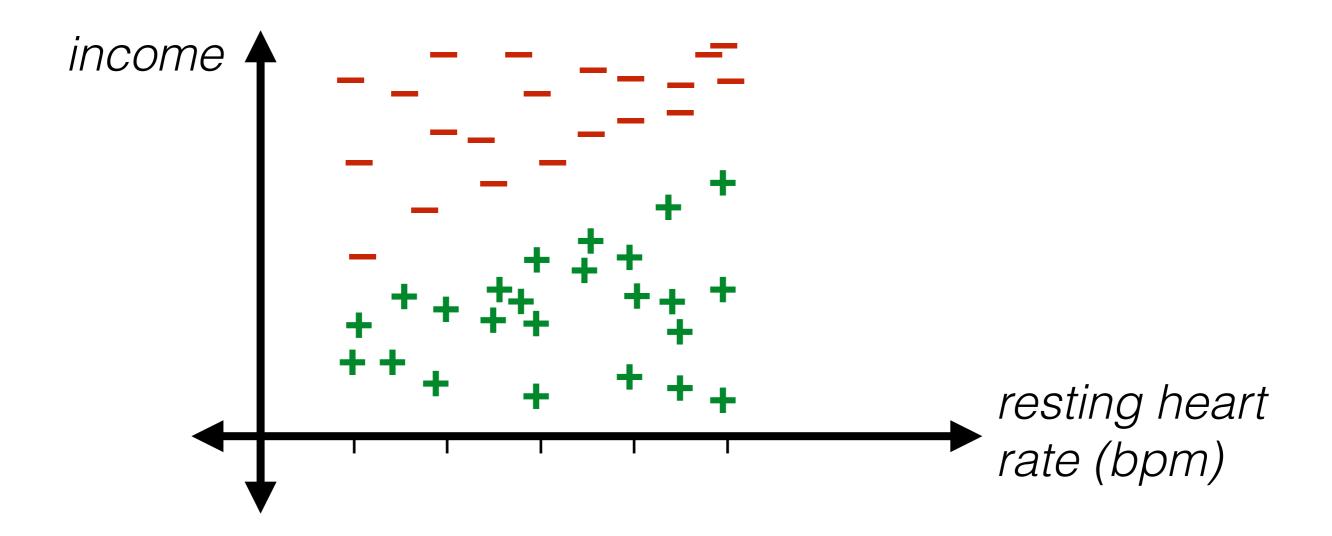
Identify the features and encode as real numbers

	resting heart rate (bpm)	pain?	j1,j2,j3,j4,j5	m1, m2	decade	family income (USD)
1	55	0	1,0,0,0,0	1,0	4	133000
2	71	0	0,1,0,0,0	1,1	2	34000
3	89	1	1,0,0,0,0	0,1	5	40000
4	67	0	0,0,0,1,0	0,0	5	120000

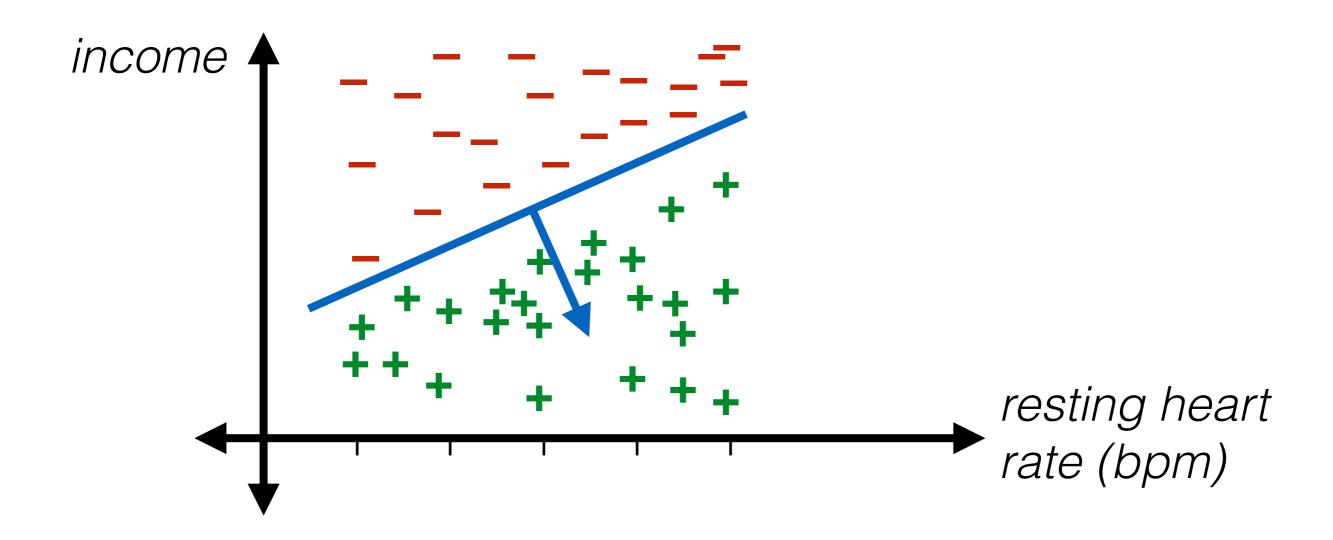
17



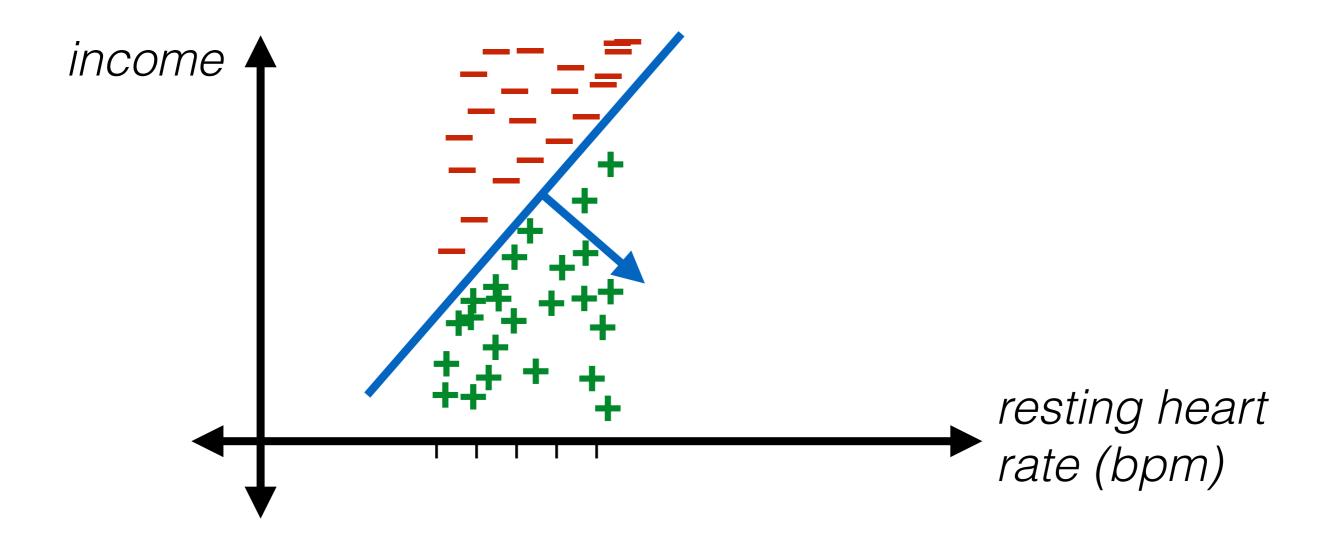




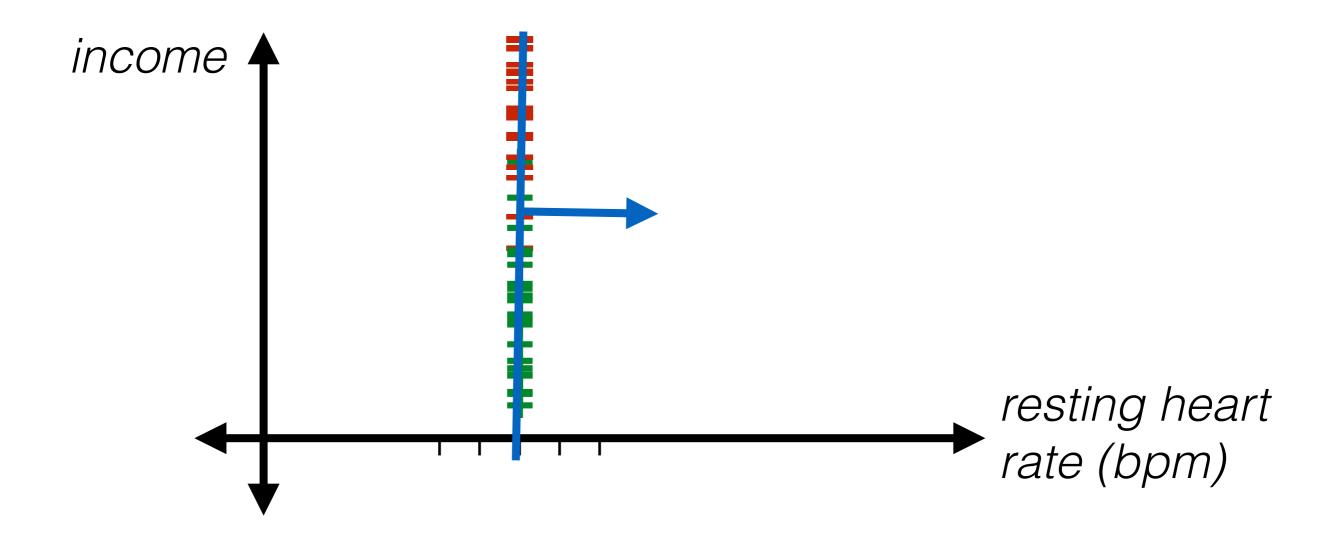
A closer look at the output of a linear classifier



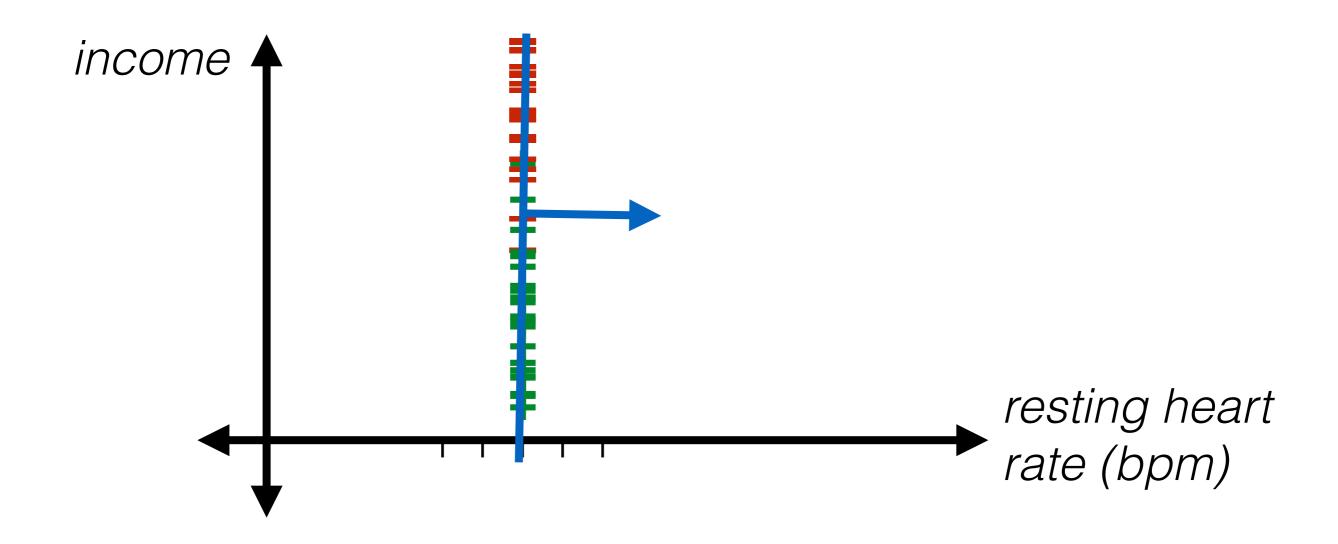
A closer look at the output of a linear classifier



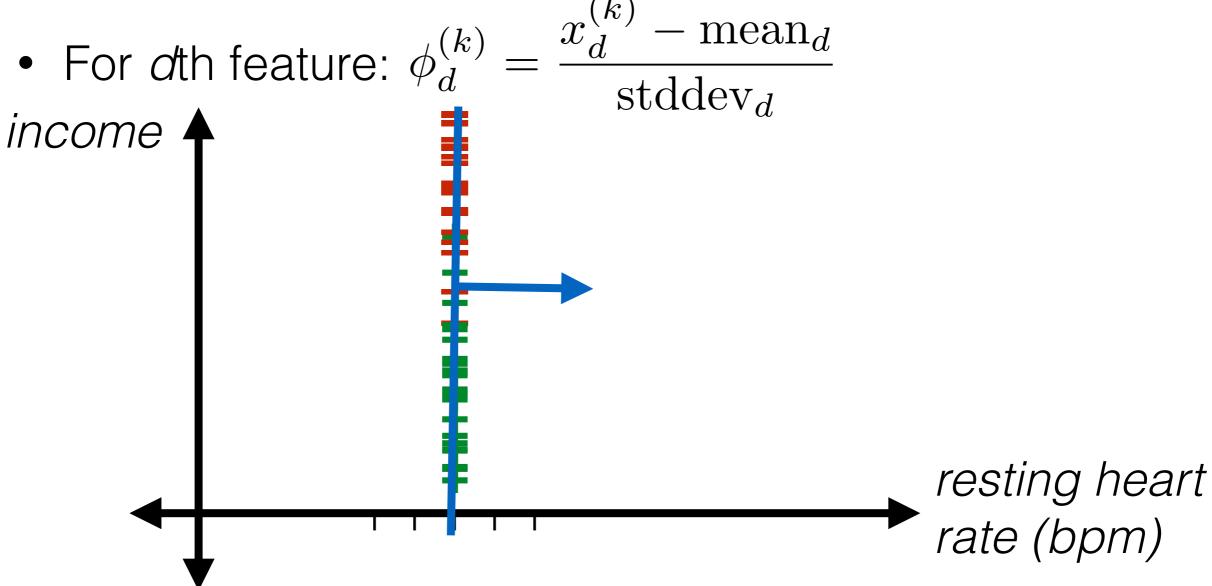
A closer look at the output of a linear classifier



- A closer look at the output of a linear classifier
- Idea: standardize numerical data

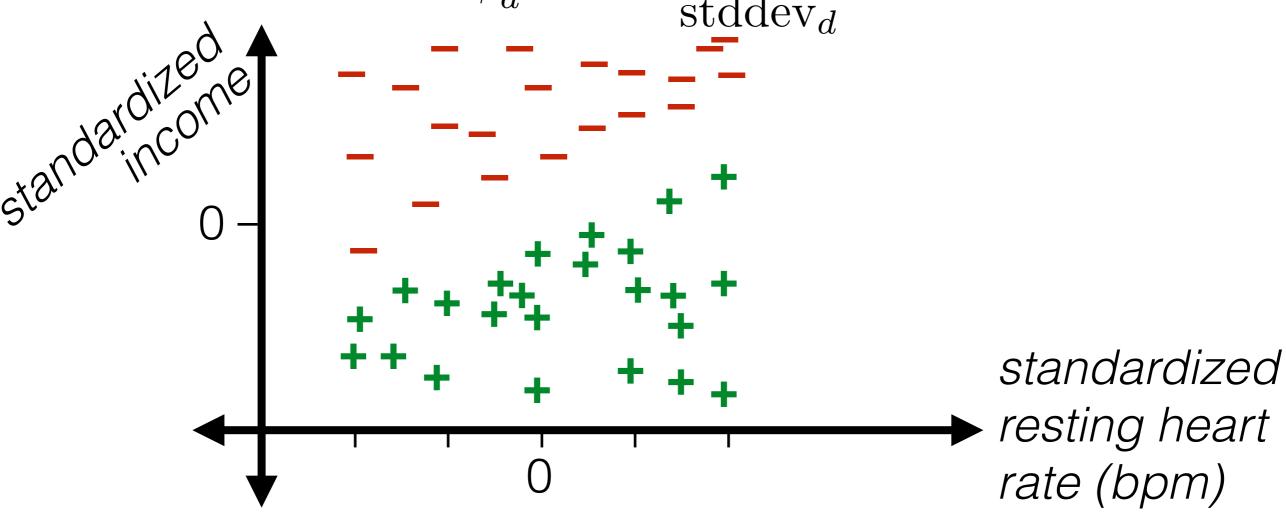


- A closer look at the output of a linear classifier
- Idea: standardize numerical data



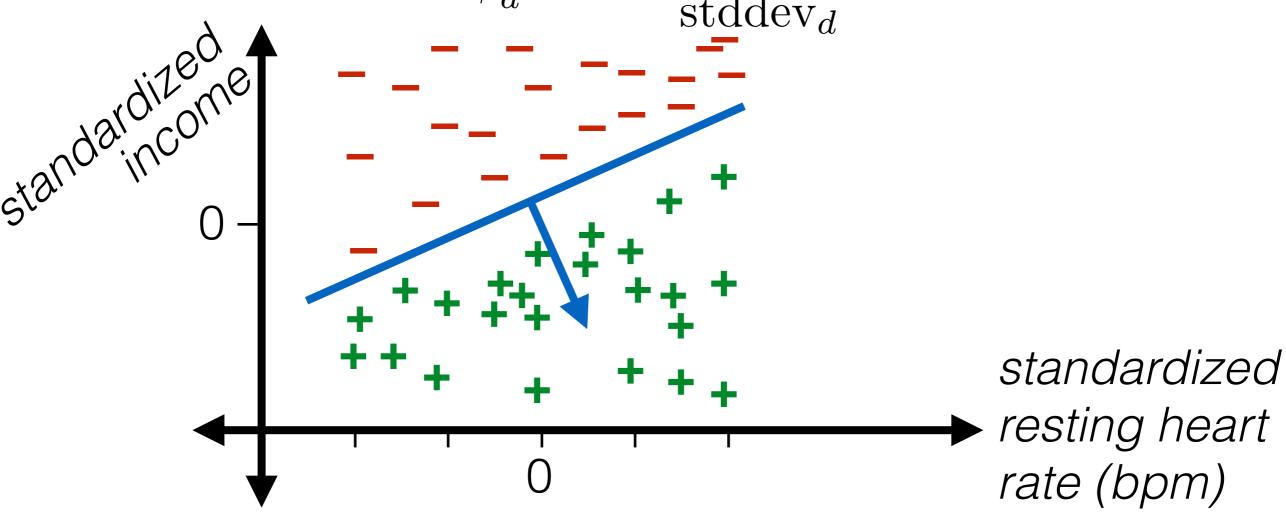
- A closer look at the output of a linear classifier
- Idea: standardize numerical data

• For dth feature:  $\phi_d^{(k)} = \frac{x_d^{(k)} - \text{mean}_d}{\text{stable}}$ 



- A closer look at the output of a linear classifier
- Idea: standardize numerical data

• For dth feature:  $\phi_d^{(k)} = \frac{x_d^{(k)} - \text{mean}_d}{\text{gradient}}$ 



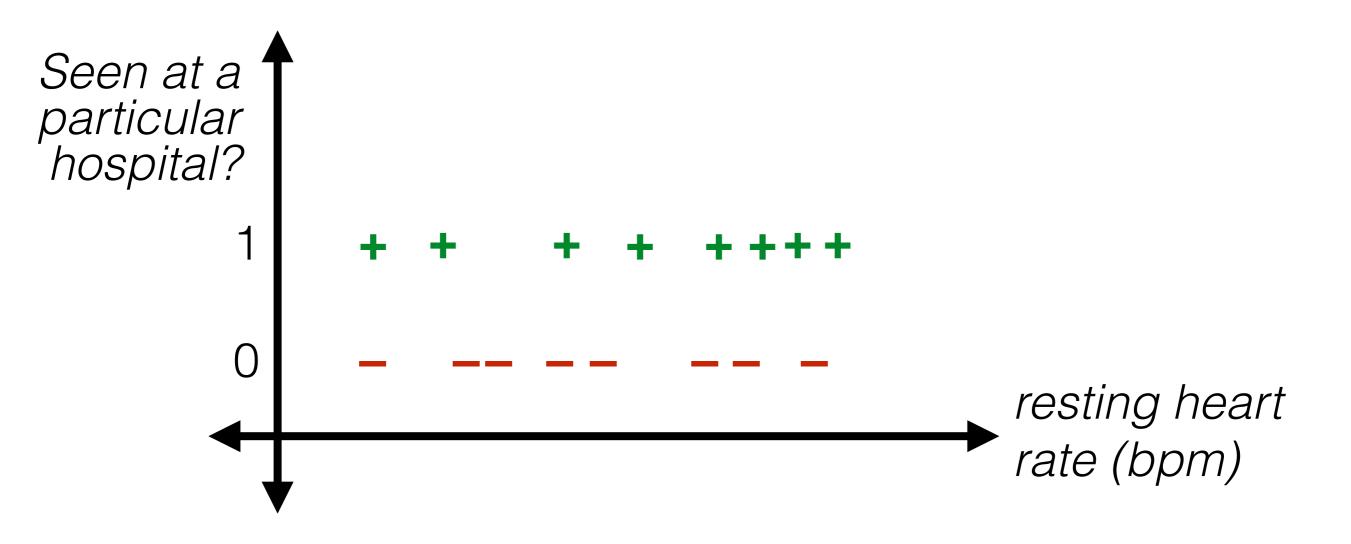
More benefits of plotting your data

## More benefits of plotting your data

And talking to experts

## More benefits of plotting your data

And talking to experts



Identify the features and encode as real numbers

	resting heart rate (bpm)	pain?	j1,j2,j3,j4,j5	m1, m2	decade	family income (USD)
1	55	0	1,0,0,0,0	1,0	4	133000
2	71	0	0,1,0,0,0	1,1	2	34000
3	89	1	1,0,0,0,0	0,1	5	40000
4	67	0	0,0,0,1,0	0,0	5	120000

- Identify the features and encode as real numbers
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	resting heart rate (bpm)	pain?	j1,j2,j3,j4,j5	m1, m2	decade	family income (USD)
1	55	0	1,0,0,0,0	1,0	4	133000
2	71	0	0,1,0,0,0	1,1	2	34000
3	89	1	1,0,0,0,0	0,1	5	40000
4	67	0	0,0,0,1,0	0,0	5	120000

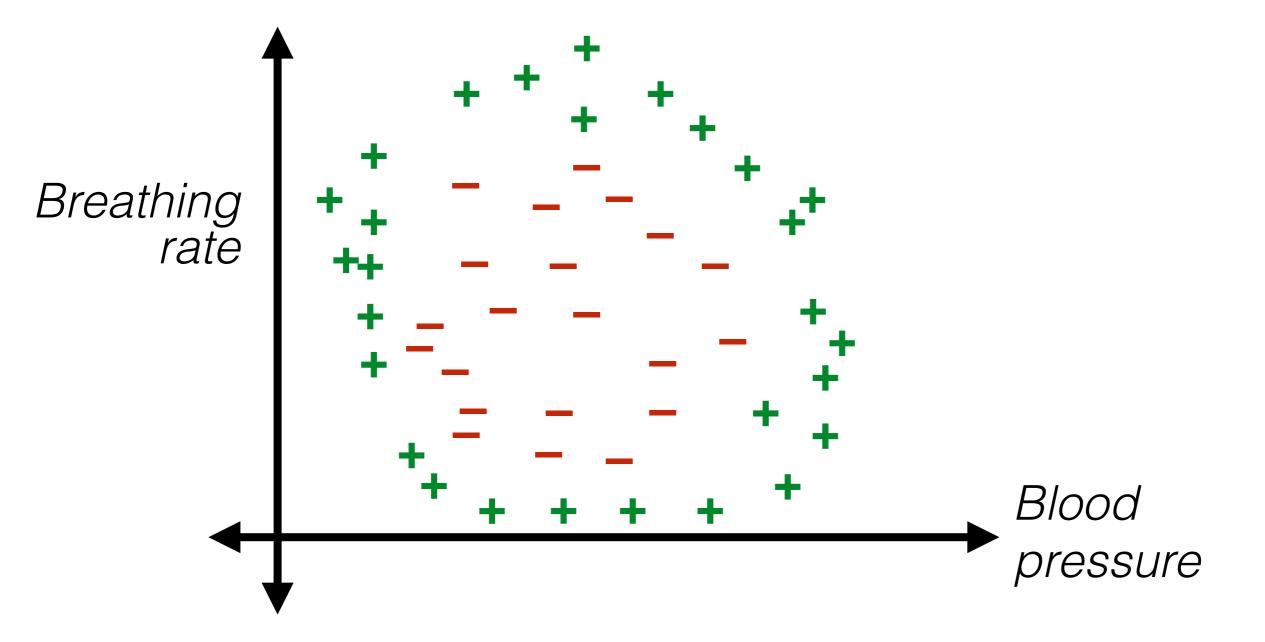
- Identify the features and encode as real numbers
- Standardize numerical features

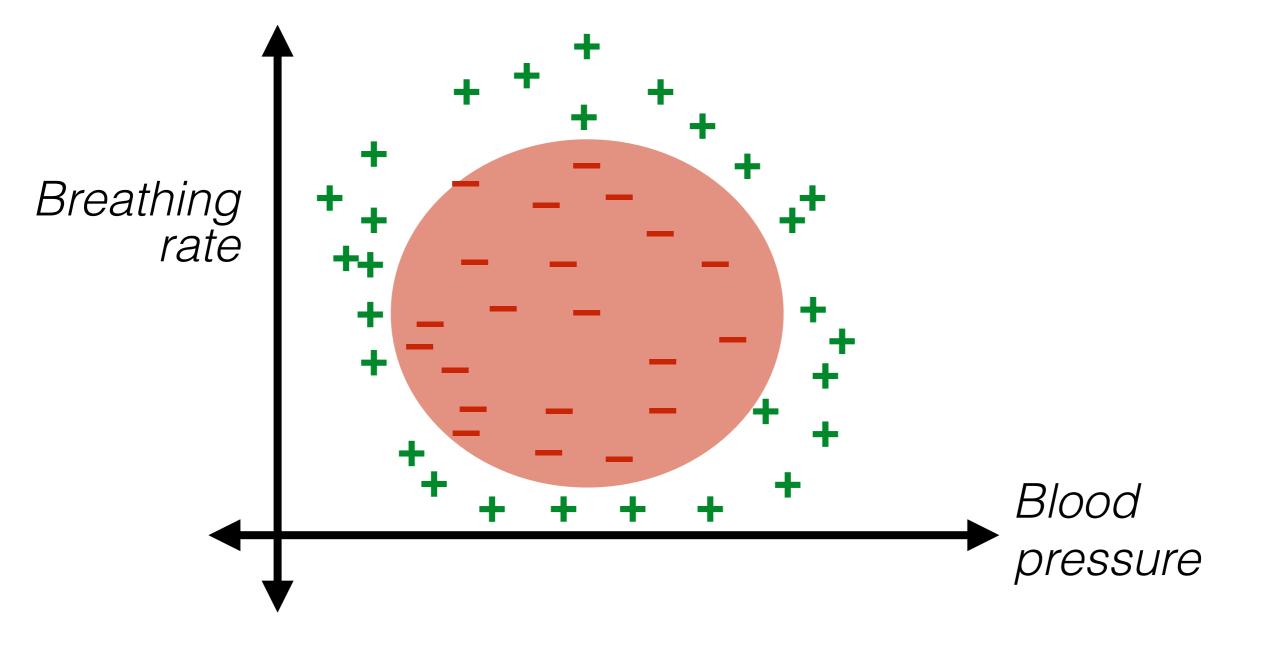
	resting heart rate (bpm)	pain?	j1,j2,j3,j4,j5	m1, m2	decade	family income (USD)
1	55	0	1,0,0,0,0	1,0	4	133000
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3	89	1	1,0,0,0,0	0,1	5	40000
4	67	0	0,0,0,1,0	0,0	5	120000

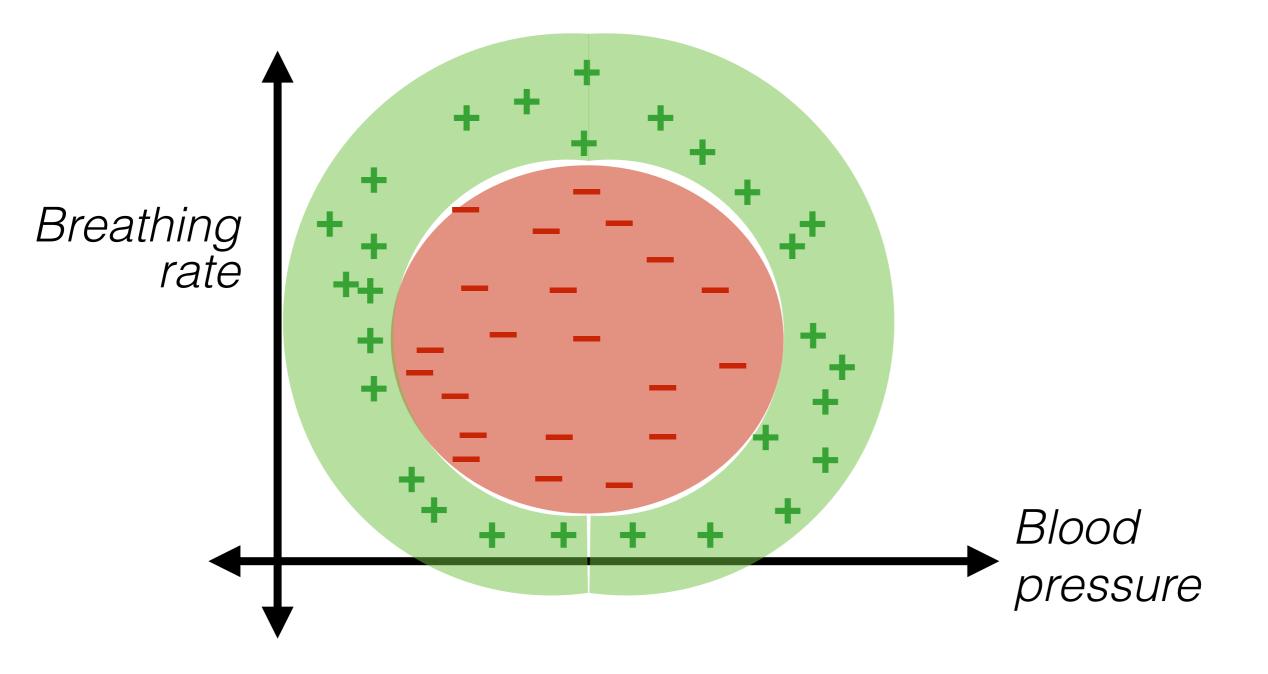
- Identify the features and encode as real numbers
- Standardize numerical features

	resting heart rate (bpm)	pain?	j1,j2,j3,j4,j5	m1, m2	decade	family income (USD)
1	-1.5	0	1,0,0,0,0	1,0	1	2.075
2	0.1	0	0,1,0,0,0	1,1	-1	-0.4
3	1.9	1	1,0,0,0,0	0,1	2	-0.25
4	-0.3	0	0,0,0,1,0	0,0	2	1.75

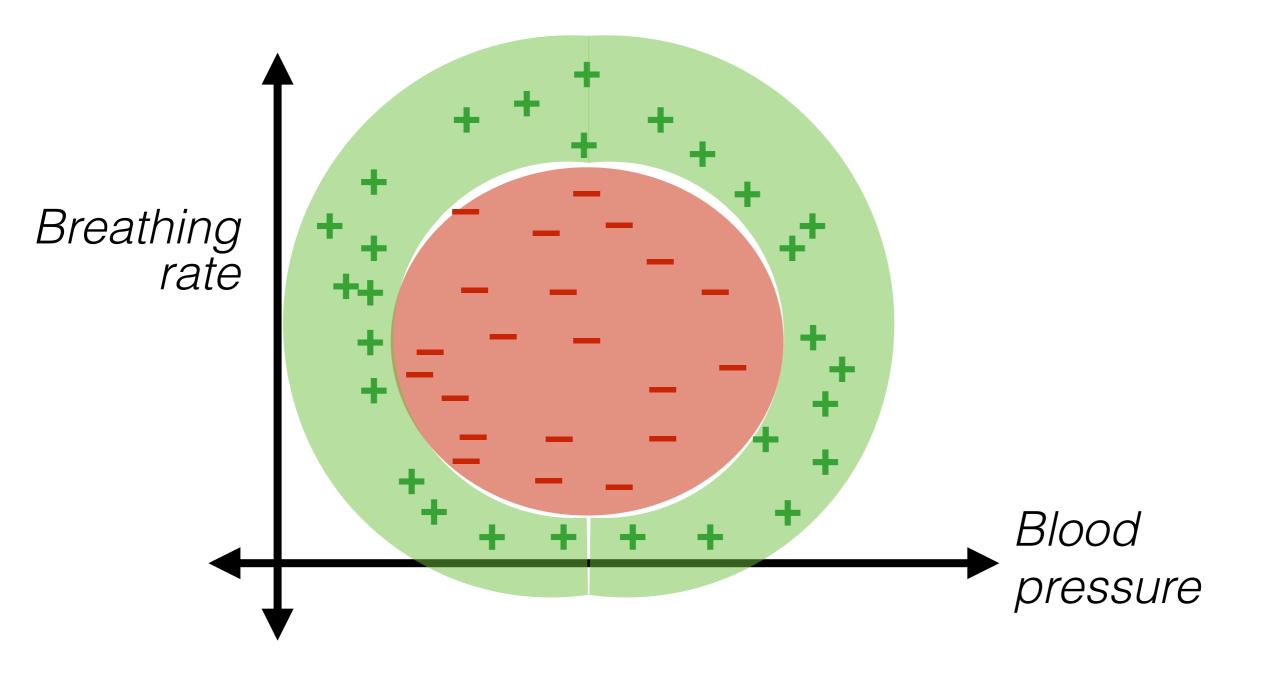
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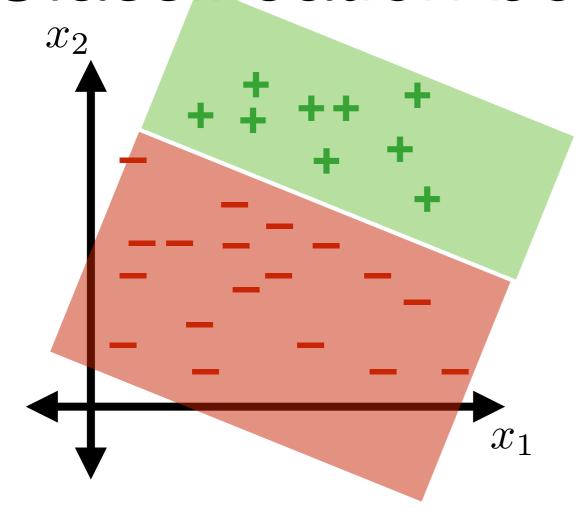


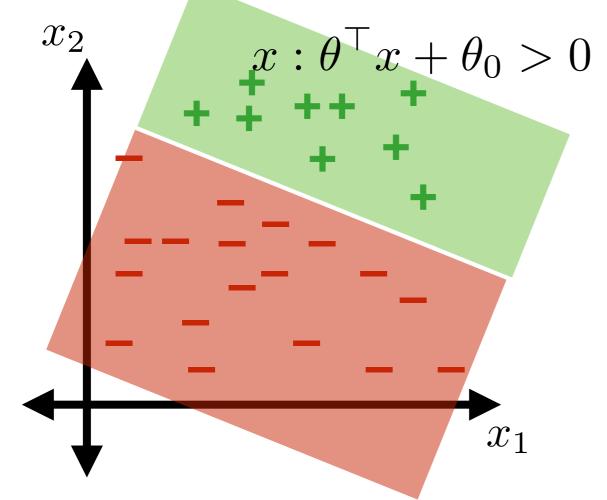


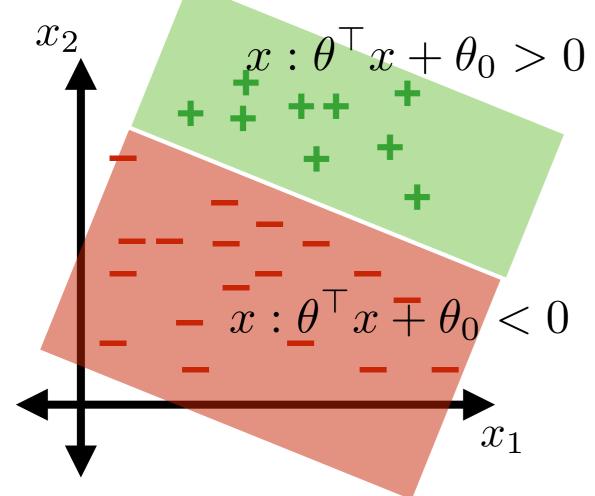


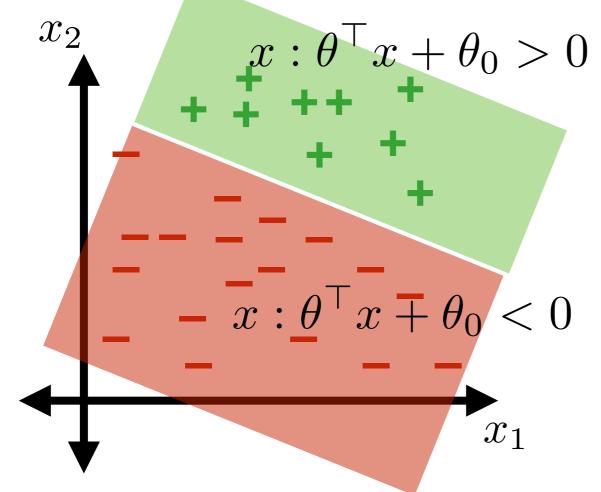
## Nonlinear boundaries

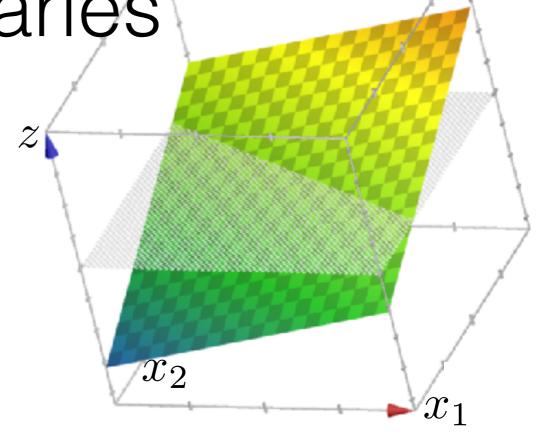


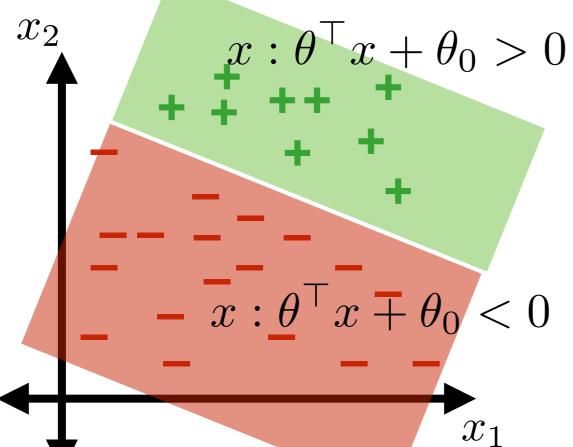


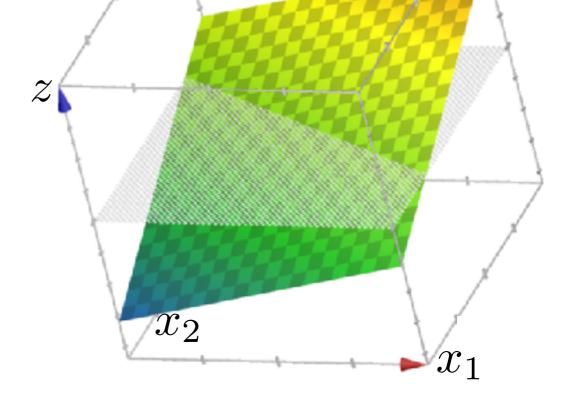


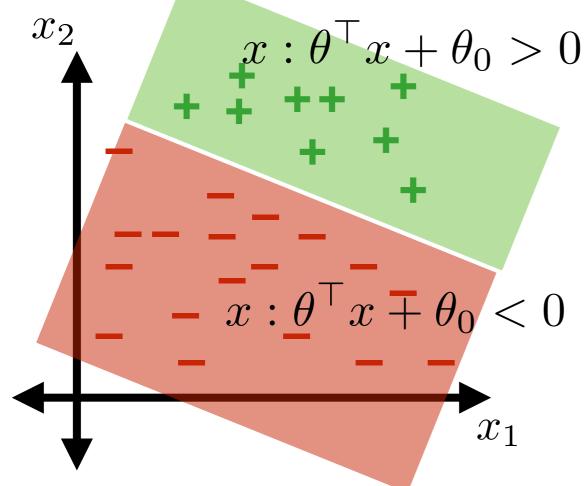


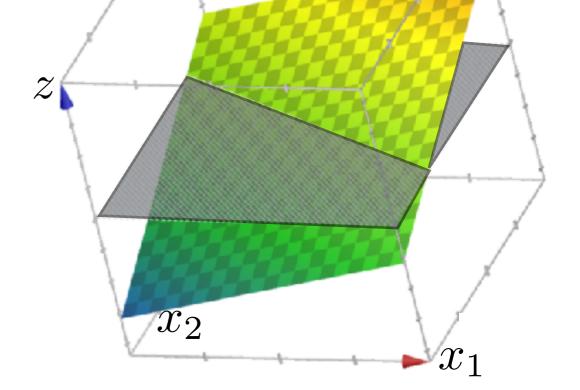


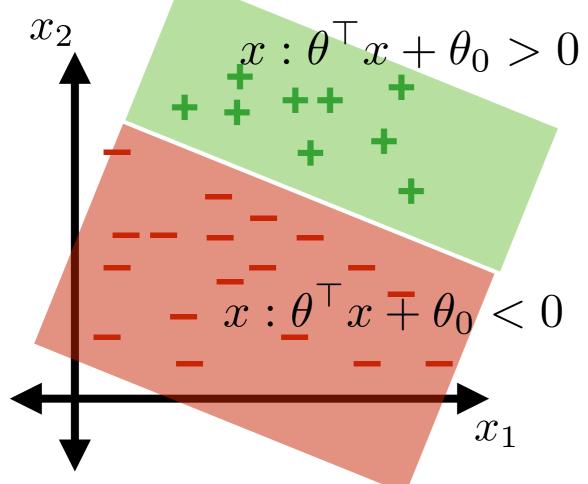


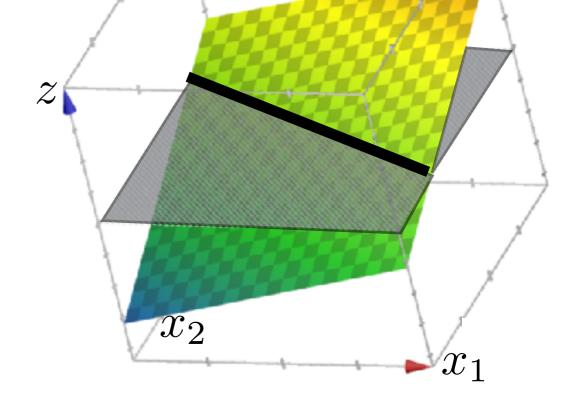


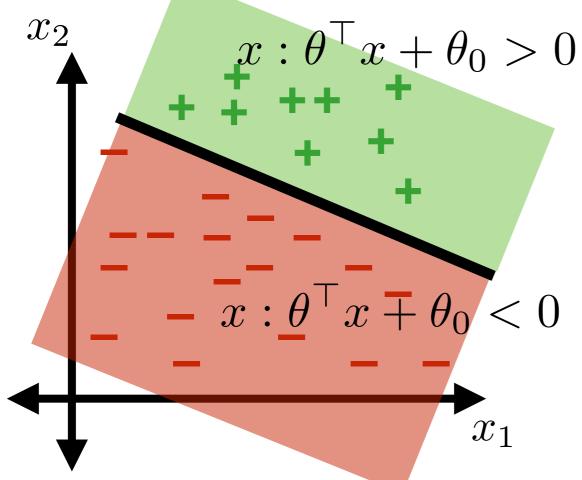


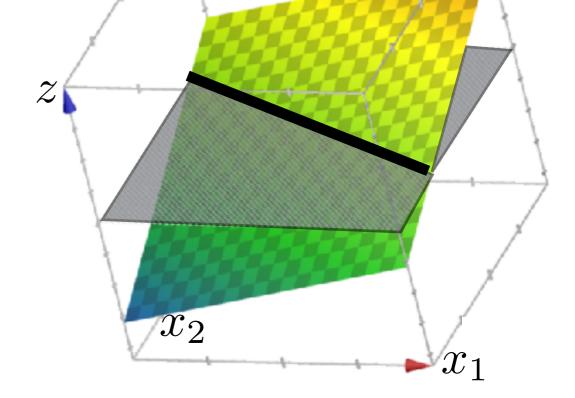


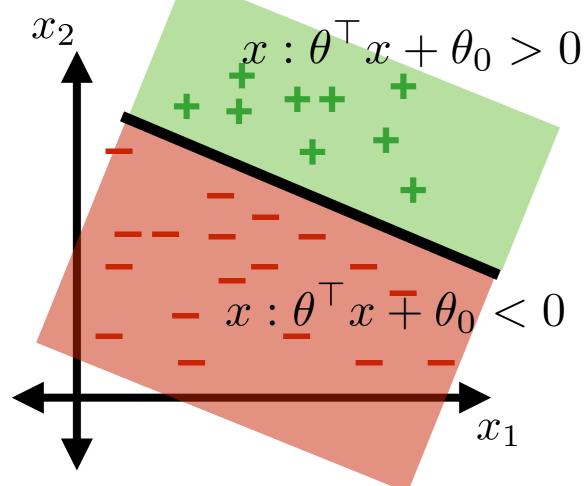


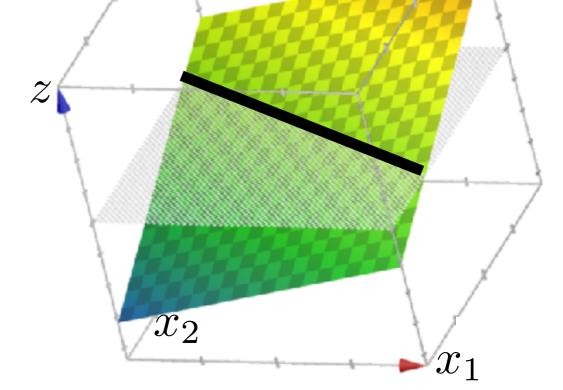


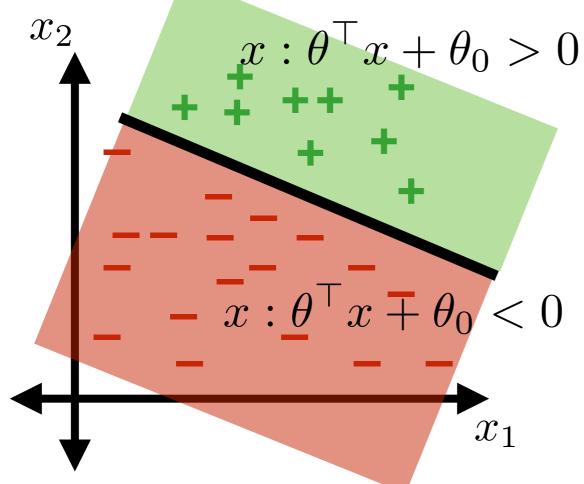


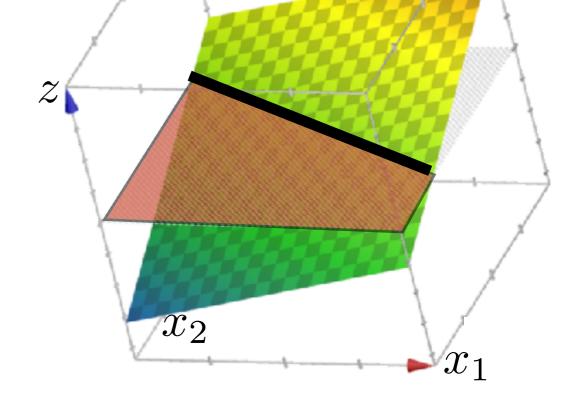


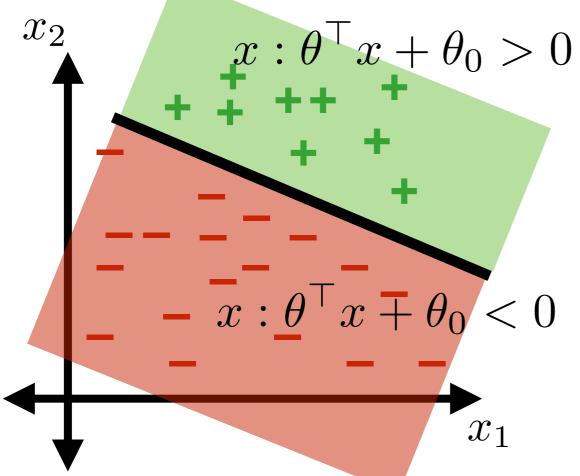


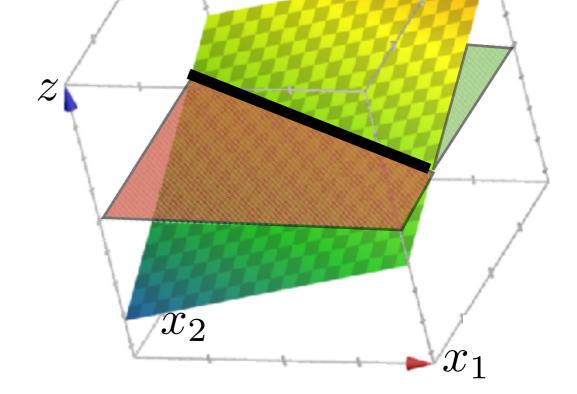


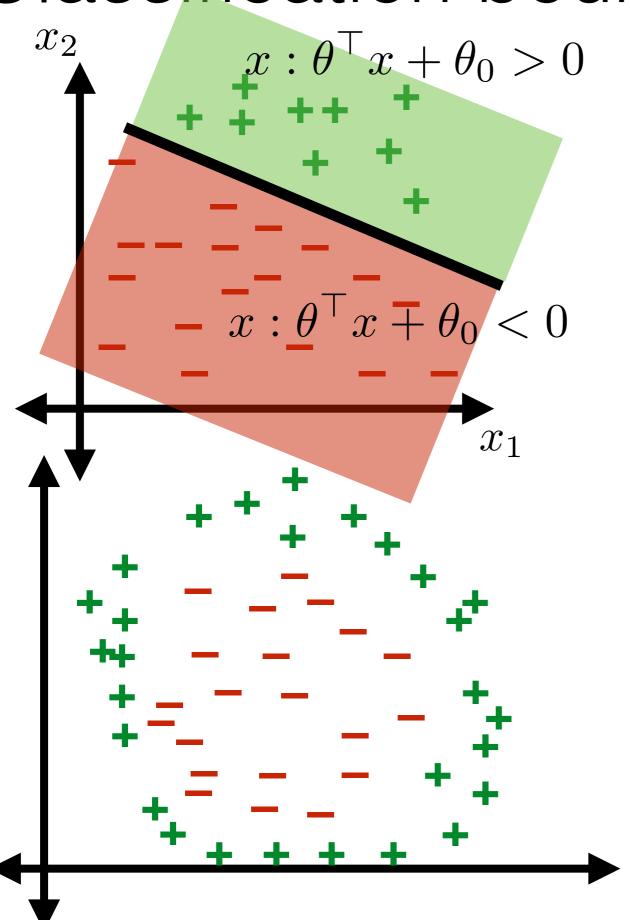


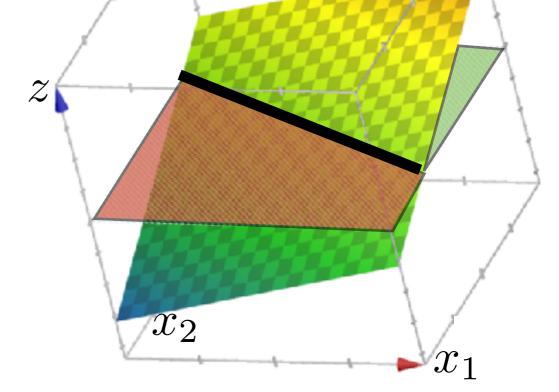


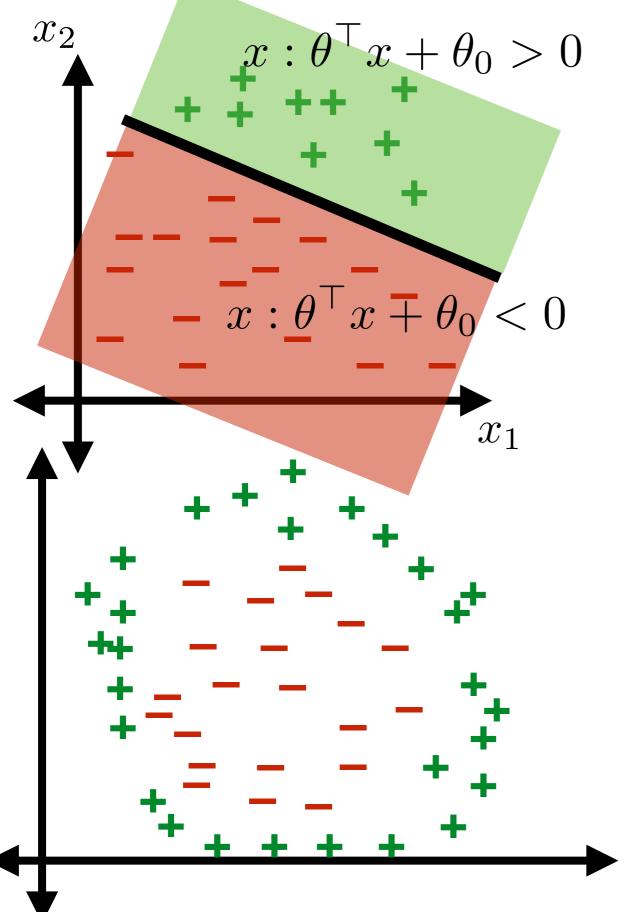


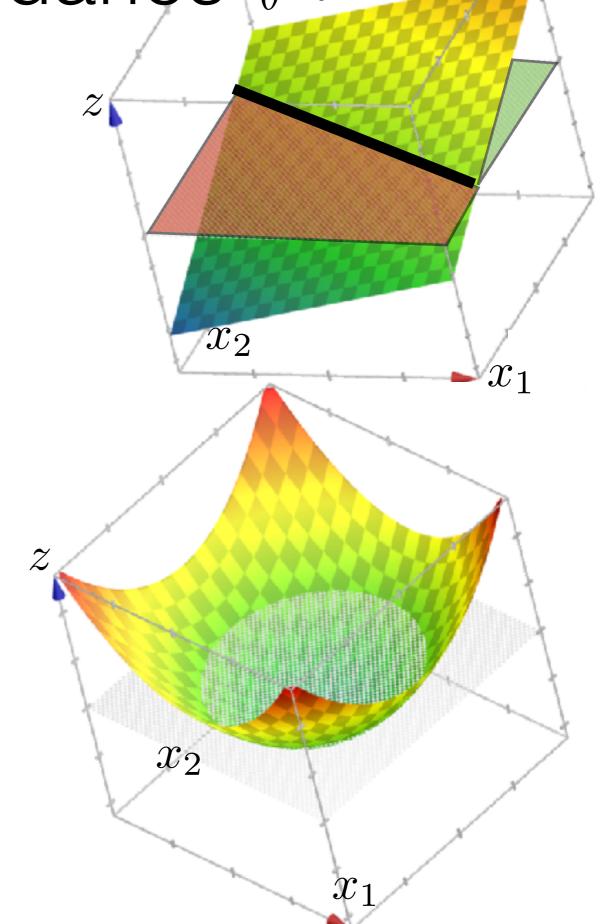


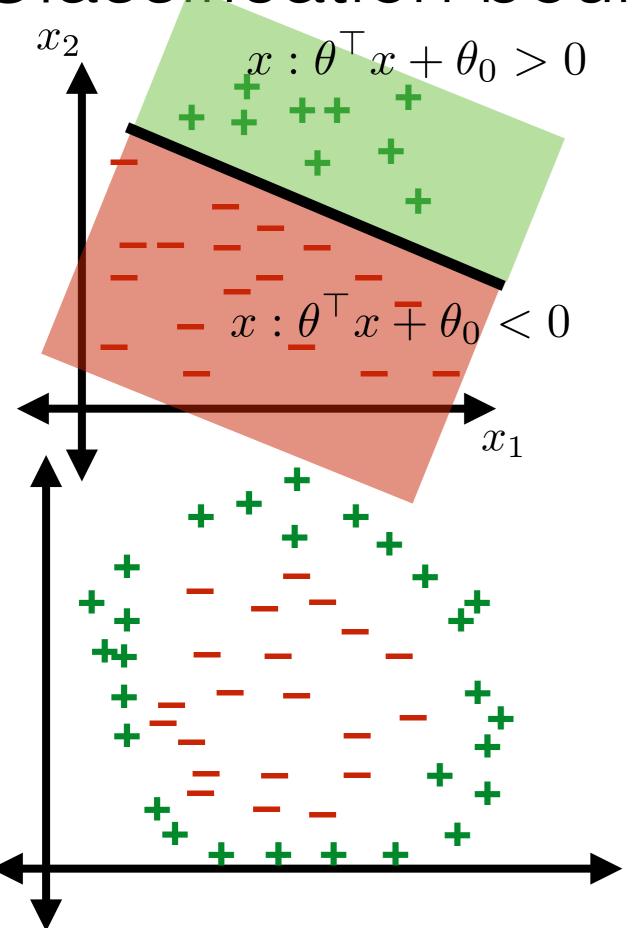


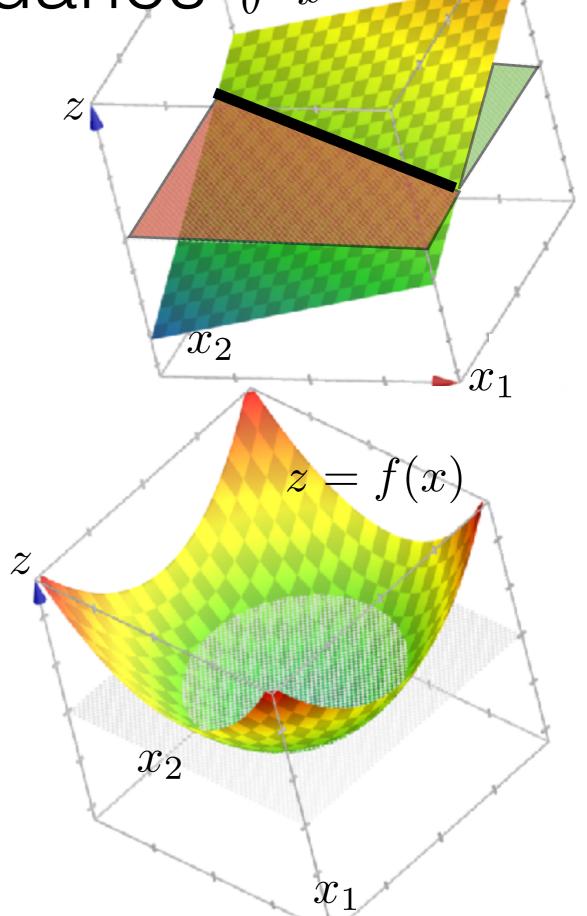


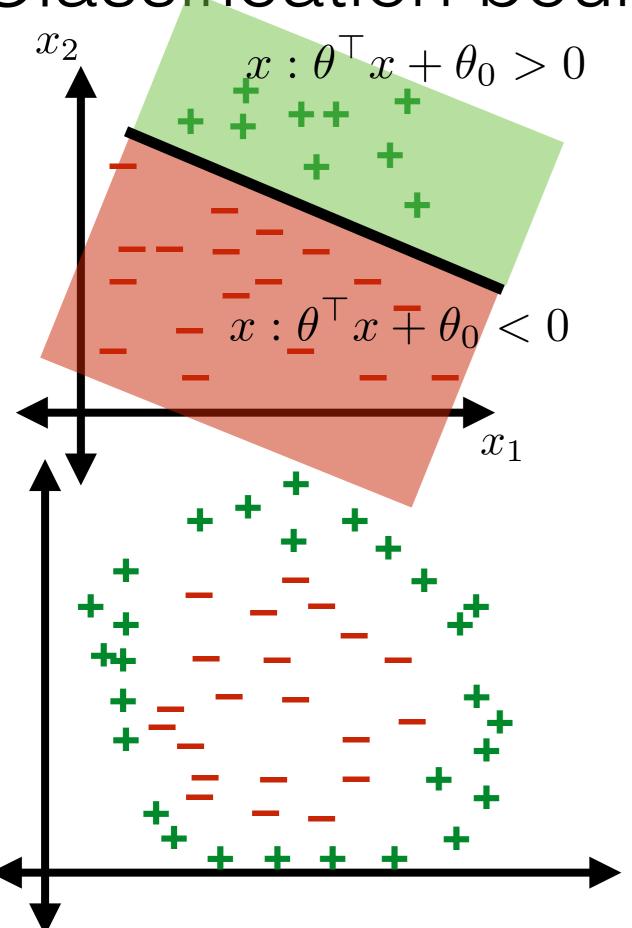


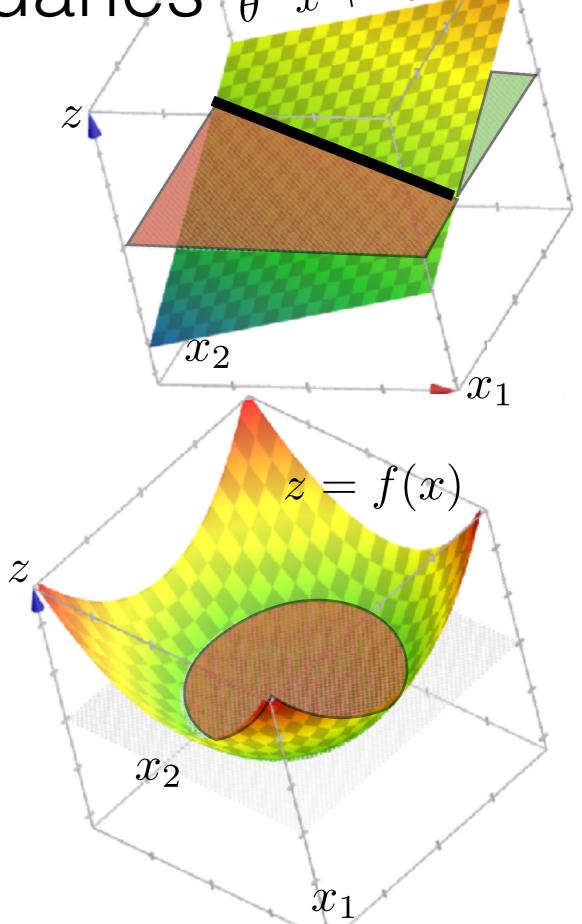


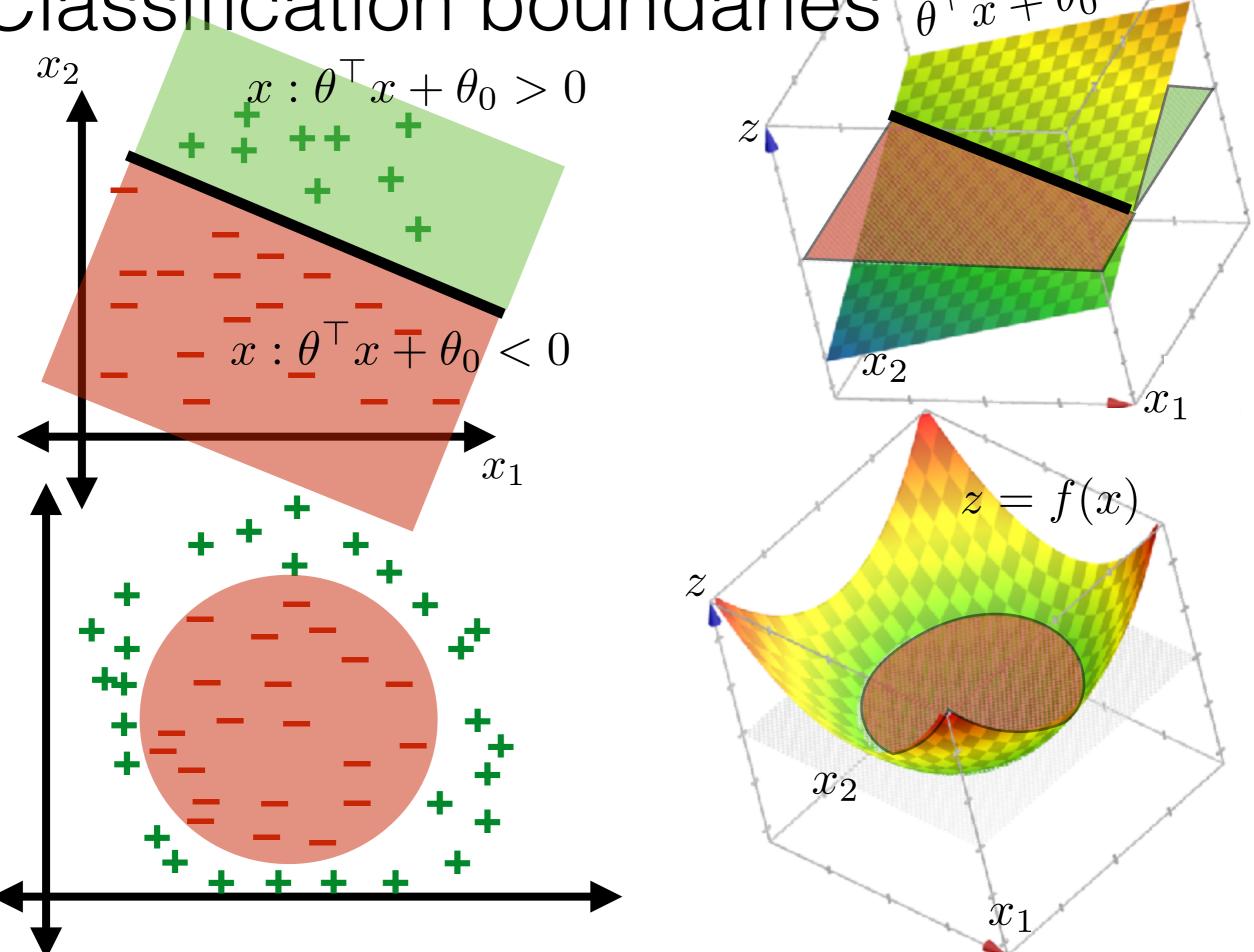


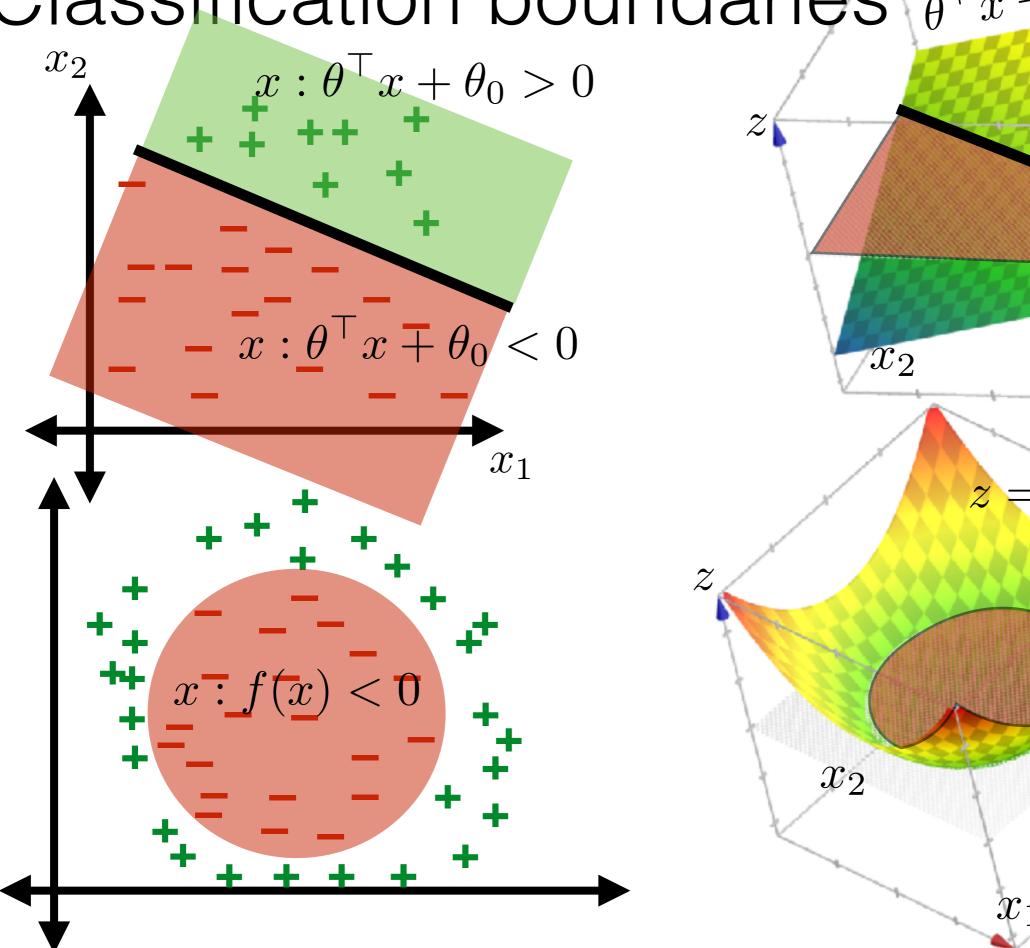


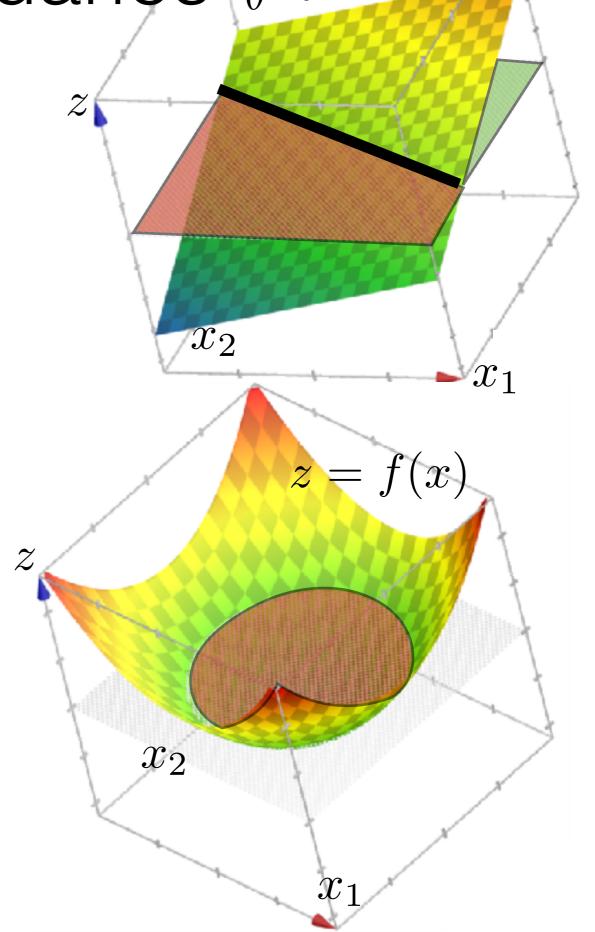




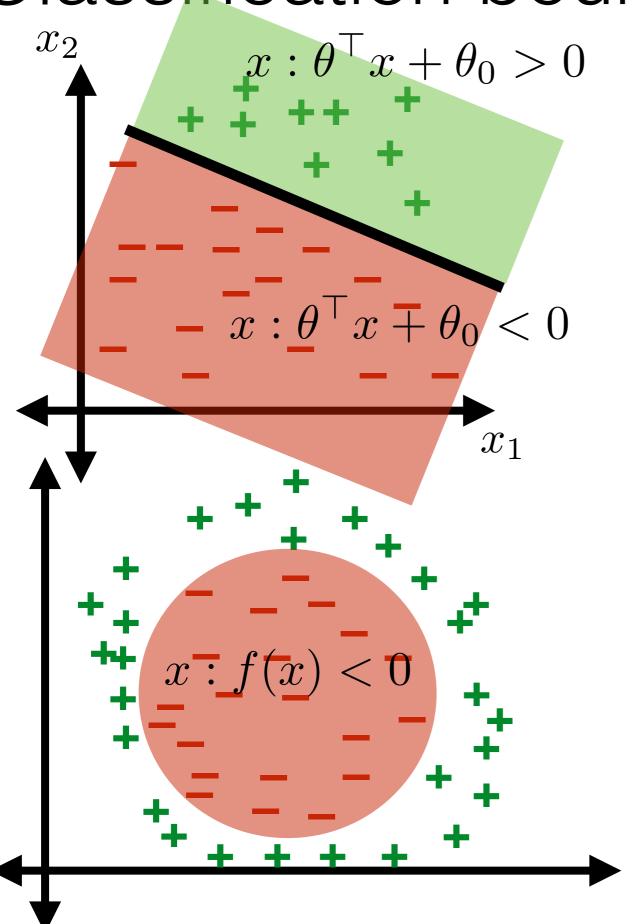


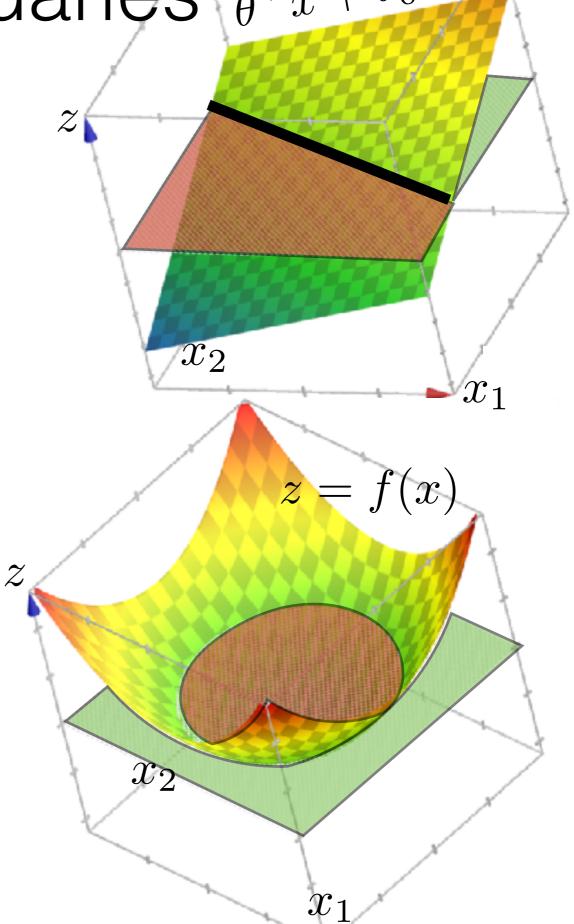


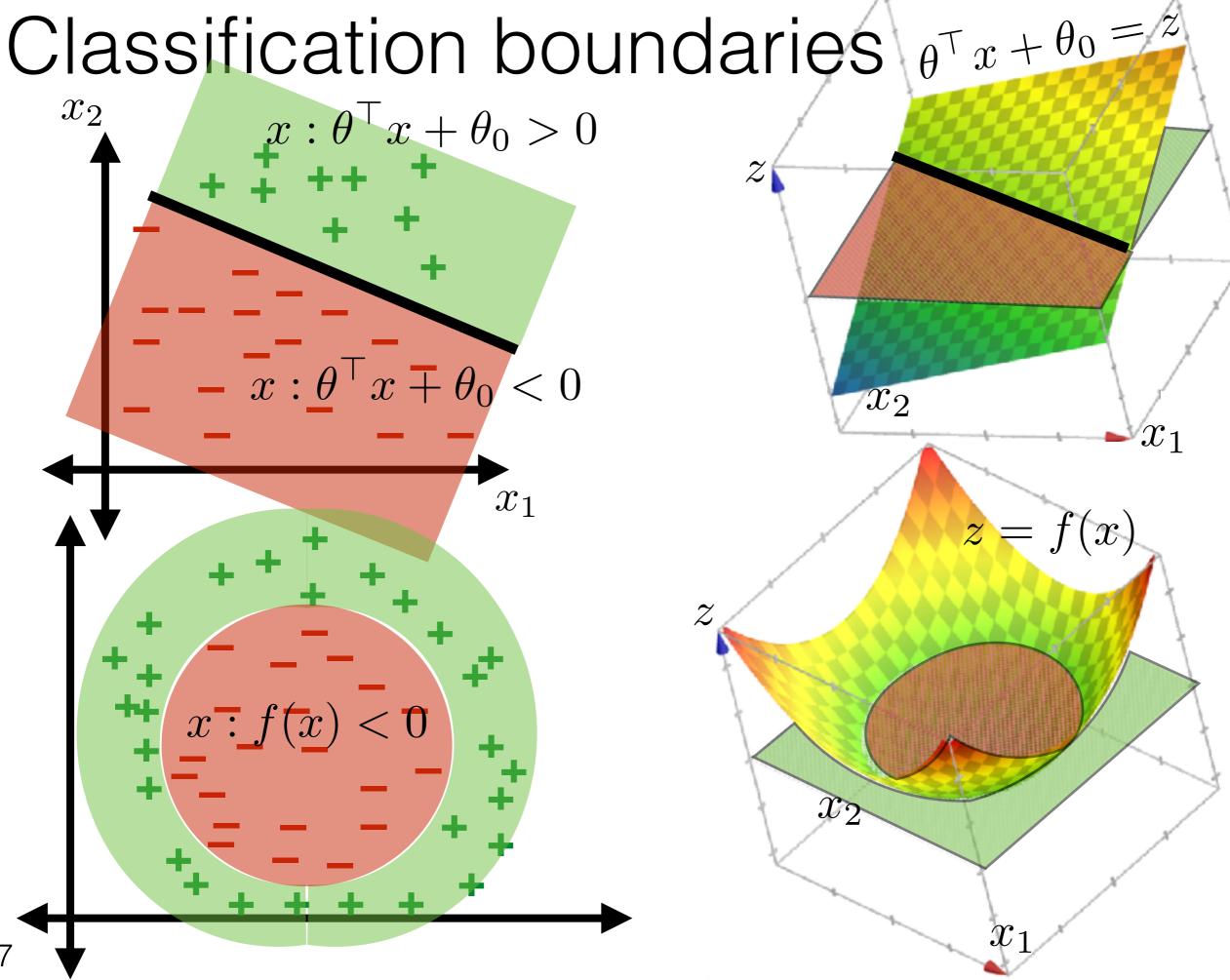


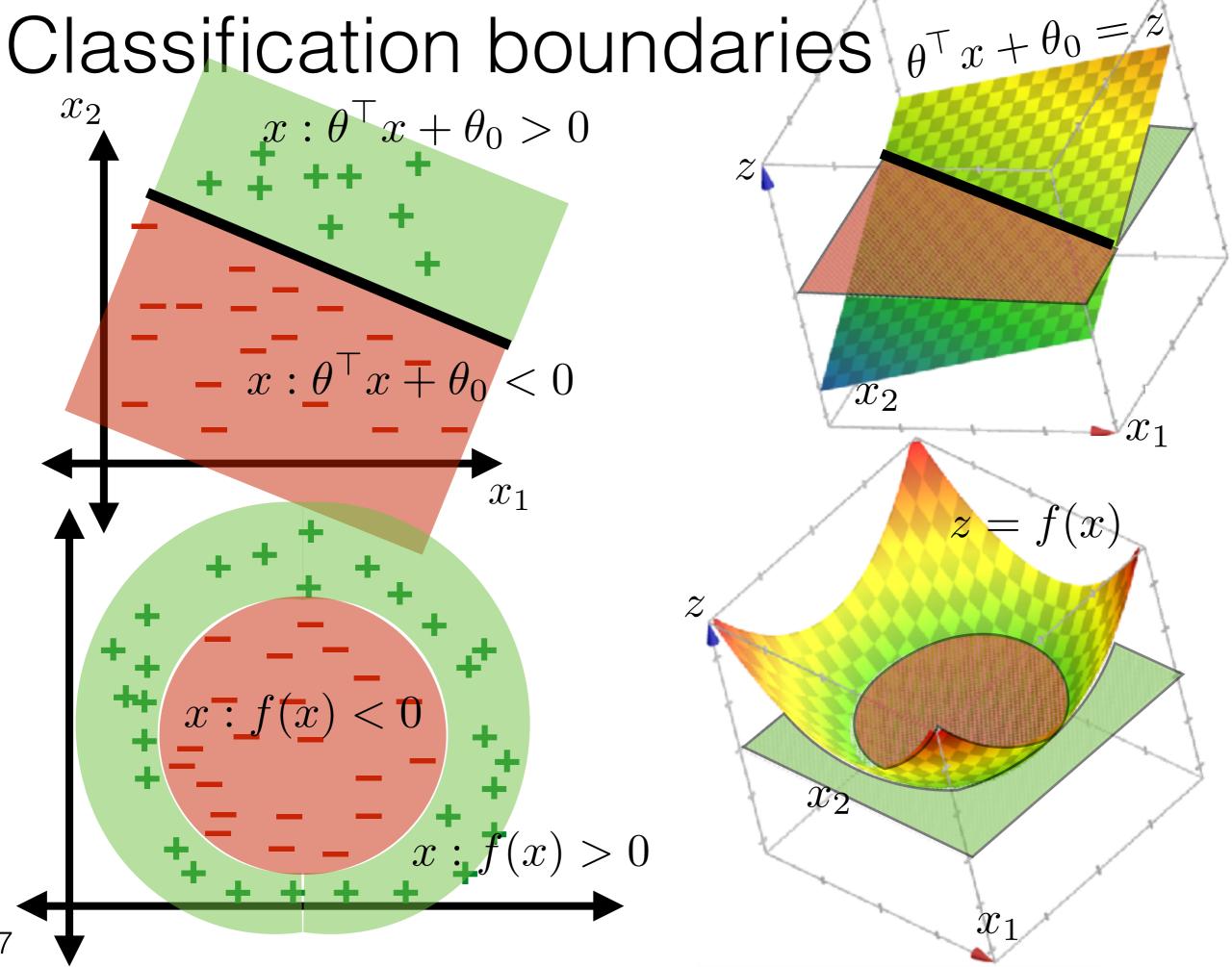


# Classification boundaries $\theta^{T}x + \theta_0 = 2$









order ( <i>k</i> )	terms when <i>d</i> =1	terms for general d
0		
1		
2		
3		

order ( <i>k</i> )	terms when <i>d</i> =1	terms for general d
0	[1]	
1		
2		
3		

order ( <i>k</i> )	terms when <i>d</i> =1	terms for general d
0	[1]	
1	$[1, x_1]$	
2		
3		

order ( <i>k</i> )	terms when <i>d</i> =1	terms for general d
0	[1]	
1	$[1, x_1]$	
2	$[1, x_1, x_1^2]$	
3		

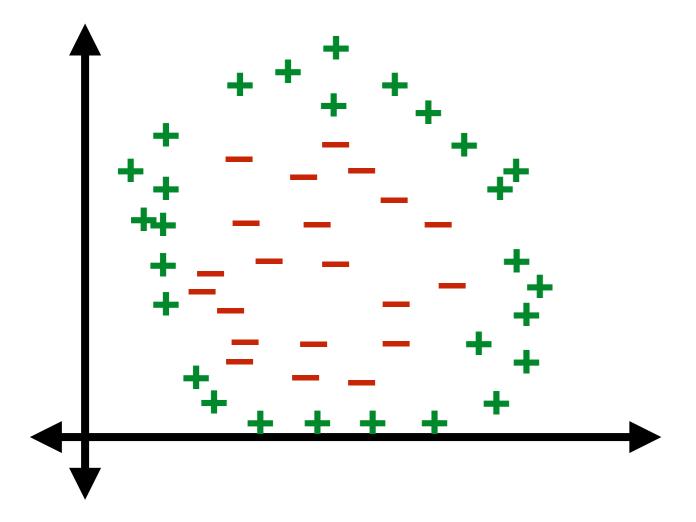
order ( <i>k</i> )	terms when <i>d</i> =1	terms for general d
0	[1]	
1	$[1, x_1]$	
2	$[1, x_1, x_1^2]$	
3	$[1, x_1, x_1^2, x_1^3]$	

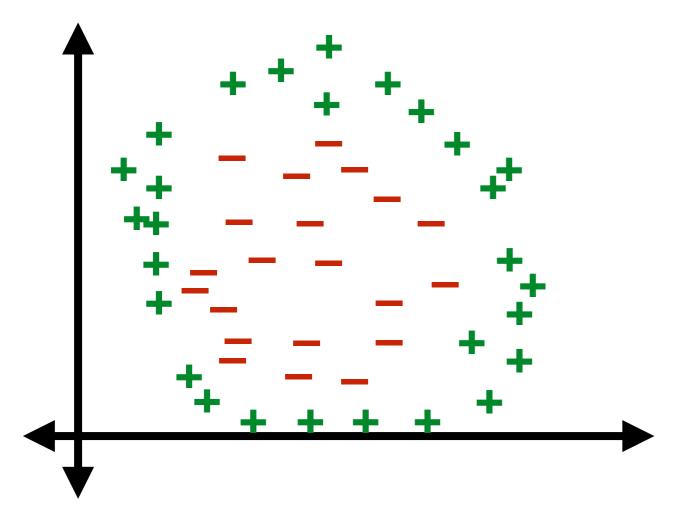
order ( <i>k</i> )	terms when <i>d</i> =1	terms for general d
0	[1]	[1]
1	$[1, x_1]$	
2	$[1, x_1, x_1^2]$	
3	$[1, x_1, x_1^2, x_1^3]$	

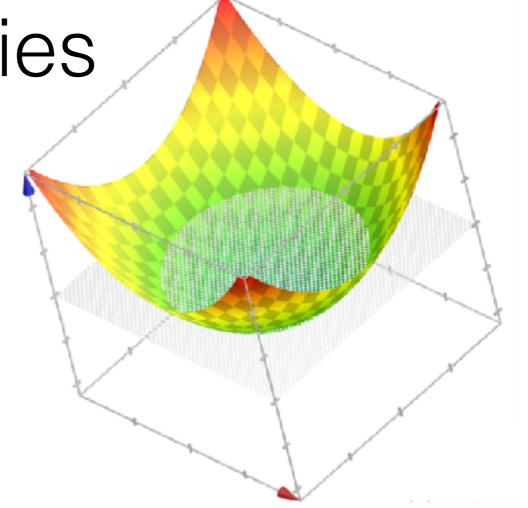
order ( <i>k</i> )	terms when <i>d</i> =1	terms for general d
0	[1]	[1]
1	$[1, x_1]$	$[1, x_1, \ldots, x_d]$
2	$[1, x_1, x_1^2]$	
3	$[1, x_1, x_1^2, x_1^3]$	

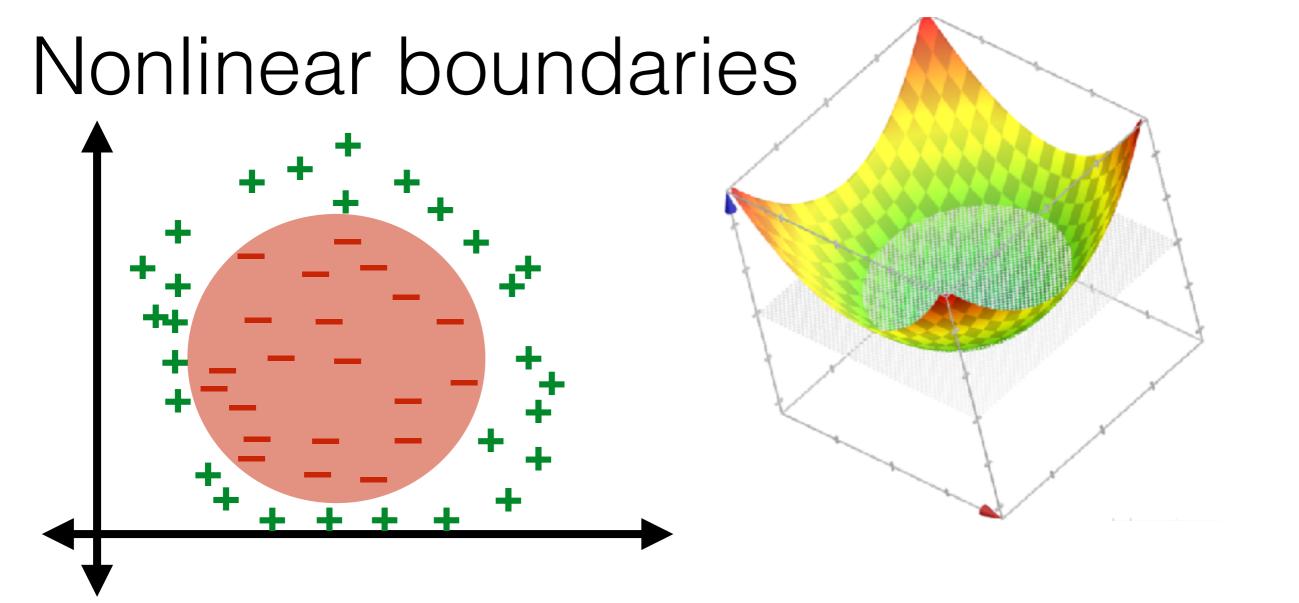
order ( <i>k</i> )	terms when <i>d</i> =1	terms for general d
0	[1]	[1]
1	$[1, x_1]$	$[1, x_1, \ldots, x_d]$
2	$[1, x_1, x_1^2]$	$[1, x_1, \dots, x_d, x_1^2, x_1 x_2, \dots, x_{d-1} x_d, x_d^2]$
3	$[1, x_1, x_1^2, x_1^3]$	

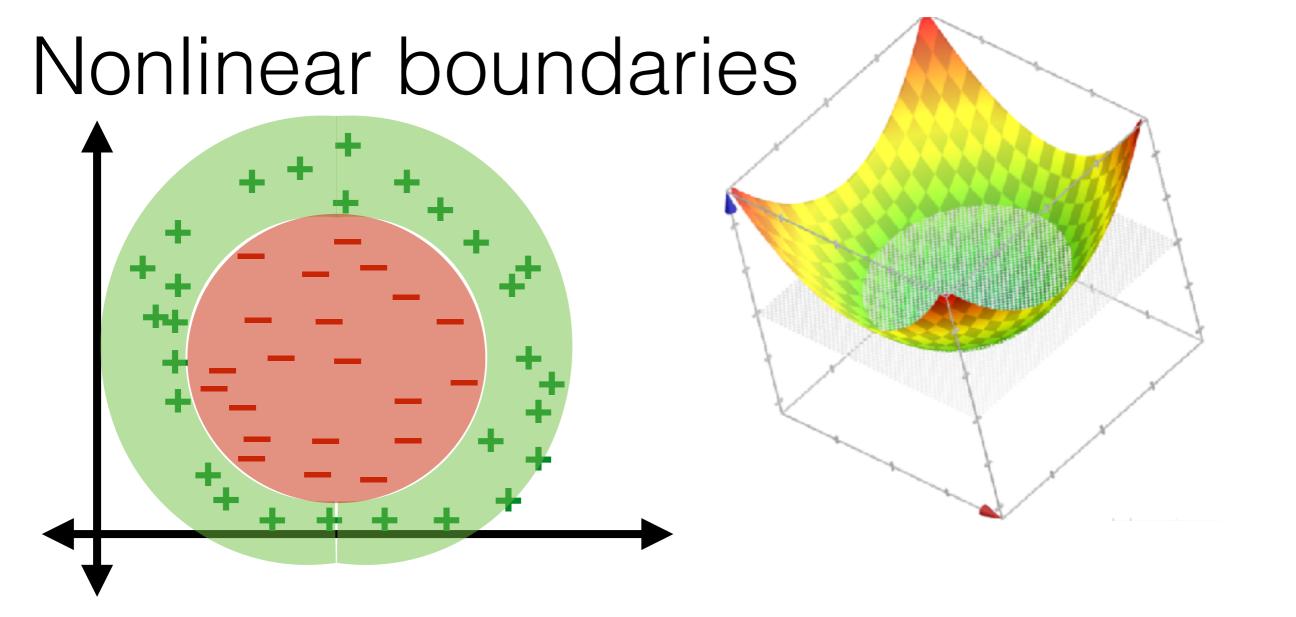
order ( <i>k</i> )	terms when <i>d</i> =1	terms for general d
0	[1]	[1]
1	$[1, x_1]$	$[1, x_1, \ldots, x_d]$
2	$[1, x_1, x_1^2]$	$[1, x_1, \dots, x_d, x_1^2, x_1 x_2, \dots, x_{d-1} x_d, x_d^2]$
3	$[1, x_1, x_1^2, x_1^3]$	$   \begin{bmatrix}     1, x_1, \dots, x_d, \\     x_1^2, x_1 x_2, \dots, x_{d-1} x_d, x_d^2, \\     x_1^3, x_1^2 x_2, x_1 x_2 x_3, \dots, x_d^3   \end{bmatrix} $

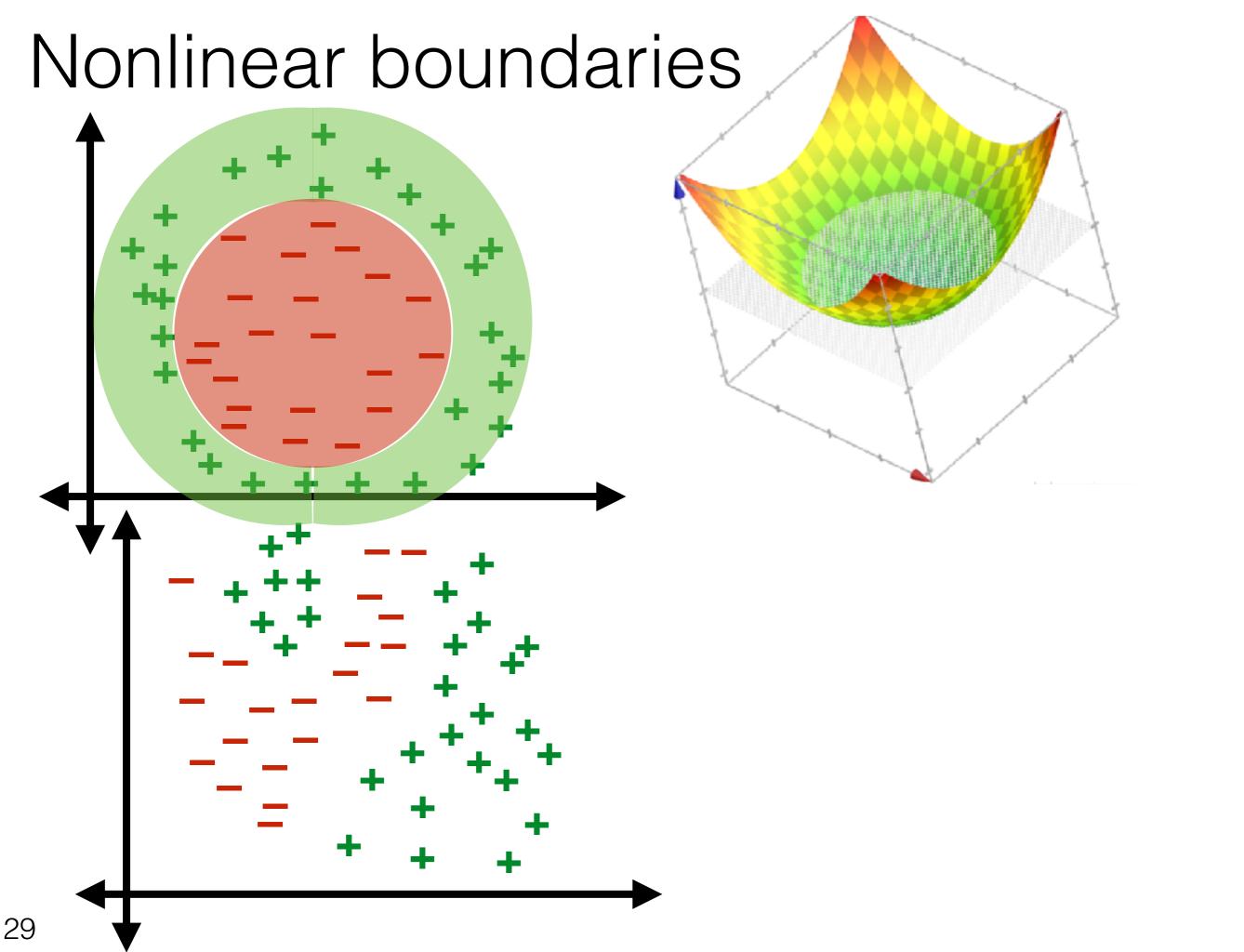


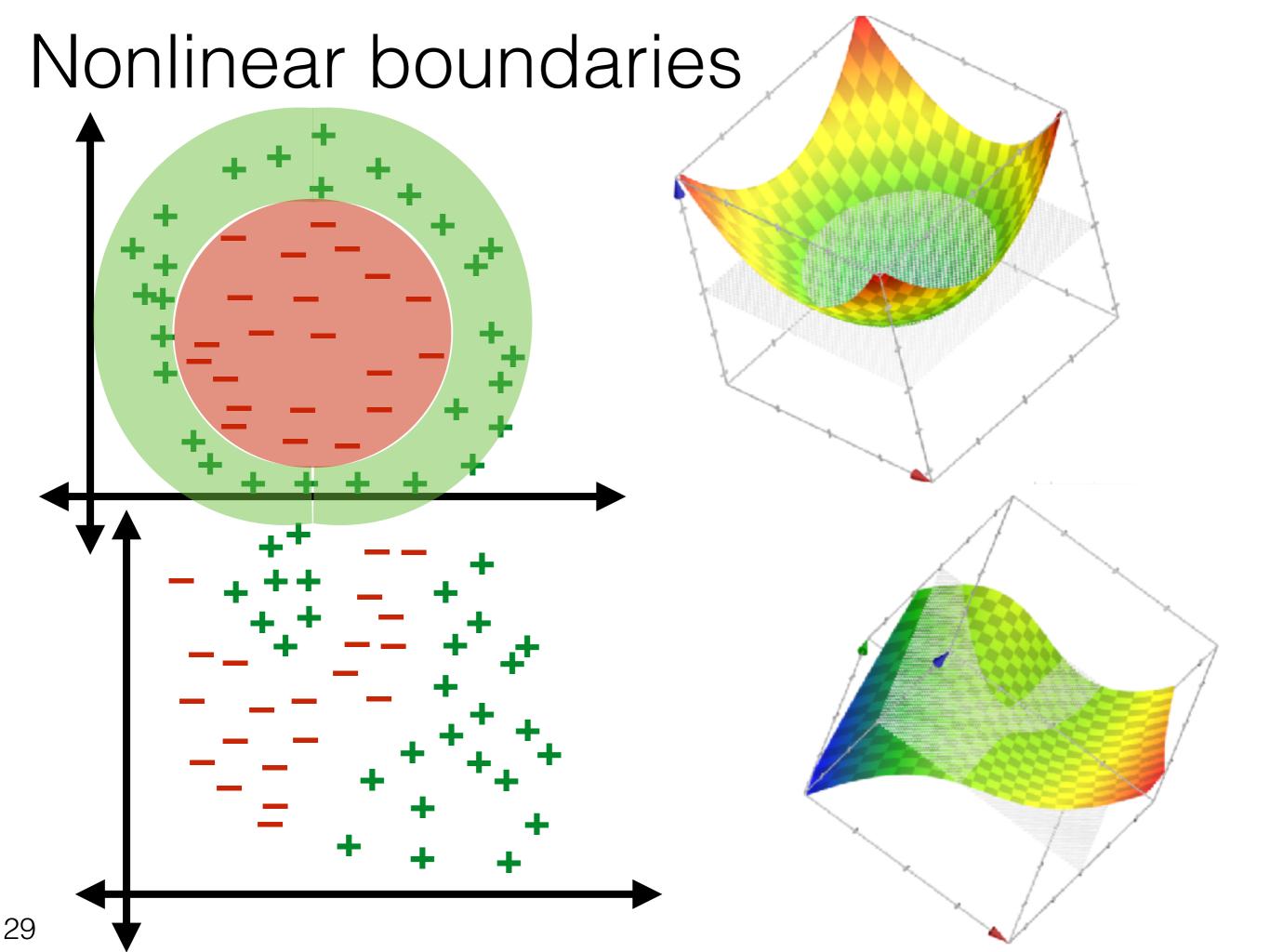


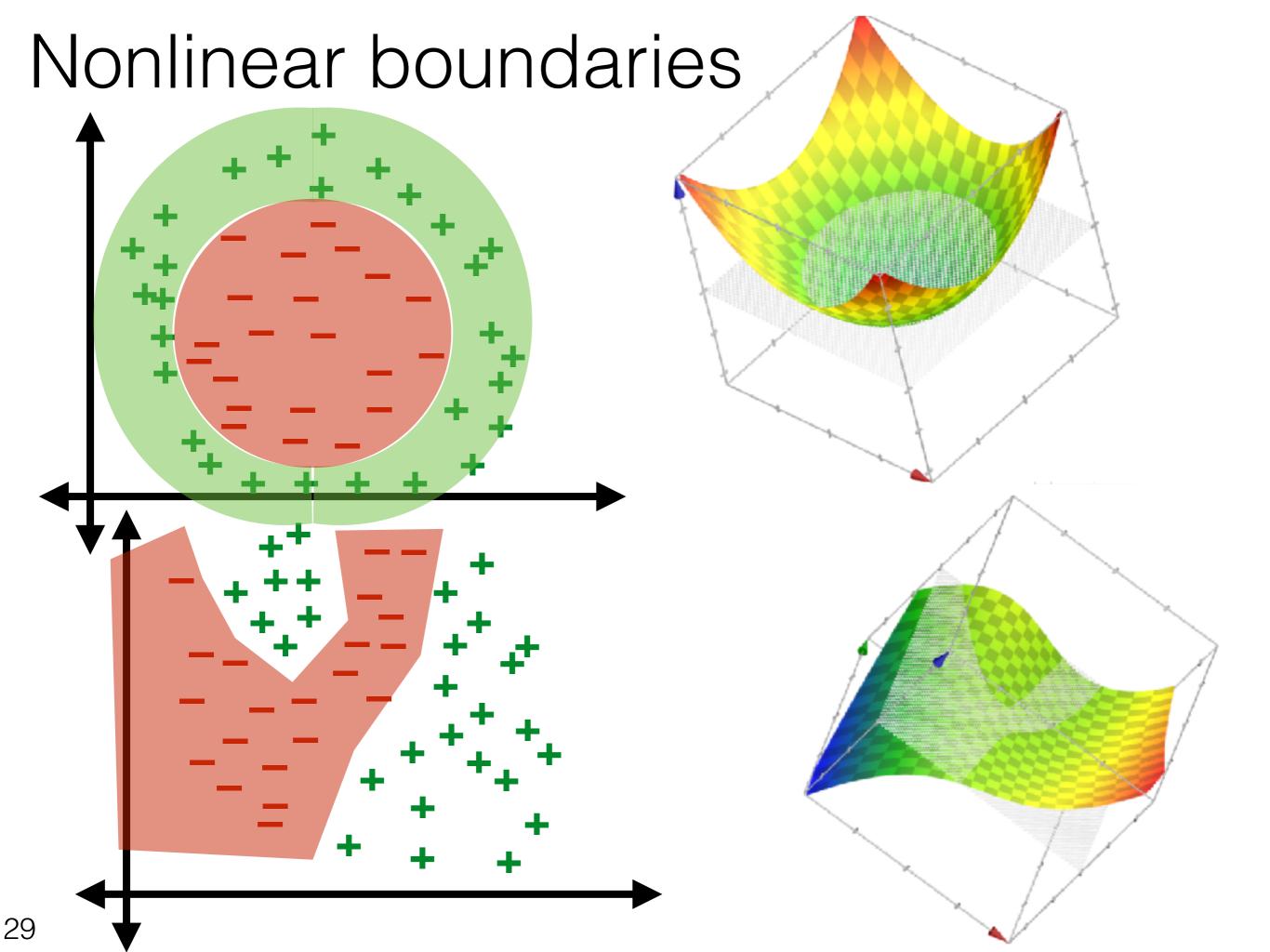


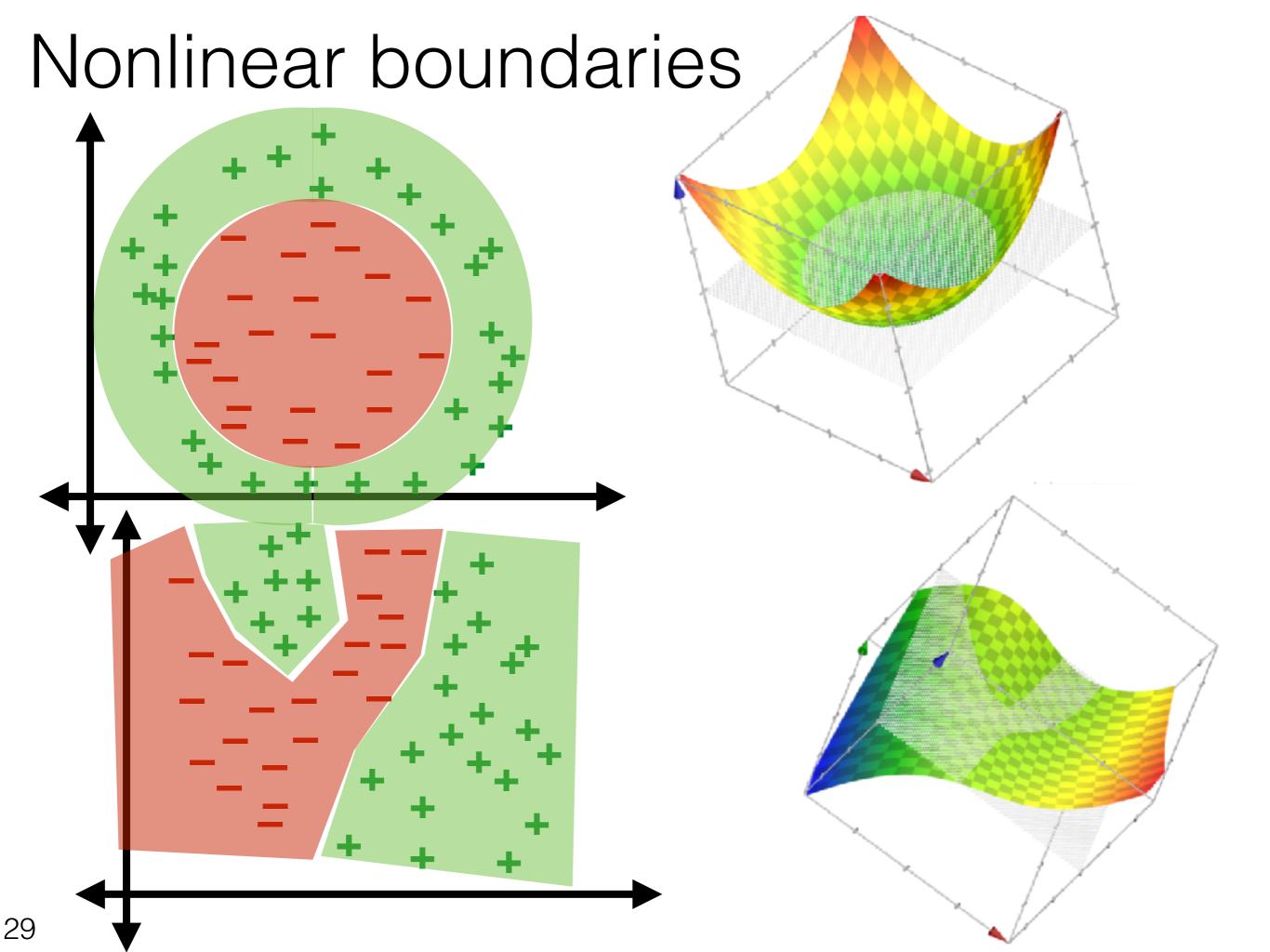


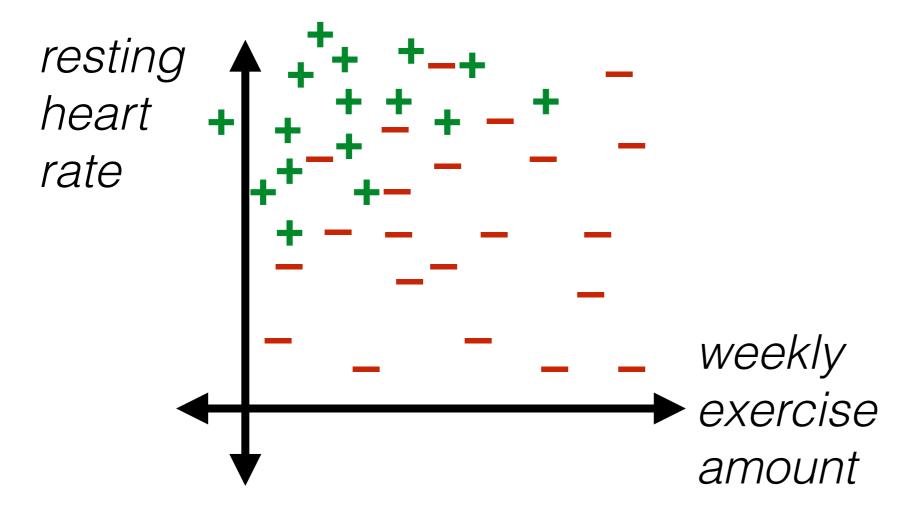


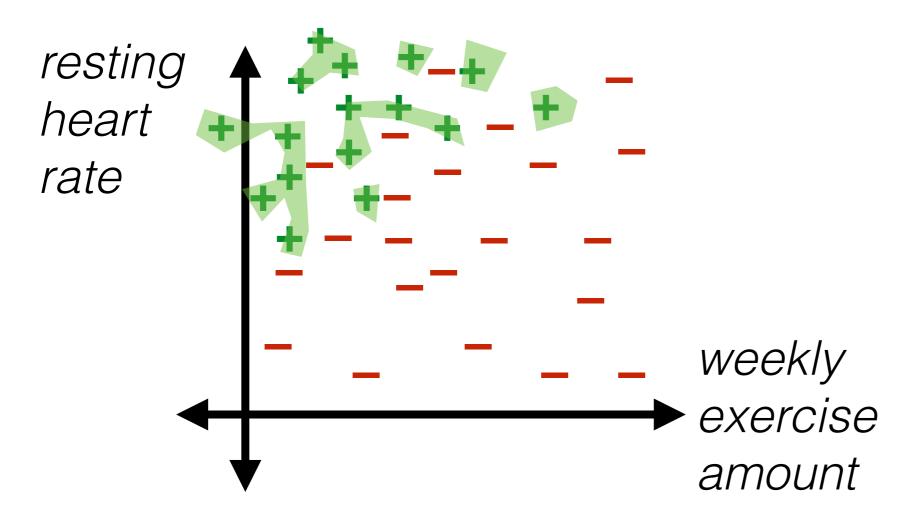


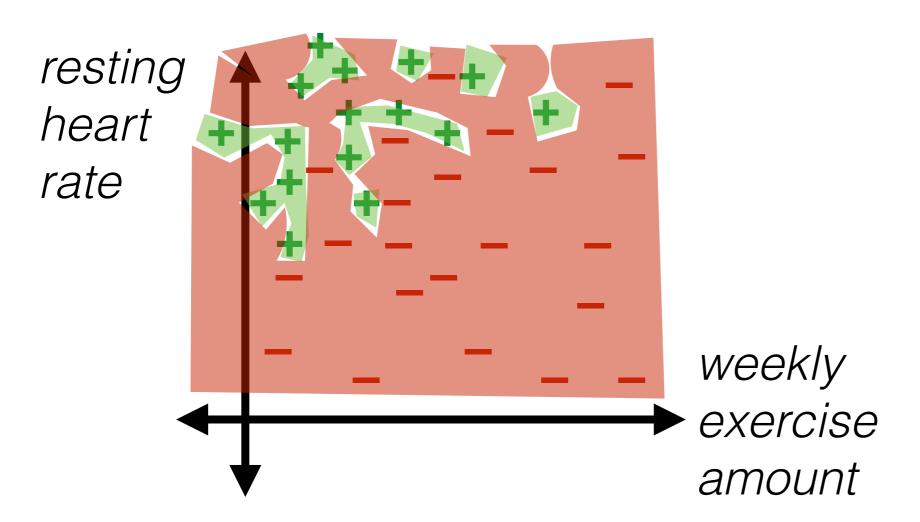


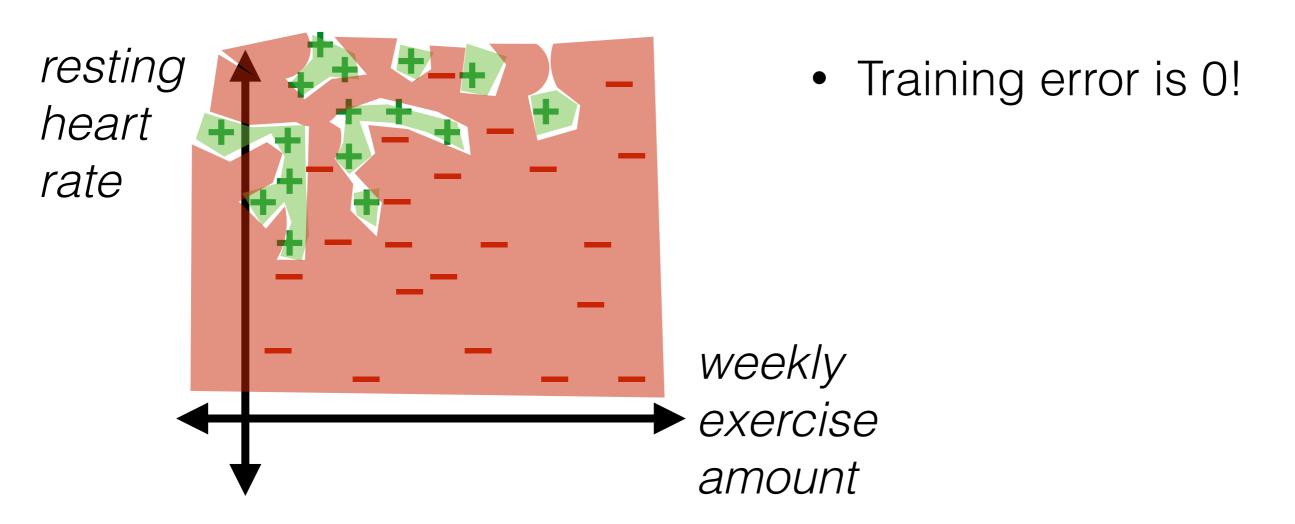


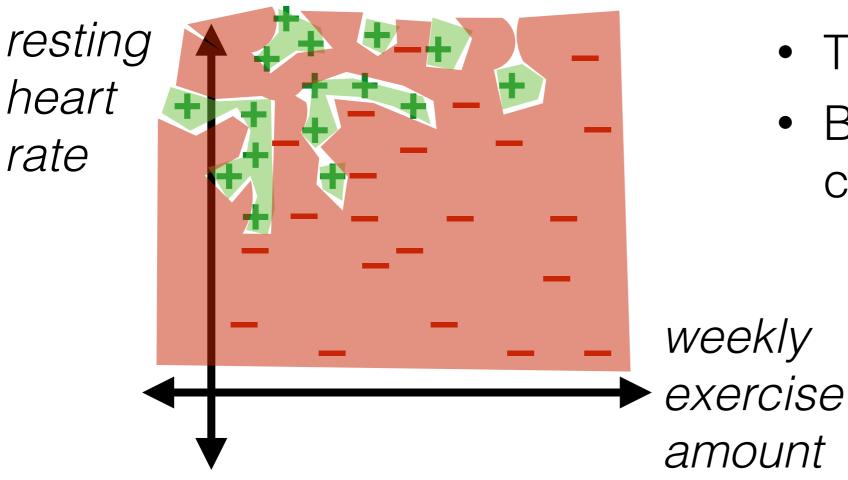




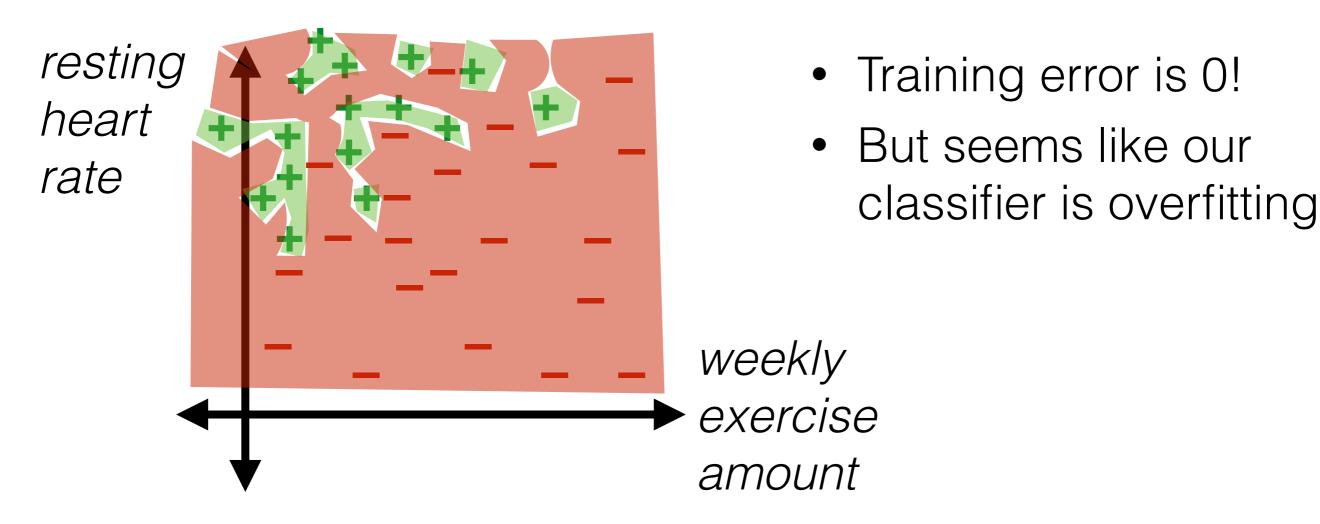




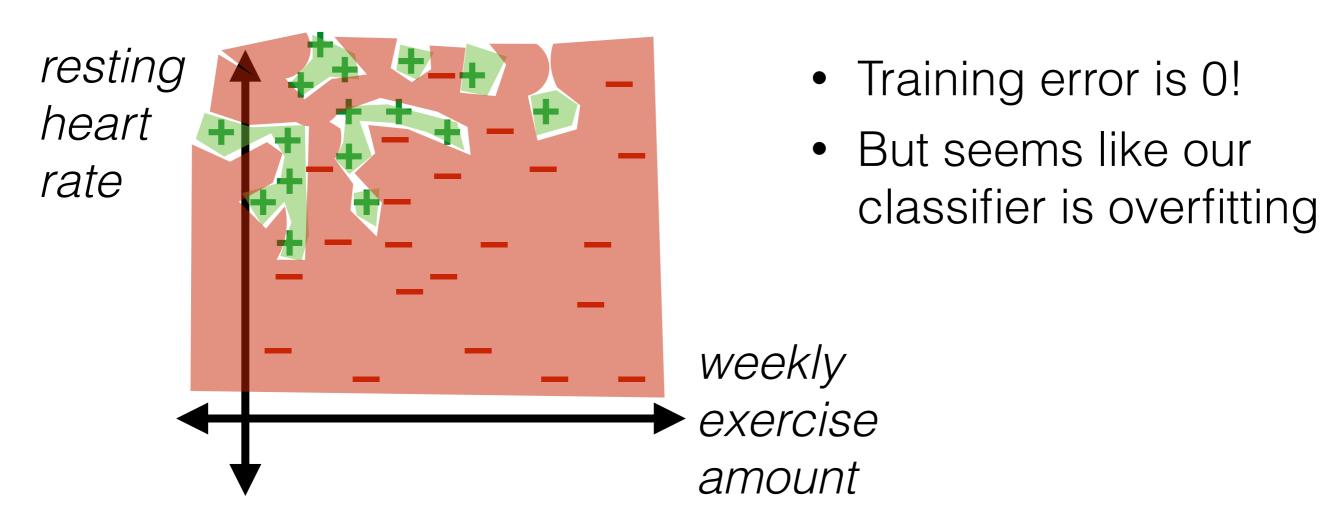




 But seems like our classifier is overfitting



How can we detect overfitting?



- How can we detect overfitting?
- How can we avoid overfitting?

- How good is our learning algorithm on data like ours?
- Idea: use full data for training and then report training error

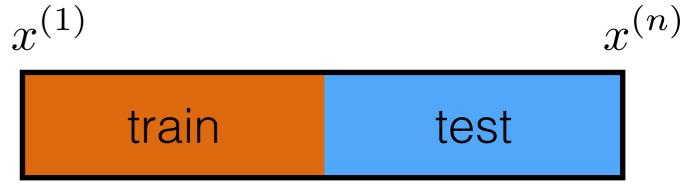
- How good is our learning algorithm on data like ours?
- Idea: use full data for training and then report training error
- Idea: reserve some data for testing



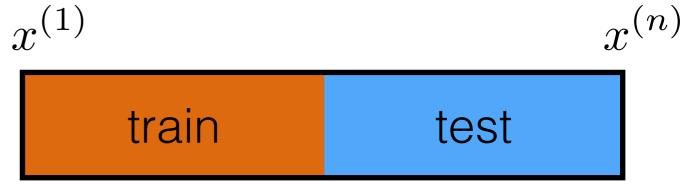
- Idea: use full data for training and then report training error
- Idea: reserve some data for testing



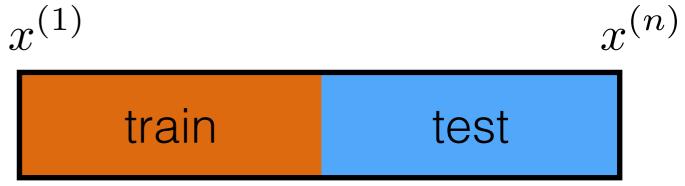
- Idea: use full data for training and then report training error
- Idea: reserve some data for testing



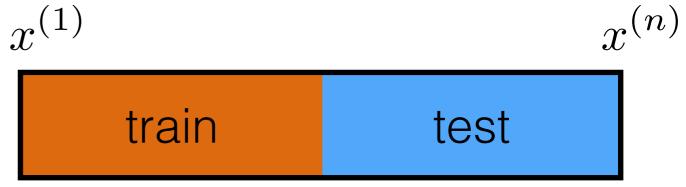
- Idea: use full data for training and then report training error
- Idea: reserve some data for testing



- Idea: use full data for training and then report training error
- Idea: reserve some data for testing
  - More training data: closer to training on full data



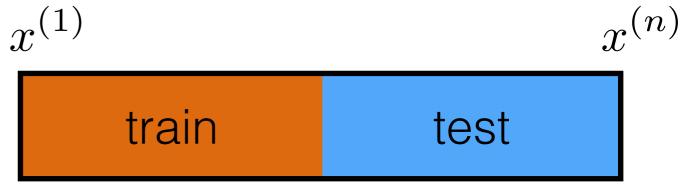
- Idea: use full data for training and then report training error
- Idea: reserve some data for testing
  - More training data: closer to training on full data
  - More testing data: less noisy estimate of performance



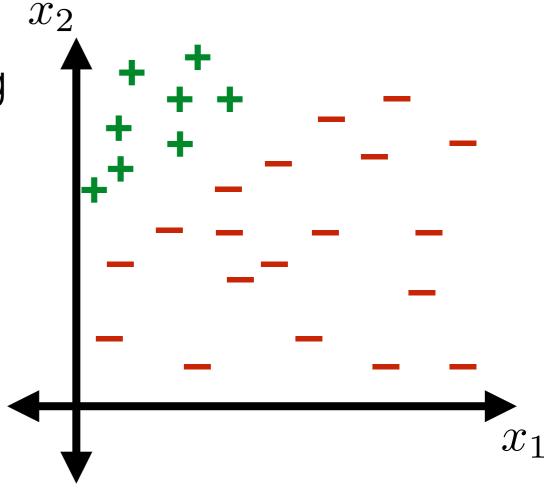
- Idea: use full data for training and then report training error
- Idea: reserve some data for testing
  - More training data: closer to training on full data
  - More testing data: less noisy estimate of performance
  - Only one classifier might not be representative

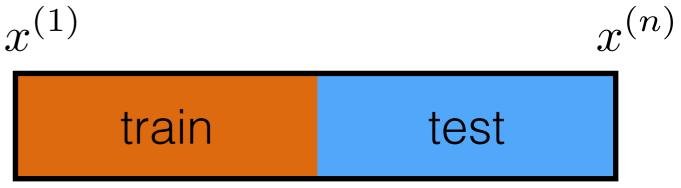


- Idea: use full data for training and then report training error
- Idea: reserve some data for testing
  - More training data: closer to training on full data
  - More testing data: less noisy estimate of performance
  - Only one classifier might not be representative
  - Good idea to shuffle order of data

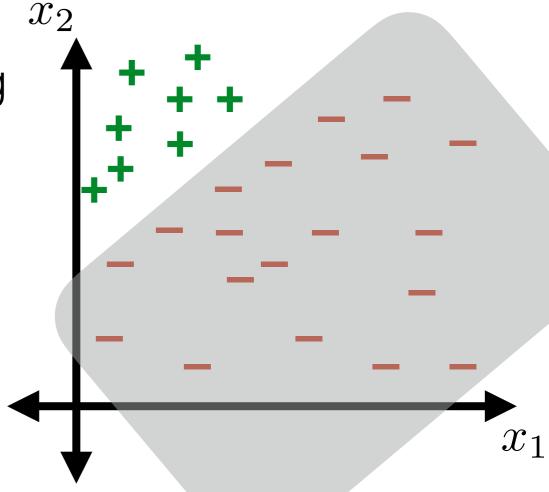


- Idea: use full data for training and then report training error
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  - More training data: closer to training on full data
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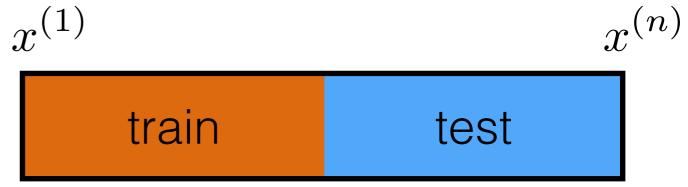




- Idea: use full data for training and then report training error
- Idea: reserve some data for testing
  - More training data: closer to training on full data
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  - Only one classifier might not be representative
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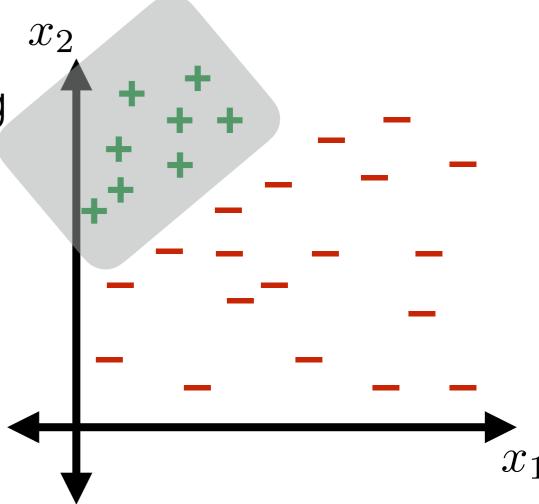
 How good is our learning algorithm on data like ours?



 Idea: use full data for training and then report training error

Idea: reserve some data for testing

- More training data: closer to training on full data
- More testing data: less noisy estimate of performance
- Only one classifier might not be representative
- Good idea to shuffle order of data

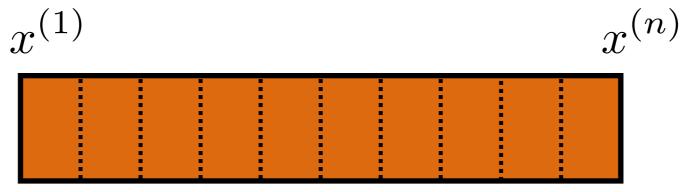


Cross-validate ( $\mathcal{D}_n$  , k )

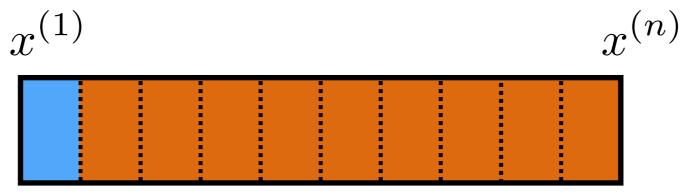
```
Cross-validate(\mathcal{D}_n, k)
Divide \mathcal{D}_n into k chunks \mathcal{D}_{n,1},\ldots,\mathcal{D}_{n,k} (of roughly equal size)
```



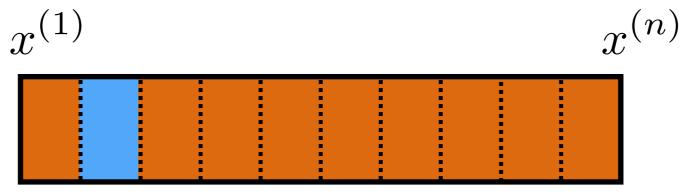
Cross-validate( $\mathcal{D}_n$ , k)
Divide  $\mathcal{D}_n$  into k chunks  $\mathcal{D}_{n,1},\ldots,\mathcal{D}_{n,k}$  (of roughly equal size)



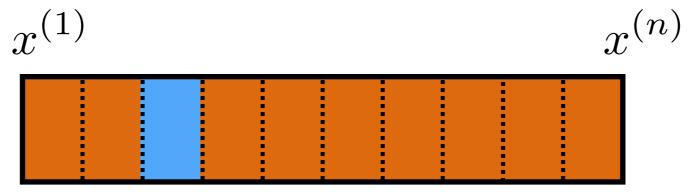
Cross-validate( $\mathcal{D}_n$ , k)
Divide  $\mathcal{D}_n$  into k chunks  $\mathcal{D}_{n,1},\dots,\mathcal{D}_{n,k}$  (of roughly equal size)



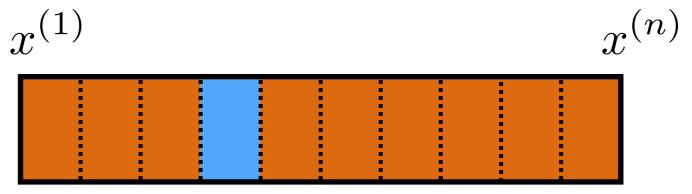
```
Cross-validate(\mathcal{D}_n, k)
   Divide \mathcal{D}_n into k chunks \mathcal{D}_{n,1},\dots,\mathcal{D}_{n,k} (of roughly equal size)
   for i = 1 to k
```



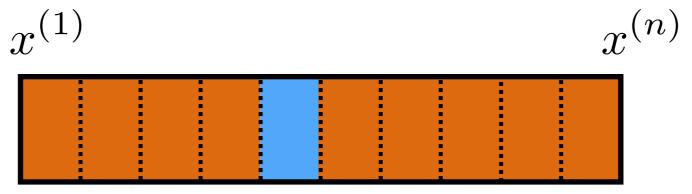
```
Cross-validate(\mathcal{D}_n, k)
   Divide \mathcal{D}_n into k chunks \mathcal{D}_{n,1},\dots,\mathcal{D}_{n,k} (of roughly equal size)
   for i = 1 to k
```



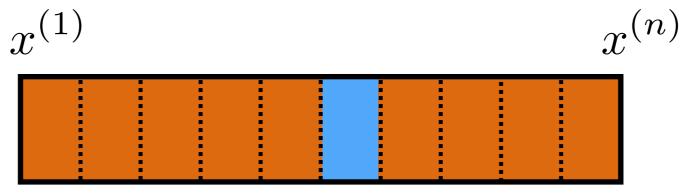
```
Cross-validate(\mathcal{D}_n, k)
   Divide \mathcal{D}_n into k chunks \mathcal{D}_{n,1},\dots,\mathcal{D}_{n,k} (of roughly equal size)
   for i = 1 to k
```



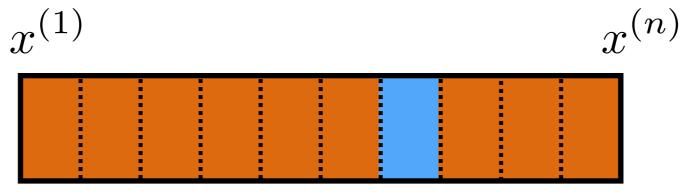
```
Cross-validate(\mathcal{D}_n, k)
   Divide \mathcal{D}_n into k chunks \mathcal{D}_{n,1},\dots,\mathcal{D}_{n,k} (of roughly equal size)
   for i = 1 to k
```



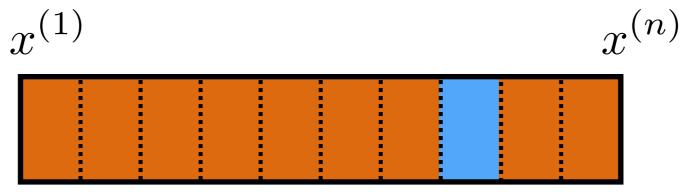
```
Cross-validate(\mathcal{D}_n, k)
   Divide \mathcal{D}_n into k chunks \mathcal{D}_{n,1},\dots,\mathcal{D}_{n,k} (of roughly equal size)
   for i = 1 to k
```



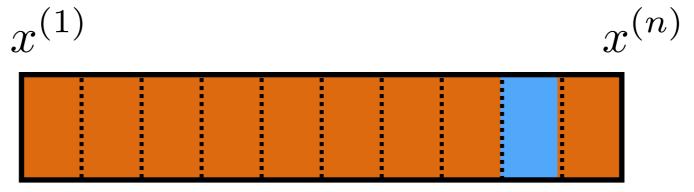
```
Cross-validate(\mathcal{D}_n, k)
   Divide \mathcal{D}_n into k chunks \mathcal{D}_{n,1},\dots,\mathcal{D}_{n,k} (of roughly equal size)
   for i = 1 to k
```



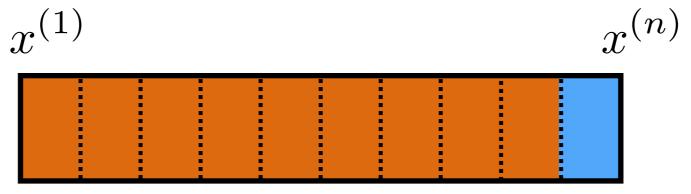
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   for i = 1 to k
```



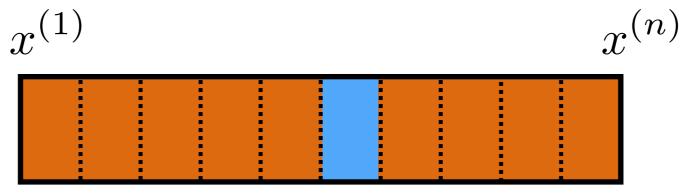
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   Divide \mathcal{D}_n into k chunks \mathcal{D}_{n,1},\dots,\mathcal{D}_{n,k} (of roughly equal size)
   for i = 1 to k
```



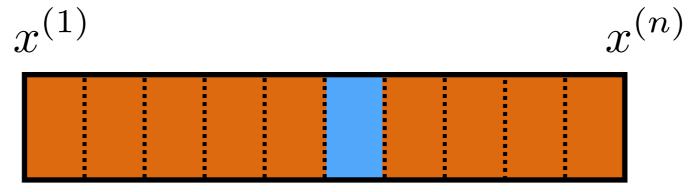
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Cross-validate(\mathcal{D}_n, k)
   Divide \mathcal{D}_n into k chunks \mathcal{D}_{n,1},\dots,\mathcal{D}_{n,k} (of roughly equal size)
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   Divide \mathcal{D}_n into k chunks \mathcal{D}_{n,1},\dots,\mathcal{D}_{n,k} (of roughly equal size)
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```
Cross-validate(\mathcal{D}_n, k)
   Divide \mathcal{D}_n into k chunks \mathcal{D}_{n,1},\dots,\mathcal{D}_{n,k} (of roughly equal size)
   for i = 1 to k
```

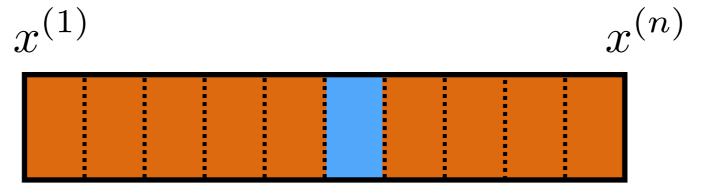


```
Cross-validate (\mathcal{D}_n, k)

Divide \mathcal{D}_n into k chunks \mathcal{D}_{n,1},\ldots,\mathcal{D}_{n,k} (of roughly equal size)

for i=1 to k

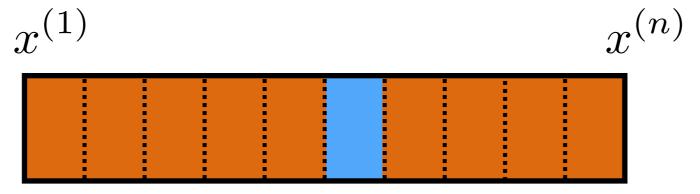
train h_i on \mathcal{D}_n \backslash \mathcal{D}_{n,i} (i.e. except chunk i)
```



```
Cross-validate (\mathcal{D}_n, k)
Divide \mathcal{D}_n into k chunks \mathcal{D}_{n,1},\ldots,\mathcal{D}_{n,k} (of roughly equal size)

for i=1 to k

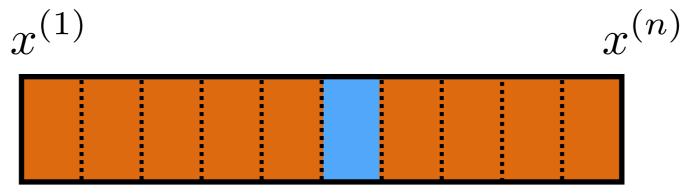
train h_i on \mathcal{D}_n \backslash \mathcal{D}_{n,i} (i.e. except chunk i) compute "test" error \mathcal{E}(h_i,\mathcal{D}_{n,i}) of h_i on \mathcal{D}_{n,i}
```



Cross-validate ( $\mathcal{D}_n$ , k)

Divide  $\mathcal{D}_n$  into k chunks  $\mathcal{D}_{n,1},\ldots,\mathcal{D}_{n,k}$  (of roughly equal size)

for i=1 to ktrain  $h_i$  on  $\mathcal{D}_n\backslash\mathcal{D}_{n,i}$  (i.e. except chunk i) compute "test" error  $\mathcal{E}(h_i,\mathcal{D}_{n,i})$  of  $h_i$  on  $\mathcal{D}_{n,i}$ Return  $\frac{1}{k}\sum_{i=1}^k \mathcal{E}(h_i,\mathcal{D}_{n,i})$ 



```
Cross-validate (\mathcal{D}_n, k)
Divide \mathcal{D}_n into k chunks \mathcal{D}_{n,1},\ldots,\mathcal{D}_{n,k} (of roughly equal size)

for i=1 to k

train h_i on \mathcal{D}_n\backslash\mathcal{D}_{n,i} (i.e. except chunk i) compute "test" error \mathcal{E}(h_i,\mathcal{D}_{n,i}) of h_i on \mathcal{D}_{n,i}

Return \frac{1}{k}\sum_{i=1}^k \mathcal{E}(h_i,\mathcal{D}_{n,i})
```

Again, good idea to shuffle order of data first